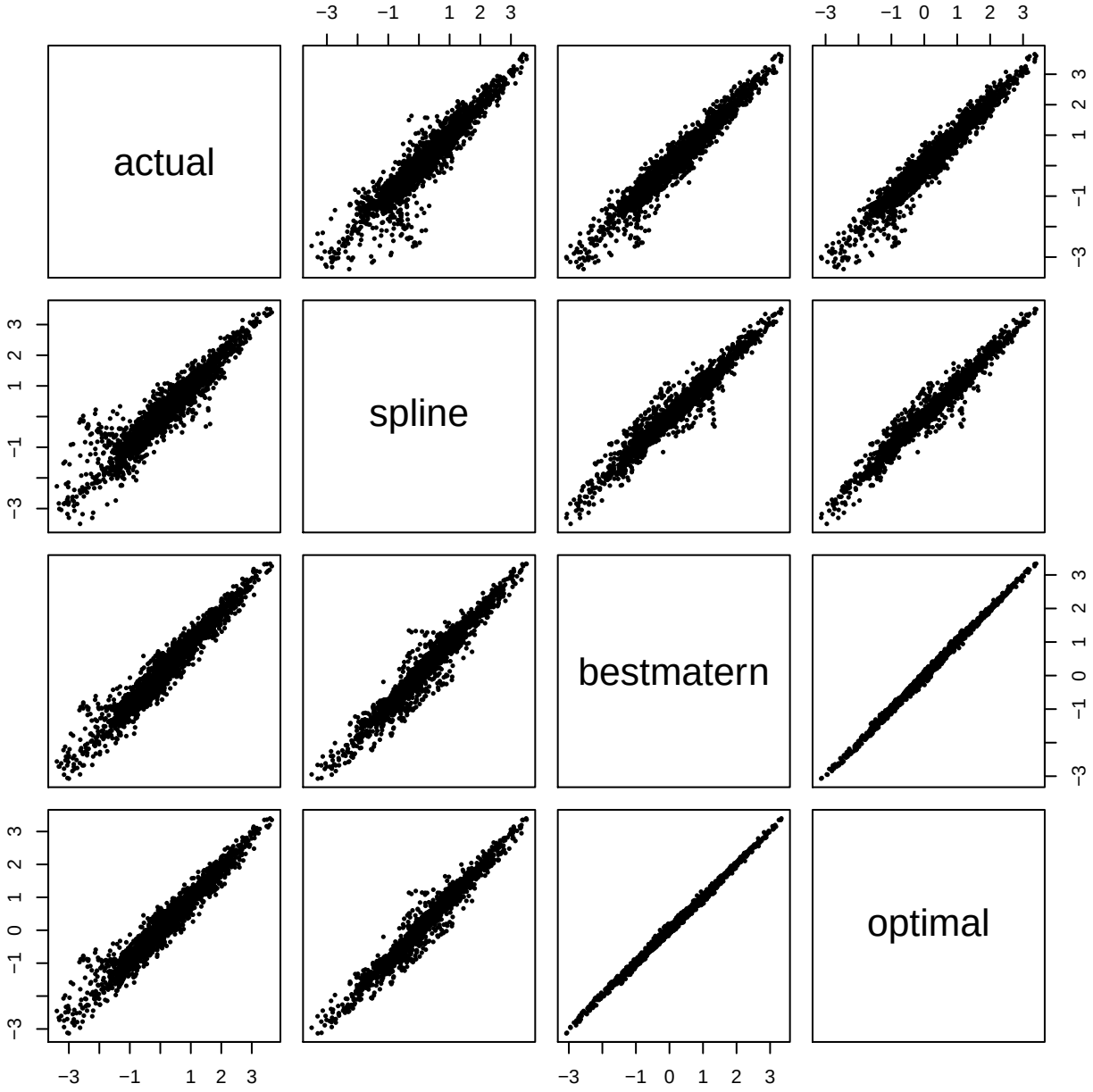
actual
spline
bestmatern
optimal
−3
−1
0
1
2
3