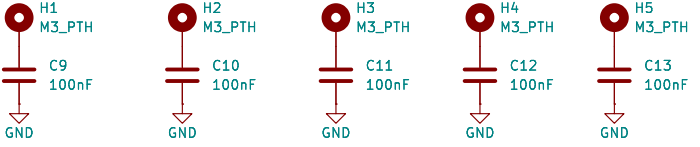


Table 8: Default Configuration of Strapping Pins

Strapping Pin	Default Configuration	Bit Value
GPIO0	Pull-up	1
GPIO2	Pull-down	0
MTDI	Pull-down	0
MTDO	Pull-up	1
GPIO5	Pull-up	1

GPIO12 = MTDI  
GPIO15 = MTDO



George Sleen  
Team 5

Sheet: /  
File: robot-motherboard.kicad\_sch

Title: Robot Motherboard

Size: A3

Date: 2025-07-03

Rev: A

KiCad E.D.A. 9.0.2

Id: 1/1