

FELINE: A something...

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Summary

Feline combines a fully parallelized galaxy line template matching with the matched filter approach for individual emission features of LSDcat [@HerenzE_17a]. For the 3D matched filtering, the complete data cube is first median filtered to remove all continuum sources, and then cross-correlated with a template of an isolated emission feature in two spatial and one spectral dimension. We assumed a simple Gaussian with a FWHM of 250 km/s for the line profile and a PSF based on the given seeing in the data cube. The FELINE algorithm then evaluates the likelihood in each spectrum of the cube for emission lines at the positions provided by a given redshift and a certain combination of typical emission features. FELINE probes all possible combinations of up to 14 transitions paired in 9 groups: Ha, Hb, Hg, Hd, OII, OIII, NII, SII, and NeIII for the redshift range of interest (0.4 < z < 1.4). This particular selection of lines is motivated by the most prominent emission features expected in the MUSE data within this redshift range. This results in 512 (2^9) different models that are assessed at roughly 8,000 different redshifts for each of the approx 90,000 spectra in a single data cube. To ensure that only lines above a certain S/N threshold contribute to each model, a penalty value is subtracted for each additional line. The S/N near strong sky lines are set exactly to that threshold. Hence lines that fall onto such a contaminated region will not affect model quality. This is particularly useful for doublet lines that then contribute to a model even when one of the lines aligns with a skyline. Furthermore, the S/N is saturated at a certain threshold to limit the impact of extremely strong lines on the overall budget of the tested template. For each spaxel the model with the highest accumulative probability over all contributing lines and its corresponding redshift are determined. This approach has the benefit to pick up extremely weak emitters that show multiple emissions lines while avoiding the deluge of false positives when looking for single lines below a certain S/N threshold.

This can be applied to each spatial element independently and was thus fully parallelized. From the resulting spatial map of best model probabilities, the peaks were automatically selected via maximum filter and 1D spectra were extracted for each emission line galaxy candidate. Those extracted spectra are fitted with an emission line galaxy template and with the redshift as well as the individual line strengths as only free parameter to reach sub pixel accuracy in an early redshift estimate as well as deriving further diagnostics for the later manual inspection, such as the OII line ratio.

Statement of need

Here comes the statement of needs



Mathematics

- 40 Here we talk about the math behind our software Parts of the summary will eventually end up
- here I guess. I just wanted to give it a start somehow.

42 Citations

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49 Figures

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57 References