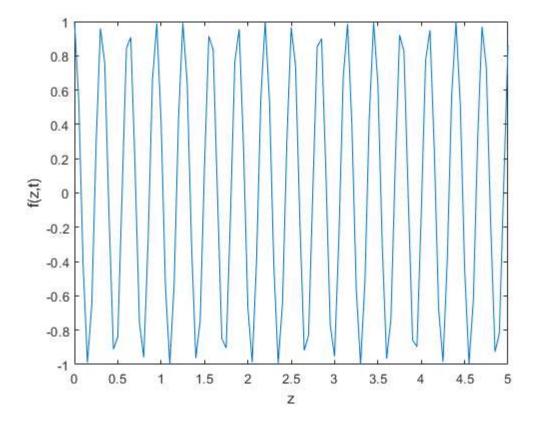
Contents

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```
Nz = 101;
Nt = 1001;
zmax = 5;
tmax = 10;
z = linspace(0, zmax, Nz); %(0, 5, 101)
t = linspace(0, tmax, Nt); %(0,10,1001)
f = 20; % a frequency
omega = 2.*pi.*f; % calculate omegas
k = 20;
%cycle through each time step
```

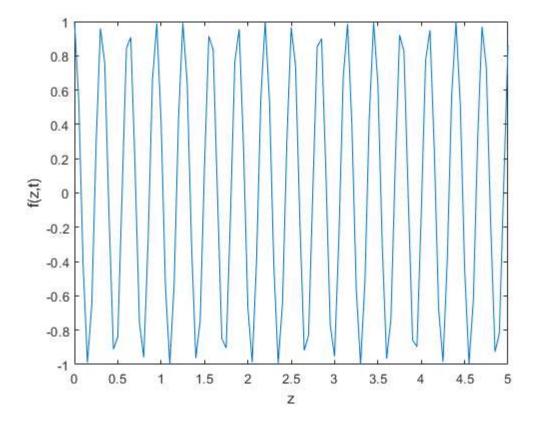
а

```
for t_ = t
    %update function f at this time step
    f = cos((omega.*t_)-(k.*z));
    figure(1)
    cla()
    plot(z,f)
    xlim([min(z),max(z)])
    ylim([-1,1])
    xlabel('z')
    ylabel('f(z,t)')
    drawnow()
end
% omega changes how fast the function oscillates
% k determines how far the wave travels
```



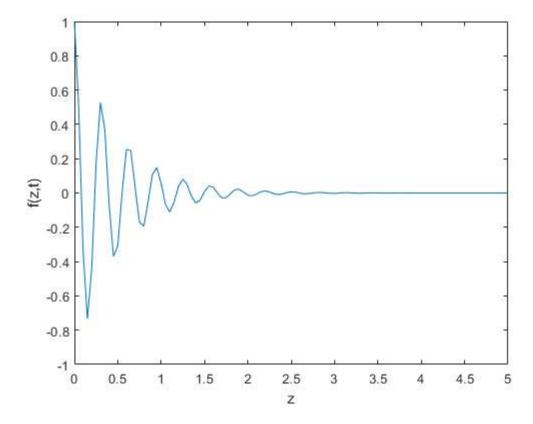
b

```
for t_ = t
    %update function f at this time step
    f = cos((omega.*t_)+(k.*z));
    figure(2)
    cla()
    plot(z,f)
    xlim([min(z),max(z)])
    ylim([-1,1])
    xlabel('z')
    ylabel('f(z,t)')
    drawnow()
end
% omega changes how fast the function oscillates
% k determines how far the wave travels
```



С

```
alpha = 2;
for t_{-} = t
    %update function f at this time step
    f = (exp(-1*alpha*z)).*cos((omega.*t_)-(k.*z));
    figure(3)
    cla()
    plot(z,f)
    xlim([min(z),max(z)])
    ylim([-1,1])
    xlabel('z')
    ylabel('f(z,t)')
    drawnow()
end
% omega changes how fast the function oscillates
% k determines how far the wave travels
% alpha determines what is happening at time = 0
```



d

```
A = 2;
B = 2;
for t_{-} = t
    %update function f at this time step
    f = A.*cos((omega.*t_)-(k.*z)) + B.*cos((omega.*t_)+(k.*z));
    figure(4)
    cla()
    plot(z,f)
    xlim([min(z),max(z)])
    ylim([-1,1])
    xlabel('z')
    ylabel('f(z,t)')
    drawnow()
end
% omega changes how fast the function oscillates
% k determines how far the wave travels
\ensuremath{\text{\%}} A and B determines the size of the amplitude of the waves
```

