# **Testing Techniques**

# **Functional Testing**

# Brute force approach:

In order to exercise the use of brute force testing I will use it to test the following requirement:

## Drone can test whether a coordinate is 'close to' (within 0.00015 degrees) another coordinates

I will form the test suite by looking at the requirement and simply developing the test cases myself just form the requirement.

## **Test specification:**

Given two longlat coordinates, the closeTo() function returns true if they are within 0.00015 degrees and false otherwise.

#### Test case:

#### Inputs:

1. (0.0, 0.0), (0.0, 0.0) 2. (0.0, 0.0) (0.0, 0.00015) 3. (0.0, 0.0) (0.00015, 0.0) 4. (0.0, 0.0) (0.0, 0.00014) 5. (0.0, 0.0) (0.00014, 0.0) 6. (0.0, 0.0) (0.00007, 0.00007) 7. (0.0, 0.0) (12, 12) 8. (-3.186874, 55.944494), (-3.186767933982822, 55.94460006601717) 9. (-3.186874, 55.944494), (-3.1873,55.9430) 10. (-1, -1), (-1, -1.00014) 11. (0,0)

## **Expected Outputs:**

1. True 2. False 3. False 4. True 5. True 6. True 7. False 8. True 9. False 10. True 11. Error

#### Execution conditions:

The first longlat must be created as a longlat class and the second longlat should be supplied as the input to the closeTo function of that class.

# Pass/fail criterion:

Pass – output of the closeTo function is as specified in expected outputs

Fail – the output is anything else

#### Example test:

# Random approach:

In order to exercise the use of random testing I will use it to test the following requirement:

#### The system can calculate the delivery cost for a given list of items (unit)

I will form the input by randomly generating combinations of food items in order to test the function that calculates the cost of a given list.

#### Test case specification

Given a list of between 1 and 5 items, the getDeliveryCost function returns an integer value representing the delivery cost.

#### **Execute conditions**

The webserver must be running, and a menus class must be instantiated before the test is run.

#### Test case:

#### Randomly generated inputs:

```
    {"item": "Flaming tiger latte", "pence": 460 },
    {"item": "Dirty matcha latte", "pence": 460 },
    {"item": "Strawberry matcha latte", "pence": 460 },
    {"item": "Fresh taro latte", "pence": 460 },
    {"item": "Guava fruit tea", "pence": 380 },
    {"item": "Apple fruit tea", "pence": 380 },
    {"item": "Strawberry fruit tea", "pence": 380 },
    {"item": "Lemon fruit tea", "pence": 380 },
    {"item": "Coronation chicken sandwich (Large)", "pence": 400 },
    {"item": "Bacon, brie and cranberry sandwich (Regular)", "pence": 320 },
    {"item": "Bacon, brie and cranberry sandwich (Large)", "pence": 400 },
```

#### **Expected output**

1.	1890
2.	1570
3.	1170

## Pass fail criterion

For each random input the test passes if the output matches the expected output and fails otherwise.

#### **Example Test:**

# Systematic approach:

Requirement I'll test using this technique:

Given two coordinates the system can generate a series of moves moving the drone from one to another, avoiding no-fly zones and staying within the confinement area.

- 1. First step is to identify independently testable features (ITFs):
- System can test whether a coordinate is in the confinement area
  - Inputs coordinate, confinement area (static value)
- System can test whether a proposed route enters any no-fly zones
  - Inputs current and next, noFlyzones
- System can make a record of a move it has made
  - Inputs current, next, angle, orderNo
- System can tell when it is close to its destination coordinate
  - Inputs coord1, coord2
- System can generate series of moves from A to B avoiding no fly zones and staying within confinement area
  - All above mentioned
- 2. Partition categories and constraints
  - a. System can test whether a coordinate is in the confinement area
    - i. Coordinate empty, within confinement area, on edge of confinement area, outside confinement area
    - ii. Confinement area empty, nonempty
  - b. System can test whether a proposed route enters any no-fly zones

- i. StartCoord, EndCoord empty, path doesn't cross no-fly zones, path does cross no-fly zones
- ii. NoFlyZones empty, nonempty
- c. System can make a record of a move it has made
  - i. Current empty, nonempty
  - ii. Next empty, nonempty
  - iii. angle empty, nonempty
  - iv. OrderNo empty, nonempty
- d. System can tell when it is close to destination coordinate
  - i. Current empty, is close to, isn't close to
  - ii. Destination empty, is close to, is close to.
- 3. Write and process test specifications

a.

- i. Consider case where coordinate is empty
- ii. Consider case where coordinate is within confinement area
- iii. Consider case where coordinate is on edge of confinement area
- iv. Consider case where coordinate is outside of confinement area

b.

- i. Consider case where start and end coords are empty
- ii. Consider case where path crosses no-fly zones
- iii. Consider case where path doesn't cross any no-fly zones
- iv. Consider case where no-fly zones is empty

c.

- i. Consider cases where each of the inputs is empty
- ii. Consider cases where one (test for each) variable is empty
- iii. Consider case where all are nonempty

d.

- i. Consider case where both coords are empty
- ii. Consider case where neither coords are empty and:
  - 1. Coords are close to each other
  - 2. Coords aren't close to each other
- 4. Create test cases

a. .

i. Input

() - current, () - next () - No-fly zones

## **Expected output**

False

#### Pass fail criterion

The test should pass if False is returned and fail if true is returned

ii. Input

```
(-3.186874, 55.944494) - within (\( \)55.942617, 55.946233, -3.192473, -3.184319)
Expected output
True
Execution conditions
The input must be saved as the current coordinates in the longlat object before
                                                                                                   running
Pass fail criterion
The test should pass if the function returns True and fail otherwise
                    iii. Input
(155.942617,, -3.184319) - edge (155.942617, 55.946233, -3.192473, -3.184319)
Expected output
True
Execution conditions
The input must be saved as the current coordinates in the longlat object before
                                                                                                   running
Pass fail criterion
The test should pass if the function returns True and fail otherwise
                    iv. Input
(-3.1928,55.9469) - outside (155.942617, 55.946233, -3.192473, -3.184319)
Expected output
False
Execution conditions
The input must be saved as the current coordinates in the longlat object before
                                                                                                   running
Pass fail criterion
The test should pass if the function returns False and fail otherwise
            b.
                     i. Input
() - current, () - next, No-fly zones downloaded from webserver
Expected output
True
                        Pass fail criterion
```

The test should pass if True is returned and fail otherwise

ii. Input

(55.945626,-3.191065) - start, (-3.186874, 55.944494) - next, nofly zones downloaded from webserver

#### **Expected output**

False

## **Execution conditions**

The input must be saved as the current coordinates in the longlat object before

running

## Pass fail criterion

The test should pass if the function returns False and fail otherwise

iii. Input

(55.945868,-3.188656 )- start, (-3.186874, 55.944494) - next, nofly zones downloaded from web server

#### **Expected output**

True

## **Execution conditions**

The input must be saved as the current coordinates in the longlat object before

running

# Pass fail criterion

The test should pass if the function returns True and fail otherwise

Due to time and resource constraints, I am only including the test cases for the first two ITFs, however this shows that I understand the process and would continue to do the same for the others.

Example tests:

IsConfined:

```
± Eoin Reid
@Test
public void testIsConfinedTrueA() { assertTrue(appletonTower.isConfined()); }
```

#### IsPossible:

# **Combinatorial Testing**

# Catalogue based testing:

Requirement I'll test using this technique:

Drone can only fly in a direction that is a multiple of 10 from 0 to 350

#### Categories:

- 1. The element immediately preceding the lower bound of the interval
- 2. The lower bound of the interval
- 3. A non-boundary element within the interval
- 4. The upper bound of the interval
- 5. The element immediately following the upper bound

#### Test case specification:

The angle between a given longlat and the result of nextPosition(int x) (for a range of x) should be between 0 and 350 and divisible by 10 or an error if the input is incorrect.

# Test case:

#### Inputs based on categories:

```
-1 0 1 2 15 17 57 60 67 73 77 88 89 95 108 111 122 126 130 137 142 144 148 151 157 158 166 193 197 198 208 217 219 226 229 235 243 247 264 265 273 283 284 289 317 346 349 357 359 360 361
```

## **Execution conditions:**

A longlat must be instantiated in order to run the test, choose (0.0, 0.0) to be the longlat coordinates

#### Pass fail criterion:

Pass – angle between result of nextPosition() and the longlat we provided is 0<=angle<=350 and is divisible by 10. Or error is thrown if input is incorrect

Fail – angle is anything else, error isn't thrown on incorrect input.

# Example Test:

```
public void testAngle190(){
   LongLat nextPosition = appletonTower.nextPosition( angle: 190);
   LongLat calculatedPosition = new LongLat( longi: -3.1870217211629517, lat: 55.94446795277335);
   assertTrue(approxEq(nextPosition, calculatedPosition));
}
```