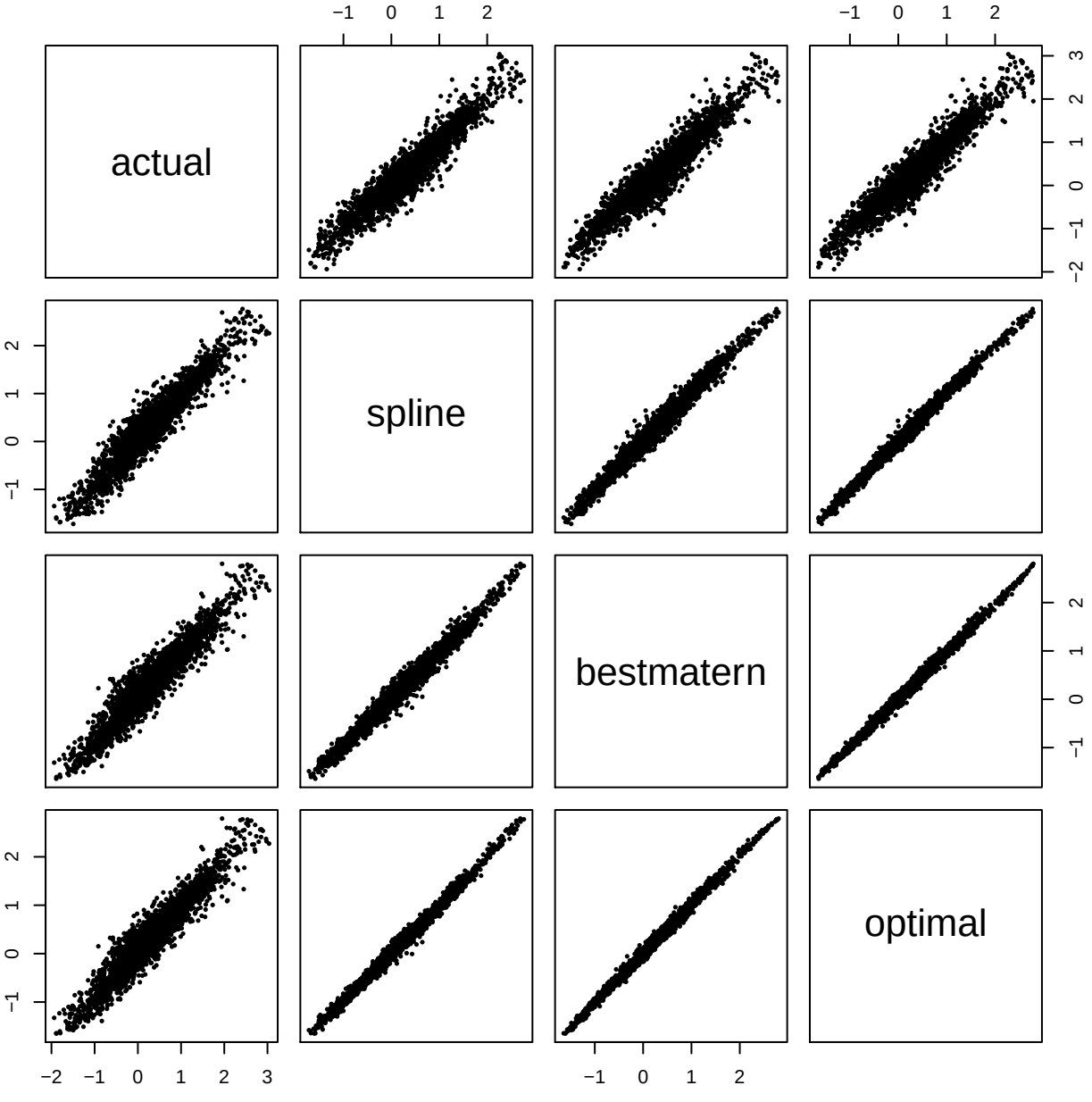
actual
spline
bestmatern
optimal
−1 0 1 2
−2 −1 0 1 2 3