

Assignment -1

Ans. An Operating System (0s) is

System software that manages

computer hardware and software

resources; providing services for

computer programs. It acts as an

interface between users and the

hardware, ensuring efficient res
ource allocation and system

functionality.

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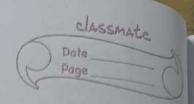
Application 29900

Operating System

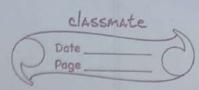
Hardware

Q.2. What are the various main functions of an 05?

Ans. The main functions of an Operating System include:

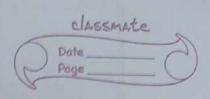


1. Process Management - Controls the execution of processes, scheduling and resource allocation. 2. Memory Management-Manages primary memory allocation for processes. 3 File System Management - Organ izes, stores pretrieves, and secur Affice ensuring ensulh 4. Device Management - Manages input loutput (II 10) devices via device drivers 5 Security & Access Control-Prote cts data from unauthonized access and moil gold 6 User Interface (UI) Management Provides CLT/ Command-line Interface or GUI (Graphical User Interface) 7. Networking-Enables communication between devices over a network 8 Error Detection & Handling-Identifies and responds to system envorsa

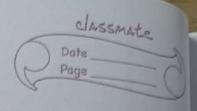


0.3.	Describe the structure of the
of a con	Process Control Block (PCB).
Ans.	2) dot anno 29 hubat and
timil	send by PIDdo + hasarings
	Process State
0	ail- noispea BET outote OIT a
190	CPU registers
	Memory
minta	IIO Status, 10
	scheduling info
D	.091 900
	The Process Control Block (PCB) is
two o	a data structure used by the
	as to store information about
2530000	a process. It contains:
	Process ID (PID) - Unique iden-
2 15 17 18	tifier to each process.
1 2	Process State - Indicates if the
aldot	process is running ready wait
	ingsetc.
09 1/3.	Program Counter (PC)-Stores
22	the address of the next
	instruction of 900 state
1 + 4.	CPU Registers - Holds value for

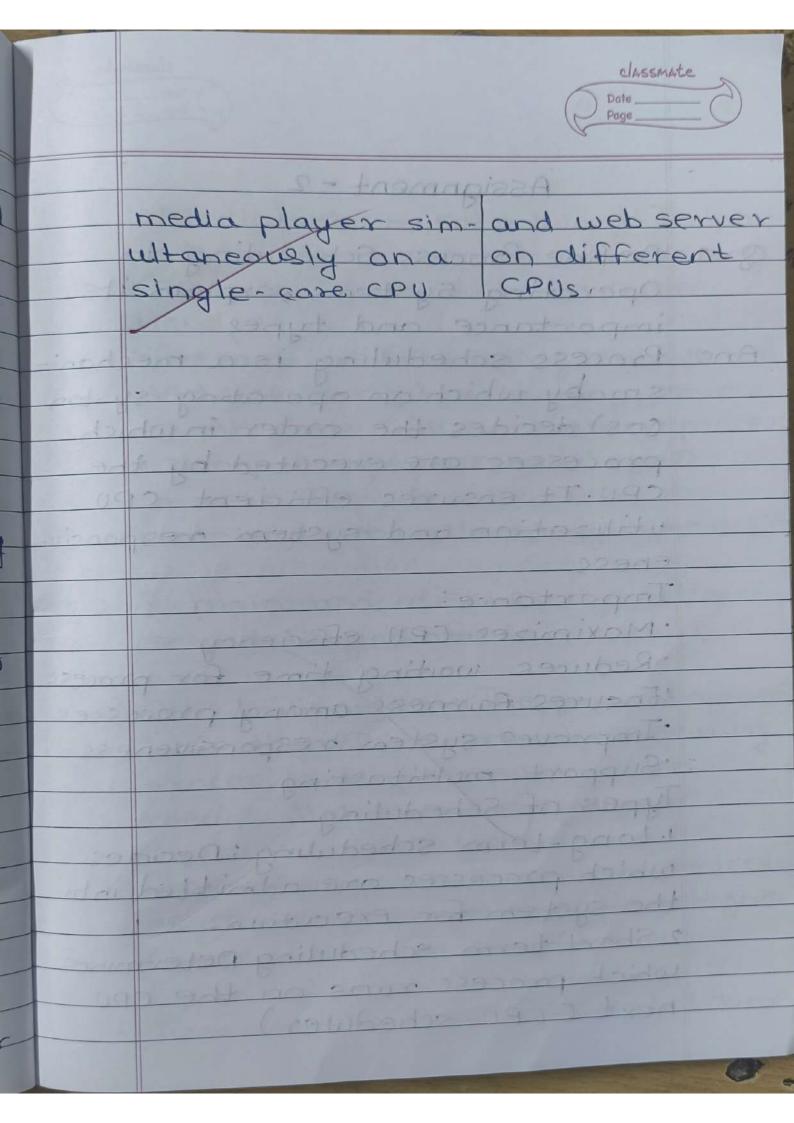
process execution
. 5 Memony management infance
ion-Includes page table
segment tables , and basellini
registers.
6 Ilo Status Information - lists
and carra resources and open
files. Mondom
7. Scheduling Information - Contain
The state of the s
queues.
The Proceed Content Prock Circes is
9.4. What do you understand about
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Switching is the
na process a l'ille et a ruppi-
state of and loading the
state of another process. It
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the CPU between multiple
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state CPCB update).
2 loading the new process state

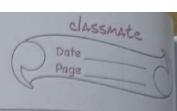


3. Resuming execution of the new process. This process ensures fair CPU utilization but incurs overhead due to frequent switching Q.S. What do you understand about threads 7 Explain the concept of multithreading in an Operating System. paisognongithum Ans. A thread is the smallest unit of a process that can be executed independently. It shares process resources like memory but has its own stack and registers. Multithreading refers to the execution of multiple threads within a single process. It imp roves performance by allowing parallel execution of tasks within the same program. Types of Multithreading: 1. User-Level Threads - Managed by wer applications, not the O Sendatah han goward daw



2 Kernel-Level Threads - Manage
directly by the os
Careery by All Hithmooding
Benefite of Multithreading
-Improved CPU utilization
Faster execution of tasks
Better system responsiveness
threads 7 Explain the conc
Differentiate Multitasking and
MATI OTOCESSING.
Multitasking Multiprocessing
NS ad and but esquarg a
Running multiple Running multiple
processes on a processes wing
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single CPU using multiple cpus
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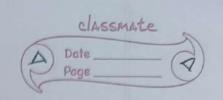
Assignment - 2

g. 1. Define Process Scheduling in Operating systems sexplain its importance and types. Ans. Process scheduling is a mechanic sm by which an operating system cos) decides the order in which processes are executed by the CPU. It ensures efficient CPU utilization and system responsit enesc Importance: · Maximizes CPU efficiency · Reduces waiting time for process Ensures fairness among processes ·Improves system responsiveness

· Support multitasting. Types of Scheduling!

1. Long-term scheduling: Decides which processes are admitted into the system for execution

2. Short-term scheduling: Determines which process runs on the CPU next CCPU scheduler)

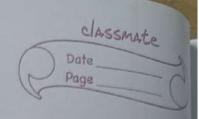


3. Medium-term scheduling: Temporanily removes processes frommemory (Swapping) to optimize resource usuage.

os to interrupt a running process
to allocate CPU to another process
5. Non-preemptive scheduling: A

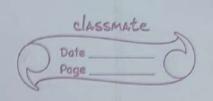
process keeps the CPU until it

- g.2. Explain and discuss the following scheduling criteria:
 - a) CPU Utilization The percentage of time the CPU is actively executing processes. Higher utilization means better performance.
 - b) Throughput- The number of processes es completed per unit time. Higher throughput is desirable.
 - c) Turnaround Time-The total time

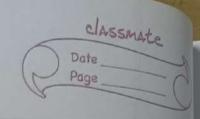


taken for a process from submission to completion Lower turnamend and time is better

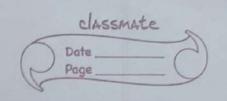
- d) Waiting Time-The time a process
 spending waiting in the ready
 queue Lower waiting time
 improves system efficiency
- e) Response Time-The time taken from process submission to the first response. Lower response time is crucial for interactive systems
- 9.3. Compare and contrast the performance of different sched uling algorithm with respect to CPU utilization a Throughput, Turnaround Time, waiting Time Response Time



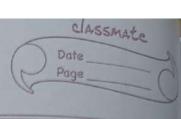
ba	Scheduling CPU Through TAT WT RT						
	Algo Utilization put						
1.	FCFS Low Moderate High High						
2.	SJF high high low low						
3.	RR Moderate high Moderate Moderate low						
	Priority high variable Variable Variable Variable Variable						
70 25	no malding anthan looted						
9.4.	Define Inter-Process Communication						
9	CIPC) and explain its importance						
200	in a multi-process system.						
Ans.	Inter-Process Communication						
	refer to mechanism that allow						
Jan Contract	process to exchange data and						
Along	co-ordinate execution.						
	Importance:						
	enable data sharing between						
	· support synchronization in						
0.7	- PARCUTALIA						
	1 compadillar acsign						
-100	processes perform independent						
	1 dictor hitecation						
	essential in assument and multiprocessing environment.						
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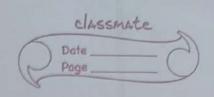
9.5. What is Mutual Exclusion sand how doest it relate to the critical section problem Ans. Mutual exclusion ensures that one process access a shared resource at a time. Critical section problem occurs when multiple process attempt to access a shared resource simultaneously leading to data inconsistency Solution: Use synchronization mechanisa like Semaphores blocks, Peak rson's algorithm to ensure Mutual Exclusion. Q.6. Explain Peterson's solution to the critical section problem? Ans. Used for two processes to all ieve mutual exclusion. ·USPR ! -1) Flag (2) - Indicates if a process



7 turn - Decides whose turn it is. · Process set its flag to tirk and gives turn to the other process. · Enters critical section only if the other process is not in it. · After execution it resets its Flag to false. · Ensures mutual exclusion, avoids deadlock and allows tair execution. 97 Explain strict alteration solution for the critical section problem? Ans uses a tyrn variable to allow two process to take turns accessing the critical section. · Process Po mins if turn == 0, to sets turn = 1, · Process P, runs if turn == 1, then set turn=0. · Problem - muses unnecessary waiting if one process is slow.
Not efficient for real-world systems



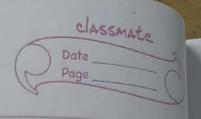
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Q.8.	Explain following terms.
a	Semaphores
Ans	A counter used to control accept
DAT B	to shared resources.
	at reinforce ai pagrongs read-to
b)	Event counter
	Similar to semaphones but well
	when order matters.
- Anthon	ova moderation being stantangle
()	Monitors
	High level synchronization tool
Emel4	that allows safe access to
ourt 6	Shared resources
pai	somme add to the some.
a)	Message passing
Ans.	Processes communicate by
	sending and receiving
1344	messaging.
	OF MONTH 499
Q.9.	What are potential challenges
- Bril	or issues faced when implement
The part	ing inter-organic
	mechanisms? communication
Ans.	2 can de la canada
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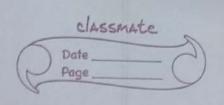
- · Synchronization issues · Deadlocks · Data consistency problems
- · Performance overhead
 - g.10. Compare & contrast dif synchron ization techniques (semaphores, monitors, message passing) with respect to:
 - · Ease to use
 - · Performance de dinom
 - · Deadlock prevention
 - · Scalability in multicose system

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11113	Ease of use	Performance	Deadlack	Schbility
Semaphore		High	needs	Good
Tall lead to to	(d leanit	000 2 20	extraina	
Monlton	Easy	medium	Handles deadlock	limited
Message	0	Medium	Prevent	Scalable
passing	000 00 00	ill Ayava	deadlocks	-

9.11. How do semaphores help in solving the producer-consumer problem &



what is the role of the buffer in this solution? Ans. Semaphores control access to the shared buffer to ensure sm oth synchronization between producer (who adds item) ? the consumer Cubo retheresite · How semaphores help! 1 Mutex semaphore - Ensure mutual exclusion so only one process modifies the buffer at a time @ Empty Semaphone - Keeps track of empty slots in the buffer 3 Full semaphase - keeps track of filled slots in the buffer. · Buffer Roxe - Holds items produced by the produced & consumed by the consumer, milles - Prevents overfilling or underflow ·Working - Producer adds an item ? decreases empty, increases full - Consumer remove an tem ?



increases empty, decreases full. - Mutex ensures only one process accesses the buffer at a time 9.12. How can message passing be used to solve the producer-consu mer problem? Ans. Message passing allows the producer to send items to the consumer through a communication channel (like a queue or pipe) · The producer sends a messagel item) to the queue & the consumer retrieves it. · How it works: - Producer place an item in the queux (message passing) - Consumer retrieves the item From the queue when ready. - No client access to the buffer, synchronization is handled by the message-passing system.