Assignment -2

- 1. What is synchronization in the context of operating systems, and mention the problems that could occur if synchronization is not achieved.
- 2. What is a critical section? Why is it necessary to protect critical sections in a concurrent environment?
- 3. What is a race condition? Explain using the example of the Producer–Consumer problem.
- 4. List and define the three conditions needed to achieve synchronization.
- 5. Explain the concept of strict alternation as a software solution for synchronization. Under what conditions is it effective?
- 6. Discuss Peterson's solution and how it ensures mutual exclusion, progress and bounded waiting.
- 7. What is semaphore? Explain the types of the semaphore.
- 8. Describe Down()/P() and Up()/V() operations for counting and binary semaphores.
- 9. Explain how semaphores can be used to solve the producer-consumer problem.
- 10. Present the dining philosopher problem. Why does it illustrate challenges in synchronization? Provide a solution to the dining philosopher problem using semaphores.
- 11. Define the reader-writer problem. Explain how semaphores can be used to address the reader-writer problem.
- 12. Define a monitor in the context of synchronization. Provide an example of producer—consumer problem and explain how monitors can be applied to solve a synchronization problem.
- 13. In the below reader-write implementation using semaphore, consider the following situations and answer accordingly.

```
typedef int semaphore:
                                       /* use your imagination */
semaphore mutex = 1;
                                       /* controls access to rc */
semaphore db = 1:
                                       /* controls access to the database */
int rc = 0;
                                       /* # of processes reading or wanting to */
void reader(void)
     while (TRUE) {
                                       /* repeat forever */
          down(&mutex);
                                       /* get exclusive access to rc */
          rc = rc + 1;
                                       /* one reader more now */
          if (rc == 1) down(\&db);
                                      /* if this is the first reader ... */
          up(&mutex);
                                       /* release exclusive access to rc */
          read_data_base();
                                       /* access the data */
          down(&mutex);
                                       /* get exclusive access to rc */
          rc = rc - 1;
                                       /* one reader fewer now */
          if (rc == 0) up(\&db);
                                       /* if this is the last reader ... */
          up(&mutex);
                                       /* release exclusive access to rc */
          use_data_read();
                                       /* noncritical region */
void writer(void)
     while (TRUE) {
                                       /* repeat forever */
          think_up_data();
                                       /* noncritical region */
          down(&db);
                                       /* get exclusive access */
          write_data_base();
                                       /* update the data */
          up(&db);
                                       /* release exclusive access */
     }
```

- (A) What happens, if we interchange, Down(&mutex) and rc = rc+1 in the reader's code.
- (B) What happens if we interchange if(rc==1) down(&db) and up(mutex) in reader's code.
- 14. Suppose we want to synchronize two concurrent processes P and Q using binary semaphores S and T. The code for the processes P and Q is shown below.

```
Process P:
while (1) {
W:
    print '0';
    print '0';
X:
}
Process Q:
while (1) {
Y:
    print '1';
    print '1';
Z:
}
```

Synchronization statements can be inserted only at points W, X, Y and Z.

Which of the following will ensure that the output string never contains a substring of the form 01ⁿ0 or 10ⁿ1 where n is odd? **Justify your answer with analysis.**

```
(A) P(S) at W, V(S) at X, P(T) at Y, V(T) at Z, S and T initially 1 (B) P(S) at W, V(T) at X, P(T) at Y, V(S) at Z, S and T initially 1 (C) P(S) at W, V(S) at X, P(S) at Y, V(S) at Z, S initially 1 (D) V(S) at W, V(T) at X, P(S) at Y, P(T) at Z, S and T initially 1
```