## MATH 2023 Fall 2021 Multivariable Calculus

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## Chapter 15 Vector Field

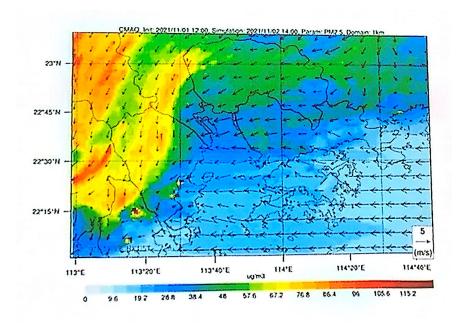
## 1 Intro. to Vector Field

So far, we have learned two kinds of functions involving vector:

- $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ : for each t, provides a position vector  $\langle x(t), y(t), z(t) \rangle$ , so this is a (parametric) curve.
- $z = f(\mathbf{r}) = f(x_1, x_2, \dots, x_n)$ : for a given vector r, this gives a real number, so this is a function of several variables. This is also a scalar field since for any point r in field, it gives a scalar value.

Now we are looking at **vector-valued** function  $\mathbf{F}$  of a vector  $\mathbf{r}$ , i.e.,  $\mathbf{F}(\mathbf{r})$ . This is a **vector field**, which means for any point  $\mathbf{r}$  in **field**, it gives a vector  $\mathbf{F}(\mathbf{r})$ .

You can consider a world map showing the *speed* and *direction* of wind.



You can see that in a 2D map(like above), if we put a vector on each point, the vector must have same dimension as the map, i.e., all vectors must also be 2D vectors.

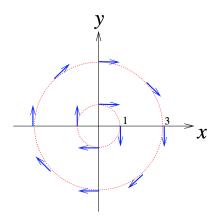
$$\mathbf{F}(\mathbf{r}) = \begin{cases} (F_1(\mathbf{r}), F_2(\mathbf{r})) & \mathbf{r} = (x, y) & 2D \\ (F_1(\mathbf{r}), F_2(\mathbf{r}), F_3(\mathbf{r})) & \mathbf{r} = (x, y, z) & 3D \\ (F_1(\mathbf{r}), F_2(\mathbf{r}), \cdots, F_n(\mathbf{r})) & \mathbf{r} = (x_1, x_2, \cdots, x_n) & nD \end{cases}$$

Summary: dimension of F must be the same as r.

[Example.] Assume a vector field:  $\mathbf{F}(x,y) = \frac{y\mathbf{i} - x\mathbf{j}}{\sqrt{x^2 + y^2}}$ .

[Solution.] Notice that  $||\mathbf{F}|| = \frac{y^2}{x^2 + y^2} + \frac{x^2}{x^2 + y^2} = 1$ , all vectors  $\mathbf{F}(x, y)$  are unit vectors. Moreover, let  $\mathbf{r} = (x, y)$ , then  $\mathbf{r} \cdot \mathbf{F} = 0$ , so  $\mathbf{r} \perp \mathbf{F}$ .

So all vectors are unit vectors tangent to circles centered at the origin with radius  $\sqrt{x^2+y^2}$ .



## 2 Divergence and Curl

Recall that the **gradient operator** is a *vector operator*:

$$\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) \qquad \text{(a vector)}$$

If  $\mathbf{F}(\mathbf{r}) = F_1(\mathbf{r})\mathbf{i} + F_2(\mathbf{r})\mathbf{j} + F_3(\mathbf{r})\mathbf{k}$ , then we define:

• divergence of F, written div F:

$$\operatorname{div} \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

• curl of **F**, written curl **F**:

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = \left( \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) \mathbf{i} - \left( \frac{\partial h}{\partial x} - \frac{\partial f}{\partial z} \right) \mathbf{j} + \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \mathbf{k}$$

This example shows basic computation of **divergence** and **curl**.

[Example.] Let  $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$  and  $\mathbf{u} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ , where a, b and c are constants, show that

- (a)  $\nabla \cdot \mathbf{r} = 3$
- (b)  $\nabla \times \mathbf{r} = \mathbf{0}$
- (c)  $\nabla \cdot (\mathbf{u} \times \mathbf{r}) = 0$
- (d)  $\nabla \times (\mathbf{u} \times \mathbf{r}) = 2\mathbf{u}$ .

[Solution.] (a) 
$$\nabla \cdot \mathbf{r} = \left(\mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z}\right) \cdot (x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) = \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 3$$

(b) 
$$\nabla \times \mathbf{r} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = \mathbf{0}$$

(c) 
$$\mathbf{u} \times \mathbf{r} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a & b & c \\ x & y & z \end{vmatrix} = (bz - cy)\mathbf{i} - (az - cx)\mathbf{j} + (ay - bx)\mathbf{k}$$

$$\therefore \nabla \cdot (\mathbf{u} \times \mathbf{r}) = \frac{\partial}{\partial x} (bz - cy) - \frac{\partial}{\partial y} (az - cx) + \frac{\partial}{\partial z} (ay - bx) = 0$$

(d) 
$$\nabla \times (\mathbf{u} \times \mathbf{r}) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ bz - cy & -az + cx & ay - bx \end{vmatrix} = 2(a\mathbf{i} + b\mathbf{j} + c\mathbf{k}) = 2\mathbf{u}$$