

# Optimization for Active Learning-based Interactive Database Exploration

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## Interactive Data Exploration

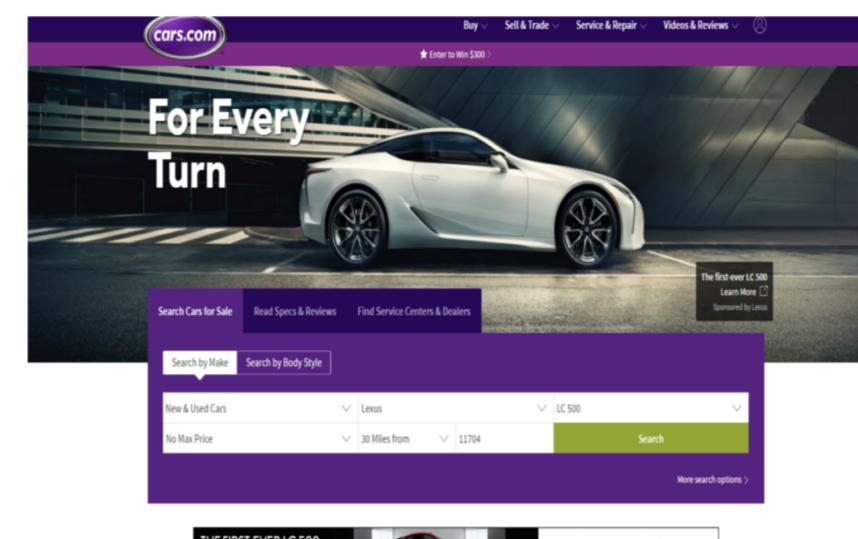
- Human-in-the-loop applications that search big datasets to discover interesting information.
- Need system-assisted exploration tools to accelerate information discovery.



Medical Applications

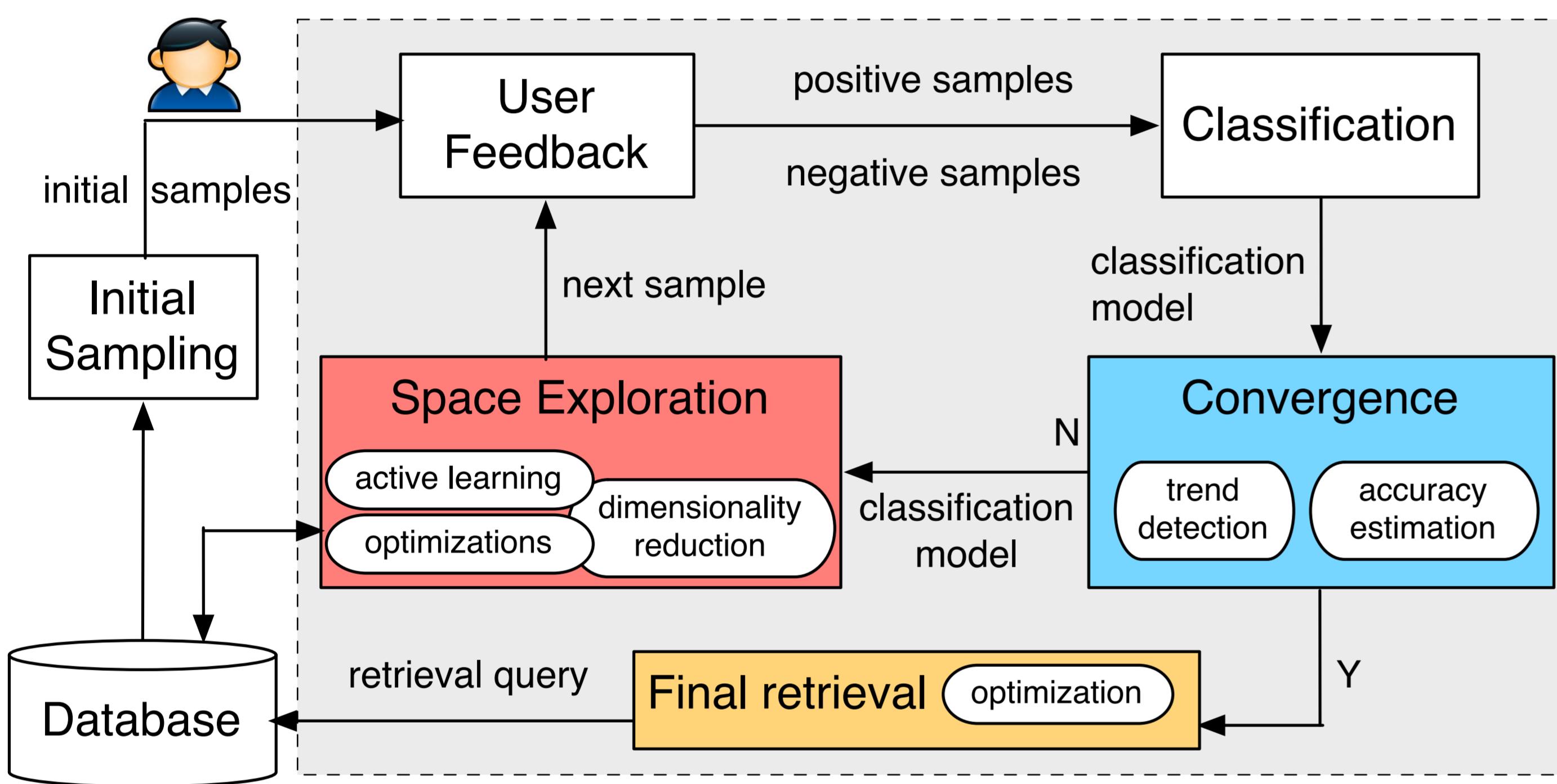


Scientific Applications



Web Applications

## An “Explore-by-Example” Approach



System architecture for explore by example

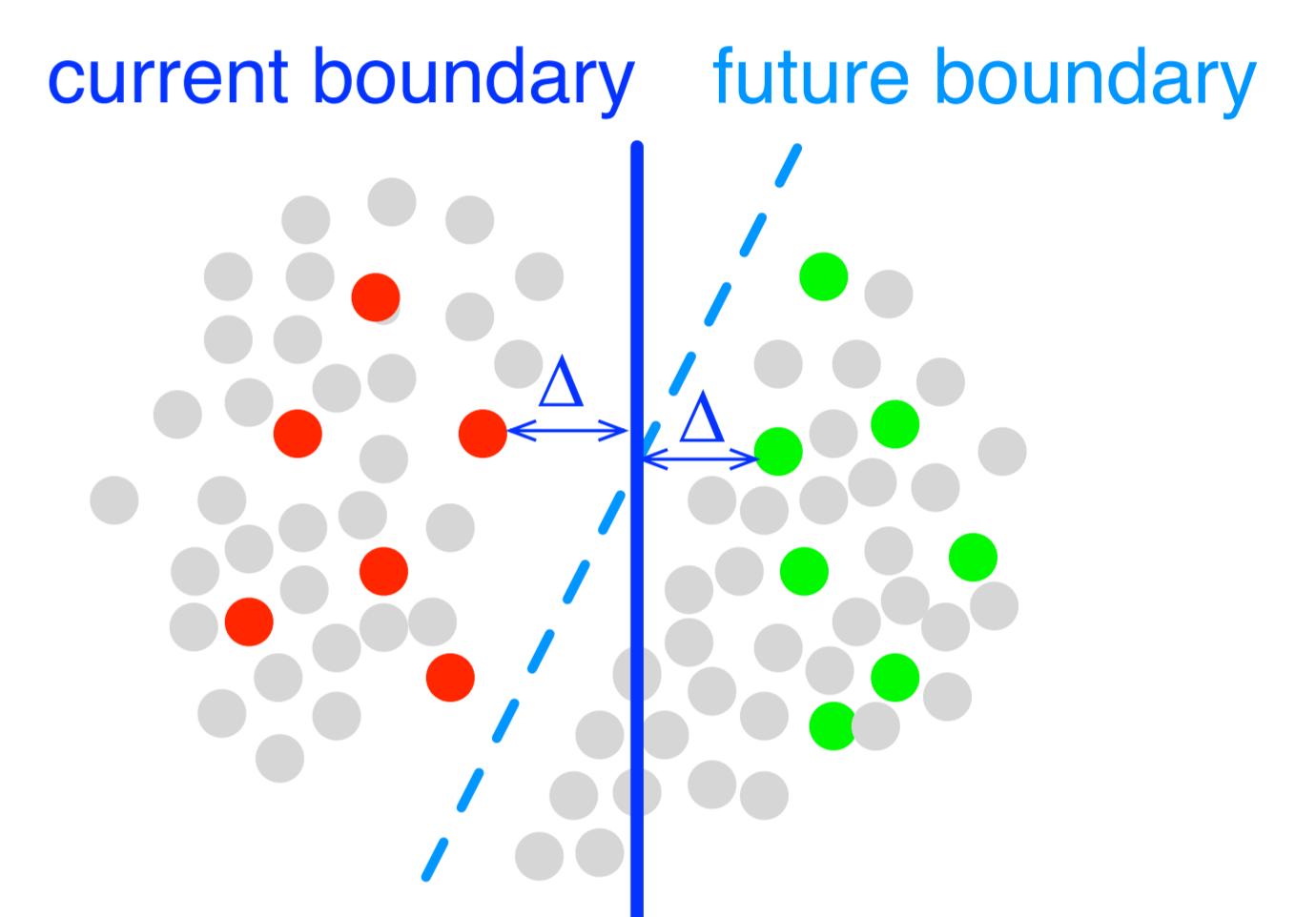
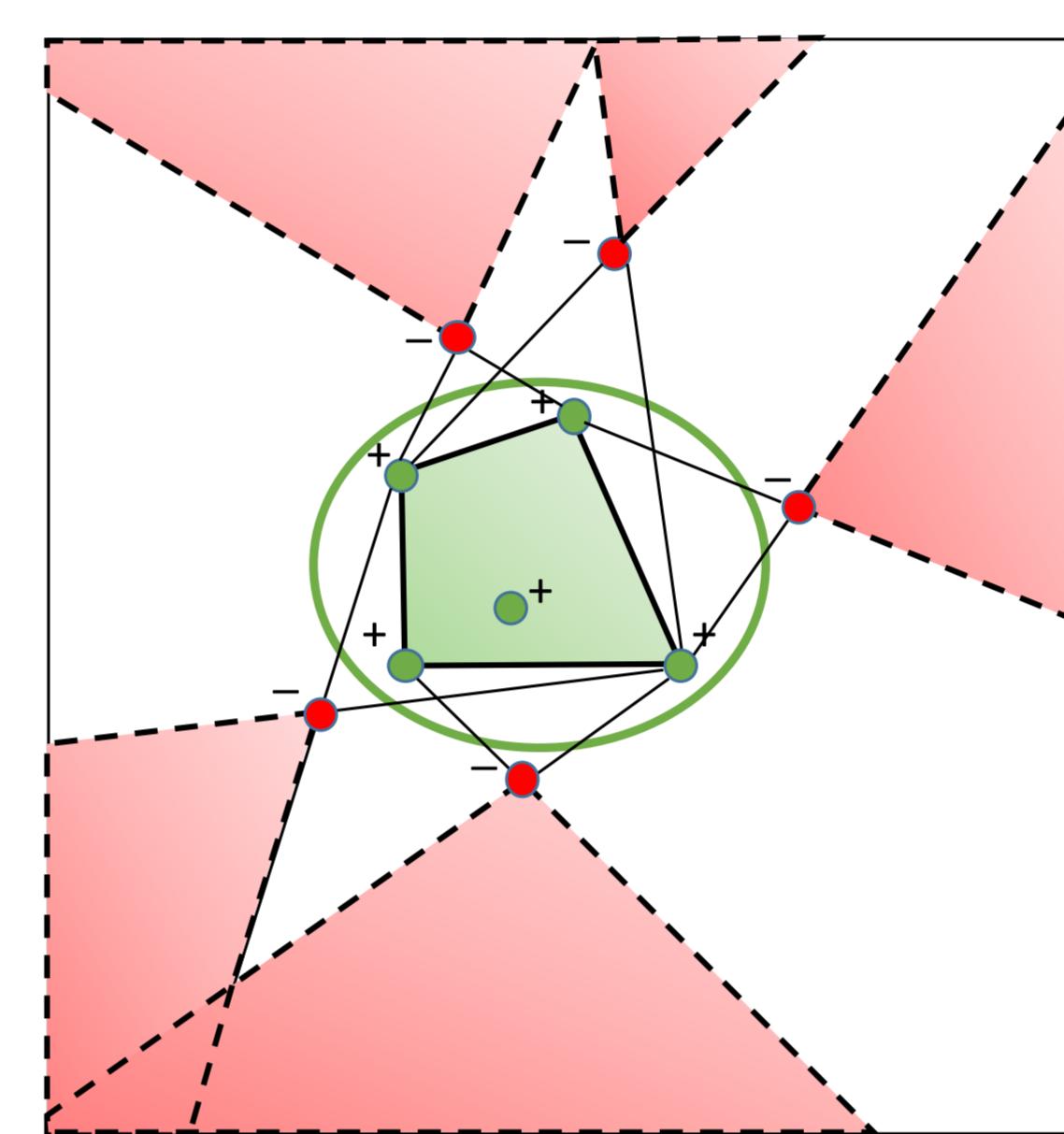
## User Interface

- **Scenario:**
  - Interactive Exploration with user-generated queries
  - Interactive Exploration with pre-defined queries
  - Comparison to Manual Exploration
- **Database:** SDSS (Sloan Digital Sky Survey), Housing, Cars

The screenshot shows the AIDE interface. On the left, there's a map of California with various locations marked. A specific house is highlighted with a callout showing details: price: 745,000, beds: 3, baths: 2. On the right, there's a control panel with dropdown menus for X Attribute (price), Y Attribute (beds), and Label (positive). Buttons for Start, switch, Label, Next Iteration, Stop, and All Relevant Objects are present. Below these are fields for Number of Samples (10), Positive Samples (3), Negative Samples (2), and Iterations (2).

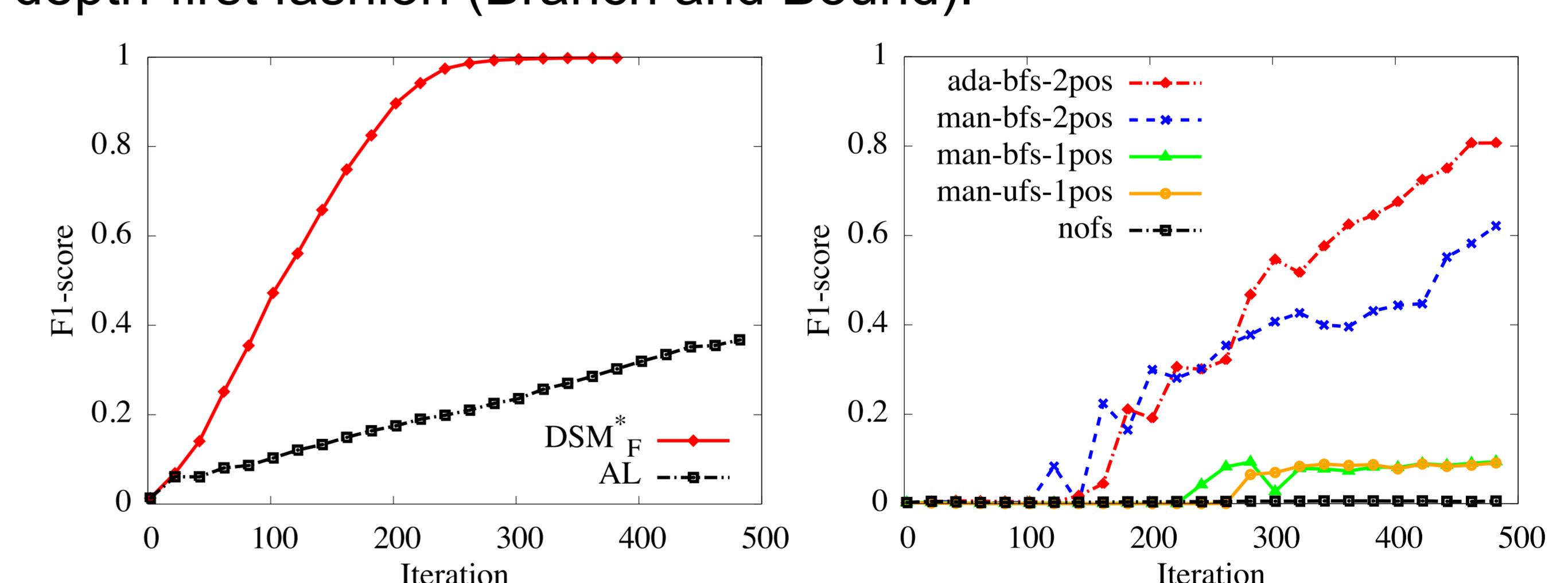
## Dual-Space Model (DSM)

- **Data-Space Model (Three-Set Partition)**  
At each iteration, all available labeled examples are leveraged to build a partitioning function of the data space, dividing the data space into three disjoint regions.
  - I. Positive region ( $R^+$ ): a convex polytope
  - II. Negative region ( $R^-$ ): the union of negative convex cones
  - III. Unknown region ( $R^u$ ):  $R^u = \mathbb{R}^d - R^+ - R^-$
- **SVM-based active learning**  
To quickly improve the accuracy of the current model, choose the most informative example which is closest to the current decision boundary as the next to-be-labeled example.



## Optimizations

- **Factorization on feature space**  
With increased dimensionality, the volume of the uncertain region may grow fast. This problem, referred to as slow convergence, can be addressed by factorizing a high-dimensional data space into a set of low-dimensional spaces and combining DSMs built in each subspace together by some rules.
- **GBRT-based dimensionality reduction**  
Adaptive strategy of using Gradient Boosting Regression Trees (GBRT) to choose top-k features from the original features based on feature importance scores.
- **Final result retrieval**  
To expedite the retrieval of the final results, build R-tree as the index over the database, and perform a top-down search in a depth-first fashion (Branch and Bound).



## User Study using a Car Database

