

# A New Setting for Some Inverse Potential Problem and The Bubbling Method

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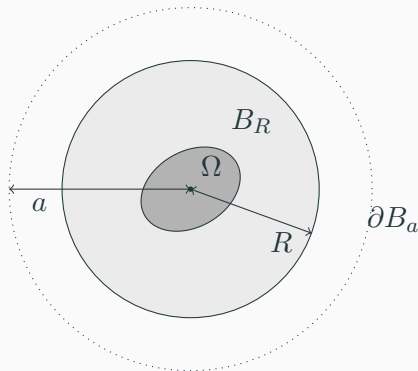
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# Abstract

Can the potential take the place of the gravity?

We investigate the influence for reconstructing the shape of  $\Omega$  when we observe the potential or the gravity on  $\partial B_a$ .



Core-Shell Model

# Core-Shell Body

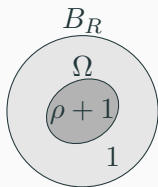
The potential of Core-shell body  $U$  is written as

$$U(x) = \frac{\int_{B_R} E(x-y)dy}{U^{B_R}} + \rho \frac{\int_{\Omega} E(x-y)dy}{U^{\Omega}},$$

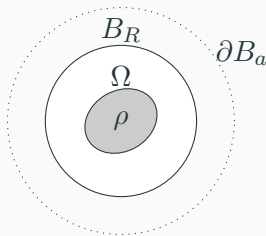
where  $E$  is the fundamental solution of the Laplace equation.

The potential  $\rho U^{\Omega}$  can be calculated on the  $\partial B_a$ .

$$\rho U^{\Omega} = U(\text{observed}) - U^{B_R}(\text{known}) \quad \text{on} \quad \partial B_a.$$



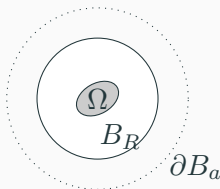
Core-shell body



Extract buried body

# A New Setting for The Inverse Potential Problem

Observe the gravity or the potential on  $\partial B_a$ , and recover the shape of  $\Omega$ .



We will compare reconstruction by observation of the gravity and the potential.

- Observation of Gravity (traditional)

$$\rho \nabla U^\Omega = \vec{g} \quad \text{on} \quad \partial B_a$$

- Observation of Potential (new)

$$\rho U^\Omega = p \quad \text{on} \quad \partial B_a$$

# Sketch of Reconstruction Algorithm

We can observe only at the finite points  $\{A_n\}_{n=1}^N \subset \partial B_a$ .

- Observation of Gravity

$$\rho \nabla U^\Omega = \vec{g} \quad \text{on} \quad \{A_n\}_{n=1}^N \subset \partial B_a$$

- Observation of Potential

$$\rho U^\Omega = p \quad \text{on} \quad \{A_n\}_{n=1}^N \subset \partial B_a$$

Reconstruction algorithm consists of two parts.

1. Approximate the body  $\Omega$  by a set of point masses  $\rightarrow$   
Optimization method
2. Homogenize the set of point masses  $\rightarrow$  Bubbling method

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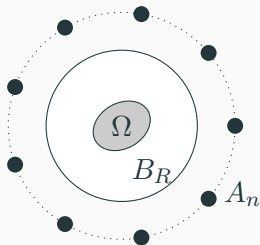
$$\rho U^\Omega = p \quad \text{on} \quad \{A_n\}_{n=1}^N \subset \partial B_a$$

Reconstruction algorithm consists of two parts.

1. Approximate the body  $\Omega$  by a set of point masses  $\rightarrow$  Optimization method
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## Apprx. Body by a Set of Point Masses (Gravity observation)

Observation points  $\{A_n\}_{n=1}^N \subset \partial B_a$ .



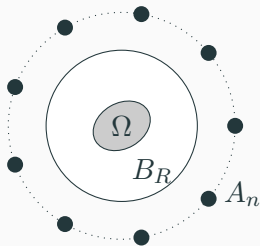
We define a cost function  $J_G$  as following. set of point mass has representation  $(X, M) = (X_1, \dots, X_K, M_1, \dots, M_K)$ .

$$J_G(X, M) = \frac{1}{N} \sum_{n=1}^N \left| \rho \nabla U^\Omega(A_n) - G_K(A_n; X, M) \right|^2,$$

$$G_K(A_n; X, M) = \frac{1}{4\pi} \sum_{k=1}^K \frac{M_k (A_n - X_k)}{|A_n - X_k|^3}$$

## Apprx. Body by a Set of Point Mass (Potential observation)

Observation points  $\{A_n\}_{n=1}^N \subset \partial B_a$ .



We define a cost function  $J_P$  as following. set of point mass has representation  $(X, M) = (X_1, \dots, X_K, M_1, \dots, M_K)$ .

$$J_P(X, M) = \frac{1}{N} \sum_{n=1}^N \left| \rho U^\Omega(A_n) - P_K(A_n; X, M) \right|^2,$$

$$P_K(A_n; X, M) = \frac{1}{4\pi} \sum_{k=1}^K \frac{M_k}{|A_n - X_k|}$$



# Sketch of Reconstruction Algorithm

We can observe only at the finite points  $\{A_n\}_{n=1}^N \subset \partial B_a$ .

- Observation of Gravity

$$\rho \nabla U^\Omega = \vec{g} \quad \text{on} \quad \{A_n\}_{n=1}^N \subset \partial B_a$$

- Observation of Potential

$$\rho U^\Omega = p \quad \text{on} \quad \{A_n\}_{n=1}^N \subset \partial B_a$$

Reconstruction algorithm consists of two parts.

1. Approximate the body  $\Omega$  by a set of point masses  $\rightarrow$  Optimization method
2. Homogenize the set of point masses  $\rightarrow$  Bubbling method

# Bubbling Method (Partial Mass Scattering)

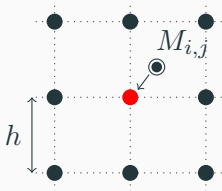
We homogenize the set of point masses to homogeneous body with density  $\rho$ .

Point mass  $(X_k, M_k)$  move to lattice point  $\tilde{X}_k = (ih, jh)$ .

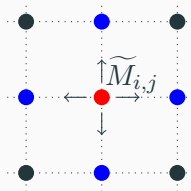
$\tilde{M}_{i,j} = M_k$ . When  $\Delta\tilde{M}_{i,j} = \tilde{M}_{i,j} - \rho h^2 > \varepsilon$ ,

$$\tilde{M}_{i,j}^{(1)} = \rho h^2 - \varepsilon,$$

$$\tilde{M}_{i\pm 1,j}^{(1)} = \tilde{M}_{i\pm 1,j} + \frac{1}{4}(\Delta\tilde{M}_{i,j} + \varepsilon), \quad \tilde{M}_{i,j\pm 1}^{(1)} = \tilde{M}_{i,j\pm 1} + \frac{1}{4}(\Delta\tilde{M}_{i,j} + \varepsilon).$$



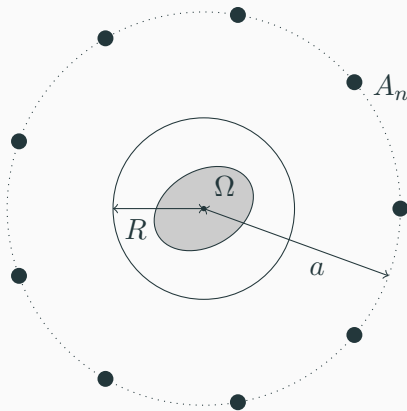
Move to lattice point



Mass Scattering

## Reconfirm The Aid of Computation

When we change radius of observation  $a$ , we verify influence for the reconstruction which is caused by this change.

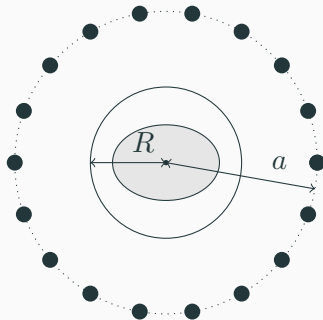


Observation at  $\{A_n\}_{n=1}^N$  and Reconstruction  $\Omega \subset B_R$

## Example: Reconstruction of Ellipsoid

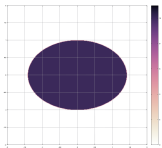
Set  $R = 2$ . We reconstruct an elliptic shape with long radius  $\sqrt{2}$ , short radius 1 and density  $\rho = 10$ . Limit of resolution is  $10^{-4}$ .

We select Levenberg-Marquardt method as a optimization method.

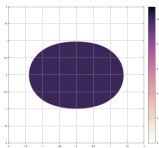


## Example: Observation of Gravity

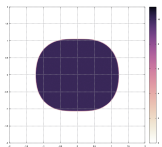
Number of point masses is  $K = 100$ , number of observation points is  $N = 300$ .  $a$  is observation radius.



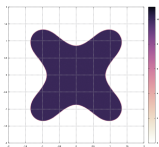
source



$a = 10$



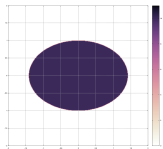
$a = 30$



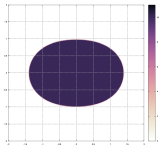
$a = 200$

## Example: Observation of Potential

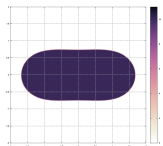
Number of point masses is  $K = 100$ , number of observation points is  $N = 300$ .  $a$  is observation radius.



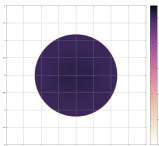
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$a = 10$



$a = 30$



$a = 200$

# Conclusion

We observe the potential and reconstruct the shape of the body, compared to observation of the gravity.

- Reconstruction of Ellipsoid

Reconstruction by observation of the potential can reconstruct source body more correctly.

