

# Exercise Sheet 1, Question 4: 1D Phase Portraits

## Complete Solution with XYZ Methodology

### Methods of Applied Mathematics [SEMT30006]

## Problem Statement

Sketch phase portraits for the following differential equations, and describe the long-time behaviour for the given starting conditions.

(a)  $\frac{du}{dt} = \frac{2}{1+u^2} - 1$ , with  $u(0) = -2$ ,  $u(0) = 0$  and  $u(0) = 2$ .

(b)  $\frac{du}{dt} = u^3 + 5u^2 - 6u$ , with  $u(0) = -1$  and  $u(0) = 4$ .

## 1 Foundational Concepts: 1D Phase Portraits

### What is a Phase Portrait?

- **STAGE X (Definition):** A **phase portrait** is a geometric representation of the trajectories of a dynamical system in the phase space. For 1D systems  $\frac{du}{dt} = f(u)$ :

- The **phase space** is the  $u$ -axis (one dimension)
- **Equilibria** (fixed points) occur where  $f(u) = 0$
- The **flow** is represented by arrows showing direction of motion
- Trajectories are solution curves  $u(t)$  plotted against  $u$

- **STAGE Y (Why phase portraits are useful):** Phase portraits provide qualitative understanding without solving explicitly:

1. Identify all equilibria quickly
2. Determine stability (stable/unstable)
3. Predict long-time behavior from any initial condition
4. Visualize the global dynamics

- **STAGE Z (How to construct):**

1. Find equilibria: solve  $f(u) = 0$
2. Determine flow direction: check sign of  $f(u)$  in each region
  - $f(u) > 0$ : flow to the right ( $u$  increases)
  - $f(u) < 0$ : flow to the left ( $u$  decreases)
3. Classify equilibria:
  - $f'(u^*) < 0$ : stable (attractor)
  - $f'(u^*) > 0$ : unstable (repeller)

4. Draw arrows and trajectories

**KEY PRINCIPLE:** For 1D autonomous systems, solutions can never cross. Time flows monotonically along the phase line, and trajectories either approach equilibria or diverge to  $\pm\infty$ .

## 2 Part (a): $\frac{du}{dt} = \frac{2}{1+u^2} - 1$

**Step 1: Find Equilibria**

- **STAGE X (Setting up equilibrium equation):** Equilibria occur where  $\frac{du}{dt} = 0$ :

$$\frac{2}{1+u^2} - 1 = 0 \quad (1)$$

- **STAGE Y (Solving for equilibria):**

$$\frac{2}{1+u^2} = 1 \quad (2)$$

$$2 = 1 + u^2 \quad (3)$$

$$u^2 = 1 \quad (4)$$

$$u = \pm 1 \quad (5)$$

- **STAGE Z (Equilibrium points):**

$$u_1^* = -1, \quad u_2^* = +1 \quad (6)$$

There are exactly two equilibria.

**Step 2: Determine Flow Direction**

- **STAGE X (Define the function):** Let  $f(u) = \frac{2}{1+u^2} - 1$ .

We need to determine the sign of  $f(u)$  in each region:

- Region I:  $u < -1$
- Region II:  $-1 < u < 1$
- Region III:  $u > 1$

- **STAGE Y (Test points in each region):**

**Region I:**  $u < -1$  (test at  $u = -2$ ):

$$f(-2) = \frac{2}{1+4} - 1 = \frac{2}{5} - 1 = -\frac{3}{5} < 0 \quad (7)$$

Flow to the LEFT ( $\leftarrow$ )

**Region II:**  $-1 < u < 1$  (test at  $u = 0$ ):

$$f(0) = \frac{2}{1+0} - 1 = 2 - 1 = 1 > 0 \quad (8)$$

Flow to the RIGHT ( $\rightarrow$ )

**Region III:**  $u > 1$  (test at  $u = 2$ ):

$$f(2) = \frac{2}{1+4} - 1 = \frac{2}{5} - 1 = -\frac{3}{5} < 0 \quad (9)$$

Flow to the LEFT ( $\leftarrow$ )

- **STAGE Z (Flow pattern):**

$$u < -1 : f(u) < 0 \quad (\text{decreasing}) \quad (10)$$

$$-1 < u < 1 : f(u) > 0 \quad (\text{increasing}) \quad (11)$$

$$u > 1 : f(u) < 0 \quad (\text{decreasing}) \quad (12)$$

### Step 3: Classify Equilibria Stability

- **STAGE X (Method 1: Flow direction analysis):**

At  $u^* = -1$ :

- Just left ( $u < -1$ ): flow is  $\leftarrow$  (away)
- Just right ( $u > -1$ ): flow is  $\rightarrow$  (away)

Both sides flow **away** from  $u^* = -1 \Rightarrow \text{UNSTABLE}$

At  $u^* = +1$ :

- Just left ( $u < 1$ ): flow is  $\rightarrow$  (toward)
- Just right ( $u > 1$ ): flow is  $\leftarrow$  (toward)

Both sides flow **toward**  $u^* = +1 \Rightarrow \text{STABLE}$

- **STAGE Y (Method 2: Linear stability analysis):** Compute  $f'(u)$ :

$$f'(u) = \frac{d}{du} \left( \frac{2}{1+u^2} - 1 \right) = -\frac{4u}{(1+u^2)^2} \quad (13)$$

At  $u^* = -1$ :

$$f'(-1) = -\frac{4(-1)}{(1+1)^2} = \frac{4}{4} = 1 > 0 \quad \Rightarrow \quad \text{UNSTABLE} \quad (14)$$

At  $u^* = +1$ :

$$f'(1) = -\frac{4(1)}{(1+1)^2} = -\frac{4}{4} = -1 < 0 \quad \Rightarrow \quad \text{STABLE} \quad (15)$$

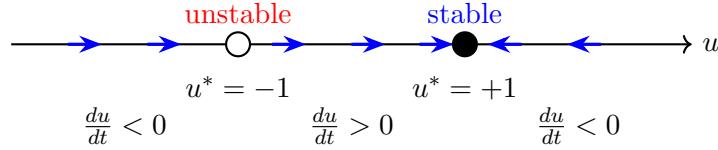
- **STAGE Z (Summary):**

$$u^* = -1 : \text{Unstable equilibrium (repeller)} \quad (16)$$

$$u^* = +1 : \text{Stable equilibrium (attractor)} \quad (17)$$

### Step 4: Sketch Phase Portrait

- **STAGE X (Phase line diagram):**



- **STAGE Y (Interpretation):**

- Open circle at  $u = -1$ : unstable equilibrium (repeller)
- Filled circle at  $u = +1$ : stable equilibrium (attractor)
- Arrows show flow direction
- All trajectories eventually approach  $u = +1$  (except starting exactly at  $u = -1$ )

- **STAGE Z (Global dynamics):** The system has a single basin of attraction at  $u^* = +1$ , attracting all trajectories except the unstable equilibrium at  $u^* = -1$ .

## Step 5: Analyze Specific Initial Conditions

- **STAGE X (Three initial conditions):**

**Case 1:**  $u(0) = -2$

- Starting position:  $u = -2$  (in region  $u < -1$ )
- Flow direction:  $\leftarrow$  (decreasing)
- Long-time behavior:  $u(t) \rightarrow -\infty$  as  $t \rightarrow \infty$

**Case 2:**  $u(0) = 0$

- Starting position:  $u = 0$  (in region  $-1 < u < 1$ )
- Flow direction:  $\rightarrow$  (increasing)
- Long-time behavior:  $u(t) \rightarrow +1$  as  $t \rightarrow \infty$

**Case 3:**  $u(0) = 2$

- Starting position:  $u = 2$  (in region  $u > 1$ )
- Flow direction:  $\leftarrow$  (decreasing)
- Long-time behavior:  $u(t) \rightarrow +1$  as  $t \rightarrow \infty$

- **STAGE Y (Detailed trajectory behavior):**

**Trajectory from  $u(0) = -2$ :**

$$u(t) : -2 \rightarrow -3 \rightarrow -4 \rightarrow \dots \rightarrow -\infty \quad (18)$$

This trajectory escapes to  $-\infty$ . Since  $f(u) \approx -1$  for large  $|u|$ , the escape rate is approximately linear:  $u(t) \approx u_0 - t$ .

**Trajectory from  $u(0) = 0$ :**

$$u(t) : 0 \rightarrow 0.5 \rightarrow 0.8 \rightarrow 0.95 \rightarrow \dots \rightarrow 1^- \quad (19)$$

This trajectory monotonically approaches  $u^* = +1$  from below. Near equilibrium,  $u(t) \approx 1 - Ce^{-t}$  (exponential approach).

**Trajectory from  $u(0) = 2$ :**

$$u(t) : 2 \rightarrow 1.5 \rightarrow 1.2 \rightarrow 1.05 \rightarrow \dots \rightarrow 1^+ \quad (20)$$

This trajectory monotonically approaches  $u^* = +1$  from above. Near equilibrium,  $u(t) \approx 1 + Ce^{-t}$ .

- **STAGE Z (Summary of long-time behavior):**

$$u(0) = -2 : u(t) \rightarrow -\infty \quad (\text{diverges}) \quad (21)$$

$$u(0) = 0 : u(t) \rightarrow +1 \quad (\text{converges to stable equilibrium}) \quad (22)$$

$$u(0) = 2 : u(t) \rightarrow +1 \quad (\text{converges to stable equilibrium}) \quad (23)$$

## Step 6: Separatrix and Basin of Attraction

- **STAGE X (Separatrix):** The **separatrix** is the boundary between different long-time behaviors. In this system:
  - The unstable equilibrium  $u^* = -1$  acts as a separatrix
  - Initial conditions  $u_0 > -1$  converge to  $u^* = +1$
  - Initial conditions  $u_0 < -1$  diverge to  $-\infty$
- **STAGE Y (Basin of attraction):** The **basin of attraction** for  $u^* = +1$  is:

$$\mathcal{B}(u^* = +1) = (-1, +\infty) \quad (24)$$

All initial conditions in this interval converge to the stable equilibrium.

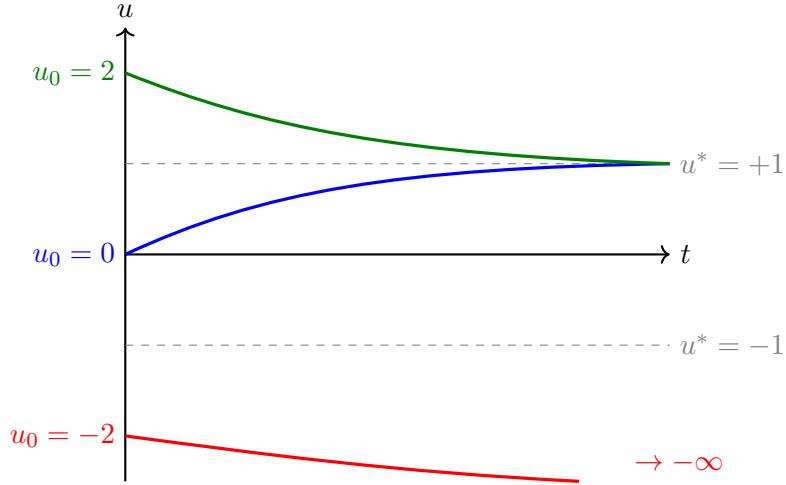
- **STAGE Z (Physical interpretation):** This system exhibits a threshold behavior:

- Above threshold ( $u > -1$ ): system stabilizes at  $u = +1$
- Below threshold ( $u < -1$ ): system escapes to  $-\infty$
- At threshold ( $u = -1$ ): unstable balance

**KEY INSIGHT:** The unstable equilibrium at  $u^* = -1$  is the critical threshold separating bounded behavior (convergence to  $u^* = +1$ ) from unbounded behavior (divergence to  $-\infty$ ).

## Step 7: Time Evolution (Qualitative)

- **STAGE X (Sketch of  $u(t)$  vs  $t$ ):**



- **STAGE Y (Rates of convergence/divergence):**

For  $u_0 = 0$  or  $u_0 = 2$  approaching  $u^* = +1$ :

- Near equilibrium:  $|u(t) - 1| \sim e^{-t}$  (exponential)
- Rate constant:  $|f'(+1)| = 1$
- Time scale:  $\tau = 1$  (reaches  $\approx 63\%$  of final value in time  $\tau$ )

For  $u_0 = -2$  diverging to  $-\infty$ :

- Far from equilibria:  $f(u) \approx -1$  (approximately constant)

- Divergence rate:  $u(t) \approx u_0 - t$  (approximately linear)
- **STAGE Z (Summary):**
    - Two trajectories converge exponentially to stable equilibrium
    - One trajectory diverges approximately linearly to  $-\infty$
    - The unstable equilibrium at  $u^* = -1$  separates these behaviors

### 3 Part (b): $\frac{du}{dt} = u^3 + 5u^2 - 6u$

#### Step 1: Find Equilibria

- **STAGE X (Setting up equilibrium equation):** Equilibria occur where  $\frac{du}{dt} = 0$ :

$$u^3 + 5u^2 - 6u = 0 \quad (25)$$

- **STAGE Y (Factoring):** Factor out  $u$ :

$$u(u^2 + 5u - 6) = 0 \quad (26)$$

This gives  $u = 0$  or  $u^2 + 5u - 6 = 0$ .

For the quadratic, use the quadratic formula or factor:

$$u^2 + 5u - 6 = (u + 6)(u - 1) = 0 \quad (27)$$

So  $u = -6$  or  $u = 1$ .

- **STAGE Z (Three equilibria):**

$$\boxed{u_1^* = -6, \quad u_2^* = 0, \quad u_3^* = +1} \quad (28)$$

There are exactly three equilibria, ordered:  $-6 < 0 < 1$ .

#### Step 2: Rewrite in Factored Form

- **STAGE X (Factored form):**

$$\frac{du}{dt} = u(u + 6)(u - 1) \quad (29)$$

- **STAGE Y (Why factored form is useful):** The sign of  $f(u) = u(u + 6)(u - 1)$  depends on the signs of each factor:

- $u$ : negative for  $u < 0$ , positive for  $u > 0$
- $(u + 6)$ : negative for  $u < -6$ , positive for  $u > -6$
- $(u - 1)$ : negative for  $u < 1$ , positive for  $u > 1$

- **STAGE Z (Sign analysis regions):** We have 4 regions separated by the three equilibria:

- Region I:  $u < -6$
- Region II:  $-6 < u < 0$
- Region III:  $0 < u < 1$
- Region IV:  $u > 1$

### Step 3: Determine Flow Direction

- **STAGE X (Sign table method):**

Region	$u$	$(u + 6)$	$(u - 1)$	$f(u) = u(u + 6)(u - 1)$
$u < -6$	-	-	-	$(-)(-)(-) = -$
$-6 < u < 0$	-	+	-	$(-)(+)(-) = +$
$0 < u < 1$	+	+	-	$(+)(+)(-) = -$
$u > 1$	+	+	+	$(+)(+)(+) = +$

- **STAGE Y (Flow directions):**

**Region I:**  $u < -6$  (e.g.,  $u = -7$ ):

$$f(-7) = (-7)(-1)(-8) = -56 < 0 \Rightarrow \text{flow LEFT } (\leftarrow) \quad (30)$$

**Region II:**  $-6 < u < 0$  (e.g.,  $u = -3$ ):

$$f(-3) = (-3)(3)(-4) = 36 > 0 \Rightarrow \text{flow RIGHT } (\rightarrow) \quad (31)$$

**Region III:**  $0 < u < 1$  (e.g.,  $u = 0.5$ ):

$$f(0.5) = (0.5)(6.5)(-0.5) = -1.625 < 0 \Rightarrow \text{flow LEFT } (\leftarrow) \quad (32)$$

**Region IV:**  $u > 1$  (e.g.,  $u = 2$ ):

$$f(2) = (2)(8)(1) = 16 > 0 \Rightarrow \text{flow RIGHT } (\rightarrow) \quad (33)$$

- **STAGE Z (Summary of flow):**

$$u < -6 : f(u) < 0 \quad (\text{decreasing}) \quad (34)$$

$$-6 < u < 0 : f(u) > 0 \quad (\text{increasing}) \quad (35)$$

$$0 < u < 1 : f(u) < 0 \quad (\text{decreasing}) \quad (36)$$

$$u > 1 : f(u) > 0 \quad (\text{increasing}) \quad (37)$$

### Step 4: Classify Equilibria Stability

- **STAGE X (Flow analysis at each equilibrium):**

At  $u^* = -6$ :

- Just left ( $u < -6$ ): flow is  $\leftarrow$  (away)
- Just right ( $u > -6$ ): flow is  $\rightarrow$  (away)

Both sides flow away  $\Rightarrow$  **UNSTABLE**

At  $u^* = 0$ :

- Just left ( $u < 0$ ): flow is  $\rightarrow$  (toward)
- Just right ( $u > 0$ ): flow is  $\leftarrow$  (toward)

Both sides flow toward  $\Rightarrow$  **STABLE**

At  $u^* = +1$ :

- Just left ( $u < 1$ ): flow is  $\leftarrow$  (away)

- Just right ( $u > 1$ ): flow is  $\rightarrow$  (away)

Both sides flow away  $\Rightarrow$  **UNSTABLE**

- **STAGE Y (Linear stability verification):** Compute  $f'(u)$ :

$$f(u) = u^3 + 5u^2 - 6u \quad (38)$$

$$f'(u) = 3u^2 + 10u - 6 \quad (39)$$

At  $u^* = -6$ :

$$f'(-6) = 3(36) + 10(-6) - 6 = 108 - 60 - 6 = 42 > 0 \Rightarrow \text{UNSTABLE} \quad (40)$$

At  $u^* = 0$ :

$$f'(0) = 3(0) + 10(0) - 6 = -6 < 0 \Rightarrow \text{STABLE} \quad (41)$$

At  $u^* = +1$ :

$$f'(+1) = 3(1) + 10(1) - 6 = 3 + 10 - 6 = 7 > 0 \Rightarrow \text{UNSTABLE} \quad (42)$$

- **STAGE Z (Classification summary):**

$$u^* = -6 : \text{Unstable equilibrium (repeller)} \quad (43)$$

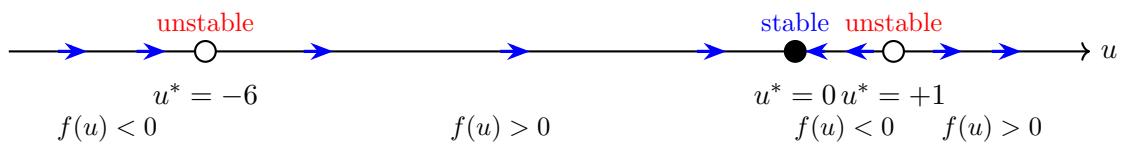
$$u^* = 0 : \text{Stable equilibrium (attractor)} \quad (44)$$

$$u^* = +1 : \text{Unstable equilibrium (repeller)} \quad (45)$$

The pattern is: unstable-stable-unstable.

### Step 5: Sketch Phase Portrait

- **STAGE X (Phase line diagram):**



- **STAGE Y (Interpretation):**

- Open circles at  $u = -6$  and  $u = +1$ : unstable equilibria
- Filled circle at  $u = 0$ : stable equilibrium (attractor)
- Arrows show flow direction in each region

- **STAGE Z (Global structure):** The system has:

- One stable equilibrium at  $u^* = 0$  with basin of attraction  $(-6, +1)$
- Two unstable equilibria acting as separatrices
- Trajectories outside  $[-6, +1]$  diverge to  $\pm\infty$

## Step 6: Analyze Specific Initial Conditions

- **STAGE X (Two initial conditions):**

**Case 1:**  $u(0) = -1$

- Starting position:  $u = -1$  (in region  $-6 < u < 0$ )
- Flow direction:  $\rightarrow$  (increasing)
- Path:  $-1 \rightarrow -0.5 \rightarrow -0.1 \rightarrow \dots \rightarrow 0^-$
- Long-time behavior:  $u(t) \rightarrow 0$  as  $t \rightarrow \infty$

**Case 2:**  $u(0) = 4$

- Starting position:  $u = 4$  (in region  $u > 1$ )
- Flow direction:  $\rightarrow$  (increasing)
- Path:  $4 \rightarrow 5 \rightarrow 10 \rightarrow 100 \rightarrow \dots \rightarrow +\infty$
- Long-time behavior:  $u(t) \rightarrow +\infty$  as  $t \rightarrow \infty$

- **STAGE Y (Detailed trajectory analysis):**

**From**  $u(0) = -1$ :

- Trajectory stays in region  $(-6, 0)$
- Monotonically increases toward stable equilibrium  $u^* = 0$
- Near equilibrium:  $u(t) \approx -Ce^{-6t}$  (exponential approach)
- Decay rate:  $|f'(0)| = 6$  (fast convergence)
- Time scale:  $\tau = 1/6 \approx 0.167$

**From**  $u(0) = 4$ :

- Trajectory starts beyond unstable equilibrium  $u^* = 1$
- Flows away from  $u^* = 1$  to the right
- Growth accelerates:  $f(u) = u(u+6)(u-1)$  grows cubically for large  $u$
- For large  $u$ :  $f(u) \approx u^3$
- Divergence is finite-time:  $\frac{du}{dt} \sim u^3$  leads to blow-up

- **STAGE Z (Finite-time blow-up for  $u_0 = 4$ ):**

For  $u > 1$ , approximate  $f(u) \approx u^3$  for large  $u$ :

$$\frac{du}{dt} \approx u^3 \quad \Rightarrow \quad \frac{du}{u^3} \approx dt \quad (46)$$

Integrating:

$$-\frac{1}{2u^2} \approx t + C \quad (47)$$

At  $t = 0$ :  $C = -\frac{1}{2u_0^2}$

$$-\frac{1}{2u^2} = t - \frac{1}{2u_0^2} \quad (48)$$

$$\frac{1}{u^2} = \frac{1}{u_0^2} - 2t \quad (49)$$

$$u(t) = \frac{1}{\sqrt{\frac{1}{u_0^2} - 2t}} \quad (50)$$

This blows up at time  $t^* = \frac{1}{2u_0^2}$ .

For  $u_0 = 4$ :

$$t^* = \frac{1}{2(16)} = \frac{1}{32} \approx 0.03125 \quad (51)$$

The solution reaches  $+\infty$  in finite time  $t^* \approx 0.031!$

### Step 7: Basin of Attraction and Separatrices

- **STAGE X (Basin of attraction for  $u^* = 0$ ):**

$$\mathcal{B}(u^* = 0) = (-6, +1) \quad (52)$$

All initial conditions in this open interval converge to  $u^* = 0$ .

- **STAGE Y (Separatrices):** The unstable equilibria act as separatrices:

–  $u^* = -6$  separates:

- \*  $u_0 < -6$ : divergence to  $-\infty$
- \*  $u_0 > -6$ : bounded behavior

–  $u^* = +1$  separates:

- \*  $u_0 < 1$ : convergence to  $u^* = 0$  (if  $u_0 > -6$ )
- \*  $u_0 > 1$ : divergence to  $+\infty$

- **STAGE Z (Complete classification by initial condition):**

$$u_0 < -6 : u(t) \rightarrow -\infty \quad (53)$$

$$u_0 = -6 : u(t) = -6 \text{ (stays at unstable equilibrium)} \quad (54)$$

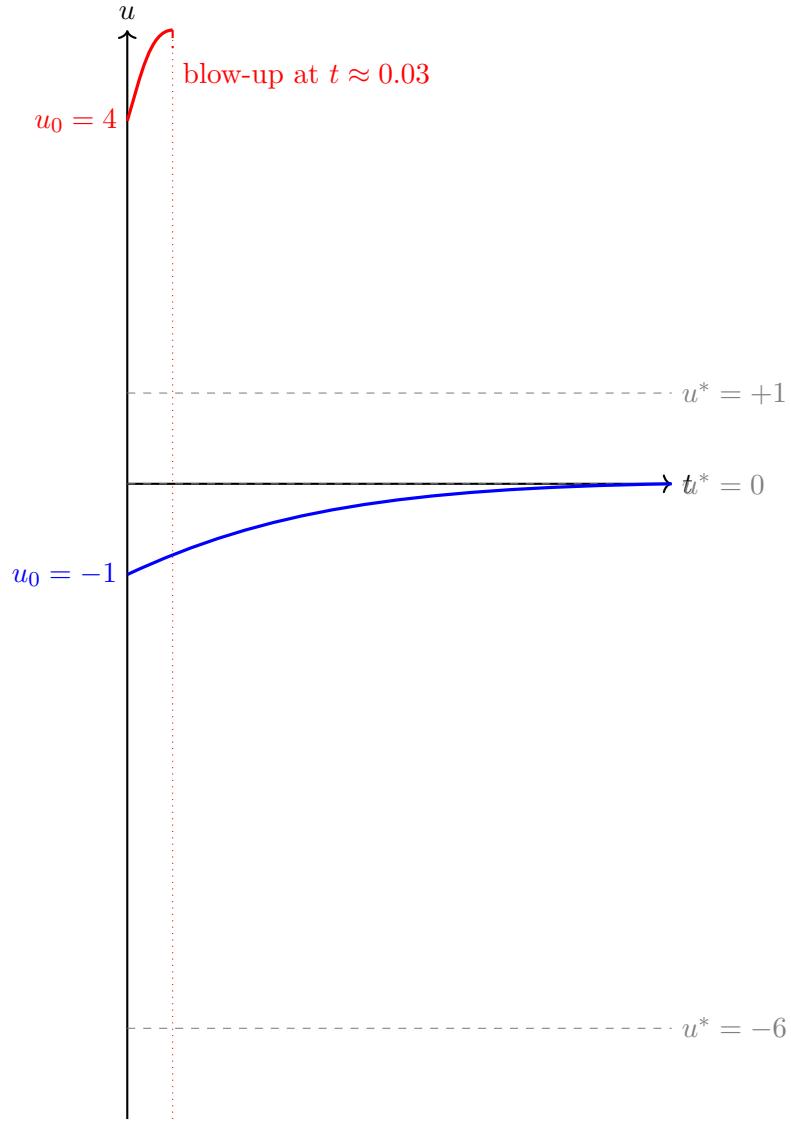
$$-6 < u_0 < 1 : u(t) \rightarrow 0 \quad (55)$$

$$u_0 = 1 : u(t) = 1 \text{ (stays at unstable equilibrium)} \quad (56)$$

$$u_0 > 1 : u(t) \rightarrow +\infty \text{ (finite-time blow-up)} \quad (57)$$

### Step 8: Time Evolution Sketch

- **STAGE X (Plot of  $u(t)$  vs  $t$ ):**



- **STAGE Y (Key features):**

- Blue curve ( $u_0 = -1$ ): smooth exponential convergence to  $u^* = 0$
- Red curve ( $u_0 = 4$ ): rapid divergence to  $+\infty$  in finite time
- Vertical asymptote at blow-up time for  $u_0 = 4$

- **STAGE Z (Summary):**

$$u(0) = -1 : \quad u(t) \rightarrow 0 \text{ exponentially, } \tau = 1/6 \quad (58)$$

$$u(0) = 4 : \quad u(t) \rightarrow +\infty \text{ at } t \approx 0.031 \quad (59)$$

**KEY INSIGHT:** This system exhibits rich dynamics with a stable attractor at  $u^* = 0$  flanked by two unstable equilibria. Initial conditions outside the basin  $(-6, +1)$  lead to finite-time blow-up, a phenomenon common in cubic nonlinearities.

## 4 Summary and Comparison

### Comparison of Parts (a) and (b)

Feature	Part (a)	Part (b)
Number of equilibria	2	3
Stable equilibria	1 (at $u = +1$ )	1 (at $u = 0$ )
Unstable equilibria	1 (at $u = -1$ )	2 (at $u = -6, +1$ )
Basin of attraction	$(-1, +\infty)$	$(-6, +1)$
Divergence to $-\infty$	Yes (if $u_0 < -1$ )	Yes (if $u_0 < -6$ )
Divergence to $+\infty$	No	Yes (if $u_0 > +1$ )
Finite-time blow-up	No	Yes (for $u_0 > 1$ )
Nonlinearity	Rational function	Cubic polynomial

### Key Lessons from 1D Phase Portraits

- **STAGE X (What we learned):**

1. **Equilibria classification:** Use flow direction or  $f'(u^*)$  to determine stability
2. **Separatrices:** Unstable equilibria separate regions with different long-time behavior
3. **Basins of attraction:** The set of initial conditions leading to each attractor
4. **Global structure:** Complete understanding of all possible trajectories

- **STAGE Y (Techniques mastered):**

1. Finding equilibria by solving  $f(u) = 0$
2. Determining flow direction using sign analysis
3. Classifying stability using flow or derivatives
4. Sketching phase portraits on the phase line
5. Predicting long-time behavior from phase portraits
6. Identifying finite-time blow-up

- **STAGE Z (Connection to higher dimensions):** In 1D:

- Phase space is a line
- Trajectories can't cross
- Only nodes (stable/unstable) exist
- Analysis is completely solvable

In 2D (next question):

- Phase space is a plane
- More complex equilibria: nodes, saddles, foci, centers
- Closed orbits (limit cycles) possible
- Richer dynamics, but still analyzable

**UNIVERSAL PRINCIPLE:** In 1D autonomous systems, trajectories are monotonic between equilibria. Solutions either approach equilibria or diverge to  $\pm\infty$ . No oscillations or closed orbits are possible in 1D.

**END OF QUESTION 4**