Linguaggio L

Sintassi (BNF)

(by value)

C ::= nil | **Id** = **E** | **C**;**C** | if (**E**) {**C**} *[*else {**C**}*]* | while (**E**) {**C**} | **D**;**C** | return **E**

E ::= v | **Id** | **uop E** | **E bop E** | (**E**) | **Id**(**ae**)

D ::= nil | const **Id***[*:**T***]** = **E** | var **Id***[*:**T***]** = **E** | **D**;**D** | function **Id**(**form**) -> **T** {**C**; return **E**} | **form = ae** | rec **D**

form ::= nil | const **Id: T, form** | var **Id: T, form**

ae ::= nil | **E, ae**

uop ::= + | - | !

bop ::= + | - | * | \ | % | == | != | > | >= | < | <= | && | ||

Id ::= insieme degli identificatori validi

Val_E ::= $\mathbb{Z} \cup \mathbb{R} \cup$ {true, false} $\cup$ {*s* | *s* $\in$ *ASCII**}

T ::= Int | Double | Bool | String

`Int`	$n, n', n_1, \ldots$
`Double`	$d, d', d_1, \ldots$
`Bool`	$b, b', b_1, \ldots \in \{true, false\}$
`String`	$s, s', s_1, \ldots$

Metavariabili

$C, C', C'', C_0, C_1, \ldots$

$E, E', E'', E_0, E_1, \ldots$

$D, D', D'', D_0, D_1, \ldots$

$Id, Id', Id_1, x, x', x_1, \ldots$

$v, v', v'', v_0, v_1, \ldots$

$\tau, \tau', \tau'', \tau_0, \tau_1, \ldots$

(by reference)

form ::= nil | const **Id: T, form** | var **Id: T, form** | ref **Id: T, form**

ae ::= nil | **E, ae** | **l, ae**

Altri comandi:

C ::= do {**C**} while (**E**) | for (**D**; **E**; **C**) {**C**} | switch (**E**) {
case v1: **C**; break
case v2: **C**; break
:
*[*default: **C**; break*]*
}

C simbolo distinto della grammatica, quindi un **programma** è un comando

Semantica Statica

comando ben formato **C**: $\Delta \vdash_c C$
espressione ben formata **E**: $\Delta \vdash_e E : \tau$
dichiarazione ben formata **D**: $\Delta \vdash_d D : \Delta'$

ambiente statico Δ : Id ∪ Val $\longrightarrow T \cup T\text{Loc}$

Semantica Statica Espressioni

Assiomi: $(A1)\ \varnothing \vdash_e i : \text{Int}$, $(A2)\ \varnothing \vdash_e d : \text{Double}$, $(A3)\ \varnothing \vdash_e b : \text{Bool}$, $(A4)\ \varnothing \vdash_e s : \text{String}$

Regole di inferenza:

$$(R1)\ \frac{(\Delta(Id) = \tau \vee \Delta(Id) = \tau\text{Loc})}{\Delta \vdash_e Id : \tau}, \quad (R2)\ \frac{\Delta \vdash_e E_1 : \tau_1, uop : \tau_1 \to \tau}{\Delta \vdash_e uop\, E_1 : \tau}, \quad (R3)\ \frac{\Delta \vdash_e E_1 : \tau_1, \Delta \vdash_e E_2 : \tau_2, bop : \tau_1 \times \tau_2 \to \tau}{\Delta \vdash_e E_1\, bop\, E_2 : \tau}$$

$$(R4)\ \frac{\Delta \vdash_e E : \tau}{\Delta \vdash_e (E) : \tau}$$

Semantica Statica Comandi

Assiomi: $(A5)\ \varnothing \vdash_c nil$

Regole di inferenza:

$$(R5)\ \frac{\Delta(Id) = \tau\text{Loc}, \Delta \vdash_e E : \tau}{\Delta \vdash_c Id = E}, \quad (R6)\ \frac{\Delta \vdash_c C_1, \Delta \vdash_c C_2}{\Delta \vdash_c C_1; C_2}, \quad (R7)\ \frac{\Delta \vdash_e E : \text{Bool}, \Delta \vdash_c C_1, \Delta \vdash_c C_2}{\Delta \vdash_c \text{if } (E)\{C_1\} \text{ else } \{C_2\}}$$

$$(R8)\ \frac{\Delta \vdash_e E : \text{Bool}, \Delta \vdash_c C}{\Delta \vdash_c \text{while } (E)\ \{C\}}, \quad (R9)\ \frac{\Delta \vdash_d D : \Delta', \Delta[\Delta'] \vdash_c C}{\Delta \vdash_c D; C}$$

$$\Delta[\Delta'](x) = \begin{cases} \Delta'(x), & \text{se } \Delta'(x) \text{ definito} \\ \Delta(x), & \text{altrimenti} \end{cases}$$

Semantica Statica Dichiarazioni

Assiomi: $(A6)\ \varnothing \vdash_d nil : \varnothing$

Regole di inferenza:

$$(R10)\ \frac{\Delta \vdash_e E : \tau, T == \tau}{\Delta \vdash_a^{\text{const}} Id : T = E : [(Id, \tau)]}, \quad (R11)\ \frac{\Delta \vdash_e E : \tau, T == \tau}{\Delta \vdash_d \text{var } Id : T = E : [(Id, \tau Loc)]}, \quad (R12)\ \frac{\Delta \vdash_d D_1 : \Delta_1, \Delta[\Delta_1] \vdash_d D_2 : \Delta_2}{\Delta \vdash_d D_1; D_2 : \Delta_1[\Delta_2]}$$

Semantica Statica Funzioni

$$(FS1)\frac{\Delta \vdash_E E : \tau}{\Delta \vdash_C \text{return } E} \qquad \begin{cases} \mathcal{T}(nil) = nil \\ \mathcal{T}(\text{const Id} : \tau, \text{form}) = \tau, \mathcal{T}(\text{form}) \\ \mathcal{T}(\text{var Id} : \tau, \text{form}) = \tau, \mathcal{T}(\text{form}) \end{cases}$$

$$(FS2)\frac{\text{form} : \Delta_0, \Delta[\Delta_0] \vdash_C \text{var } res : \tau = E; C; \text{return } res, \cancel{\Delta[\Delta_0][(res, \tau Loc)] \vdash_E res : \tau}}{\Delta \vdash_D \text{function Id(form)} \ \to \tau \ \{\text{var } res : \tau = E; C; \text{return } res\} \ : \ [(\text{Id}, \mathcal{T}(\text{form}) \to \tau)]}$$

Ovvio!

$$(FS3) \quad nil : \varnothing, \quad \frac{\text{form} : \Delta_0, \text{Id} \notin \Delta_0}{\text{const Id} : \tau, \text{form} : \Delta_0[(\text{Id}, \tau)]} \quad \frac{\text{form} : \Delta_0, \text{Id} \notin \Delta_0}{\text{var Id} : \tau, \text{form} : \Delta_0[(\text{Id}, \tau loc)]}$$

$$(FS4)\frac{\Delta \vdash_{ae} ae : aet, \Delta(\text{Id}) = aet \to \tau}{\Delta \vdash_E \text{Id}(ae) : \tau} \qquad \begin{cases} \Delta \vdash_{ae} nil \\ \dfrac{\Delta \vdash_E E{:}\tau, \Delta \vdash_{ae} ae{:}aet}{\Delta \vdash_{ae} E, ae{:}\tau, aet} \end{cases}$$

Semantica Statica (dichiarazione) Funzioni Ricorsive

Creazione ambiente:

$(FS2') \vdash_D \text{func Id(form)} \ \to \tau \ \{\text{var } res : \tau = E; C; \text{return } res\} \ : \ [(\text{Id}, \mathcal{T}(\text{form}) \to \tau)]$

Validazione ambiente:

$$(FS2'')\frac{\text{form} : \Delta_0, \Delta[\Delta_0] \vdash_C \text{var } res : \tau = E; C; \text{return } res, \Delta[\Delta_0][(res, \tau)] \vdash_E E : \tau}{\Delta \vdash_D \text{func Id(form)} \ \to \tau \ \{\text{var } res : \tau = E; C; \text{return } res\}}$$

$$(RS1')\frac{\vdash_D D : \Delta}{\vdash_D rec\ D : \Delta}$$

$$(RS1'')\frac{\vdash_D D : \Delta', \Delta[\Delta'_{|I_0}] \vdash_D D}{\Delta \vdash_D rec\ D}, \ I_0 = FI(D) \cap BI(D)$$

Semantica Dinamica

esecuzione **C**: $\langle C,\rho,\sigma\rangle \longrightarrow_c \langle C',\rho',\sigma'\rangle,\ \mathbf{Exec}(C,\rho,\sigma)=\sigma' \iff \langle C,\rho,\sigma\rangle \longrightarrow_c^* \sigma'$

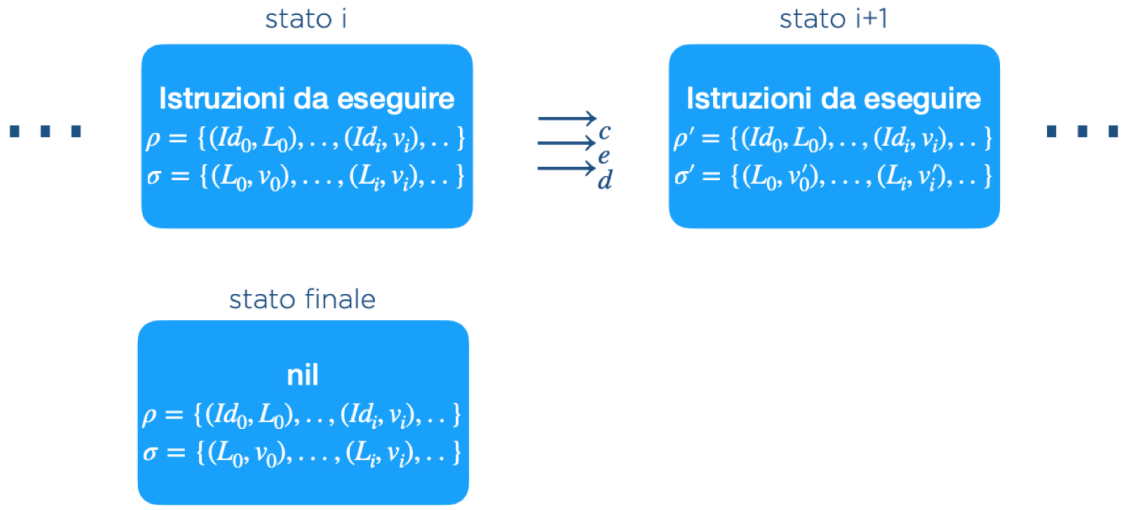
valutazione **E**: $\langle E,\rho,\sigma\rangle \longrightarrow_e \langle E',\rho,\sigma\rangle,\ \mathbf{Eval}(E,\rho,\sigma)=v\in Val \iff \langle E,\rho,\sigma\rangle \longrightarrow_e^* v$

elaborazione **D**: $\langle D,\rho,\sigma\rangle \longrightarrow_d \langle D',\rho',\sigma'\rangle,\ \mathbf{Elab}(D,\rho,\sigma)=\langle\rho',\sigma'\rangle \iff \langle D,\rho,\sigma\rangle \longrightarrow_d^* \langle\rho',\sigma'\rangle$

ambiente (dinamico) ρ : Id $\longrightarrow$ Loc ∪ Val memoria σ : Loc $\longrightarrow$ Val

$\longrightarrow_c$, $\longrightarrow_e$, $\longrightarrow_d$ sono le funzioni di interpretazione semantica di C, E e D

SISTEMA DI TRANSIZIONI



Semantica Dinamica Espressioni

$$(Id1)\ \frac{\rho(Id) = v \ \vee \ (\rho(Id) = L \in Loc \wedge \sigma(L) = v)}{\langle Id, \rho, \sigma\rangle \longrightarrow_e v}$$

$$(uop1)\ \frac{\langle E, \rho, \sigma\rangle \longrightarrow_e \langle E', \rho, \sigma\rangle}{\langle uop\ E, \rho, \sigma\rangle \longrightarrow_e \langle uop\ E', \rho, \sigma\rangle} \qquad (uop2)\ \langle uop\ v, \rho, \sigma\rangle \longrightarrow_e v' = \text{uop } v$$

$$(bop1)\ \frac{\langle E_1, \rho, \sigma\rangle \longrightarrow_e \langle E_1', \rho, \sigma\rangle}{\langle E_1\ bop\ E_2, \rho, \sigma\rangle \longrightarrow_e \langle E_1'\ bop\ E_2, \rho, \sigma\rangle} \qquad (bop2)\ \frac{\langle E_2, \rho, \sigma\rangle \longrightarrow_e \langle E_2', \rho, \sigma\rangle}{\langle v_1\ bop\ E_2, \rho, \sigma\rangle \longrightarrow_e \langle v_1\ bop\ E_2', \rho, \sigma\rangle}$$

$$(bop3)\ \langle v_1 bop\ v_2, \rho, \sigma\rangle \longrightarrow_e v = v_1 \text{ bop } v_2$$

!!! *bop* è sintassi
bop è semantica

Semantica Dinamica Comandi

$$(id2)\ \frac{\langle E, \rho, \sigma\rangle \longrightarrow_e^* v}{\langle Id = E, \rho, \sigma\rangle \longrightarrow_c \langle Id = v, \rho, \sigma\rangle} \qquad (id3)\ \langle Id = v, \rho, \sigma\rangle \longrightarrow_c \sigma[\rho(Id)] = v$$

$$(seq1)\ \frac{\langle C_1, \rho, \sigma\rangle \longrightarrow_c \langle C_1', \rho, \sigma'\rangle}{\langle C_1; C_2, \rho, \sigma\rangle \longrightarrow_c \langle C_1'; C_2, \rho, \sigma'\rangle} \qquad (seq2)\ \frac{\langle C_1, \rho, \sigma\rangle \longrightarrow_c \sigma'}{\langle C_1; C_2, \rho, \sigma\rangle \longrightarrow_c \langle C_2, \rho, \sigma'\rangle}$$

$$(if1)\ \frac{\langle E, \rho, \sigma\rangle \longrightarrow_e^* true}{\langle \mathbf{if}\ (E)\{C_1\}\ \mathbf{else}\ \{C_2\}, \rho, \sigma\rangle \longrightarrow_c \langle C_1, \rho, \sigma\rangle} \qquad (if2)\ \frac{\langle E, \rho, \sigma\rangle \longrightarrow_e^* false}{\langle \mathbf{if}\ (E)\{C_1\}\ \mathbf{else}\ \{C_2\}, \rho, \sigma\rangle \longrightarrow_c \langle C_2, \rho, \sigma\rangle}$$

$$(rep1)\ \frac{\langle E, \rho, \sigma\rangle \longrightarrow_e^* true}{\langle \mathbf{while}\ (E)\{C\}\ \rho, \sigma\rangle \longrightarrow_c \langle C; \mathbf{while}\ (E)\{C\}, \rho, \sigma\rangle} \qquad (rep2)\ \frac{\langle E, \rho, \sigma\rangle \longrightarrow_e^* false}{\langle \mathbf{while}\ (E)\{C\}, \rho, \sigma\rangle \longrightarrow_c \sigma}$$

$$(b1)\ \frac{\langle D, \rho, \sigma\rangle \longrightarrow_d^* \langle \rho', \sigma'\rangle}{\langle D; C, \rho, \sigma\rangle \longrightarrow_c \langle C, \rho[\rho'], \sigma[\sigma']\rangle}$$

Semantica Dinamica Dichiarazioni

$$(const1)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* v}{< const\ Id : T = E,\rho,\sigma\rangle \longrightarrow_d \langle [(Id,v)],\sigma\rangle}$$

$$(var1)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* v}{\langle var\ Id : T = E,\rho,\sigma\rangle \longrightarrow_d \langle [(Id,new\ L)],[(L,v)]\rangle}$$

$$(dd1)\ \frac{\langle D_1,\rho,\sigma\rangle \longrightarrow_d \langle D_1',\rho',\sigma'\rangle}{\langle D_1;D_2,\rho,\sigma\rangle \longrightarrow_d \langle D_1';D_2,\rho',\sigma'\rangle} \qquad (dd2)\ \frac{\langle D_2,\rho[\rho_1],\sigma\rangle \longrightarrow_d \langle D_2',\rho[\rho_1]',\sigma'\rangle}{\langle \rho_1;D_2,\rho[\rho_1],\sigma\rangle \longrightarrow_d \langle \rho_1;D_2',\rho[\rho_1]',\sigma'\rangle}$$

$$(dd3)\ \langle \rho_1;\rho 2,\rho,\sigma\rangle \longrightarrow_d \langle \rho_1[\rho_2],\sigma\rangle$$

le regole (dd2) e (dd3) contengono configurazioni non ammissibili rispetto alla definizione di sistema di transizione

$(dd2)\ \langle \rho_1;D_2,\rho,\sigma\rangle, \langle \rho_1;D_2',\rho,\sigma'\rangle$ $(dd3)\ \langle \rho_1;\rho 2,\rho,\sigma\rangle$

la parte codice delle configurazioni di stato deve essere generabile dalla grammatiche che definisce D, e questo non vale per le configurazioni sopra

aggiungo gli ambienti alla sintassi

D ::= nil | const ID[:T] = E | var ID[:T] = E | D;D | ϱ **!!!** solo il compilatore può generare gli ambienti della sintassi, non l'utente

Il sistema di transizione delle dichiarazioni è

$(\{\langle D,\rho,\sigma\rangle \cup \langle \rho', sigma'\rangle\}, \longrightarrow_d, \{\langle \rho', sigma'\rangle\},$ ⟨dichiarazione da elaborare, ambiente iniziale, memoria iniziale⟩)

Semantica Dinamica Funzioni (scoping statico e dinamico)

$$(FD1)\langle \text{func Id(form)} \rightarrow T\{C; \text{return } E\}, \rho, \sigma\rangle \rightarrow_d \langle (Id, \lambda \text{ form} . \{\rho'; C; \text{return } E\}), \sigma\rangle$$

$$\begin{cases} \rho' = \rho_{|FI(C)-BI(form)} & scoping\ statico \\ \rho' = nil & scoping\ dinamico \end{cases}$$

qui C indica {ρ';C; return E}

$$(FD2)\frac{\rho(Id) = \lambda \text{ form} . C}{\langle Id(ae), \rho, \sigma\rangle \rightarrow_e \langle \{form = ae; C\}, \rho, \sigma\rangle}$$

$$(FD3)\frac{\langle E, \rho, \sigma\rangle \rightarrow_e \langle E', \rho, \sigma\rangle}{\langle E, ae, \rho, \sigma\rangle \rightarrow_{ae} \langle E', ae, \rho, \sigma\rangle}$$

$$(FD4)\frac{\langle ae, \rho, \sigma\rangle \rightarrow_{ae} \langle ae', \rho, \sigma\rangle}{\langle k, ae, \rho, \sigma\rangle \rightarrow_{ae} \langle k, ae', \rho, \sigma\rangle}$$

$$(FD5)\frac{\langle ae, \rho, \sigma\rangle \rightarrow_{ae} \langle ae', \rho, \sigma\rangle}{\langle \text{form} = ae, \rho, \sigma\rangle \rightarrow_d \langle \text{form} = ae', \rho, \sigma\rangle}$$

$$(FD6)\frac{av \vdash \text{form} : \rho_0, \sigma_0}{\langle \text{form} = av, \rho, \sigma\rangle \rightarrow_d \langle \rho_0, \sigma_0\rangle}$$

$$nil \vdash nil : \emptyset, \emptyset$$

$$\frac{av \vdash \text{form} : \rho, \sigma}{v, av \vdash \text{let Id} : \tau, \text{form} : \rho[(\text{Id}, v)], \sigma}$$

$$\frac{av \vdash \text{form} : \rho, \sigma}{v, av \vdash \text{var Id} : \tau, \text{form} : \rho[(\text{Id}, l_{(new)})], \sigma[(l_{(new)}, v)]}$$

$$(FD7)\langle \text{return } E, \rho, \sigma\rangle \rightarrow_c \langle E, \rho, \sigma\rangle$$

Semantica Dinamica (dichiarazione) Funzioni Ricorsive (DA NON FARE)

Dichiarazione di funzione come se non fosse ricorsiva (effetto: ci sono identificatori liberi nel corpo - in sostanza il nome della funzione):

$$(RD1)\frac{\langle D, \rho - I_0, \sigma\rangle \rightarrow_d \langle D', \rho', \sigma'\rangle}{\langle rec\ D, \rho, \sigma\rangle \rightarrow_d \langle rec\ D', \rho', \sigma'\rangle}, I_0 = FI(D) \cap BI(D)$$

Quando finiamo con la applicazione della RD1, possiamo applicare la RD2:

$$(RD2)\ \langle rec\ \rho_0, \rho, \sigma\rangle \rightarrow \langle \{(f, \lambda form . (rec\ \rho_0) - form; C) \mid \rho_0(f) = \lambda form . C\}, \sigma\rangle$$

Identificatori Liberi

$FI_e : E \rightarrow$ {occorrenze Id liberi}

FI_e(v) = ∅

FI_e(Id) = {Id}

FI_e(uop E) = FI_e(E)

FI_e(E1 bop E2) = FI_e(E1) ∪ FI_e(E2)

$FI_c : C \rightarrow$ {occorrenze Id liberi}

FI_c(nil) = ∅

FI_c(Id = E) = {Id} ∪ FI_e(E)

FI_c(C1;C2) = FI_c(C1) ∪ FI_c(C2)

FI_c(if (E) {C1} else {C2}) =
FI_e(E) ∪ FI_c(C1) ∪ FI_c(C2)

FI_c(while (E) {C}) = FI_e(E) ∪ FI_c(C)

FI_c(D;C) = FI_d(D) ∪ (FI_c(C) - BI_d(D))

$FI_d : D \rightarrow$ {occorrenze Id liberi}

FI_d(nil) = ∅

FI_d(const Id:T = E) = FI_e(E)

FI_d(var Id:T = E) = FI_e(E)

FI_d(D1;D2) = FI_d(D1) ∪ (FI_d(D2)-BI_d(D1))

$$BI_c = \overline{FI}_c$$

$$BI_e = \overline{FI}_e$$

$$BI_d = \overline{FI}_d$$

Identificatori Liberi Funzioni

FI_c(return E) = FI_e(E)

FI_e(Id(ae)) = {Id} ∪ FI_{ae}(ae)

FI_d(function Id(form))-> T{C} = FI_c(C) - BI_{form}(form)

FI_{form}(form) = ∅

FI_{ae}(E,ae) = FI_e(E) ∪ FI_{ae}(ae)

Anatomia delle funzioni