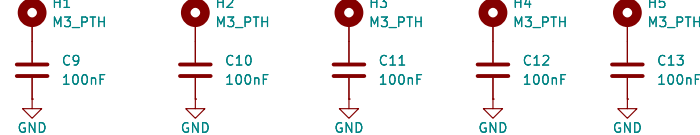


Table 8: Default Configuration of Strapping Pins

Strapping Pin	Default Configuration	Bit Value
GPIO0	Pull-up	1
GPIO2	Pull-down	0
MTDI	Pull-down	0
MTDO	Pull-up	1
GPIO5	Pull-up	1

GPIO12 = MTDI
GPIO15 = MTDO



George Sleen
Team 5

Sheet: /
File: robot-motherboard.kicad_sch

Title: Robot Motherboard

Size: A3
KiCad E.D.A. 9.0.2

Date: 2025-07-06

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