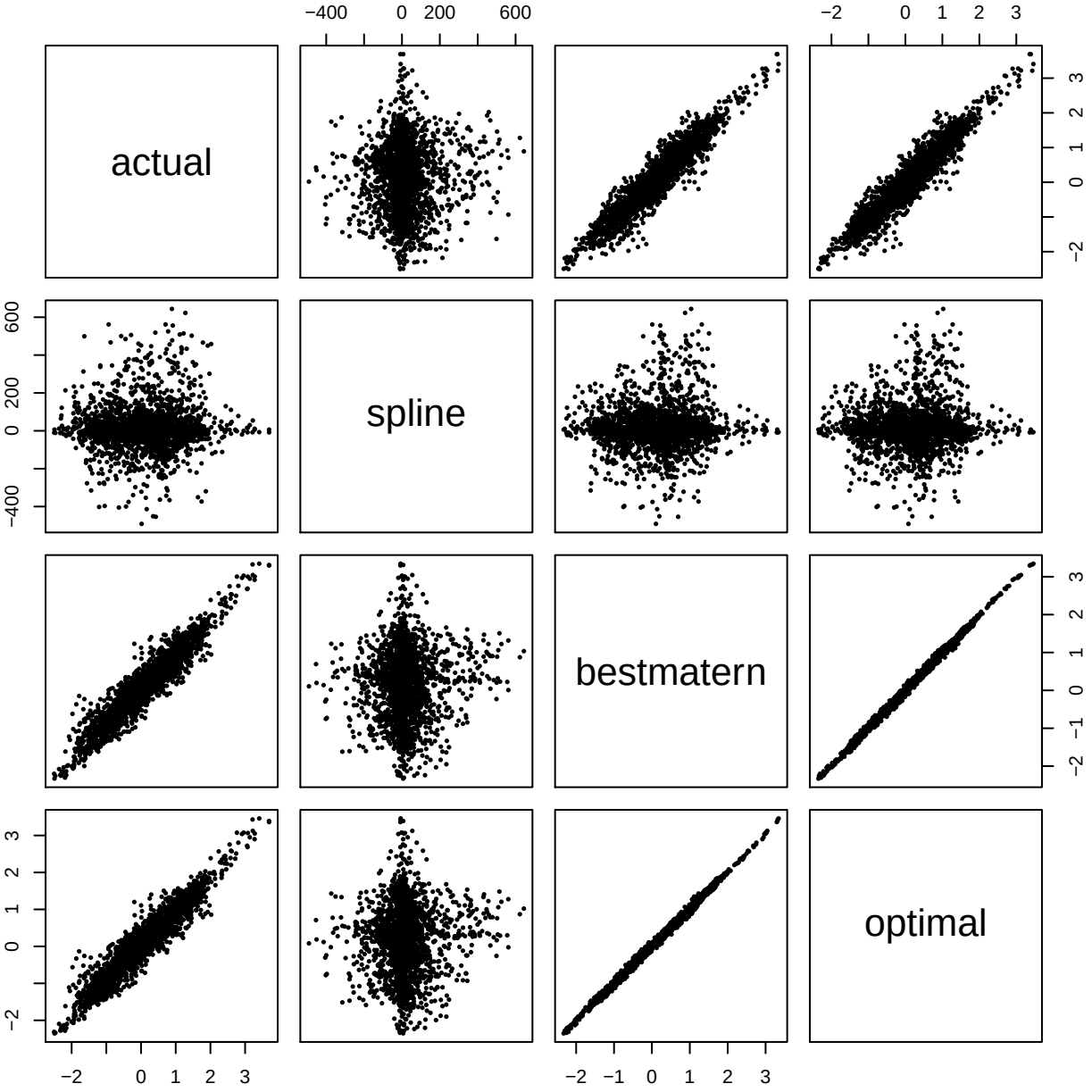
actual
spline
bestmatern
optimal
−400
0
200
600
−2
0
1
2
3
−1