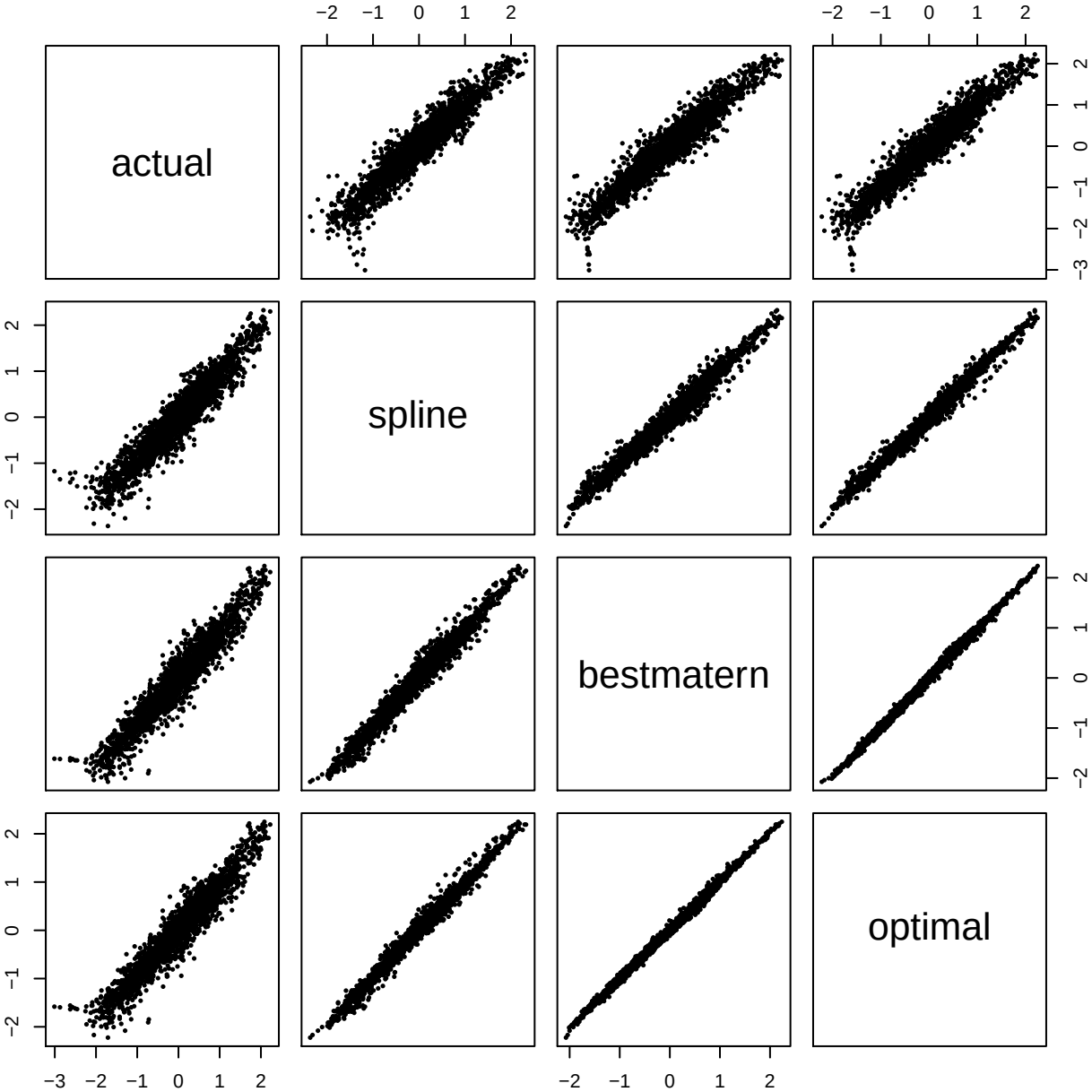
actual
spline
bestmatern
optimal
−3 −2 −1 0 1 2