

HW5-1

Explanation: How interval_1ms value is determined

RealViewPB uses a **1 MHz timer clock** as shown in the lab material.

Lab05_timer

That means the timer increments **1,000,000 times per second**, or **1 tick = 1 microsecond (1µs)**.

The timer reload value is calculated using the formula given in the slide:

TimerXLoad = (Interval × TIMCLK_FREQ) / (TIMCLKENx_DIV × PRESCALE_DIV)

So:

$$\begin{aligned} \text{TimerXLoad} &= 0.001\text{s} \times 1,000,000 \text{ Hz} / (1 \times 1) \\ &= 1,000 \text{ ticks} \end{aligned}$$

The code in Slide 9 does exactly that by computing:

```
uint32_t interval_1ms = TIMER_1MZ_INTERVAL / 1000; // = 1,000,000 / 1000 = 1000
```

```
Timer->timerxload = interval_1ms;
```

So the timer reload value becomes **1000**, meaning the timer counts down 1000 clock cycles before generating an interrupt — which equals **1 millisecond**.

HW5-2

Why the line Timer->timerxintclr = 1; is necessary

Inside the timer interrupt handler:

```
static void interrupt_handler(void)
{
    slinternal_1ms_counter++;
    Timer->timerxintclr = 1; // <-- IMPORTANT
}
```

This line is required because writing **1** to **TIMERXINTCLR** register **clears the interrupt flag** in the timer hardware.

Without this line:

- The interrupt status bit remains set,
- The timer will repeatedly trigger the interrupt **immediately**,
- The CPU will stay stuck inside the interrupt handler forever,
- The system would never return to normal program execution.

So this write operation tells the timer:

The interrupt has been serviced. Clear the flag so next interrupt occurs only after the next 1 ms countdown.