

# Capturing, rendering and simulation for large scale grassland

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**Abstract**—Grass is a very import element of nature, however create and implement a large scale, realistic grassland is not that easy due to extremely high computation complexity and large amount of data needed for simulation and rendering. Common sense tells us grass blades are simple, however there are numerous kinds of grass blade in the world and it's not possible for any system to store all kinds of grass blades beforehand. Obtain grass blade with interactive camera can be an intuitive solution for this problem. We provide a method

**Index Terms**—Grass, Capture, Render, Simulation, GPU

## 1 INTRODUCTION

THIS demo file is intended to serve as a “starter file” for IEEE Computer Society journal papers produced under L<sup>A</sup>T<sub>E</sub>X using IEEEtran.cls version 1.8a and later. I wish you the best of success.

mds  
September 17, 2014



**Michael Shell** Biography text here.

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## 2 RELATED WORK

## 3 ALGORITHM OVERVIEW

## 4 BLADE CAPTURE

## 5

## 6 CONCLUSION

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**John Doe** Biography text here.

## APPENDIX A

### PROOF OF THE FIRST ZONKLAR EQUATION

Appendix one text goes here.

## APPENDIX B

Appendix two text goes here.

## ACKNOWLEDGMENTS

The authors would like to thank...

**Jane Doe** Biography text here.

## REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to L<sup>A</sup>T<sub>E</sub>X*, 3rd ed. Harlow, England: Addison-Wesley, 1999.

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