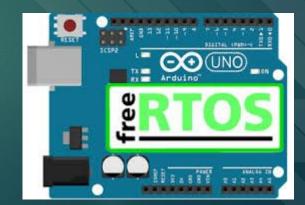
FreeRTOS: A brief introduction With Arduino

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Outlines

- Introduction
- Multi-tasking and scheduling Basics
- Queues
- Task Suspension / Resume
- Mutex
- Recommended Resource

Multi-tasking and Scheduling

With FreeRTOS (an RTOS), logical functions are placed into separate tasks that run independently

Two types of task-scheduling

- Preemptive multitasking
 - Time slice
 - Blocked
 - Yields control explicitly

- Cooperative multitasking (coroutines)
- Current task runs until it gives up control

Helloworld Program

https://github.com/engrhamzaaliimran/FreeRTOSArduino/blob/master/helloWorld.cpp

Queues

Message-queue facility provides a safe way to communicate a complete message

It limits the length of the queue so that a sending task can't use up all the memory

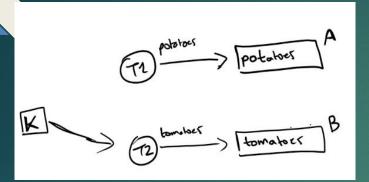
By using a predetermined queue length, the task adding messages becomes blocked until space is available

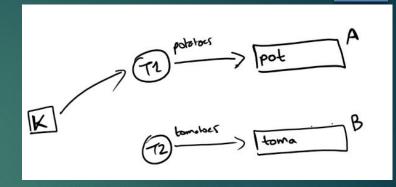
Example Program

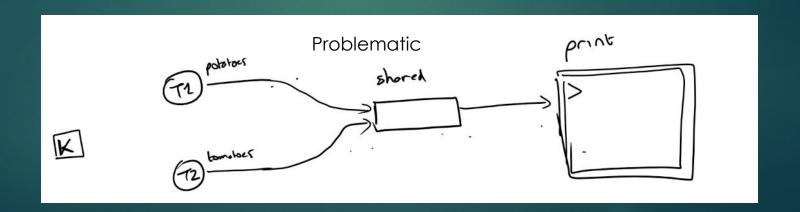
https://github.com/engrhamzaaliimran/FreeRTOSArduino/blob/master/queue.cpp

Mutex

Not Problematic









Mutex is like a lock which one puts on some shared resource before using it so that if the context switches during the processing the shared resource which could have some task being done partially, stays safe until the control come back to the original task. Following tutorial explains with example

https://github.com/engrhamzaaliimran/FreeRTOSArduino/blob/master/Mutex_use_concurency_issue_resolved.cpp



There are not much resource available for FreeRTOS with Arduino as case study. Most common option available are ARM Cortex-M3 and M4. Based boards majority stuff is same. Following are links to good resources.

Youtube Tutorial Videos (STM32-Cortex M4 based board)

https://www.youtube.com/watch?v=7efj3bJbGbk&list=PLEfMFrwVdbPYzMgeaLiFRb4ogjV8m3lt6

A detailed book (STM32-M3 based Board "Blue Pill")

https://drive.google.com/file/d/1Ls2HDznlPQs7w3KtBpnF01dkDZNX3FXU/view?usp=sharing