

# GE864 Hardware User Guide

For GE864-PY and GE864-QUAD  
1w0300694 Rev.12 – 2009-08-20



## APPLICABILITY TABLE

PRODUCT
GE864-PY
GE864-QUAD



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# 1. Introduction

## 1.1. Scope

The aim of this document is the description of some hardware solutions useful for developing a product with the Telit GE864-QUAD / PY module.

## 1.2. Audience

This document is intended for Telit customers, who are integrators, about to implement their applications using our GE864 modules.

## 1.3. Contact Information, Support

For general contact, technical support, to report documentation errors and to order manuals, contact Telit's Technical Support Center (TTSC) at:

[TS-EMEA@telit.com](mailto:TS-EMEA@telit.com)  
[TS-NORTHAMERICA@telit.com](mailto:TS-NORTHAMERICA@telit.com)  
[TS-LATINAMERICA@telit.com](mailto:TS-LATINAMERICA@telit.com)  
[TS-APAC@telit.com](mailto:TS-APAC@telit.com)

Alternatively, use:

<http://www.telit.com/en/products/technical-support-center/contact.php>

For detailed information about where you can buy the Telit modules or for recommendations on accessories and components visit:

<http://www.telit.com>

To register for product news and announcements or for product questions contact Telit's Technical Support Center (TTSC).

Our aim is to make this guide as helpful as possible. Keep us informed of your comments and suggestions for improvements.

Telit appreciates feedback from the users of our information.



## 1.4. Document Organization

This document contains the following chapters:

Chapter 1: “Introduction” provides a scope for this document, target audience, contact and support information, and text conventions.

Chapter 2: “Overview” provides an overview of the document.

Chapter 3: “GE864 Mechanical Dimensions”

Chapter 4: “GE864 Module Connections” deals with the pin out configuration and layout.

Chapter 5: “Hardware Commands” How to operate on the module via hardware.

Chapter 6: “Power supply” Power supply requirements and general design rules.

Chapter 7: “Antenna” The antenna connection and board layout design are the most important parts in the full product design.

Chapter 8: “Logic Level specifications” Specific values adopted in the implementation of logic levels for this module.

Chapter 9: “Serial ports” The serial port on the Telit GE864 is the core of the interface between the module and OEM hardware

Chapter 10: “Audio Section overview” Refers to the audio blocks of the Base Band Chip of the GE864 Telit Modules.

Chapter 11: “General Purpose I/O” How the general purpose I/O pads can be configured.

Chapter 12 “DAC and ADC Section” Deals with these two kind of converters.

Chapter 13: “Mounting the GE864 on the application board” Recommendations and specifics on how to mount the module on the user’s board.





## 1.5. Text Conventions



***Danger – This information MUST be followed or catastrophic equipment failure or bodily injury may occur.***



***Caution or Warning – Alerts the user to important points about integrating the module, if these points are not followed, the module and end user equipment may fail or malfunction.***



**Tip or Information – Provides advice and suggestions that may be useful when integrating the module.**

All dates are in ISO 8601 format, i.e. YYYY-MM-DD.

## 1.6. Related Documents

- Telit's GSM/GPRS Family Software User Guide, [1w0300784](#)
- Audio settings application note , [80000NT10007a](#)
- Digital voice Interface Application Note, [80000NT10004a](#)
- GE864 Product description, [80273ST10008a](#)
- SIM Holder Design Guides, [80000NT10001a](#)
- AT Commands Reference Guide, [80000ST10025a](#)



## 1.7. Document History

Revision	Date	Changes
ISSUE#0	2006-06-12	Release First ISSUE# 0
ISSUE #1	2005-11-22	Added notice on page 4.
ISSUE #2	2005-12-19	Added Paragr.10 Conformity Assessment Issues
ISSUE #3	2006-02-07	Added products order codes table Added Disclaimer Added Safety Recommendations
ISSUE #4	2006-09-07	Full Review of the manual Added ADC description Added DAC description Added Pin out and Process flow description Added Packaging
ISSUE #5	2006-10-03	TGPIO23 now RESERVED; modified low pass filter example for DAC, 6.1 antenna characteristics
ISSUE #6	2006-10-23	Updated "GE864 orientation on the tray" layout.
ISSUE #7	2007-02-08	Pin out updated, Camera removed, Added Stat Led and GPIO5 description, added VAUX1, schematics updated for ON_OFF, reset, level adapter 5V, RS232 transceiver, Power supply. Modified Charger description.
ISSUE #8	2007-06-07	Updated DISCLAIMER, Added note on charger (CFUN4 and ON_OFF), Added Power consumptions table, Added new table for GPIO status in Reset and Power on, added RFTXMON timing, Switching description modified in "+ 12V input Source Power Supply Design Guidelines", Added Alternate Function for GPIO4, Added BGA balls mechanical drawing.
ISSUE #9	2007-06-19	Modified absolute maximum ratings; added GPIO2 Alternate function description
ISSUE #10	2008-06-10	Par 02: Updated Mechanical drawings Par 3.1: Removed nominal values on Audio, added DVI description Par 5.1: Added Supply Voltage Range Par 11.7: GPIO7 description; added section on Buzzer description Par 9: Audio section removed (a dedicated User guide on audio has been created) Par 5.2.1.4: added note on Charger Par 8.1: tip on RXD pull up added EVK chapter removed
ISSUE #11	2009-01-22	Updated P/N list Updated BGA grid 3.1.1 Updated operating voltage Added useful parameters for ATEX applications Updated absolute maximum range on 1.8CMOS Updated flow chart on Audio section
ISSUE#12	2009-05-26	Applied new layout + minor editing Modified idle consumption values Noted in the pin-out section about rts in need of being connected to ground p.17 Modified picture at p.74 (modules tray) Edited PCB pad design par.13.1.6 Added DVI info in the pin-out section + notice Added DVI App Note in the related documents list





## 2. Overview

In this document all the basic functions of a mobile phone will be taken into account; for each one of them a proper hardware solution will be suggested and eventually the wrong solutions and common errors to be avoided will be evidenced. Obviously this document cannot embrace the whole hardware solutions and products that may be designed. The wrong solutions to be avoided shall be considered as mandatory, while the suggested hardware configurations shall not be considered mandatory, instead the information given shall be used as a guide and a starting point for properly developing your product with the Telit GE864-QUAD / PY module. For further hardware details that may not be explained in this document refer to the Telit GE864-QUAD / PY Product Description document where all the hardware information is reported.



### NOTICE:

The integration of the GSM/GPRS GE864-QUAD / PY cellular module within user application shall be done according to the design rules described in this manual.

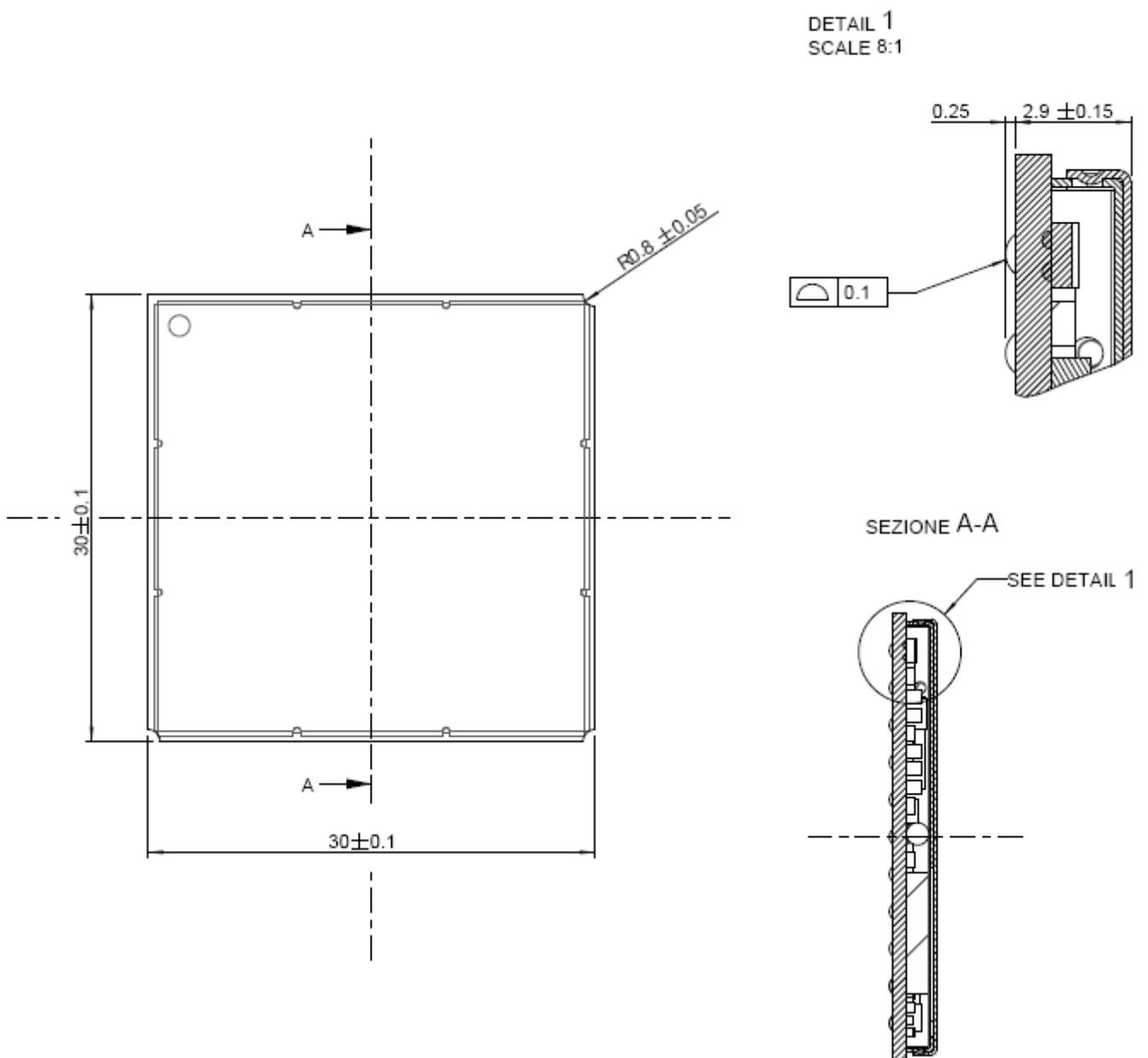
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### 3. GE864 Mechanical Dimensions

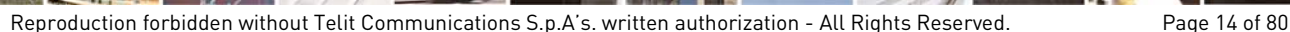
The Telit GE864 module overall dimensions are:

- Length: 30 mm
- Width: 30 mm
- Thickness: 2.9 mm



#### 4.1. PIN-OUT

<sup>1</sup> On this line a maximum of 10nF bypass capacitor is allowed





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Ball	Signal	I/O	Function	Internal PULL UP	Type
A1	GND	-	Ground		Power
F1	GND	-	Ground		Power
H1	GND	-	Ground		Power
L1	GND	-	Ground		Power
H2	GND	-	Ground		Power
L2	GND	-	Ground		Power
J3	GND	-	Ground		Power
K3	GND	-	Ground		Power
L3	GND	-	Ground		Power
K4	GND	-	Ground		Power
K5	GND	-	Ground		Power
D6	GND	-	Ground		Power
K6	GND	-	Ground		Power
L6	GND	-	Ground		Power
A11	GND	-	Ground		Power
F11	GND	-	Ground		Power
L11	GND	-	Ground		Power
RESERVED					
A10		-			
A3		-			
A4		-			
A5		-			
A6		-			
A7		-			
A8		-			
A9		-			
B10		-			
B11		-			
B2		-			
B8		-			
B9		-			
C4		-			
C8		-			
D2		-			
D3		-			
E1		-			
E10		-			
E3		-			
E4		-			
F2		-			
F3		-			
F4		-			
G6		-			
G7		-			



Ball	Signal	I/O	Function	Internal PULL UP	Type
H4		-			
H7		-			
J4		-			
J6		-			
J7		-			
K9		-			
L5		-			
E5		-			
L7		-			
G5		-			
G3		-			
C6	DVI1_TX	-	Digital Transmitting Data	4.7K	CMOS 2.8
F8		-			
C5		-			



**NOTE:**

The GE864-QUAD and GE864-PY have two DVI ports on the system interface.

Only one port can be selected and be active at the time. The choice of DVI port depends on the needs of the application.

For master mode Telit suggests that applications only use the DVI2 port as this minimizes the impact on the module functionality.

**NOTE:**

RESERVED pins must not be connected

**NOTE:**

If not used, almost all pins must be left disconnected. The only exceptions are the following pins<sup>2</sup>:

pin	signal
J1,K1,J2,K2	VBATT
A1,F1,H1,L1,H2,L2,J3,K3,L3, K4,K5,D6,K6,L6,A11,F11,L11	GND
J5	ON/OFF*
E7	TXD
A2	RESET*
H8	RXD
F7	RTS

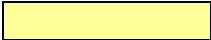









<sup>2</sup> RTS should be connected to the GND (on the module side) if flow control is not used.



*Top view*

	A	B	C	D	E	F	G	H	J	K	L
1	GND	TGPIO_19	TGPIO_01	TGPIO_11	-	GND	CHARGE	GND	VBATT	VBATT	GND
2	RESET*	-	TGPIO_03	-	VRTC	-	CHARGE	GND	VBATT	VBATT	GND
3	-	TGPIO_04	TGPIO_20	-	-	-	-	TGPIO_10	GND	GND	GND
4	-	TGPIO_14	-	SIMVCC	-	-	TGPIO_12	-	-	GND	Antenna
5	-	TGPIO_06 / ALARM		VAUX1	-	TGPIO_15	-	TGPIO_17	ON_OFF*	GND	-
6	-	C125/RING		GND	TGPIO_02 / JDR	C106 / CTS	-	TGPIO_16	-	GND	GND
7	-	C108 / DTR	DAC_OUT	DVI2_CLK	C103 / TXD	C105 / RTS	-	-	-	TGPIO_18	-
8	-	-	-	STAD_LED	TGPIO_22	-	MIC_HF+	C104 / RXD	MIC_MT+	TGPIO_05 / RFTXMON	PWRMON
9	-	-	TGPIO_09	C109 / DCD	SIMRST	AXE	MIC_MT-	EAR_MT-	MIC_HF-	-	TGPIO_07 / BUZZER
10	-	-	SIMCLK	SIMIO	-	RX_TRACE	EAR_MT+	EAR_HF+	EAR_HF-	TGPIO_13	TGPIO_21
11	GND	-	SIMIN	TX_TRACE	C107 / DSR	GND	ADC_IN3	ADC_IN2	ADC_IN1	TGPIO_08	GND



	AUDIO Signals balls
	SIM CARD interface balls
	TRACE Signals balls
	Prog. / data + Hw Flow Control signals balls
	DAC and ADC signals balls
	MISCELLANEOUS functions signals balls
	TELIT GPIO balls
	POWER SUPPLY VBATT balls
	POWER SUPPLY GND balls
	RESERVED



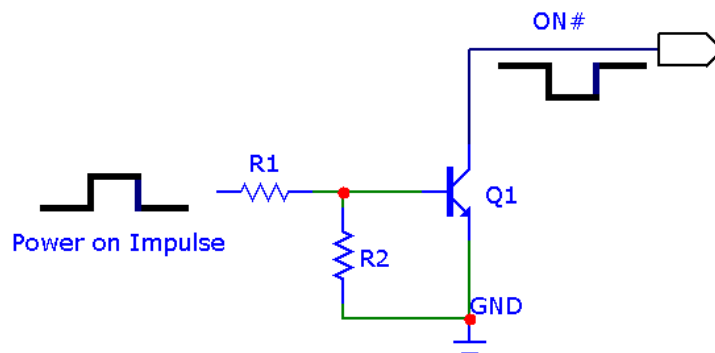
## 5. Hardware Commands

### 5.1. Turning ON the GE864-QUAD / PY

To turn on the GE864-QUAD / PY the pad ON# must be tied low for at least 1 second and then released.

The maximum current that can be drained from the ON# pad is 0,1 mA.

A simple circuit to do it is:



#### NOTE:

Do not use any pull up resistor on the ON# line, it is internally pulled up. Using pull up resistor may bring to latch up problems on the GE864-QUAD / PY power regulator and improper power on/off of the module. The line ON# must be connected only in open collector configuration.

#### NOTE:

In this document all the lines that are inverted, hence have active low signals are labeled with a name that ends with a “#” or with a bar over the name.

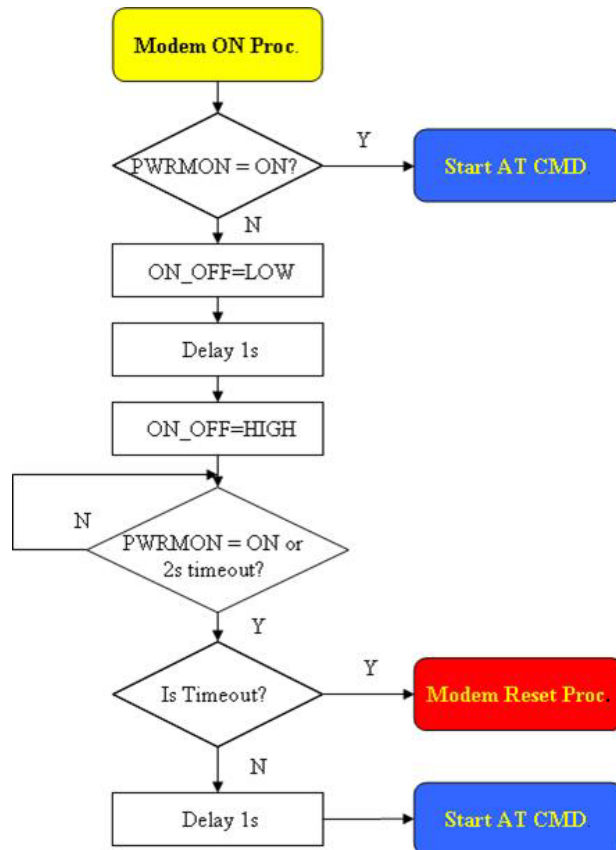
#### NOTE:

The GE864-QUAD / PY turns fully on also by supplying power to the Charge pad (Module provided with a battery on the VBATT pads).





A flow chart showing the proper turn on procedure is displayed below:



**TIP:**

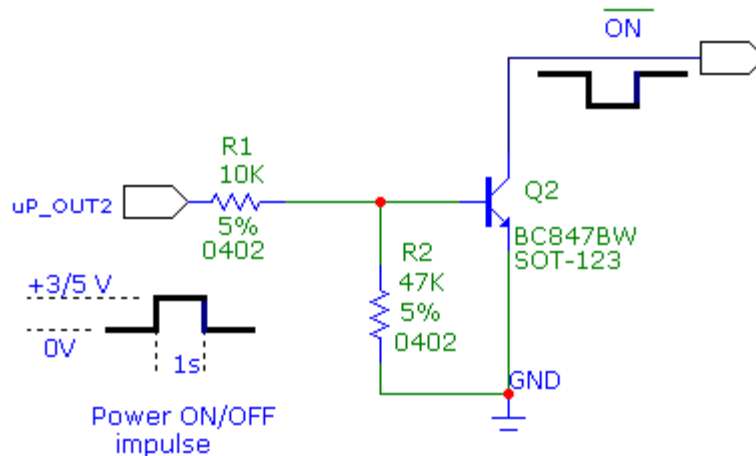
To check if the device has powered on, the hardware line PWRMON must be monitored. After 900ms the line raised up the device could be considered powered on.

PWRMON line rises up also when supplying power to the Charge pad



For example:

Let us assume you need to drive the ON# pad with a totem pole output of a +3/5 V micro controller (uP\_OUT1):



Let us assume you need to drive the ON# pad directly with an ON/OFF button:

## 5.2. Turning OFF the GE864-QUAD / PY

The turning off of the device can be done in three ways:

- by software command (see GE864-QUAD / PY Software User Guide)
- by hardware shutdown
- by Hardware Unconditional Restart

When the device is shut down by software command or by hardware shutdown, it issues to the network a detach request that informs the network that the device will not be reachable any more.

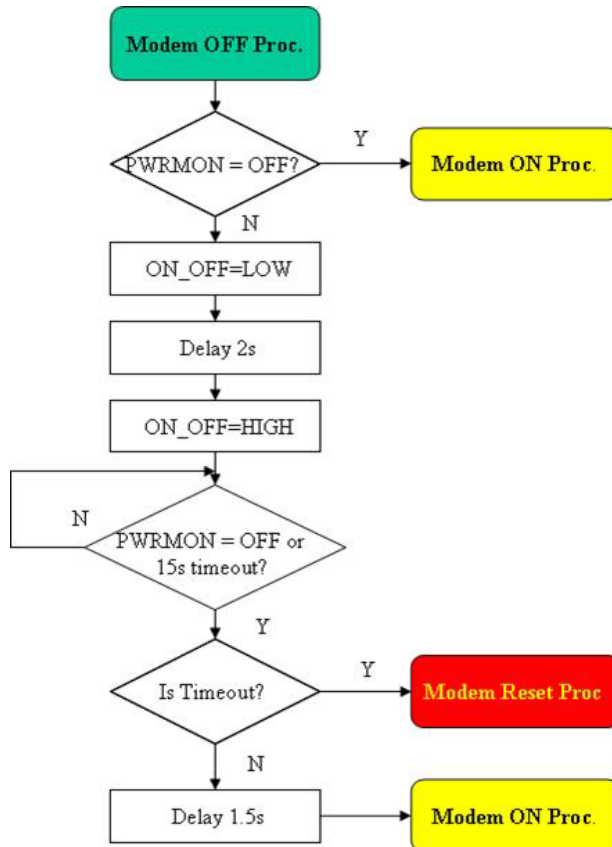
### 5.2.1. Hardware Shutdown

To turn OFF the GE864-QUAD / PY the pad ON# must be tied low for at least 2 seconds and then released.

The same circuitry and timing for the power on shall be used.

The device shuts down after the release of the ON# pad.





**TIP:**

To check if the device has powered off, the hardware line PWRMON must be monitored. When PWRMON goes low, the device has powered off.

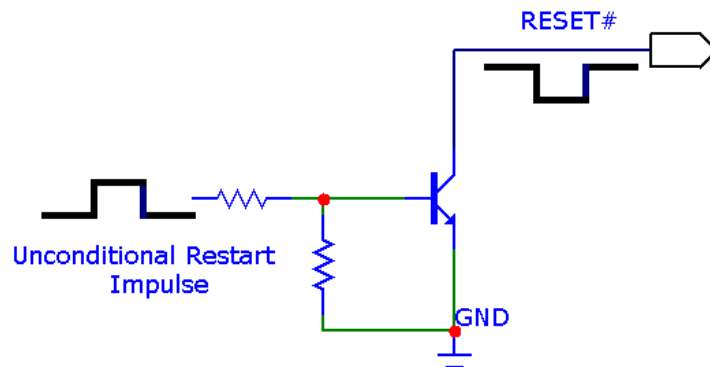
## 5.2.2. Hardware Unconditional Restart

To unconditionally Restart the GE864-QUAD / PY, the pad RESET# must be tied low for at least 200 milliseconds and then released.

The maximum current that can be drained from the ON# pad is 0.15 mA.

A simple circuit to do it is:





**NOTE:**

Do not use any pull up resistor on the RESET# line nor any totem pole digital output. Using pull up resistor may bring to latch up problems on the GE864-QUAD / PY power regulator and improper functioning of the module. The line RESET# must be connected only in open collector configuration.



**TIP:**

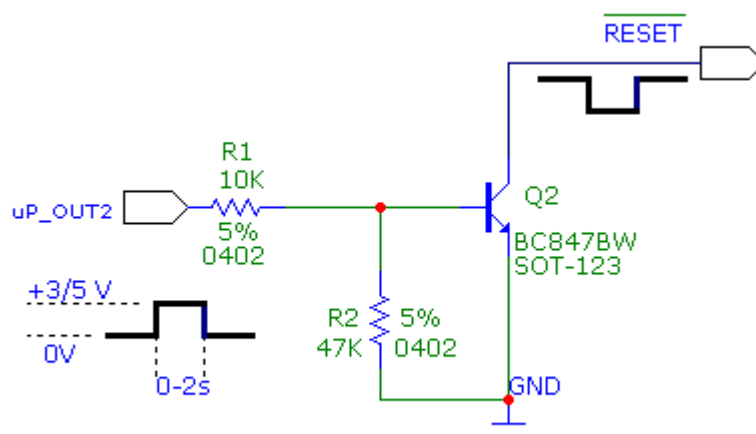
The unconditional hardware Restart must always be implemented on the boards and must be used by the software as an emergency exit procedure.



```

graph TD
    A[Modem Reset Proc] --> B[Reset = LOW]
    B --> C[Delay 200ms]
    C --> D[Reset = HIGH]
    D --> E{PWRMON = OFF}
    E -- Y --> F[Delay 1s]
    F --> G[Modem ON Proc.]
    E -- N --> H[Delay 1s]
    H --> I[Start AT CMD.]
  
```

Let us assume you need to drive the RESET# pad with a totem pole output of a +3/5 V microcontroller (uP\_OUT2):



## 6. Power Supply

The power supply circuitry and board layout are a very important part in the full product design and they strongly reflect on the product overall performances, hence read carefully the requirements and the guidelines that will follow for a proper design.

### 6.1. Power Supply Requirements

POWER SUPPLY		
	SW rel. 7.02.xx4 or older	SW rel. 7.03.x00 or newer
Nominal Supply Voltage	3.8 V	3.8 V
Max Supply Voltage	4.2 V	4.5 V
Supply voltage range	3.4 V - 4.2 V	3.22 V - 4.5 V

The table below shows the GE864-QUAD / PY power consumptions:

GE864-QUAD/PY		
Mode	Average (mA)	Mode description
<b>IDLE mode</b>		Stand by mode; no call in progress
AT+CFUN=1	24,0	Normal mode: full functionality of the module
AT+CFUN=4	22,0	Disabled TX and RX; module is not registered on the network
AT+CFUN=0 or AT+CFUN=5	2,6	Power saving: CFUN=0 module registered on the network and can receive voice call or an SMS; but it is not possible to send AT commands; module wakes up with an unsolicited code (call or SMS) or rising RTS line. CFUN=5 full functionality with power saving; module registered on the network can receive incoming calls and SMS
<b>RX mode</b>		GSM Receiving data mode
1 slot in downlink	52,3	
2 slot in downlink	65,2	
3 slot in downlink	78,6	
4 slot in downlink	88,4	
<b>GSM TX and RX mode</b>		GSM Sending data mode
Min power level	78,1	
Max power level	200,1	
<b>GPRS (class 10) TX and RX mode</b>		GPRS Sending data mode
Min power level	123,7	
Max power level	370,8	

The GSM system is made in a way that the RF transmission is not continuous, else it is packed into bursts at a base frequency of about 216 Hz, the relative current peaks can be as high as about 2A. Therefore the power supply has to be designed in order to withstand with these current peaks without big voltage drops; this means that both the electrical design and the board layout must be designed for this current flow.







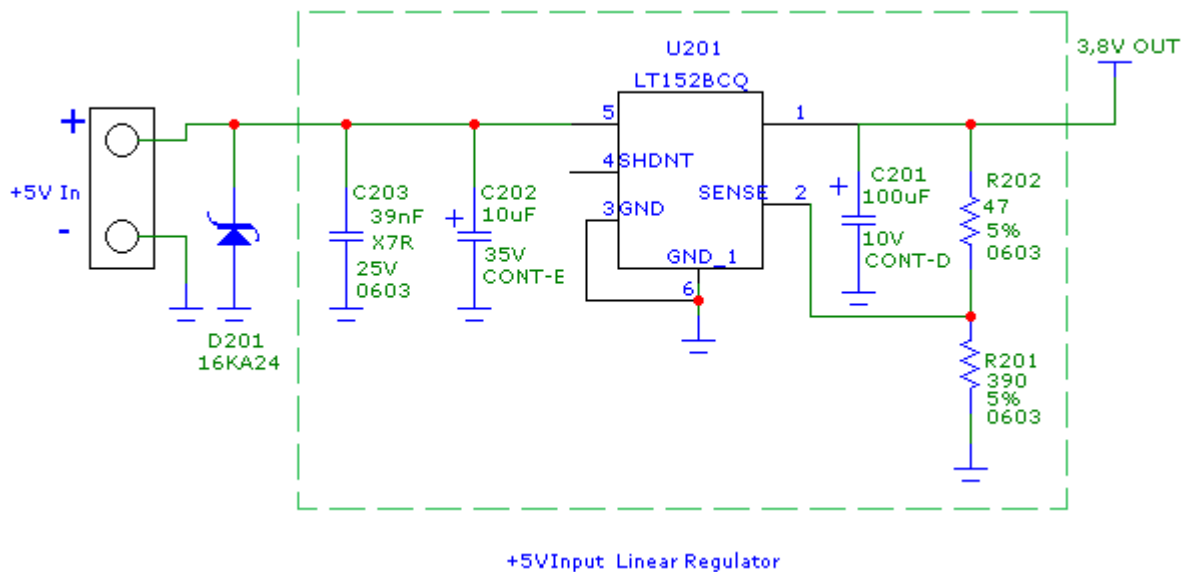
The power supply must be designed so that it is capable of a peak current output of at least 2 A.

- the electrical design
- the thermal design
- the PCB layout.

- +5V input (typically PC internal regulator output)
- +12V input (typically automotive)
- Battery

- The desired output for the power supply is 3.8V, hence there is not a big difference between the input source and the desired output and a linear regulator can be used. A switching power supply will not be suited because of the low drop out requirements.
- When using a linear regulator, a proper heat sink shall be provided in order to dissipate the power generated.
- A Bypass low ESR capacitor of adequate capacity must be provided in order to cut the current absorption peaks close to the GE864-QUAD / PY, a 100μF tantalum capacitor is usually suited.
- Make sure the low ESR capacitor on the power supply output (usually a tantalum one) is rated at least 10V.
- A protection diode must be inserted close to the power input, in order to save the GE864-QUAD / PY from power polarity inversion.





An example of linear regulator with 5V input is:

#### 6.2.1.2. +12V input Source Power Supply Design Guidelines

- The desired output for the power supply is 3.8V; hence due to the big difference between the input source and the desired output, a linear regulator is not suited and shall not be used. A switching power supply will be preferable because of its better efficiency especially with the 2A peak current load represented by the GE864-QUAD/PY.
- When using a switching regulator, a 500kHz or more switching frequency regulator is preferable because of its smaller inductor size and its faster transient response. This allows the regulator to respond quickly to the current peaks absorption.
- In any case the frequency and Switching design selection is related to the application to be developed due to the fact the switching frequency could also generate EMC interferences.
- For car PB battery the input voltage can rise up to 15.8V and this must be kept in mind when choosing components: all components in the power supply must withstand this voltage.
- A Bypass low ESR capacitor of adequate capacity must be provided in order to cut the current absorption peaks, a 100μF tantalum capacitor is usually suited.

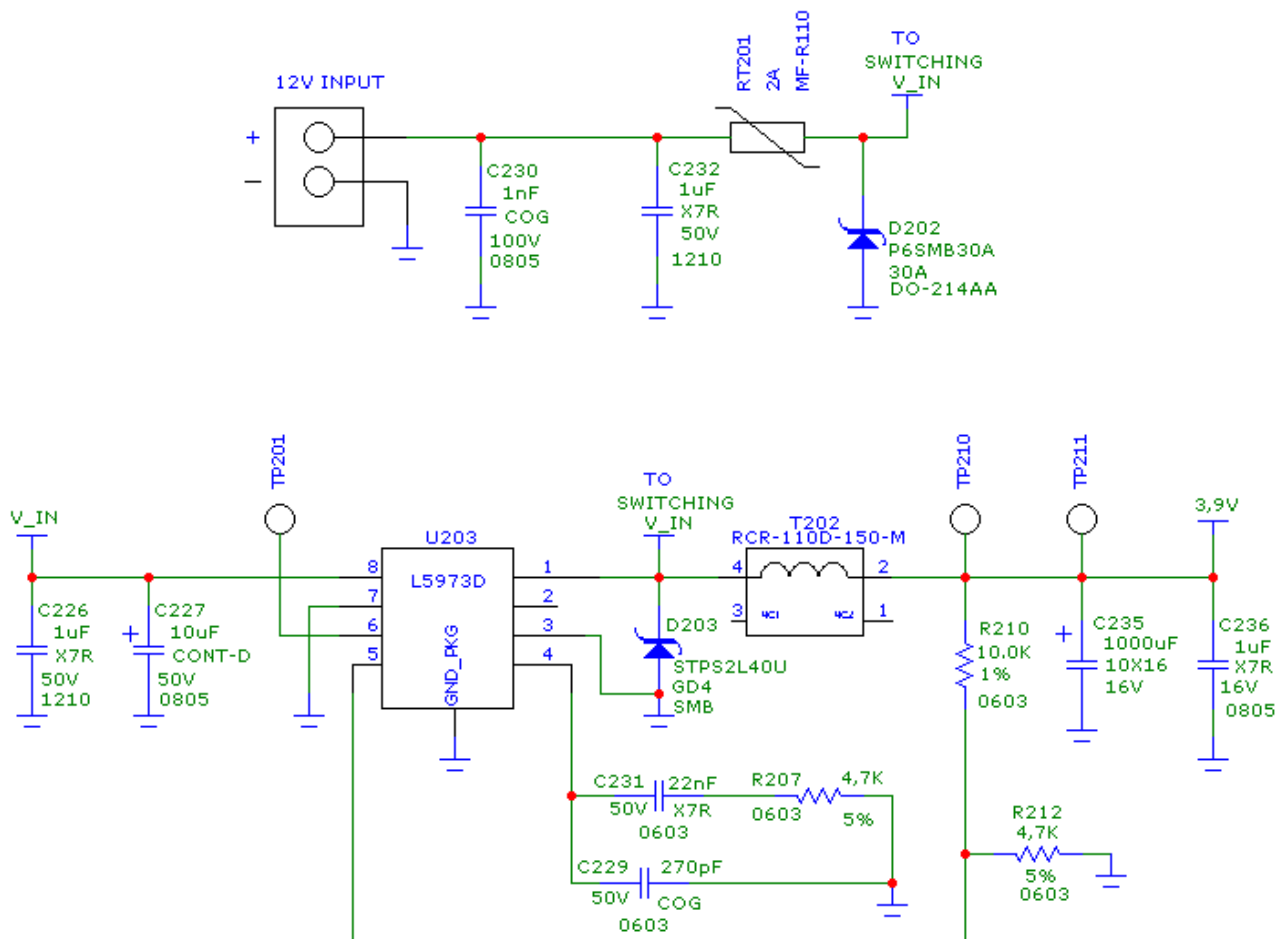


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- Make sure the low ESR capacitor on the power supply output (usually a tantalum one) is rated at least 10V.
- For Car applications a spike protection diode must be inserted close to the power input, in order to clean the supply from spikes.
- A protection diode must be inserted close to the power input, in order to save the GE864-QUAD/PY from power polarity inversion. This can be the same diode as for spike protection.

An example of switching regulator with 12V input is in the below schematic (it is split in 2 parts):





During the trickle charging the voltage across the battery terminals rises; when it reaches the fast charge threshold level the charging process goes into fast charge phase.

During the fast charge phase the process proceeds with a current limited charging; this current limit depends on the required time for the complete charge and from the battery pack capacity. During this phase the voltage across the battery terminals still raises but at a lower rate.

Once the battery voltage reaches its maximum voltage then the process goes into its third state: Final charging. The voltage measure to change the process status into final charge is very important. It must be ensured that the maximum battery voltage is never exceeded, otherwise the battery may be damaged and even explode. Moreover for the constant voltage final chargers, the constant voltage phase (final charge) must not start before the battery voltage has reached its maximum value, otherwise the battery capacity will be highly reduced.

The final charge can be of two different types: constant voltage or pulsed. GE864-QUAD/PY uses constant voltage.

The constant voltage charge proceeds with a fixed voltage regulator (very accurately set to the maximum battery voltage) and hence the current will decrease while the battery is becoming charged. When the charging current falls below a certain fraction of the fast charge current value, then the battery is considered fully charged, the final charge stops and eventually starts the maintenance.

The pulsed charge process has no voltage regulation, instead the charge continues with pulses. Usually the pulse charge works in the following manner: the charge is stopped for some time, let us say few hundreds of ms, then the battery voltage will be measured and when it drops below its maximum value a fixed time length charging pulse is issued. As the battery approaches its full charge the off time will become longer, hence the duty-cycle of the pulses will decrease. The battery is considered fully charged when the pulse duty-cycle is less than a threshold value, typically 10%, the pulse charge stops and eventually the maintenance starts.

The last phase is not properly a charging phase, since the battery at this point is fully charged and the process may stop after the final charge. The maintenance charge provides an additional charging process to compensate for the charge leak typical of a Li-Ion battery. It is done by issuing pulses with a fixed time length, again few hundreds of ms, and a duty-cycle around 5% or less.

This last phase is not implemented in the GE864-QUAD/PY internal charging algorithm, so that the battery once charged is left discharging down to a certain threshold so that it is cycled from full charge to slight discharge even if the battery charger is always inserted. This guarantees that anyway the remaining charge in the battery is a good percentage and that the battery is not damaged by keeping it always fully charged (Li-Ion rechargeable battery usually deteriorates when kept fully charged).





Last but not least, in some applications it is highly desired that the charging process restarts when the battery is discharged and its voltage drops below a certain threshold, GE864-QUAD/PY internal charger does it.

As you can see, the charging process is not a trivial task to be done; moreover all these operations must start only if battery temperature is inside a charging range, usually 5°C – 45°C.

The GE864-QUAD/PY measures the temperature of its internal component, in order to satisfy this last requirement, it is not exactly the same as the battery temperature but in common application the two temperature must not differ too much and the charging temperature range must be guaranteed.


**NOTE:**

For all the threshold voltages, inside the GE864-QUAD/PY all thresholds are fixed in order to maximize Li-Ion battery performances and do not need to be changed.

**NOTE:**

In this application the battery charger input current must be limited to less than 400mA. This can be done by using a current limited wall adapter as the power source.

**NOTE:**

When starting the charger from Module powered off the startup will be in CFUN4; to activate the normal mode a command AT+CFUN=1 has to be provided. This is also possible using the POWER ON.

There is also the possibility to activate the normal mode using the ON\_OFF\* signal.

In this case, when HW powering off the module with the same line (ON\_OFF\*) and having the charger still connected, the module will go back to CFUN4.

**NOTE:**

It is important having a 100uF Capacitor to VBAT in order to avoid instability of the charger circuit if the battery is accidentally disconnected during the charging activity.

## 6.2.2. Thermal Design Guidelines

The thermal design for the power supply heat sink must be done with the following specifications:

- Average current consumption during transmission @ max PWR level: 500mA
- Average current consumption during transmission @ min PWR level: 100mA





- Average current during Power Saving (CFUN=5): 4mA
- Average current during idle (Power Saving disabled): 24mA

**NOTE:**

The average consumption during transmissions depends on the power level at which the device is requested to transmit by the network. The average current consumption hence varies significantly.

Considering the very low current during idle, especially if Power Saving function is enabled, it is possible to consider from the thermal point of view that the device absorbs current significantly only during calls.

If we assume that the device stays into transmission for short periods of time (let us say few minutes) and then remains for a quite long time in idle (let us say one hour), then the power supply has always the time to cool down between the calls and the heat sink could be smaller than the calculated one for 500mA maximum RMS current, or even could be the simple chip package (no heat sink).

Moreover in the average network conditions the device is requested to transmit at a lower power level than the maximum and hence the current consumption will be less than the 500mA, being usually around 150mA.

For these reasons the thermal design is rarely a concern and the simple ground plane where the power supply chip is placed can be enough to ensure a good thermal condition and avoid overheating.

For the heat generated by the GE864-QUAD / PY, you can consider it to be during transmission 1W max during CSD/VOICE calls and 2W max during class10 GPRS upload.

This generated heat will be mostly conducted to the ground plane under the GE864-QUAD / PY; you must ensure that your application can dissipate it.



### 6.2.3. Power Supply PCB Layout Guidelines

As seen on the electrical design guidelines the power supply shall have a low ESR capacitor on the output to cut the current peaks and a protection diode on the input to protect the supply from spikes and polarity inversion. The placement of these components is crucial for the correct working of the circuitry. A misplaced component can be useless or can even decrease the power supply performances.

- The Bypass low ESR capacitor must be placed close to the Telit GE864-QUAD / PY power input pads or in the case the power supply is a switching type it can be placed close to the inductor to cut the ripple provided the PCB trace from the capacitor to the GE864-QUAD / PY is wide enough to ensure a dropless connection even during the 2A current peaks.
- The protection diode must be placed close to the input connector where the power source is drained.
- The PCB traces from the input connector to the power regulator IC must be wide enough to ensure no voltage drops occur when the 2A current peaks are absorbed. Note that this is not made in order to save power loss but especially to avoid the voltage drops on the power line at the current peaks frequency of 216 Hz that will reflect on all the components connected to that supply, introducing the noise floor at the burst base frequency. For this reason while a voltage drop of 300-400 mV may be acceptable from the power loss point of view, the same voltage drop may not be acceptable from the noise point of view. If your application does not have audio interface but only uses the data feature of the Telit GE864-QUAD / PY, then this noise is not so disturbing and power supply layout design can be more forgiving.
- The PCB traces to the GE864-QUAD / PY and the Bypass capacitor must be wide enough to ensure no significant voltage drops occur when the 2A current peaks are absorbed. This is for the same reason as previous point. Try to keep this trace as short as possible.
- The PCB traces connecting the Switching output to the inductor and the switching diode must be kept as short as possible by placing the inductor and the diode very close to the power switching IC (only for switching power supply). This is done in order to reduce the radiated field (noise) at the switching frequency (100-500 kHz usually).
- The use of a good common ground plane is suggested.
- The placement of the power supply on the board must be done in such a way to guarantee that the high current return paths in the ground plane are not overlapped to any noise sensitive circuitry as the microphone amplifier/buffer or earphone amplifier.



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- The power supply input cables must be kept separate from noise sensitive lines such as microphone/earphone cables.



#### 6.2.4. Parameters for ATEX Application

In order to integrate the Telit's GE864 module into an ATEX application, the appropriate reference standard IEC EN xx and integrations shall be followed.

Below are listed parameters and useful information to integrate the module in your application:

- Total capacity: 78.494  $\mu$ F
- Total inductance: 10.163  $\mu$ H
- No voltage upper than supply voltage is present in the module.
- No step-up converters are present in the module.
- In abnormal conditions, the maximum RF output power is up to 34 dBm max for few seconds.

For this particular application, we recommend the customer to involve TTSC (Telit Technical Support Center) in the design phase of the application.



## 7. Antenna

The antenna connection and board layout design are the most important part in the full product design and they strongly reflect on the product overall performances, hence read carefully and follow the requirements and the guidelines for a proper design.

### 7.1. GSM Antenna Requirements

As suggested on the Product Description the antenna and antenna line on PCB for a Telit GE864-QUAD / PY device shall fulfill the following requirements:

ANTENNA REQUIREMENTS	
<b>Frequency range</b>	Depending by frequency band(s) provided by the network operator, the customer shall use the most suitable antenna for that/those band(s)
<b>Bandwidth</b>	70 MHz in GSM850, 80 MHz in GSM900, 170 MHz in DCS & 140 MHz PCS band
<b>Gain</b>	Gain < 3dB/
<b>Impedance</b>	50 $\Omega$
<b>Input power</b>	> 2 W peak power
<b>VSWR absolute max</b>	<= 10:1
<b>VSWR recommended</b>	<= 2:1

When using the Telit GE864-QUAD / PY, since there is no antenna connector on the module, the antenna must be connected to the GE864-QUAD / PY through the PCB with the antenna pad.

In the case that the antenna is not directly developed on the same PCB, hence directly connected at the antenna pad of the GE864-QUAD / PY, then a PCB line is needed in order to connect with it or with its connector.

This line of transmission shall fulfill the following requirements:

ANTENNA LINE ON PCB REQUIREMENTS	
<b>Impedance</b>	50 $\Omega$
<b>Max Attenuation</b>	0,3 dB
<b>No coupling with other signals allowed</b>	
<b>Cold End (Ground Plane) of antenna shall be equipotential to the GE864-QUAD / PY ground pins</b>	

Furthermore if the device is developed for the US market and/or Canada market, it shall comply to the FCC and/or IC approval requirements:



This device is to be used only for mobile and fixed application. The antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter. End-Users must be provided with transmitter operation conditions for satisfying RF exposure compliance. OEM integrators must ensure that the end user has no manual instructions to remove or install the GE864-QUAD / PY module. Antennas used for this OEM module must not exceed 3dBi gain for mobile and fixed operating configurations.

## 7.2. GSM Antenna – PCB Line Guidelines

- Ensure that the antenna line impedance is 50 $\Omega$ ;
- Keep the antenna line on the PCB as short as possible, since the antenna line loss shall be less than 0,3 dB;
- Antenna line must have uniform characteristics, constant cross section, avoid meanders and abrupt curves;
- Keep, if possible, one layer of the PCB used only for the Ground plane;
- Surround (on the sides, over and under) the antenna line on PCB with Ground, avoid having other signal tracks facing directly the antenna line track;
- The ground around the antenna line on PCB has to be strictly connected to the Ground Plane by placing vias once per 2mm at least;
- Place EM noisy devices as far as possible from GE864-QUAD / PY antenna line;
- Keep the antenna line far away from the GE864-QUAD / PY power supply lines;
- If you have EM noisy devices around the PCB hosting the GE864-QUAD / PY, such as fast switching ICs, take care of the shielding of the antenna line by burying it inside the layers of PCB and surround it with Ground planes, or shield it with a metal frame cover.
- If you do not have EM noisy devices around the PCB of GE864-QUAD / PY, by using a strip-line on the superficial copper layer for the antenna line, the line attenuation will be lower than a buried one;





## 7.3. GSM Antenna – Installation Guidelines

- Install the antenna in a place covered by the GSM signal.
- The Antenna must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter;
- Antenna shall not be installed inside metal cases
- Antenna shall be installed also according Antenna manufacturer instructions.



## 8. Logic Level Specifications

Where not specifically stated, all the interface circuits work at 2.8V CMOS logic levels. The following table shows the logic level specifications used in the Telit GE864-QUAD / PY interface circuits:

### Absolute Maximum Ratings –Not Functional

Parameter	Min	Max
Input level on any digital pin when on	-0.3V	+3.6V
Input voltage on analog pins when on	-0.3V	+3.0 V

### Operating Range – Interface Levels (2.8V CMOS)

Level	Min	Max
Input high level	2.1V	3.3V
Input low level	0V	0.5V
Output high level	2.2V	3.0V
Output low level	0V	0.35V

For 1.8V signals:

### Operating Range – Interface Levels (1.8V CMOS)

Level	Min	Max
Input high level	1.6V	2.2V
Input low level	0V	0.4V
Output high level	1,65V	2.2V
Output low level	0V	0.35V

### Current Characteristics

Level	Typical
Output Current	1mA
Input Current	1uA



## 8.1. Reset Signal

Signal	Function	I/O	Bga Ball
RESET	Phone reset	I	A2

RESET is used to reset the GE864-QUAD / PY modules. Whenever this signal is pulled low, the GE864-QUAD / PY is reset. When the device is reset it stops any operation. After the release of the reset GE864-QUAD / PY is unconditionally shut down, without doing any detach operation from the network where it is registered. This behaviour is not a proper shut down because any GSM device is requested to issue a detach request on turn off. For this reason the Reset signal must not be used to normally shutting down the device, but only as an emergency exit in the rare case the device remains stuck waiting for some network response.

The RESET is internally controlled on start-up to achieve always a proper power-on reset sequence, so there is no need to control this pin on start-up. It may only be used to reset a device already on that is not responding to any command.



### NOTE:

Do not use this signal to power off the GE864-QUAD / PY. Use the ON/OFF signal to perform this function or the AT#SHDN command.

### Reset Signal Operating Levels:

Signal	Min	Max
RESET Input high	2.0V*	2.2V
RESET Input low	0V	0.2V

This signal is internally pulled up so the pin can be left floating if not used.

If unused, this signal may be left unconnected. If used, then it **must always be connected with an open collector transistor**, to permit to the internal circuitry the power on reset and under voltage lockout functions.



## 9. Serial Ports

The serial port on the Telit GE864-QUAD/PY is the core of the interface between the module and OEM hardware.

2 serial ports are available on the module:

- MODEM SERIAL PORT
- MODEM SERIAL PORT 2 (DEBUG)

### 9.1. Modem Serial Port

Several configurations can be designed for the serial port on the OEM hardware, but the most common are:

- RS232 PC com port
- Micro controller UART @ 2.8V – 3V (Universal Asynchronous Receive Transmit)
- Micro controller UART@ 5V or other voltages different from 2.8V

Depending from the type of serial port on the OEM hardware a level translator circuit may be needed to make the system work. The only configuration that does not need a level translation is the 2.8V UART.

The serial port on the GE864-QUAD/PY is a +2.8V UART with all the 7 RS232 signals. It differs from the PC-RS232 in the signal polarity (RS232 is reversed) and levels. The levels for the GE864-QUAD/PY UART are the CMOS levels:

#### Absolute Maximum Ratings – Not Functional

Parameter	Min	Max
Input level on any digital pad when on	-0.3V	+3.6V
Input voltage on analog pads when on	-0.3V	+3.0 V



### Operating Range – Interface Levels (2.8V CMOS)

Level	Min	Max
Input high level $V_{IH}$	2.1V	3.3V
Input low level $V_{IL}$	0V	0.5V
Output high level $V_{OH}$	2.2V	3.0V
Output low level $V_{OL}$	0V	0.35V



The table below shows the signals of the GE864 serial port:

RS232 Pin Number	Signal	GE864-QUAD / PY Pad Number	Name	Usage
1	DCD – dcd_uart	D9	Data Carrier Detect	Output from the GE864-QUAD / PY that indicates the carrier presence
2	RXD – tx_uart	H8	Transmit line * see Note	Output transmit line of GE864-QUAD / PY UART
3	TXD – rx_uart	E7	Receive line *see Note	Input receive of the GE864-QUAD / PY UART
4	DTR – dtr_uart	B7	Data Terminal Ready	Input to the GE864-QUAD / PY that controls the DTE READY condition
5	GND	A1,F1,H1,L1, H2, L2, J3, K3...	Ground	ground
6	DSR – dsr_uart	E11	Data Set Ready	Output from the GE864-QUAD / PY that indicates the module is ready
7	RTS – rts_uart	F7	Request to Send	Input to the GE864-QUAD / PY that controls the Hardware flow control
8	CTS – cts_uart	F6	Clear to Send	Output from the GE864-QUAD / PY that controls the Hardware flow control
9	RI – ri_uart	B6	Ring Indicator	Output from the GE864-QUAD / PY that indicates the incoming call condition



**\*NOTE:**

According to V.24, RX/TX signal names are referred to the application side, therefore on the GE864 side these signal are on the opposite direction: TXD on the application side will be connected to the receive line (here named TXD/ rx\_uart ) of the GE864 serial port and vice versa for RX.



**TIP:**

For a minimum implementation, only the TXD and RXD lines can be connected, the other lines can be left open provided a software flow control is implemented.

**TIP:**

In order to avoid noise or interferences on the RXD lines it is suggested to add a pull up resistor (100K  $\Omega$  to 2.8V)





In order to interface the Telit GE864 with a PC com port or a RS232 (EIA/TIA-232) application a level translator is required. This level translator must

- Actually, the RS232 UART 16450, 16550, 16650 & 16750 chipsets accept signals with lower levels on the RS232 side (EIA/TIA-562) , allowing for a lower voltage-multiplying ratio on the level translator. Note that the negative signal voltage must be less than 0V and hence some sort of level translation is always required.

The simplest way to translate the levels and invert the signal is by using a single chip level translator. There are a multitude of them, differing in the number of driver and receiver and in the levels (be sure to get a true RS232 level translator not a RS485 or other standards).

By convention the driver is the level translator from the 0-3V UART level to the RS232 level, while the receiver is the translator from RS232 level to 0-3V UART.

In order to translate the whole set of control lines of the UART you will need:

- 

The digital input lines working at 2.8VCMOS have an absolute maximum input voltage of 3,75V; therefore the level translator IC shall not be powered by the +3.8V supply of the module. Instead it shall be powered from a +2.8V / +3.0V (dedicated) power supply.

This is because in this way the level translator IC outputs on the module side (i.e. GE864 inputs) will work at +3.8V interface levels, stressing the module inputs at its maximum input voltage.

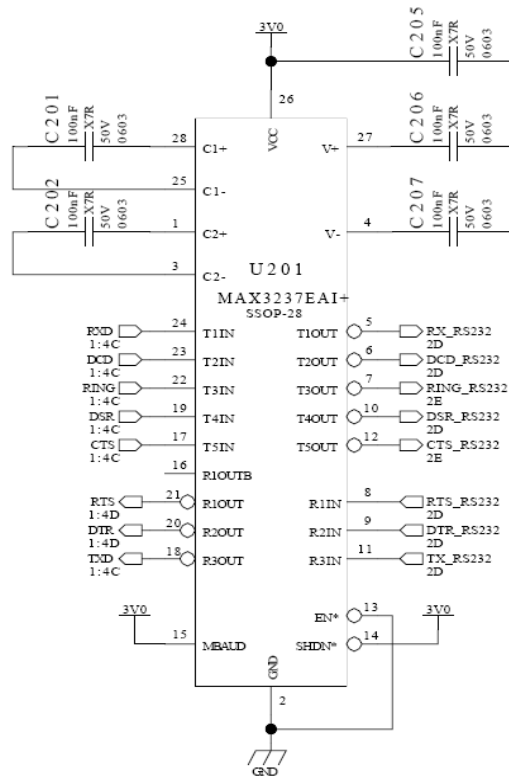
This can be acceptable for evaluation purposes, but not on production devices.

In order to be able to do in circuit reprogramming of the GE864 firmware, the serial port on the Telit GE864 shall be available for translation into RS232 and either it is controlling device shall be placed into tristate, disconnected or as a gateway for the serial data when module reprogramming occurs.

Only RXD, TXD, GND and the On/off module turn on pad are required to the reprogramming of the module, the other lines are unused.

All applicator shall include in their design such a way of reprogramming the GE864.

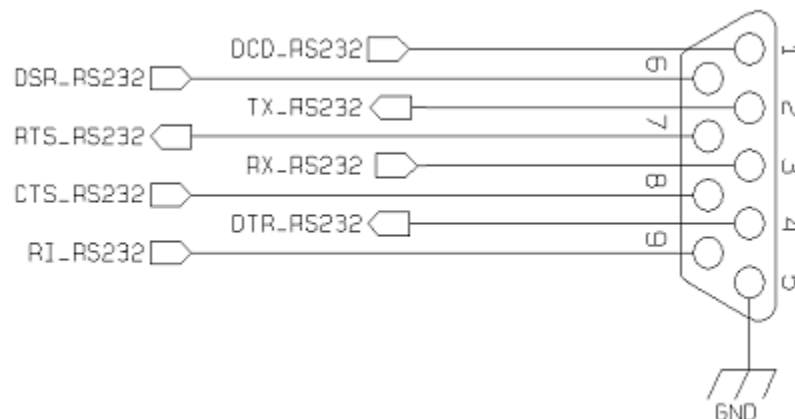




#### RS232 LEVEL TRSANSULATOR

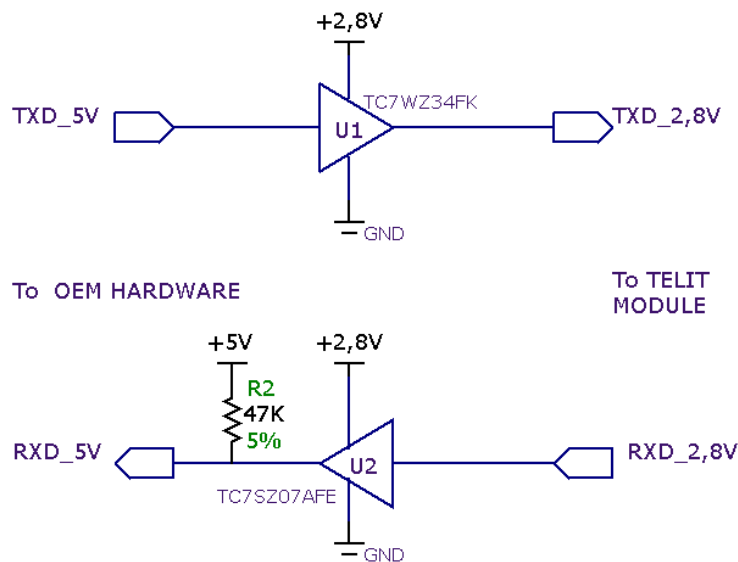
An example of level translation circuitry of this kind is:

The RS232 serial port lines are usually connected to a DB9 connector with the following layout:



### 9.3. 5V UART Level Translation

If the OEM application uses a microcontroller with a serial port (UART) that works at a voltage different from 2.8 – 3V, then a circuitry has to be provided to adapt the different levels of the two sets of signals. As for the RS232 translation there are a multitude of single chip translators. For example a possible translator circuit for a 5V TRANSMITTER/RECEIVER can be:



#### TIP:

This logic IC for the level translator and 2.8V pull-ups (not the 5V one) can be powered directly from VAUX line of the GE864-QUAD / PY. Note that the TC7SZ07AE has open drain output; therefore the resistor R2 is mandatory.



#### TIP:

The UART input line TXD (rx\_uart) of the GE864-QUAD / PY is NOT internally pulled up with a resistor, so there may be the need to place an external 47KΩ pull-up resistor, either the DTR (dtr\_uart) and RTS (rts\_uart) input lines are not pulled up internally, so an external pull-up resistor of 47KΩ may be required.



A power source of the internal interface voltage corresponding to the 2.8VCMOS high level is available at the VAUX pin on the connector,

A maximum of 9 resistors of 47 K $\Omega$  pull-up can be connected to the PWRMON pin, provided no other devices are connected to it and the pulled-up lines are GE864-QUAD / PY input lines connected to open collector outputs in order to avoid latch-up problems on the GE864-QUAD / PY.

Care must be taken to avoid latch-up on the GE864-QUAD / PY and the use of this output line to power electronic devices shall be avoided, especially for devices that generate spikes and noise such as switching level translators, micro controllers, failure in any of these condition can severely compromise the GE864-QUAD / PY functionality.

**NOTE:**

The input lines working at 2.8VCMOS can be pulled-up with 47K $\Omega$  resistors that can be connected directly to the VAUX line provided they are connected as in this example.

In case of reprogramming of the module has to be considered the use of the RESET line to start correctly the activity.

The preferable configuration is having an external supply for the buffer.



## 10. Audio Section Overview

The Baseband chip was developed for the cellular phones, which needed two separated amplifiers both in RX and in TX section.

A couple of amplifiers had to be used with internal audio transducers while the other couple of amplifiers had to be used with external audio transducers.

To distinguish the schematic signals and the Software identifiers, two different definitions were introduced, with the following meaning:

- internal audio transducers → **HS/MT** (from HandSet or MicroTelephone )
- external audio transducers → **HF** (from HandsFree )

Actually the acronyms have not the original importance.

In other words this distinction is not necessary, being the performances between the two blocks like the same.

Only if the customer needs higher output power to the speaker , he has a constraint. Otherwise the choice could be done in order to overcome the PCB design difficulties.

For these reasons we have not changed the HS and HF acronyms, keeping them in the Software and on the schematics.

The Base Band Chip of the GE864Telit Module maintains the same architecture.

For more information refer to Telit document :

***“ 80000NT10007a Audio Settings Application Note”.***

### 1.1 Selection mode

Only one block can be active at a time , and the activation of the requested audio path is done via hardware by **AXE** line or via software by **AT#CAP** command .

Moreover the Sidetone functionality could be implemented by the amplifier fitted between the transmit path and the receive path, enabled at request in both modes.









**TIP:** Being the microphone circuitry the more noise sensitive, its design and layout must be done with particular care. Both microphone paths are balanced and the OEM circuitry must be balanced designed to reduce the common mode noise typically generated on the ground plane. However the customer can use the unbalanced circuitry for particular application.

“MIC_MT” and “MIC_HF” differential microphone paths	
Line Coupling	AC*
Line Type	Balanced
Coupling capacitor	$\geq 100\text{nF}$
Differential input resistance	$50\text{k}\Omega$
Differential input voltage	$\leq 1,03\text{V}_{\text{DD}}$ @ $\text{MicG}=0\text{dB}$



**(\*) WARNING :** AC means that the signals from the microphone have to be connected to input lines of the module through capacitors which value has to be  $\geq 100\text{nf}$ . not respecting this constraint, the input stages will be damaged.

**WARNING:** when particular OEM application needs a *Single Ended Input* configuration, it is forbidden connecting the unused input directly to Ground, but only through a 100nF capacitor. Don't forget that in Single Ended configuration the useful input signal will be halved.



## 1.2.1 Output Lines Characteristics



### TIP:

We suggest driving the load differentially from both output drivers, thus the output swing will double and the need for the output coupling capacitor avoided. However if particular OEM application needs also a Single Ended circuitry can be implemented, but the output power will be reduced four times .

The OEM circuitry shall be designed to reduce the common mode noise typically generated on the ground plane and to get the maximum power output from the device (low resistance tracks).



### WARNING:

The loads are directly connected to the amplifier outputs when in *Differential* configuration, through a capacitor when in *Single Ended* configuration. Using Single Ended configuration, the unused output line must be left open. Not respecting this constraint, the output stage will be damaged.



### TIP:

Remember that there are slightly different electrical performances between the two internal audio amplifiers:

- the "*Ear\_MT*" lines can directly drive a **16  $\Omega$  load** at -12dBFS (\*\*) in *Differential* configuration
- the "*Ear\_HF*" lines can directly drive a **16  $\Omega$  load** in *Differential* or *Single Ended* configurations
- There is no difference if the amplifiers drive an external amplifier

(\*\*) *0dBFS* is the normalized overall Analog Gain for each Output channel equal to  $3,7V_{pp}$  differential



“EAR_MT” Output Lines	
line coupling	AC single-ended DC differential
output load resistance	$\geq 14 \Omega$
internal output resistance	$4 \Omega$ ( <i>typical</i> )
signal bandwidth	150 - 4000 Hz @ -3 dB
max. differential output voltage	$1.31 V_{rms}$ ( <i>typical, open circuit</i> )
differential output voltage	$328 mV_{rms} / 16 \Omega / @ -12dBFS$
volume increment	2 dB per step
volume steps	10

“EAR_HF” Output Lines	
line coupling:	AC single-ended DC differential
output load resistance :	$\geq 14 \Omega$
internal output resistance:	$4 \Omega (>1,7 \Omega)$
signal bandwidth:	150 - 4000 Hz @ -3 dB
max. differential output voltage	$1.31 V_{rms}$ ( <i>typical, open circuit</i> )
max. S.E. output voltage	$656 mV_{rms}$ ( <i>typical, open circuit</i> )
volume increment	2 dB per step
volume steps	10



## 11. External SIM Holder Implementation

Please refer to the related Telit User Guide :

*“80000NT10001a SIM Holder Design Guides”*



## 12. General Purpose I/O

The general purpose I/O pads can be configured to act in three different ways:

- input
- output
- alternate function (internally controlled)

Input pads can only be read and report the digital value (high or low) present on the pad at the read time; output pads can only be written or queried and set the value of the pad output; an alternate function pad is internally controlled by the GE864-QUAD / PY firmware and acts depending on the function implemented. For Logic levels please refer to chapter 7.

The following GPIO are available on the GE864-QUAD and GE864-PY:

Ball	Signal	I/O	Function	Type	Input / output current	Default State	ON_OFF state	State during Reset	Note
C1	TGPIO_01	I/O	GPIO01 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
E6	TGPIO_02	I/O	GPIO02 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (JDR)
C2	TGPIO_03	I/O	GPIO03 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
B3	TGPIO_04	I/O	GPIO04 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (RF Transmission Control)
K8	TGPIO_05	I/O	GPIO05 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (RFTXMON)
B5	TGPIO_06	I/O	GPIO06 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	Pict 01	1	Alternate function (ALARM)
L9	TGPIO_07	I/O	GPIO07 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		Alternate function (BUZZER)
K11	TGPIO_08	I/O	GPIO08 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
C9	TGPIO_09	I/O	GPIO09 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
H3	TGPIO_10	I/O	GPIO10 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
D1	TGPIO_11	I/O	GPIO11 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
G4	TGPIO_12	I/O	GPIO12 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
K10	TGPIO_13	I/O	GPIO13 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
B4	TGPIO_14	I/O	GPIO14 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
F5	TGPIO_15	I/O	GPIO15 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
H6	TGPIO_16	I/O	GPIO16 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
H5	TGPIO_17	I/O	GPIO17 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
K7	TGPIO_18	I/O	GPIO18 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
B1	TGPIO_19	I/O	GPIO19 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
C3	TGPIO_20	I/O	GPIO20 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0		
L10	TGPIO_21	I/O	GPIO21 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	1		
E8	TGPIO_22	I/O	GPIO22 Configurable GPIO	<b>CMOS 1.8V (not 2.8V !!)</b>	1uA / 1mA	INPUT	0		

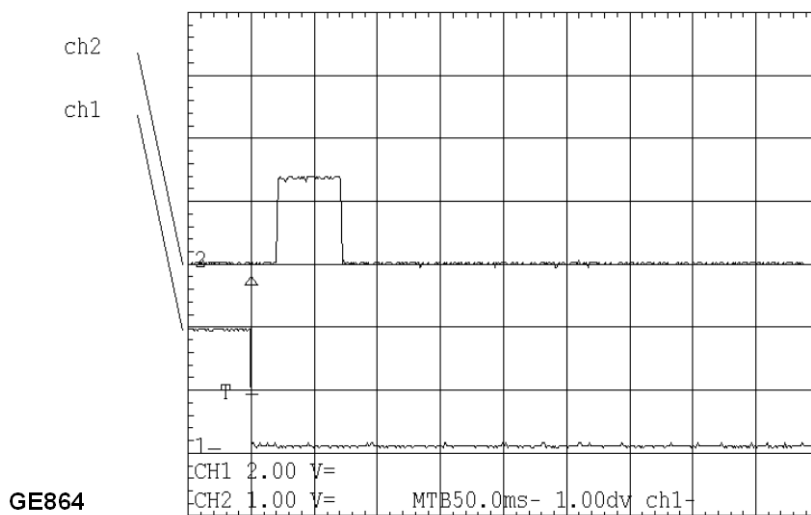


Not all GPIO pads support all these three modes:

- GPIO2 supports all three modes and can be input, output, Jamming Detect Output (Alternate function)
- GPIO4 supports all three modes and can be input, output, RF Transmission Control (Alternate function)
- GPIO5 supports all three modes and can be input, output, RFTX monitor output (Alternate function)
- GPIO6 supports all three modes and can be input, output, alarm output (Alternate function)
- GPIO7 supports all three modes and can be input, output, buzzer output (Alternate function)

**ch1:** ON\_OFF (2sec)

**ch2:** GPIO 06 [ bis ]





## 12.1. GPIO Logic Levels

Where not specifically stated, all the interface circuits work at 2.8V CMOS logic levels.

The following tables show the logic level specifications used in the GE864-QUAD/PY interface circuits:

### Absolute Maximum Ratings – Not Functional

Parameter	Min	Max
Input level on any digital pin when on	-0.3V	+3.6V
Input voltage on analog pins when on	-0.3V	+3.0 V

### Operating Range – Interface Levels (2.8V CMOS)

Level	Min	Max
Input high level	2.1V	3.3V
Input low level	0V	0.5V
Output high level	2.2V	3.0V
Output low level	0V	0.35V

For 1.8 V signals:

### Operating Range – Interface Levels (1.8V CMOS)

Level	Min	Max
Input high level	1.6V	2.2V
Input low level	0V	0.4V
Output high level	1,65V	2.2V
Output low level	0V	0.35V



## 12.2. Using a GPIO Pad as INPUT

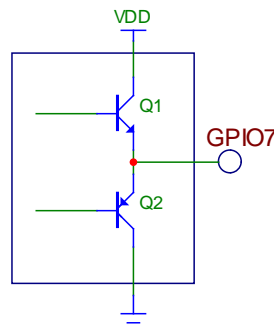
The GPIO pads, when used as inputs, can be connected to a digital output of another device and report its status, provided this device has interface levels compatible with the 2.8V CMOS levels of the GPIO.

If the digital output of the device to be connected with the GPIO input pad has interface levels different from the 2.8V CMOS, then it can be buffered with an open collector transistor with a 47K pull up to 2.8V.

## 12.3. Using a GPIO Pad as OUTPUT

The GPIO pads, when used as outputs, can drive 2.8V CMOS digital devices or compatible hardware. When set as outputs, the pads have a push-pull output and therefore the pull-up resistor may be omitted.

The illustration below shows the base circuit of a push-pull stage:



The GPIO4 pin, when configured as RF Transmission Control Input, permits to disable the Transmitter when the GPIO is set to Low by the application.

In the design is necessary to add a pull up resistor (47K to VAUX).

## 12.5. Using the RFTXMON Output GPIO5

The GPIO5 pin, when configured as RFTXMON Output, is controlled by the GE864-QUAD / PY module and will rise when the transmitter is active and fall after the transmitter activity is completed.

For example, if a call is started, the line will be HIGH during all the conversation and it will be again LOW after hanged up.

The line rises up 300ms before first TX burst and will become again LOW from 500ms to 1sec after last TX burst.



The GPIO6 pad, when configured as Alarm Output, is controlled by the GE864-QUAD / PY module and will rise when the alarm starts and fall after the issue of a dedicated AT command.

This output can be used to power up the GE864-QUAD / PY controlling micro controller or application at the alarm time, giving you the possibility to program a timely system wake-up to achieve some periodic actions and completely turn off either the application and the GE864-QUAD / PY during sleep periods, dramatically reducing the sleep consumption to few  $\mu\text{A}$ .

In battery-powered devices this feature will greatly improve the autonomy of the device.



**NOTE:**

During RESET the line is set to HIGH logic level.



## 12.7. Using the Buzzer Output GPIO7

As *Alternate Function*, the GPIO7 is controlled by the firmware that depends on the function implemented internally.

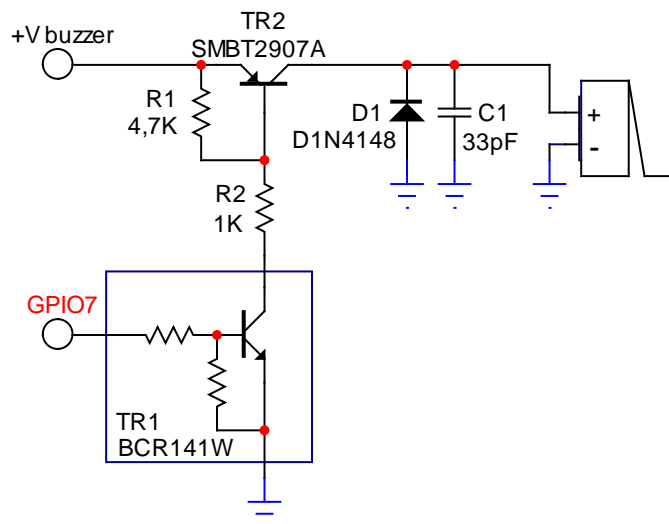
This setup places always the GPIO7 pin in *OUTPUT* direction and the corresponding function must be activated properly by **AT#SRP** command (refer to *AT commands specification*).

Also in this case, the *dummy value* for the pin state can be both “0” or “1”.

- Send the command                      AT#GPIO=7, 1, 2<cr>:
- Wait for response                      OK
- Send the command                      AT#SRP=3

The GPIO7 pin will be set as *Alternate Function* pin with its dummy logic status set to *HIGH* value.

The “*Alternate function*” permits your application to easily implement **Buzzer feature** with some small hardware extension of your application as shown in the sample figure below.



Example of Buzzer's driving circuit



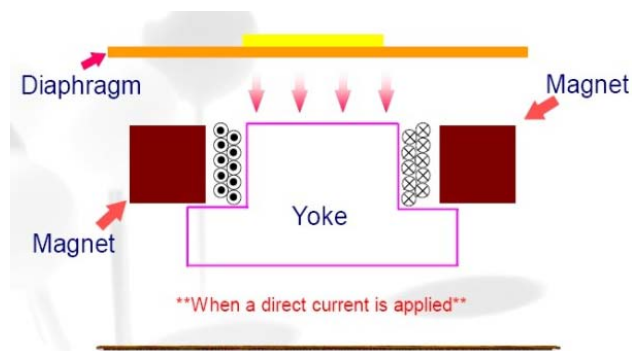
### NOTE:

To correctly drive a buzzer, a driver must be provided; its characteristics depend on the Buzzer and for them refer to your buzzer vendor.

## 12.8. Magnetic Buzzer Concepts

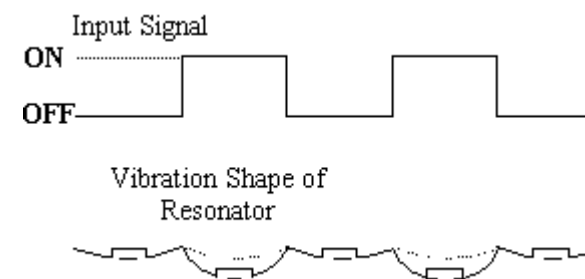
### 12.8.1. Short Description

A magnetic Buzzer is a sound-generating device with a coil located in the magnetic circuit consisting of a permanent magnet, an iron core, a high permeable metal disk, and a vibrating diaphragm.



*Drawing of the Magnetic Buzzer*

The disk and diaphragm are attracted to the core by the magnetic field. When an oscillating signal is moved through the coil, it produces a fluctuating magnetic field, which vibrates the diaphragm at a frequency of the drive signal. Thus the sound is produced relative to the frequency applied.



*Diaphragm movement*

### 12.8.2. Frequency Behavior

The frequency behavior represents the effectiveness of the reproduction of the applied signals.



Because its performance is related to a square driving waveform (whose amplitude varies from 0V to  $V_{pp}$ ), if you modify the waveform (e.g. from square to sinus) the frequency response will change.

### 12.8.3. Power Supply Influence

Applying a signal whose amplitude is different from that suggested by manufacturer, the performance change following the rule:

*“if resonance frequency  $f_0$  increases, amplitude decreases”.*

Because of resonance frequency depends from acoustic design, lowering the amplitude of the driving signal the response bandwidth tends to become narrow, and vice versa.

Summarizing:

$V_{pp} \uparrow \rightarrow f_0 \downarrow$

$V_{pp} \downarrow \rightarrow f_0 \uparrow$

The risk is that the  $f_0$  could easily fall outside of new bandwidth; consequently the SPL could be much lower than the expected.



#### **WARNING:**

It is very important to respect the sense of the applied voltage: never apply to the “-” pin a voltage more positive than the “+” pin: if this happens, the diaphragm vibrates in the opposite direction with a high probability to be expelled from its physical position. This damages the device permanently.

### 12.8.4. Working Current Influence

In the component data sheet you will find the value of MAX CURRENT that represents the maximum average current that can flow at nominal voltage without current limitation.

In other words it is not the peak current, which could be twice or three times higher.

If driving circuitry does not support these peak values, the SPL will never reach the declared level or the oscillations will stop.







## 12.10. Indication of Network Service Availability

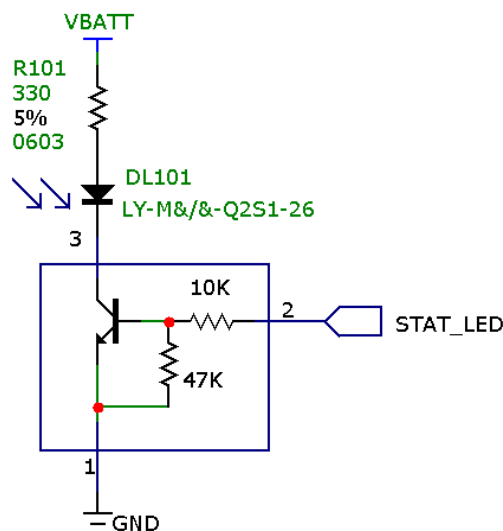
The STAT\_LED pin status shows information on the network service availability and Call status.

In the GE864 modules, the STAT\_LED usually needs an external transistor to drive an external LED.

Therefore, the status indicated in the following table is reversed with respect to the pin status.

LED status	Device Status
Permanently off	Device off
Fast blinking (Period 1s, Ton 0,5s)	Net search / Not registered / turning off
Slow blinking (Period 3s, Ton 0,3s)	Registered full service
Permanently on	a call is active

A schematic example could be:



## 12.11. RTC Bypass Out

The VRTC pin brings out the Real Time Clock supply, which is separate from the rest of the digital part, allowing having only RTC going on when all the other parts of the device are off.

To this power output a backup capacitor can be added in order to increase the RTC autonomy during power off of the battery. NO Devices must be powered from this pin.

## 12.12. VAUX1 Power Output

A regulated power supply output is provided in order to supply small devices from the module.

This output is active when the module is ON and goes OFF when the module is shut down.

The operating range characteristics of the supply are:

### Operating Range – VAUX1 power supply

	Min	Typical	Max
Output voltage	2.75V	2.85V	2.95V
Output current			100mA
Output bypass capacitor (inside the module)			2.2 $\mu$ F



## 13. DAC and ADC Section

### 13.1. DAC Converter

#### 13.1.1. Description

The GE864-QUAD / PY module provides a Digital to Analog Converter. The signal (named DAC\_OUT) is available on BGA Ball C7 of the GE864-QUAD / PY module and on pin 17 of PL102 on EVK2 Board (CS1152).

The on board DAC is a 10-bit converter, able to generate a analogue value based a specific input in the range from 0 up to 1023. However, an external low-pass filter is necessary

	Min	Max	Units
Voltage range (filtered)	0	2,6	Volt
Range	0	1023	Steps

The precision is 10 bits so, if we consider that the maximum voltage is 2V, the integrated voltage could be calculated with the following formula:

$$\text{Integrated output voltage} = 2 * \text{value} / 1023$$

DAC\_OUT line must be integrated (for example with a low band pass filter) in order to obtain an analog voltage.

#### 13.1.2. Enabling DAC

The AT command below is available to use the DAC function:

**AT#DAC[=<enable>[,<value>]]**

**<value>** – scale factor of the integrated output voltage (0..1023 – 10 bit precision)

it must be present if **<enable>=1**

Refer to SW User Guide or AT Commands Reference Guide for the full description of this function.

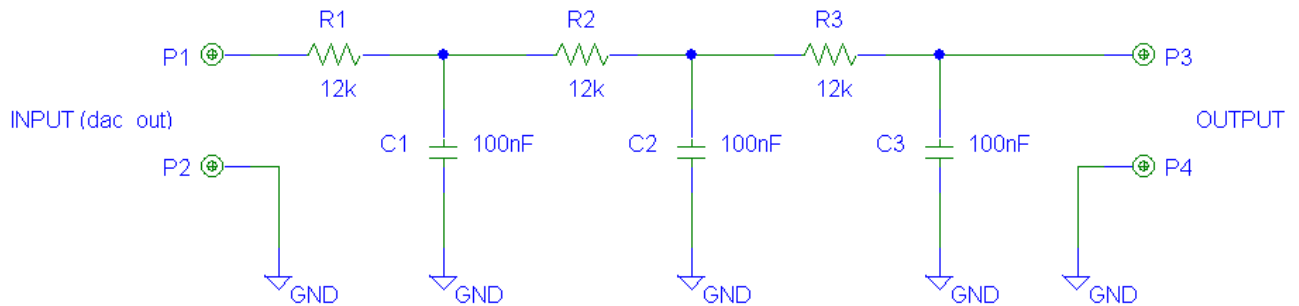


#### NOTE:

The DAC frequency is selected internally. D/A converter must not be used during POWERSAVING.



### 13.1.3. Low Pass Filter Example



## 13.2. ADC Converter

### 13.2.1. Description

The on board A/D are 11-bit converter. They are able to read a voltage level in the range of 0÷2 volts applied on the ADC pin input, store and convert it into 11 bit word.

	Min	Max	Units
Input Voltage range	0	2	Volt
AD conversion	-	11	bits
Resolution	-	< 1	mV

The GE864-QUAD / PY module provides 3 Analog to Digital Converters. The input lines are:

ADC\_IN1 available on Ball J11 and Pin 19 of PL102 on EVK2 Board (CS1152).

ADC\_IN2 available on Ball H11 and Pin 20 of PL102 on EVK2 Board (CS1152).

ADC\_IN3 available on Ball G11 and Pin 21 of PL102 on EVK2 Board (CS1152).

### 13.2.2. Using ADC Converter

The AT command below is available to use the ADC function:

**AT#ADC=1,2**

The read value is expressed in mV

Refer to SW User Guide or AT Commands Reference Guide for the full description of this function.

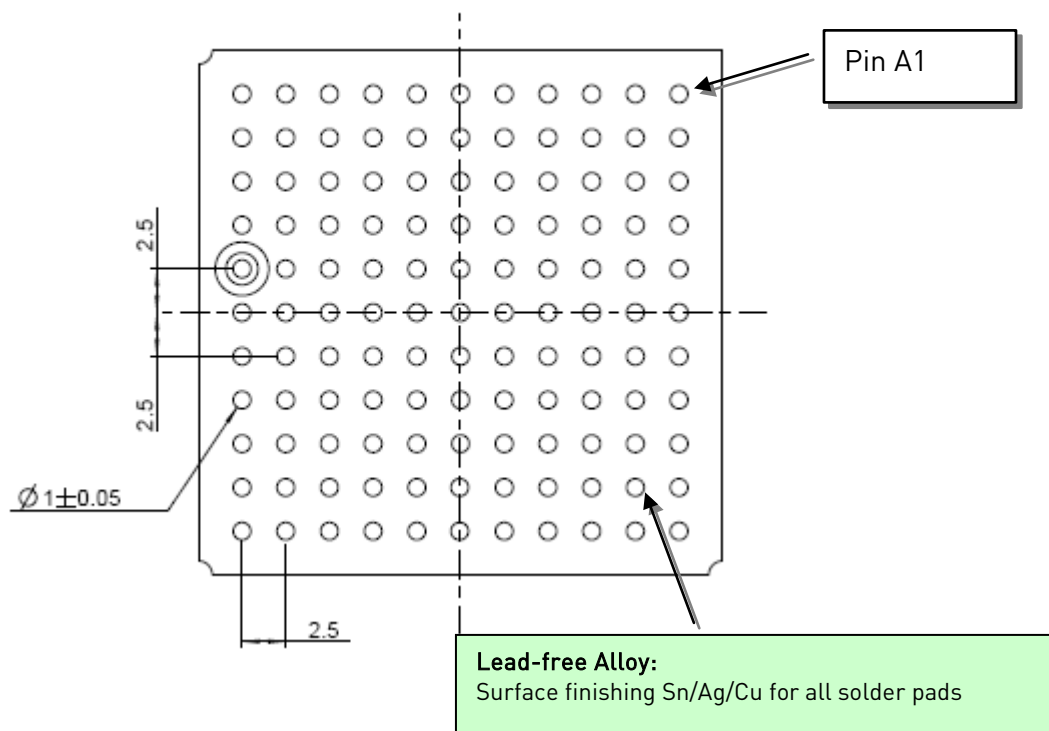


## 14. Mounting the GE864 on the Board

### 14.1. General

The Telit GE864 modules have been designed in order to be compliant with a standard lead-free SMT process.

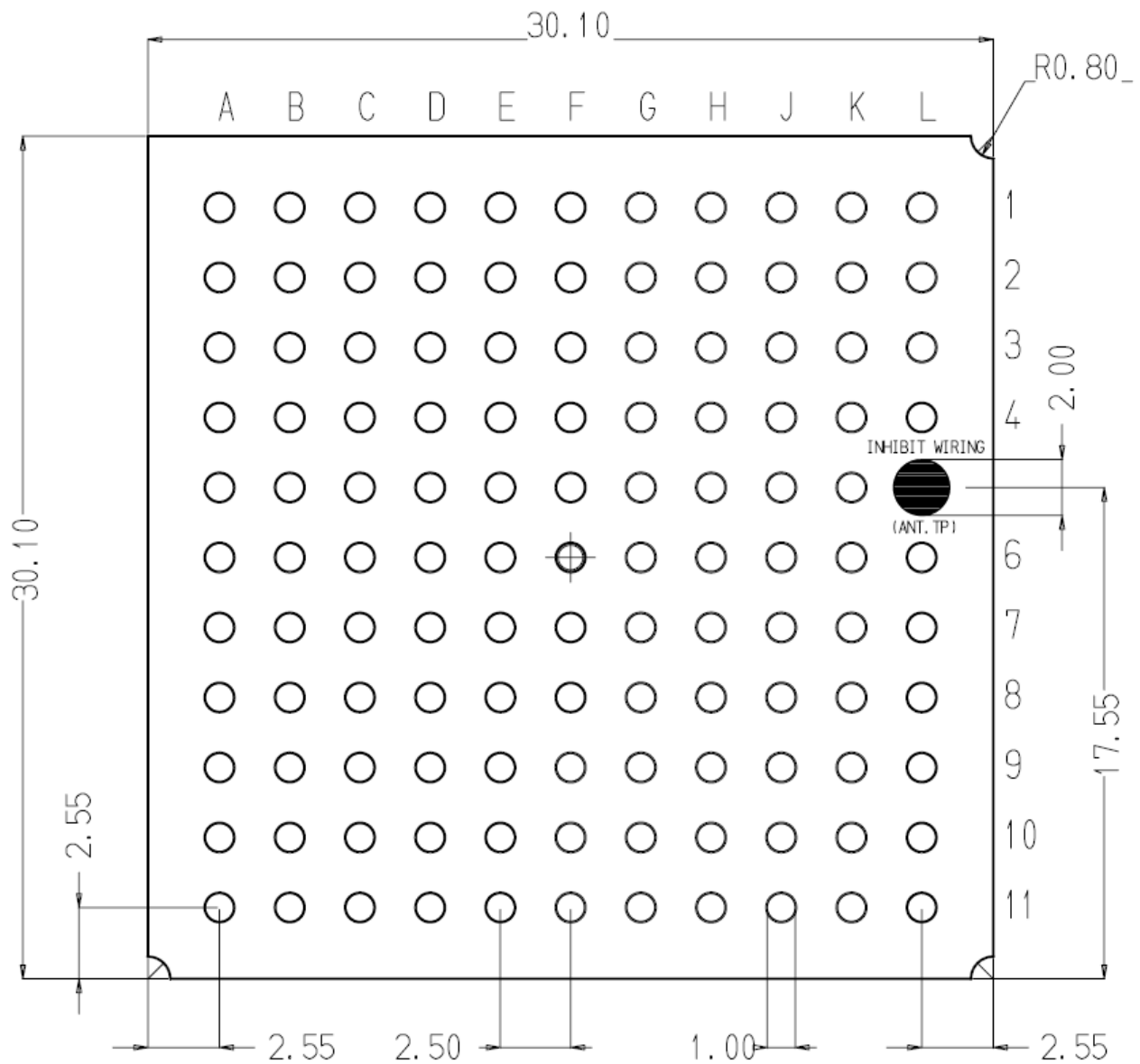
#### 14.1.1. Module Finishing & Dimensions





## 14.1.2. Recommended Foot Print for the Application (GE864)

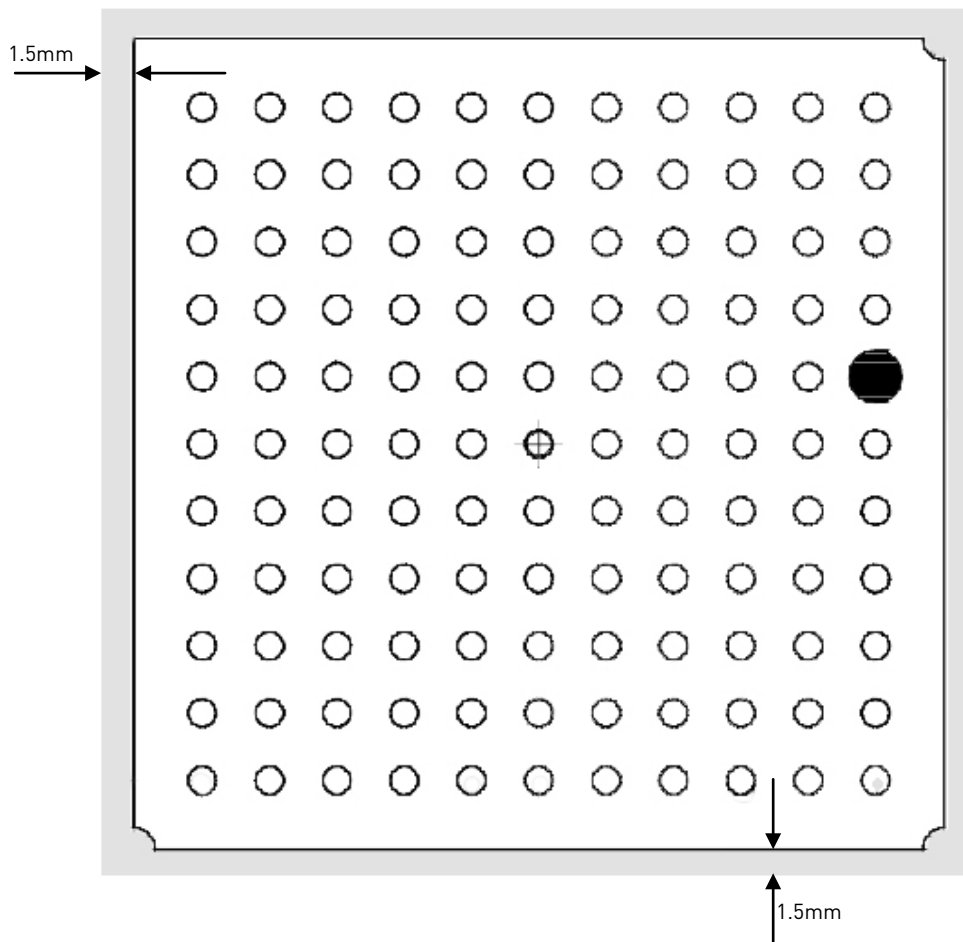
*Top view*



### 14.1.3. Suggested Inhibit Area

In order to easily rework the GE864 is suggested to consider on the application a 1.5mm Inhibit area around the module:

*Top view*



It is also suggested, as common rule for an SMT component, to avoid having a mechanical part of the application in direct contact with the module.



#### 14.1.4. Debug of the GE864 in Production

To test and debug the mounting of the GE864, we strongly recommend to foreseen test pads on the host PCB, in order to check the connection between the GE864 itself and the application and to test the performance of the module connecting it with an external computer. Depending by the customer application, these pads include, but are not limited to the following signals:

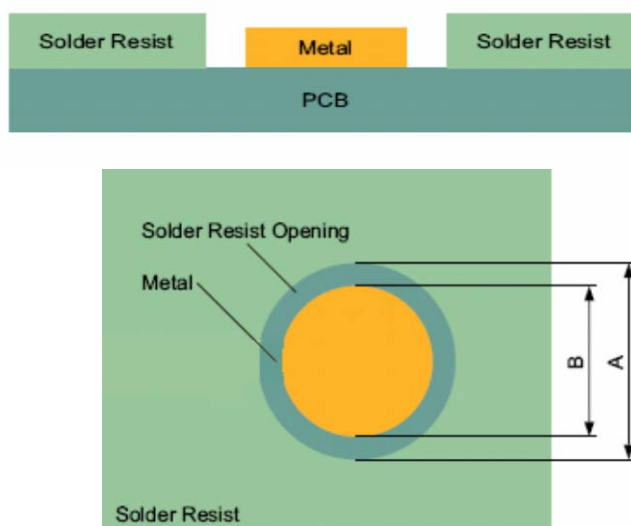
- TXD
- RXD
- ON/OFF
- RESET
- GND
- VBATT
- TX\_TRACE
- RX\_TRACE
- PWRMON

#### 14.1.5. Stencil

Stencil's apertures layout can be the same of the recommended footprint (1:1), we suggest a thickness of stencil foil  $\geq 120\mu\text{m}$ .

#### 14.1.6. PCB Pad Design

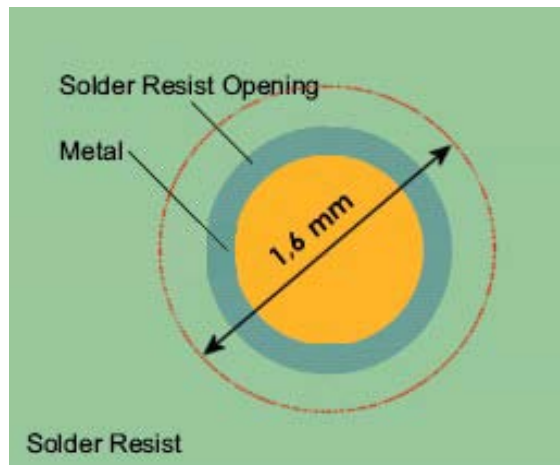
Non solder mask defined" (NSMD) type is recommended for the solder pads on the PCB.



Recommendations for PCB pad dimensions:

Ball pitch [mm]	2,5
Solder resist opening diameter A [mm]	1,150
Metal pad diameter B [mm]	1 ± 0.05

It is recommended no microvia without solder resist cover under the module and no microvia around the pads (see following figure).



Holes in pad are allowed only for blind holes and not for through holes.

Recommendations for PCB pad surfaces:

Finish	Layer thickness [µm]	Properties
Electro-less Ni / Immersion Au	3 -7 / 0.05 – 0.15	good solder ability protection, high shear force values

The PCB must be able to resist the higher temperatures which are occurring at the lead-free process. This issue must be discussed with the PCB-supplier. Generally, the wettability of tin-lead solder paste on the described surface plating is better compared to lead-free solder paste.

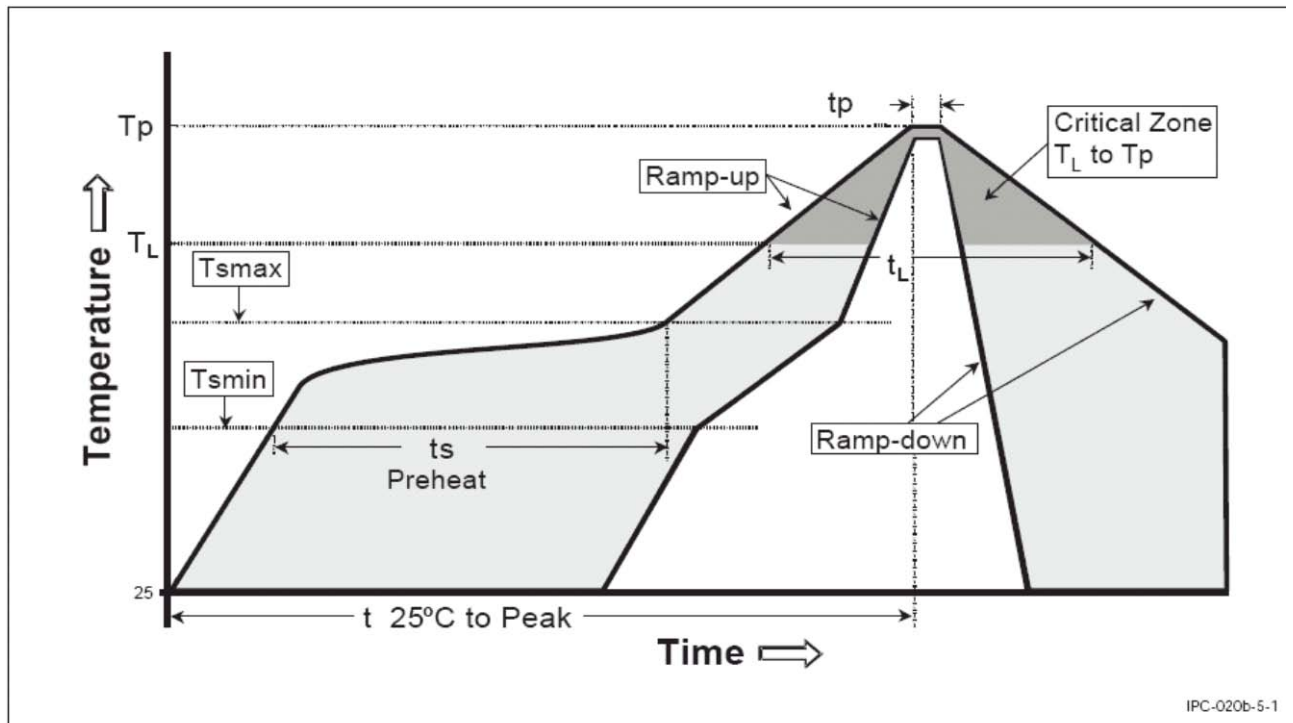
### 14.1.7. Solder Paste

	Lead free
Solder paste	Sn/Ag/Cu



### 14.1.8. GE864 Solder Reflow

The illustration below shows the recommended solder reflow profile:



Profile Feature	Pb-Free Assembly
Average ramp-up rate ( $T_L$ to $T_P$ )	3°C/second max
Preheat	
8 Temperature Min ( $T_{min}$ )	150°C
8 Temperature Max ( $T_{max}$ )	200°C
– Time (min to max) ( $t_s$ )	60-180 seconds
$T_{max}$ to $T_L$	
– Ramp-up Rate	3°C/second max
Time maintained above:	
8 Temperature ( $T_L$ )	217°C
– Time ( $t_L$ )	60-150 seconds
Peak Temperature ( $T_P$ )	245 +0/-5°C
Time within 5°C of actual Peak Temperature ( $t_p$ )	10-30 seconds
Ramp-down Rate	6°C/second max.
Time 25°C to Peak Temperature	8 minutes max.





The Telit GE864 modules are packaged on trays of 20 pieces each. This is especially suitable for the GE864 according to SMT processes for pick & place movement requirements.

[illegible]

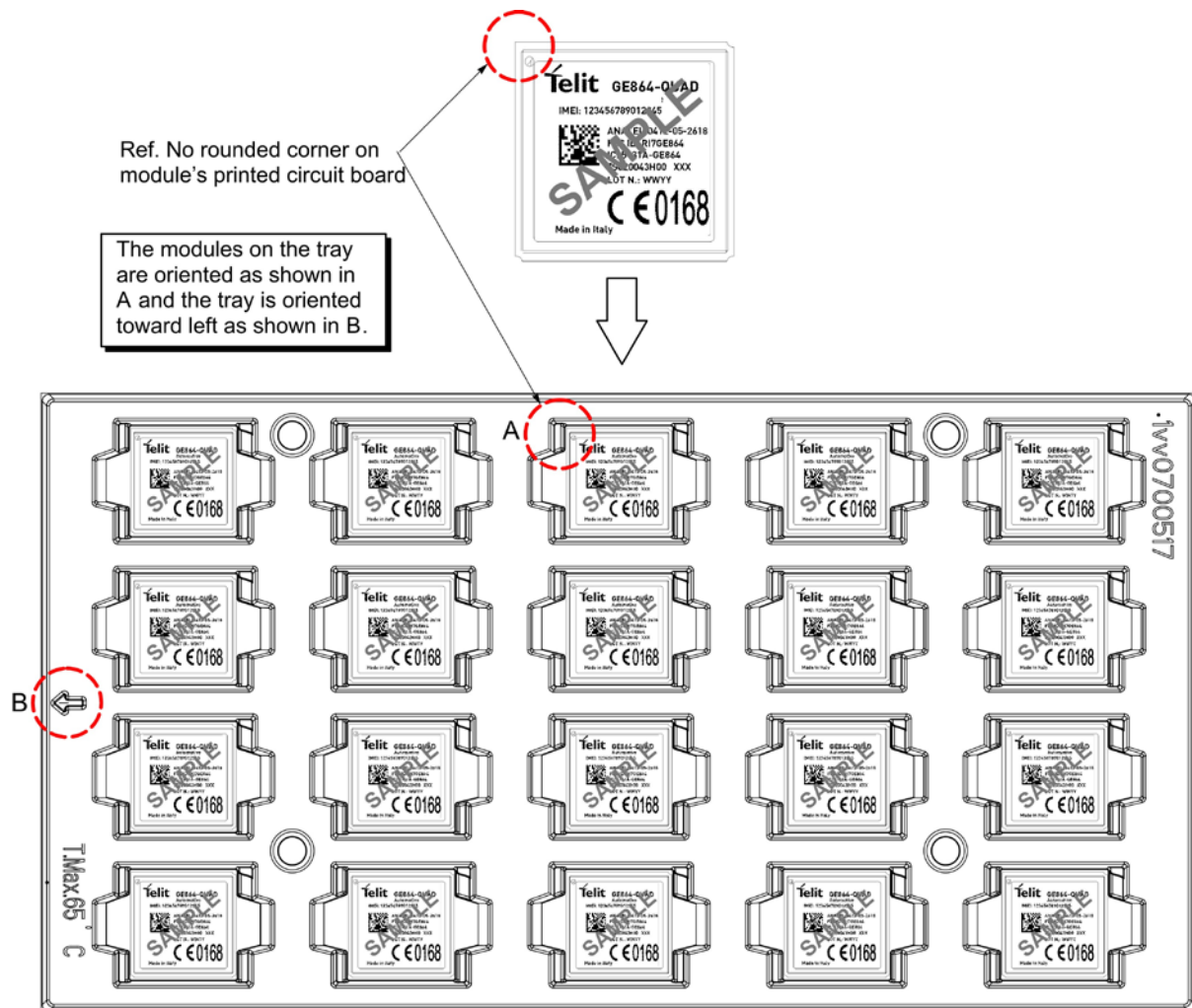




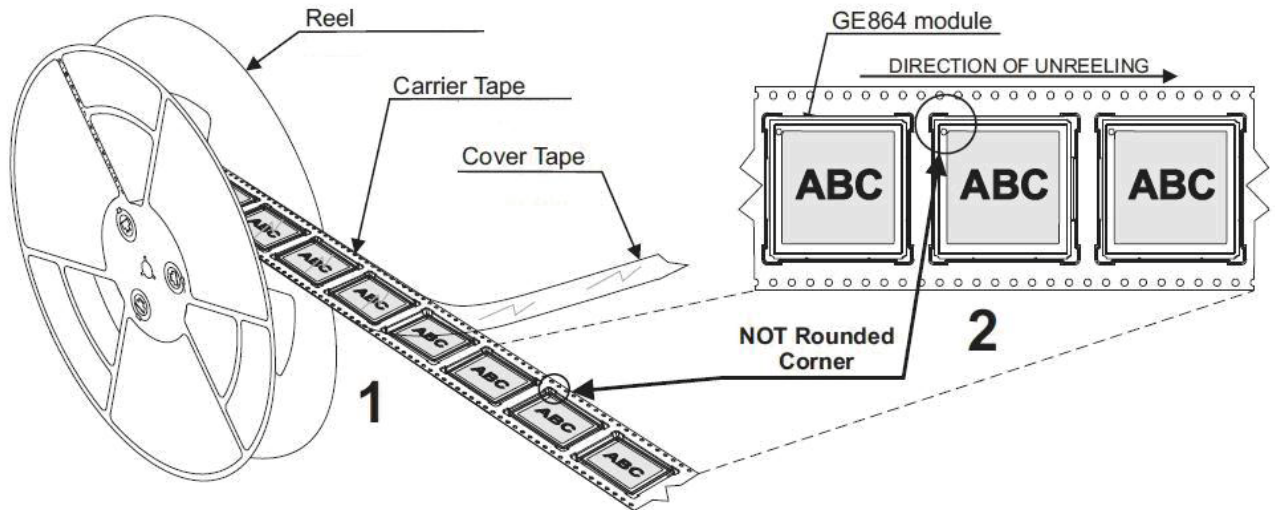
**WARNING:**

These trays can withstand the maximum temperature of 65° C.

**GE864 Orientation on the Tray**



## Reel Drawing



### 14.2.1. Moisture Sensibility

The level of moisture sensibility of GE864 module is “3”, in according with standard IPC/JEDEC J-STD-020, take care all the relatives requirements for using this kind of components.



## 15. Conformity Assessment Issues

The Telit **GE864** has been assessed in order to requirements of the R&TTE Directive 1999/05/EC (Radio Telecommunications Terminal Equipments) to conformity against the harmonised standards with the Notified Body.

**C€0168**

If the module is installed in conformance to the Telit installation manuals, no further evaluation under **Article 3.2** of the R&TTE Directive and do not require further involvement of a R&TTE Directive Notified Body for the final product.  
In all other cases, or if the manufacturer of the final product is in doubt, then the equipment integrating the radio module must be assessed against **Article 3.2** of the R&TTE Directive.

In all cases the assessment of the final product must be made against the Essential requirements of the R&TTE Directive **Articles 3.1(a)** and **(b)**, Safety and EMC respectively, and any relevant Article 3.3 requirements.

This Product Description, the Hardware User Guide and Software User Guide contain all the information you may need for developing a product meeting the R&TTE Directive.

Furthermore the **GE864** module is FCC Approved as module to be installed in other devices. This device is to be used only for fixed and mobile applications. If the final product after integration is intended for portable use, a new application and FCC is required.  
The **GE864** is conforming to the following US Directives:

- Use of RF Spectrum. Standards: FCC 47 Part 24 (GSM 1900)
- EMC (Electromagnetic Compatibility). Standards: FCC47 Part 15

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) this device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

To meet the FCC's RF exposure rules and regulations:

- The system antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all the persons and must not be co-located or operating in conjunction with any other antenna or transmitter.
- The system antenna(s) used for this module must not exceed 1.4dBi (850MHz) and 3.0dBi (1900MHz) for mobile and fixed or mobile operating configurations.
- Users and installers must be provided with antenna installation instructions and transmitter operating conditions for satisfying RF exposure compliance.



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Manufacturers of mobile, fixed or portable devices incorporating this module are advised to clarify any regulatory questions and to have their complete product tested and approved for FCC compliance.



## 16. SAFETY RECOMMENDATIONS



### NOTE:

Read this section carefully to ensure the safe operation.

Be sure the use of this product is allowed in the country and in the environment required. The use of this product may be dangerous and has to be avoided in the following areas:

- Where it can interfere with other electronic devices in environments such as hospitals, airports, aircrafts, etc
- Where there is risk of explosion such as gasoline stations, oil refineries, etc

It is responsibility of the user to enforce the country regulation and the specific environment regulation.

Do not disassemble the product; any mark of tampering will compromise the warranty validity.

We recommend following the instructions of the hardware user guides for a correct wiring of the product. The product has to be supplied with a stabilized voltage source and the wiring has to be conforming to the security and fire prevention regulations.

The product has to be handled with care, avoiding any contact with the pins because electrostatic discharges may damage the product itself. Same cautions have to be taken for the SIM, checking carefully the instruction for its use. Do not insert or remove the SIM when the product is in power saving mode.

The system integrator is responsible of the functioning of the final product; therefore, care has to be taken to the external components of the module, as well as of any project or installation issue, because the risk of disturbing the GSM network or external devices or having impact on the security. Should there be any doubt, please refer to the technical documentation and the regulations in force.

Every module has to be equipped with a proper antenna with specific characteristics. The antenna has to be installed with care in order to avoid any interference with other electronic devices and has to guarantee a minimum distance from the body (20 cm). In case of this requirement cannot be satisfied, the system integrator has to assess the final product against the SAR regulation EN 50360.





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The European Community provides some Directives for the electronic equipments introduced on the market. All the relevant information are available on the European Community website:

<http://europa.eu.int/comm/enterprise/rtte/dir99-5.htm>

The text of the Directive 99/05 regarding telecommunication equipments is available, while the applicable Directives (Low Voltage and EMC) are available at:

[http://europa.eu.int/comm/enterprise/electr\\_equipment/index\\_en.htm](http://europa.eu.int/comm/enterprise/electr_equipment/index_en.htm)

