Notebook to support the algebraic derivations from the manuscript `Local analysis of Lower-Hybrid Drift Instabilities in a magnetic nozzle'

This notebook is used to provide numerical symbolic manipulation support for the derivations presented in Appendix A and B of the manuscript Local analysis of Lower-Hybrid Drift Instabilities in a magnetic nozzle. It is based on the SymPy library, which proves to be quite useful in handling the symbolic manipulations of expressions and differential operators.

As in the manuscript, we are interested in capturing the effect of the gyroviscous tensor on small time-dependent fluctuations of an equilibrium time-independent inhomogeneous two-fluid plasma. Under the assumption of small amplitude waves, each plasma quantity Q is expanded as a zeroth-order, time independent part, plus a first-order contribution, through which we will model any oscillatory phenomena,

$$Q(\mathbf{x},t) = Q_0(\mathbf{x}) + rac{1}{2}[Q_1\left(\mathbf{x}
ight)\exp(i\mathbf{k}\cdot\mathbf{x}-i\omega t) + CC],$$

with $\mathbf{x}=s_\perp\mathbf{1}_\perp+s_\theta\mathbf{1}_\theta+s_\parallel\mathbf{1}_\parallel$, being $s_{\perp,\theta,\parallel}$ local coordinates about the point of analysis, and with the subscripts 0 and 1 referring to equilibrium values and their first-order corrections, respectively. For our model to be local we consider $kL\gg 1$, with k the fluctuation wavenumber and L the smallest characteristic length of the equilibrium plasma gradients. We will model the plasma as a two-species fluid. The use of a set of fluid equations to describe electrons is valid as long as the wavenumber is smaller than the electron Larmor radius at equilibrium, $k\rho_e<1$.

Furthermore, we assume our waves to have frequency ω much smaller than than the equilibrium electron gyrofrequency ω_{ce} , respecting the ordering $\omega = O(\omega_{ce} \; \epsilon)$. We also assume to be in the low-drift regime, using a similar nomenclature to that adopted in [Ref.1 {ramo21}], with equilibrium electron velocity u_{e0} much smaller than the electron thermal velocity at rest c_e , a condition expressed through the choice of ordering $u_{e0} = O(c_e \; \epsilon)$.

The notebook is structured as follows: in the first section, the expression of the divergence of the first order gyroviscous tensor $\left(\frac{-\nabla \cdot \Pi_e}{m_e n_e}\right)_1$ is presented.

In the second section, the expression for the elctron continuity and momentum equations are presented with the explicit contribution from the gyroviscous tensor, along with the expression for the matrix of coefficients A_e . In the third section, the expression for the determinant of A_e is presented.

NOTE: each cell of the present notebook depend on data computed in the cells above, so we recommend either running each cell manually in the order with which they appear or selecting the `Run All' option.

Section I: Divergence of the Gyroviscous tensor

In this first section, the expressions for $\nabla \cdot \Pi_e$ at the $0^{\rm th}$ and $1^{\rm st}$ orders are presented. As in the main manuscript, we will work with power expansions of the small parameter $\epsilon = \rho_e/L$. We will consider only terms up to the $O(\epsilon \omega_{ce} \mathbf{u}_e)$ order.

We assume our plasma to be Maxwellian and the electron temperature to be isotropic, $T_{\perp e}=T_{\parallel e}$. Moreover, being ω first order in ϵ relative to the electron gyrofrequency ω_{ce} and the slowest flow velocities to be of the order of the ion sound speed c_s , we can model the gyroviscous tensor according to the fast-dynamics ordering presented in [Ref.2 {ramo05a}]. With this set of assumptions we recover the Braginskii form of the tensor [Ref.3 {brag65}], which mainly depends on the gradient of the electron velocity. Its divergence is (Eq. B.1 of the manuscript)

$$egin{aligned} -rac{
abla\cdot\Pi_e}{m_en_e} &= rac{1}{en_e}\Bigg\{\left[
abla imes\left(rac{T_en_e}{B}\mathbf{1}_{\parallel}
ight)
ight]\cdot
abla\mathbf{u}_e - rac{
abla}{2}\left(rac{T_en_e}{B}\mathbf{1}_{\parallel}\cdot\Omega_e
ight) \\ &+B\mathbf{1}_{\parallel}\cdot
abla\left[rac{T_en_e}{B^2}\left(3\mathbf{1}_{\parallel} imes\left[\mathbf{1}_{\parallel}\cdot
abla\mathbf{u}_e+\mathbf{1}_{\parallel} imes\mathbf{\Omega}_e
ight]+\mathbf{1}_{\parallel}\cdotrac{\Omega_e}{2}\mathbf{1}_{\parallel}
ight)
ight] \\ &-
abla imes\left[rac{T_en_e}{B}\left(\mathbf{1}_{\parallel}\cdot
abla\mathbf{u}_e+rac{\mathbf{1}_{\parallel}}{2}\left[
abla\cdot\mathbf{u}_e-3\mathbf{1}_{\parallel}\cdot
abla\mathbf{u}_e\cdot\mathbf{1}_{\parallel}
ight]
ight)
ight] \Bigg\} \end{aligned}$$

which correpsonds to Eq. (28) from [Ref.4 {ramo05b}]. Here we have defined as $\Omega_e \equiv
abla imes \mathbf{u}_e$ the vorticity of the electron flow velocity.

To compute the divergence of the gyroviscous tensor in in our local curvilinear coordiante system $\{\mathbf{1}_{\parallel},\mathbf{1}_{\perp},\mathbf{1}_{\theta}\}$, with $\mathbf{B}=B\mathbf{1}_{\parallel}$, $\mathbf{1}_{\theta}$ perpendicular to the (z,r) meridian plane, and $\mathbf{1}_{\perp}=\mathbf{1}_{\theta}\times\mathbf{1}_{\parallel}$, we first need to instruct the symbolic manipulator on how to handle the differential operator ∇ . The cell below defines and displays the formulas for $\nabla\phi$, $\nabla\psi$, $\nabla\cdot\psi$ and $\nabla\times\psi$, with ϕ and ψ generic scalar and vector, respectively.

```
In [12]: # Cell 0
# THIS FIRST CELL IS FOR THE IMPORTS AND DEFINITIONS
# It should be run before any other cell in the notebook.
```

```
# imports
from sympy import *
import IPython
from IPython.display import Latex, Image, display
from sympy.printing.latex import LatexPrinter
from sympy.core.function import UndefinedFunction
init printing(use latex='mathjax')
# Defining the symbols for positions
x pe, x th, x pa, small = symbols('s_\perp, s_\\theta, s_\parallel, \epsilor
latexReplaceRules = {
                   # r'{\left(t \right)}':r' ',
                   r'\frac{d}{d s {\perp}}':r' \nabla_\perp',
                   r'\frac{d^{2}}{d s_{perp}^{2}}':r' \nabla_{perp}^{2'},
                   r'\frac{d}{d s {\theta}}':r' \nabla \theta',
                   r'\frac{d^{2}}{d s_{\theta^{2}}}':r' \nabla_{\theta^{2}}':r' \nabla_{\theta^{2}},
                   r'\frac{d}{d s {\parallel}}':r' \nabla \parallel',
                   r'\frac{d^{2}}{d s {\pi(2)}}':r' \nabla {\pi(2)}{d s {\pi(2)}}':r' \nabla {\pi(2)}{d s {\pi(2)}}':r' \nabla {\pi(2)}{d s {\pi(2)}}{d s {\pi(
                   r'\frac{d^{2}}{d s {\epsilon}}':r' \all {\epsilon}^2',
                   r'\frac{d^{2}}{d s {\theta s {\phi s {\phi s}}':r' \land {\phi s}}}':r' \land {\phi s {\phi s}}':r' \land {\phi s {\phi 
                    r'\frac{d^{2}}{d s_{perp}d s_{parallel}}':r' \nabla_{perp\parallel}^2 
                   r'\frac{d^{3}}{d s {\scriptstyle perp}^{2}d s {\scriptstyle theta}}':r' \nabla {\scriptstyle perp\perp\theta}
                   r'\frac{d^{3}}{d s {perp}^{2}d s {parallel}}':r' \nabla {perp}erp}
                   r'\frac{d^{3}}{d s {\theta^{2}} s {\rho }':r' \beta {\theta } {\theta }
                    r'\frac{d^{3}}{d s_{\theta^{2}}d s_{\phi^{2}}} : r' \nabla_{\theta^{2}} 
                   r'\frac{d^{3}}{d s {parallel}^{2}d s {perp}}':r' \nabla {parallel}par
                   r'\frac{d^{3}}{d s {\pi}}{d s {\pi}}{in {3}}{d s {\pi}}{in {3}}{in {3}}{d s {\pi}}{in {3}}{in {3}}{d s {\pi}}{in {3}}{in {3}
                   r'\frac{d^{3}}{d s {perp} d s {theta}d s {parallel}}': r' \nabla {perp} d s {theta}d s {parallel}}': r' \nabla {perp} d s {theta}d s {theta}d
def latexNew(expr,**kwargs):
                   retStr = latex(expr,**kwargs)
                   for _,__ in latexReplaceRules.items():
                                      retStr = retStr.replace( , )
                   return retStr
init printing(latex printer=latexNew)
def display(expr):
                   return IPython.display.display(expr)
# Defining symbols for electron gyrofrequency, electron gyroradius, and elec
w ce, rho e, c e = symbols('\omega {ce}, \\rho e, c e')
# Magnetic field
B = Function('B')(x pe, x pa)
Dpe_lnB = symbols(' {[\\nabla_{\perp}\ln(B)]}')
Dpa lnB = symbols(' {[\\nabla {\parallel}\ln(B)]}')
shape B = \exp(Dpe \ln B * x pe + Dpa \ln B * x pa)
B sym = symbols('B')
# Defining q = n/B and its equilibrium shape
q = Function('({n 0}/{B})')(x pe, x th, x pa)
q0 = Function('q \{e0\}')(x pe, x pa)
q0_{sym} = symbols('q_{e0}')
Dpe lnp = symbols(' [\\nabla {\perp}\ln(p {e0})]')
Dpa lnp = symbols(' [\\nabla {\parallel}\ln(p {e0})]')
shape p = exp(Dpe lnp * x pe + Dpa lnp * x pa)
shape qe = shape p / shape B**2
# Perturbed electric potential
phil sym = symbols('e\\phi {e1}/m e')
Dpe lnphi1 = symbols(' [\\nabla {\perp}\ln(\phi {e1})]')
```

```
Dpa_lnphi1 = symbols(' [\\nabla_{\parallel}\ln(\phi_{e1})]')
shape phil = exp(Dpe lnphil * x pe + Dpa lnphil * x pa)
# Perturbed electron density h e1 = n e1/n 0
hel sym = symbols('h {e1}')
Dpe lnhe1 = symbols(' [\\nabla {\perp}\ln(h {e1})]')
Dpa lnhe1 = symbols(' [\\nabla {\parallel}\ln(h {e1})]')
shape hel = exp(Dpe lnhel * x pe + Dpa lnhel * x pa)
# Equilibrium density
n \theta = symbols('n \theta')
Dpe lnn 0 = \text{symbols}(' [\nabla {\perp}\ln(n 0)]')
Dpa lnn 0 = \text{symbols}(' [\nabla {\parallel}\ln(n 0)]')
shape n0 = \exp(Dpe \ln 0 * x pe + Dpa \ln 0 * x pa)
# General functions of the components of the perturbed fields
u pel = Function('u {e\perp1}')(x pe,x pa)
u th1 = Function('u {e\\theta1}')(x pe,x pa)
u pa1 = Function('u {e\parallel1}')(x pe,x pa)
q1 = Function('q {e1}')(x pe,x pa)
# Shapes of the perturbed fields
k pe, k th, k pa, w = symbols('k \neq perp, k \land k \neq k \neq a, k \neq a, k \neq b, k \neq a, k \neq b, 
shape = \exp(1j*(k pe * x pe/small + k th * x th/small + k pa * x pa))
# Perpendicular velocity
Dpe lnu pe = symbols(' [\\nabla {\perp}\ln(u {e\perp1})]')
Dpa lnu pe = symbols(' [\\nabla {\parallel}\ln(u {e\perp1})]')
shape pe = exp(Dpe lnu pe * x pe + Dpa lnu pe * x pa)
# Azimuthal velocity
Dpe lnu th = symbols(' [\\nabla_{\perp}\ln(u_{e\\theta1})]')
Dpa lnu th = symbols(' [\\nabla {\parallel}\ln(u {e\\theta1})]')
shape th = exp(Dpe lnu th * x pe + Dpa lnu th * x pa)
# Parallel velocity
Dpe_lnu_pa = symbols(' [\\nabla_{\perp}\ln(u_{e\parallel1})]')
Dpa lnu pa = symbols(' [\\nabla {\parallel}\ln(u {e\parallel1})]')
shape_pa = exp(Dpe_lnu_pa * x_pe + Dpa_lnu_pa * x_pa)
# Functions of the components of the total and equilibrium fields
u pe = Function('u {e\perp}')(x pe,x th,x pa)
u th = Function('u {e\\theta}')(x pe,x th,x pa)
u_pa = Function('u_{e\parallel}')(x_pe,x_th,x_pa)
u pe0 = Function('u \{e perp0\}')(x pe, x pa)
u 	ext{ th0} = Function('u {e}\theta0}')(x pe,x pa)
u pa0 = Function('u {e\parallel0}')(x pe,x pa)
# Symbols of the components of the total, perturbed and equilibrium fields
u pe sym = symbols('u {e\perp}')
u th sym = symbols('u {e\\theta}')
u pa sym = symbols('u_{e\parallel}')
r sym = symbols('\\frac{1}{r}')
q sym = symbols('\left(\\frac{n e}{B}\\right)')
u pel sym = symbols('u {e\perp1}')
u th1 sym = symbols('u {e\\theta1}')
u pal sym = symbols('u {e\parallel1}')
q1 \text{ sym} = \text{symbols}('q \{e1\}')
u pe0 sym = symbols('u {e\perp0}')
u th0 sym = symbols('u \{e \setminus theta0\}')
u pa0 sym = symbols('u {e\parallel0}')
# Define the fields and the perturbed fields
u = [u pe, u th, u pa]
uel = [u pel sym * shape pe * shape, u thl sym * shape th * shape, u pal sym
ue0 = [small*u pe0, small*u th0, small*u pa0]
```

```
qe1 = q1 * shape
q0 = n \ 0 * w ce * rho e**2 * shape qe
B = B \text{ sym * shape } B
n0 = n 0 * shape n0
phi1 = phi1_sym * shape_phi1 * shape
hel = hel sym * shape hel * shape
# Define the gradient of a scalar q in 3D space
def grad scal(q):
    return [small*diff(q, x pe), small * diff(q, x th), small*diff(q, x pa)]
# Define the scalar product of a scalar q and a vector u in 3D space
def scal vect(q,u):
   W = [0, 0, 0]
    for i in [0,1,2]:
        w[i] = q * u[i]
    return w
# Define the sum of two vectors u and v in 3D space
def sum vect(u,v):
   W = [0,0,0]
    for i in [0,1,2]:
        w[i] = u[i] + v[i]
    return w
# Define the gradient of a vector field u in 3D space
def grad vect(u):
    all = small*(diff(u[0], x pe) - u[2] * diff(B, x pa)/B sym)
    a12 = small*(diff(u[1], x pe))
    a13 = small*(diff(u[2], x_pe) + u[0] * diff(B, x_pa)/B_sym)
   a21 = small*(diff(u[0], x th))
    a22 = small*(diff(u[1], x th))
    a23 = small*(diff(u[2], x th))
   a31 = small*(diff(u[0], x_pa) + u[2] * diff(B, x_pe)/B_sym)
   a32 = small*(diff(u[1], x pa))
    a33 = small*(diff(u[2], x_pa) - u[0] * diff(B, x_pe)/B_sym)
   A = [[a11, a12, a13],
         [a21, a22, a23],
         [a31, a32, a33]]
    return A
# Define the gradient of a vector field u in 3D space
def grad vect small 1(u):
    all = (diff(u[0], x_pe) - u[2] * diff(B, x_pa)/B_sym)
    a12 = (diff(u[1], x pe))
    a13 = (diff(u[2], x pe) + u[0] * diff(B, x pa)/B sym)
    a21 = (diff(u[0], x_th))
    a22 = (diff(u[1], x th))
    a23 = (diff(u[2], x th))
    a31 = (diff(u[0], x pa) + u[2] * diff(B, x pe)/B sym)
    a32 = (diff(u[1], x pa))
    a33 = (diff(u[2], x pa) - u[0] * diff(B, x pe)/B sym)
    A = [[a11, a12, a13],
         [a21, a22, a23],
         [a31, a32, a33]]
    return A
# Define the divergence of a vector field u in 3D space
def div vect(u):
    A = grad vect(u)
    d = A[0][0] + A[1][1] + A[2][2]
    return d
```

```
# Define the vector product (cross product) of two vectors u and v in 3D spa
def prod vect(u,v):
   W = [0, 0, 0]
   index vect = [0,1,2,0,1,2]
   for i in [0,1,2]:
        w[i] = u[index vect[i+1]] * v[index vect[i+2]] - u[index vect[i+2]]
# Define the rotor of a vector field u in 3D space
def rot vect(u):
   W = [0, 0, 0]
   index vect = [0,1,2,0,1,2]
   A = grad vect(u)
    for i in [0,1,2]:
        w[i] = A[index vect[i+1]][index vect[i+2]] - A[index vect[i+2]][index
    return w
# Define the scalar product of two vectors u and v in 3D space
def scal prod vect(u,v):
   w=0
    for i in [0,1,2]:
        w += u[i] * v[i]
    return w
# Define the vector-matrix product of a vector u and a tensor A in 3D space
def vect matr(u,A):
   W = [0,0,0]
    for i in [0,1,2]:
        for j in [0,1,2]:
            w[i] += u[j] * A[j][i]
    return w
# Define the matrix-vector product of a tensor A and a vector u in 3D space
def matr vect(A,u):
   w = [0.0.01]
    for i in [0,1,2]:
        for j in [0,1,2]:
            w[i] += A[i][j] * u[j]
    return w
# Define the determinant of a 2x2 matrix A
def det2(A):
    det = A[0][0] * A[1][1] - A[0][1] * A[1][0]
    return det
# Define the determinant of a 3x3 matrix A
def det3(A):
    A00 = [[A[1][1], A[1][2]],
            [A[2][1], A[2][2]]
    A01 = [[A[1][0], A[1][2]],
            [A[2][0], A[2][2]]]
    A02 = [[A[1][0], A[1][1]],
            [A[2][0], A[2][1]]]
    det = A[0][0] * det2(A00) - A[0][1] * det2(A01) + A[0][2] * det2(A02)
    return det
# Define the determinant of a 4x4 matrix A
def det4(A):
    A00 = [[A[1][1], A[1][2], A[1][3]],
            [A[2][1], A[2][2], A[2][3]],
            [A[3][1], A[3][2], A[3][3]]]
    A01 = [[A[1][0], A[1][2], A[1][3]],
            [A[2][0], A[2][2], A[2][3]],
```

```
[A[3][0], A[3][2], A[3][3]]]
   A02 = [[A[1][0], A[1][1], A[1][3]],
           [A[2][0], A[2][1], A[2][3]],
           [A[3][0], A[3][1], A[3][3]]]
   A03 = [[A[1][0], A[1][1], A[1][2]],
           [A[2][0], A[2][1], A[2][2]],
           [A[3][0], A[3][1], A[3][2]]]
   det = A[0][0] * det3(A00) - A[0][1] * det3(A01) + A[0][2] * det3(A02) -
   return det
# Substitutions for the functions and symbols (for better printing)
phi = Function('\\phi')(x pe, x th, x pa)
psi pe = Function('\\psi {\\perp}')(x pe, x th, x pa)
psi_th = Function('\\psi_{\\theta}')(x_pe, x_th, x_pa)
psi_pa = Function('\\psi_{\\parallel}')(x_pe, x_th, x_pa)
psi = [psi pe, psi th, psi pa]
phi sym = symbols('\\phi')
psi pe sym = symbols('\\psi {\\perp}')
psi th sym = symbols('\\psi {\\theta}')
psi pa sym = symbols('\\psi {\\parallel}')
psi_sym = [psi_pe_sym, psi_th_sym, psi_pa_sym]
def complete subs(exp):
   fun list = [q, u pe, u th, u pa, B, ql, u pel, u thl, u pal, q0, u pe0,
               shape pe, shape th, shape pa, shape B, shape qe, shape phil,
                   psi pe, psi th, psi pa]
   sym list = [q sym, u pe sym, u th sym, u pa sym, B sym,\
       q1 sym, u pe1 sym, u th1 sym, u pa1 sym, q0 sym, u pe0 sym, u th0 sy
           1, 1, 1, 1, 1, 1, 1, phi sym, psi pe sym, psi th sym, psi pa
   exp = Array(exp)
   for i in range(len(fun list)):
       exp = exp.subs(fun list[i], sym list[i])
   return exp
# Function to print the expression
def display subs(exp):
   exp new = complete subs(exp)
   return display(exp new)
# Function to print the expression in LaTeX format
def display latex(exp):
   exp new = complete subs(exp)
   return print latex(exp new)
display(Latex(r'$\nabla \phi$='))
nabla phi = grad scal(phi)
for i in range(3):
   nabla phi[i] = nabla phi[i].subs(phi, phi sym).subs(small, 1)
nabla phi = Matrix(nabla phi)
display_subs(nabla_phi)
print('----')
nabla psi = grad vect small 1(psi)
nabla psi = Matrix(nabla psi)
display(Latex(r'$\nabla \psi$='))
display subs(nsimplify(nabla psi))
print('-----')
div psi = div vect(psi)
for i in range(3):
   div psi = div psi.subs(small, 1)
display(Latex(r'$\nabla \cdot \psi$='))
display subs(div psi)
```

```
\begin{array}{lll} & \text{print('------')} \\ & \text{rot\_psi} = \text{rot\_vect(psi)} \\ & \text{for i in range(3):} \\ & & \text{rot\_psi[i]} = \text{rot\_psi[i].subs(small, 1)} \\ & \text{rot\_psi} = \text{Matrix(rot\_psi)} \\ & \text{display(Latex(r'\$\nabla \land times \land psi\$='))} \\ & \text{display\_subs(rot\_psi)} \\ & \nabla \phi = \\ & \begin{bmatrix} \nabla_{\perp} \phi \\ \nabla_{\theta} \phi \\ \nabla_{\parallel} \phi \end{bmatrix} \\ & \\ & \nabla \psi = \\ & \begin{bmatrix} -\psi_{\parallel} [\nabla_{\parallel} \ln(B)] + \nabla_{\perp} \psi_{\perp} & \nabla_{\perp} \psi_{\theta} & \psi_{\perp} [\nabla_{\parallel} \ln(B)] + \nabla_{\perp} \psi_{\parallel} \\ & \nabla_{\theta} \psi_{\perp} & \nabla_{\theta} \psi_{\theta} & \nabla_{\theta} \psi_{\parallel} \end{bmatrix} \end{array}
```

$$\begin{bmatrix} -\psi_{\parallel}[\nabla_{\parallel}\ln(B)] + \nabla_{\perp}\psi_{\perp} & \nabla_{\perp}\psi_{\theta} & \psi_{\perp}[\nabla_{\parallel}\ln(B)] + \nabla_{\perp}\psi_{\parallel} \\ \nabla_{\theta}\psi_{\perp} & \nabla_{\theta}\psi_{\theta} & \nabla_{\theta}\psi_{\parallel} \\ \psi_{\parallel}[\nabla_{\perp}\ln(B)] + \nabla_{\parallel}\psi_{\perp} & \nabla_{\parallel}\psi_{\theta} & -\psi_{\perp}[\nabla_{\perp}\ln(B)] + \nabla_{\parallel}\psi_{\parallel} \end{bmatrix}$$

$$\nabla \cdot \psi =$$

 $-\psi_{\parallel}[
abla_{\parallel}\ln(B)] - \psi_{\perp}[
abla_{\perp}\ln(B)] +
abla_{\parallel}\psi_{\parallel} +
abla_{\perp}\psi_{\perp} +
abla_{ heta}\psi_{ heta}$

$$\nabla \times \psi$$
=

$$egin{bmatrix}
abla_{ heta}\psi_{\parallel} -
abla_{\parallel}\psi_{ heta} \ \psi_{\parallel}[
abla_{\perp}\ln(B)] - \psi_{\perp}[
abla_{\parallel}\ln(B)] -
abla_{\perp}\psi_{\parallel} +
abla_{\parallel}\psi_{\perp} \ -
abla_{ heta}\psi_{\perp} +
abla_{\perp}\psi_{ heta} \end{bmatrix}$$

The cell below computes and displays the three components of $\frac{-\nabla \cdot \Pi_e}{m_e n_e}$ in our curvilinear coordiante system of choice, with $\mathbf{B} = B \mathbf{1}_{\parallel}$, 1_{θ} perpendicular to the (z,r) meridian plane, and $\mathbf{1}_{\perp} = \mathbf{1}_{\theta} \times \mathbf{1}_{\parallel}$.

```
In [169... # Cell 1
        # BELOW WE COMPUTE THE DIVERGENCE OF THE GYROVISCOUS TENSOR
        # First term of Eq. 1 of the notebook
        def Pi mag(q,u):
           v = [0,0,q]
           rotor = rot vect(v)
           Du = grad vect(u)
           w = vect matr(rotor, Du)
           return w
        # Potential of the econd term of Eq. 1 of the notebook
        def csi(q,u):
           rotor = rot vect(u)
           csi = q * rotor[2]
           return csi*Rational(1, 2)
        # Second term of Eq. 1 of the notebook
```

```
def Pi csi(q,u):
   w = grad scal( - csi(q,u))
    return w
# Vector a of Eq. 2 of the notebook
def ae(q,u):
    one parallel = [0,0,1]
    Du = grad vect(u)
    rotor = rot_vect(u)
   v1 1 = prod vect(one parallel, Du[2])
    v1_2_0 = prod_vect(one_parallel, rotor)
   v1 2 = prod vect(one parallel, v1 2 0)
   v1 = scal vect(q,sum vect(scal vect(3,v1 1) , v1 2))
   v2 = scal \ vect(csi(q,u), \ one \ parallel)
    v = (sum \ vect(v1, v2))
    return v
# Third term of Eq. 1 of the notebook
def Pi ae(q,u):
   a = ae(q,u)
   Da = grad vect(a)
    Da parallel = Da[2]
    negative a dlnB = scal vect( - small*diff(B,x pa)/B sym, a)
   w = sum vect(Da parallel, negative a dlnB)
    return w
# Vector b of Eq. 3 of the notebook
def be(q,u):
    one parallel = [0,0,1]
    Du = grad vect(u)
   Du parallel = Du[2]
    scalar = div vect(u) - 3 * Du[2][2]
   w = sum_vect(Du_parallel, scal_vect(scalar*Rational(1, 2), one_parallel)
    return scal vect(q,w)
# Fourth term of Eq. 1 of the notebook
def Pi be(q,u):
    b = be(q,u)
    rotor = rot vect(b)
    return scal_vect(-1, rotor)
# THIS CELL DISPLAYS THE THREE COMPONENT OF THE UNEXPANDED GYROVISCOUS TENSO
exp list = [Pi mag(q,u), Pi csi(q,u), Pi ae(q,u), Pi be(q,u)]
tit list = ['Pi']
exp Pi = [0.0, 0.0, 0.0]
Ge = [[0.0, 0.0, 0.0],
      [0.0,0.0,0.0]
      [0.0,0.0,0.0]
for i in range(4):
    for j in range(3):
        # print(exp list[i][j].dtype)
        # print(exp_Pi[j].dtype)
        exp Pi[j] += exp list[i][j]
coord_list = ['\perp', '\\theta', '\parallel']
for i in range(3):
```

print('-----')
display(Latex(f'\$\displaystyle\left(-\\frac{{\\nabla\cdot\Pi_e}}{{m_e n_display subs(exp Pi[i].subs(small,1))}

$$\begin{split} &\left(-\frac{\nabla \cdot \Pi_{e}}{m_{e}n_{e}}\right)_{\perp 1} = \\ &-\left(\frac{n_{e}}{B}\right) \left[\nabla_{\parallel} \ln(B)\right] \left(-\nabla_{\theta} u_{e\parallel} - 2\nabla_{\parallel} u_{e\theta}\right) + \frac{\left(\frac{n_{e}}{B}\right) \left[\nabla_{\perp} \ln(B)\right] \left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right)}{2} + \left(\frac{n_{e}}{B}\right) \left(-2\nabla_{\parallel\parallel}^{2} u_{e\theta}\right) \\ &-\left(\frac{n_{e}}{B}\right) \left(-\frac{\left[\nabla_{\parallel} \ln(B)\right] \nabla_{\theta} u_{e\parallel}}{2} + \frac{\nabla_{\theta\theta}^{2} u_{e\theta}}{2} + \frac{\nabla_{\perp\theta}^{2} u_{e\perp}}{2}\right) + \left(\frac{n_{e}}{B}\right) \nabla_{\parallel\parallel}^{2} u_{e\theta} + \left(\left(\frac{n_{e}}{B}\right) \left[\nabla_{\perp} \ln(B)\right] - \nabla_{\parallel}^{2} u_{e\theta}\right) \\ &-\frac{\left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right) \nabla_{\perp} \left(\frac{n_{e}}{B}\right)}{2} - \left(-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{\nabla_{\perp} u_{e\perp}}{2} + \frac{\nabla_{\theta} u_{e\theta}}{2}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) + \nabla_{\parallel} \left(\frac{n_{e}}{B}\right) \\ &-\frac{\left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right) \nabla_{\perp} \left(\frac{n_{e}}{B}\right)}{2} - \left(-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{\nabla_{\perp} u_{e\perp}}{2} + \frac{\nabla_{\theta} u_{e\theta}}{2}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) + \nabla_{\parallel} \left(\frac{n_{e}}{B}\right) \\ &-\frac{\left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right) \nabla_{\perp} \left(\frac{n_{e}}{B}\right)}{2} - \left(-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{\nabla_{\perp} u_{e\perp}}{2} + \frac{\nabla_{\theta} u_{e\theta}}{2}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) + \nabla_{\parallel} \left(\frac{n_{e}}{B}\right) \\ &-\frac{\left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right) \nabla_{\perp} \left(\frac{n_{e}}{B}\right)}{2} - \left(-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{\nabla_{\perp} u_{e\perp}}{2} + \frac{\nabla_{\theta} u_{e\theta}}{2}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) + \nabla_{\parallel} \left(\frac{n_{e}}{B}\right) \\ &-\frac{\left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right) \nabla_{\perp} \left(\frac{n_{e}}{B}\right)}{2} - \left(-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{\nabla_{\perp} u_{e\perp}}{2} + \frac{\nabla_{\theta} u_{e\theta}}{2}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) \\ &-\frac{\left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right) \nabla_{\perp} \left(\frac{n_{e}}{B}\right)}{2} - \left(-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{\nabla_{\perp} u_{e\perp}}{2} + \frac{\nabla_{\parallel} u_{e\parallel}}{2}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) \\ &-\frac{\left(-\nabla_{\theta} u_{e\perp} + \nabla_{\perp} u_{e\theta}\right) \nabla_{\perp} \left(\frac{n_{e}}{B}\right)}{2} - \left(-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{\nabla_{\parallel} u_{e\parallel}}{2} + \frac{\nabla_{\parallel} u_{e\parallel}}{2}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) \nabla_{\theta} \left(\frac{n_{e}}{B}\right) \\ &-\frac{u_{e\parallel} \left[\nabla_{\parallel} \ln(B)\right]}{2} + \frac{u_{e\parallel} u_{e\parallel}}{2} + \frac{u_{e\parallel}$$

$$\left(-rac{
abla\cdot\Pi_e}{m_en_e}
ight)_{ heta 1} =$$

$$\left(\frac{n_e}{B}\right)\left[\nabla_{\parallel}\ln(B)\right]\left(u_{e\parallel}\left[\nabla_{\perp}\ln(B)\right]+\nabla_{\parallel}u_{e\perp}\right)-\left(\frac{n_e}{B}\right)\left[\nabla_{\parallel}\ln(B)\right]\left(2u_{e\parallel}\left[\nabla_{\perp}\ln(B)\right]+u_{e\perp}\left[\nabla_{\parallel}\ln(B)\right]+u_{e\perp}\left[\nabla_{\parallel}\ln(B)\right]\right)$$

$$-rac{\left(rac{n_e}{B}
ight)\left(-
abla_{ heta heta}^2 u_{eot} +
abla_{ot heta}^2 u_{e heta}
ight)}{2} - \left(rac{n_e}{B}
ight)\left(u_{e\|}[
abla_{\|} \ln(B)][
abla_{ot} \ln(B)] + [
abla_{ot} \ln(B)]
abla_{\|} u_{e\|} +
abla_{\|\|}^2 u_{eot}
ight) + \left[rac{n_e}{B} \lim_{n heta} u_{eot} +
abla_{\|\|}^2 u_{eot}
ight]$$

$$+\left(rac{n_e}{B}
ight)\left(2u_{e\parallel}[
abla_{\parallel}\ln(B)][
abla_{\perp}\ln(B)]+u_{e\perp}[
abla_{\parallel}\ln(B)]^2+[
abla_{\parallel}\ln(B)]
abla_{\parallel}u_{e\perp}+2[
abla_{\perp}\ln(B)]
abla_{\parallel}u_{e\parallel}+2[
abla_{\parallel}\ln(B)]
abla_{\parallel}u_{e\parallel}+2[
abla_{\parallel}u_{e\parallel}+$$

$$-\left(u_{e\parallel}[\nabla_{\perp}\ln(B)]+\nabla_{\parallel}u_{e\perp}\right)\nabla_{\parallel}\left(\frac{n_{e}}{B}\right)-\frac{\left(-\nabla_{\theta}u_{e\perp}+\nabla_{\perp}u_{e\theta}\right)\nabla_{\theta}\left(\frac{n_{e}}{B}\right)}{2}+\left(-\frac{u_{e\parallel}[\nabla_{\parallel}\ln(B)]}{2}+\frac{\nabla_{\perp}u_{e\theta}}{2}\right)$$

$$+ \left(2 u_{e\parallel} [\nabla_{\perp} \ln(B)] + u_{e\perp} [\nabla_{\parallel} \ln(B)] + \nabla_{\perp} u_{e\parallel} + 2 \nabla_{\parallel} u_{e\perp} \right) \nabla_{\parallel} \left(\frac{n_e}{B}\right) + \nabla_{\theta} \left(\frac{n_e}{B}\right) \nabla_{\perp} u_{e\theta}$$

$$\left(-\frac{\nabla\cdot\Pi_e}{m_en_e}\right)_{\parallel 1} =$$

$$-rac{\left(rac{n_e}{B}
ight)\left[
abla_{\parallel}\ln(B)
ight]\left(-
abla_{ heta}u_{e\perp}+
abla_{\perp}u_{e heta}
ight)}{2}-\left(rac{n_e}{B}
ight)\left[
abla_{\perp}\ln(B)
ight]\left(-
abla_{ heta}u_{e\parallel}-2
abla_{\parallel}u_{e heta}
ight)+\left(rac{n_e}{B}
ight)\left(\left[
abla_{\perp}\ln(B)
ight]+\left(u_{e\parallel}\left[
abla_{\perp}\ln(B)
ight]+
abla_{\parallel}u_{e heta}
ight)+\left(u_{e\perp}\left[
abla_{\parallel}\ln(B)
ight]+
abla_{\perp}u_{e\parallel}
ight)
abla_{ heta}\left(rac{n_e}{B}
ight)-
abla_{\perp}\left(rac{n_e}{B}
ight)
abla_{\parallel}u_{e heta}$$

From its expression, it is apparent that at the zeroth order $% \left(x\right) =\left(x\right) +\left(x\right)$

$$\left(rac{
abla\cdot\Pi_e}{m_en_e}
ight)_0=O(\omega_{ce}u_{ heta e0}\;\epsilon^2)$$
, being $ho_e|
abla Q|\sim |Q|\epsilon$.

From the expression of $(Q)_1$, we have that its gradient is $(\nabla Q)_1 = \frac{1}{2}[(i\mathbf{k}Q_1 + \nabla Q_1)\exp(i\mathbf{k}\cdot\mathbf{x} - i\omega t) + CC]$, with with $|\nabla \ln Q_1|/k = O(\epsilon)$ by assumption.

Then the gyroviscous tensor contributes with terms of order $O\left(\omega_{ce}\mathbf{u}_{e1}\ k^2\rho_e^2\right)$ and $O\left(\omega_{ce}\mathbf{u}_{e1}\ \epsilon\right)$ in the momentum equation, the latter being of the same order of the inertial terms $\frac{\partial\mathbf{u}_{e1}}{\partial t}=-i\omega\mathbf{u}_{e1}$. Then its contribution up to our order of interest is not negligible.

We define the tensor of coefficient \overline{G}_e as

$$\left(-rac{
abla\cdot\Pi_e}{m_en_e}
ight)_1=i\overline{\overline{G}}_e\mathbf{u}_{e1}\;,$$

as a compact way to express the divergence of the gyroviscous tensor as a linear function of \mathbf{u}_{e1} . This representation is useful when computing the momentum equations.

The cell below computes and display the three components of $\left(-\frac{\nabla \cdot \Pi_e}{m_e n_e}\right)_1$ up to $O\left(\omega_{ce}\mathbf{u}_{e1}\;\epsilon\right)$. It also computes and displays the components of G_e .

```
In [170... # Cell 2
         # THIS CELL COMPUTES THE DIVERGENCE OF THE FIRST ORDER GYROV. TENS.
         exp list = [Pi mag(q0,ue1), Pi csi(q0,ue1), Pi ae(q0,ue1), Pi be(q0,ue1)]
         tit list = ['Pi']
         eq list = ['(Eq. B.2)', '(Eq. B.3)', '(Eq. B.4)']
         exp Pi = [0.0, 0.0, 0.0]
         Ge = [[0.0, 0.0, 0.0],
              [0.0, 0.0, 0.0]
              [0.0, 0.0, 0.0]
         for i in range(4):
            for j in range(3):
                exp Pi[j] += exp list[i][j]
         for j in [0,1,2]:
            x_j = [x_pe, x_th, x_pa][j]
            print('-----')
            display(Latex(f'$\displaystyle\left(-\\frac{{\\nabla\cdot\Pi e}}{{m e n}
            polynom = Poly(exp Pi[j]/shape, small)
            expr = polynom.coeffs()
            order = len(expr)-1
            if order < 2:</pre>
                expr = small*expr[order]
            else:
                expr = small*expr[1] + expr[2]
            expr = expr.subs(x pe,0).subs(x pa,0).subs(n 0,1)
            display_subs(nsimplify(expr).subs(small,1))
            display(Latex(f'{eq_list[j]}'))
            print('----')
            # display(Latex(f'$\partial\left(-\\frac{{\\nabla\cdot\Pi e}}{{m e n e}})
            display(Latex(f'$\left[\overline{{G}}}} e\\right] {{{coord li}
            expr1 = expr.subs(u pe1 sym, 1).subs(u th1 sym, 0).subs(u pa1 sym, 0)
            Ge[j][0] = expr1
            display_subs(nsimplify(Ge[j][0]).subs(small,1))
            print('----')
```

```
# display(Latex(f'$\partial\left(-\\frac{{\\nabla\cdot\Pi_e}}{{m_e n_e}})
             display(Latex(f'$\left[\overline{{\overline{{G}}}}} e\\right] {{{coord li
             expr1 = expr.subs(u pel sym, 0).subs(u thl sym, 1).subs(u pal sym, 0)
             Ge[i][1] = expr1
             display_subs(nsimplify(Ge[j][1]).subs(small,1))
             print('----')
             # display(Latex(f'$\partial\left(-\\frac{{\\nabla\cdot\Pi e}}{{m e n e}j
             display(Latex(f'$\left[\overline{{G}}}} e\\right] {{{coord li}
             expr1 = expr.subs(u pel sym, 0).subs(u thl sym, 0).subs(u pal sym, 1)
             Ge[j][2] = expr1
             display subs(nsimplify(Ge[j][2]).subs(small,1))
\left(-\frac{\nabla \cdot \Pi_e}{m_o n_o}\right) =
-i[
abla_{\parallel}\ln(p_{e0})]\omega_{ce}
ho_e^2k_{	heta}u_{e\parallel1}-i[
abla_{\parallel}\ln(u_{e\parallel1})]\omega_{ce}
ho_e^2k_{	heta}u_{e\parallel1}-rac{i[
abla_{\perp}\ln(p_{e0})]\omega_{ce}
ho_e^2k_{\perp}u_{e	heta1}}{2}-rac{i[
abla_{\perp}\ln(p_{e0})]\omega_{ce}}{2}
+\frac{3i\omega_{ce}\rho_e^2k_{\perp}u_{e\theta1}[\nabla_{\perp}\ln(B)]}{2}+\frac{\omega_{ce}\rho_e^2k_{\theta}^2u_{e\theta1}}{2}+\frac{7i\omega_{ce}\rho_e^2k_{\theta}u_{e\parallel1}[\nabla_{\parallel}\ln(B)]}{2}+\frac{3i\omega_{ce}\rho_e^2k_{\theta}u_{e\perp1}[\nabla_{\perp}\ln(B)]}{2}
(Eq. B.2)
\left[ \overline{\overline{G}}_{e} \right] =
-\frac{i[\nabla_{\perp} \ln(p_{e0})] \omega_{ce} \rho_e^2 k_{\theta}}{2} + \frac{3i \omega_{ce} \rho_e^2 k_{\theta} [\nabla_{\perp} \ln(B)]}{2}
\left| \overline{\overline{G}}_{e} \right| =
-\frac{i[\nabla_{\perp}\ln(p_{e0})]\omega_{ce}\rho_e^2k_{\perp}}{2}-i[\nabla_{\perp}\ln(u_{e\theta1})]\omega_{ce}\rho_e^2k_{\perp}+\frac{\omega_{ce}\rho_e^2k_{\perp}^2}{2}+\frac{3i\omega_{ce}\rho_e^2k_{\perp}[\nabla_{\perp}\ln(B)]}{2}+\frac{\omega_{ce}\rho_e^2k_{\theta}^2}{2}
\left| \overline{\overline{G}}_{e} \right| =
-i[
abla_{\parallel} \ln(p_{e0})]\omega_{ce}
ho_e^2k_{	heta} - i[
abla_{\parallel} \ln(u_{e\parallel1})]\omega_{ce}
ho_e^2k_{	heta} + \omega_{ce}
ho_e^2k_{\parallel}k_{	heta} + rac{7i\omega_{ce}
ho_e^2k_{	heta}[
abla_{\parallel} \ln(B)]}{2}
\left(-\frac{\nabla \cdot \Pi_e}{m_e n_e}\right)_{e=1}
i[\nabla_{\parallel} \ln(p_{e0})] \omega_{ce} \rho_e^2 k_{\perp} u_{e\parallel 1} + i[\nabla_{\parallel} \ln(u_{e\parallel 1})] \omega_{ce} \rho_e^2 k_{\perp} u_{e\parallel 1} + \frac{i[\nabla_{\perp} \ln(p_{e0})] \omega_{ce} \rho_e^2 k_{\perp} u_{e\perp 1}}{2} - \frac{i[\nabla_{\perp} \ln(p_{e0})] \omega_{ce} \rho_e^2 k_{\perp} u_{e\perp 1}}{2}
-\frac{7i\omega_{ce}\rho_e^2k_{\perp}u_{e\parallel1}[\nabla_{\parallel}\ln(B)]}{2}-\frac{3i\omega_{ce}\rho_e^2k_{\perp}u_{e\perp1}[\nabla_{\perp}\ln(B)]}{2}-\frac{\omega_{ce}\rho_e^2k_{\theta}^2u_{e\perp1}}{2}+\frac{3i\omega_{ce}\rho_e^2k_{\theta}u_{e\theta1}[\nabla_{\perp}\ln(B)]}{2}
(Eq. B.3)
```

$$\begin{split} & \left[\overline{G}_{s} \right]_{\theta \perp} = \\ & \frac{i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\perp}}{2} + i \left[\nabla_{\perp} \ln(u_{e\pm 1}) \right] \omega_{cc} \rho_{c}^{2} k_{\perp} - \frac{\omega_{cc} \rho_{c}^{2} k_{\perp}^{2}}{2} - \frac{3i \omega_{cc} \rho_{c}^{2} k_{\perp} \left[\nabla_{\perp} \ln(B) \right]}{2} - \frac{\omega_{cc} \rho_{c}^{2} k_{\theta}^{2}}{2} \\ & \frac{i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta}}{2} + \frac{3i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right]}{2} \\ & \left[\overline{G}_{s} \right]_{\theta \parallel} = \\ & i \left[\nabla_{\parallel} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\perp} + i \left[\nabla_{\parallel} \ln(u_{e\parallel 1}) \right] \omega_{cc} \rho_{c}^{2} k_{\perp} - \omega_{cc} \rho_{c}^{2} k_{\parallel} k_{\perp} - \frac{7i \omega_{cc} \rho_{c}^{2} k_{\perp} \left[\nabla_{\parallel} \ln(B) \right]}{2} \\ & \left(- \frac{\nabla \cdot \Pi_{c}}{m_{c} n_{c}} \right)_{\parallel} = \\ & i \left[\nabla_{\parallel} \ln(u_{e\parallel 1}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} u_{e\pm 1} - i \left[\nabla_{\parallel} \ln(u_{e\theta 1}) \right] \omega_{cc} \rho_{c}^{2} k_{\perp} u_{e\theta 1} - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} u_{e\parallel 1} + \omega_{cc} \rho_{c}^{2} k_{\parallel} k_{\perp} u_{e\theta 1} - i \left[\overline{G}_{c} \right]_{\parallel} = \\ & i \left[\nabla_{\parallel} \ln(u_{e\pm 1}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} - \omega_{cc} \rho_{c}^{2} k_{\parallel} k_{\perp} - \frac{i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\parallel} \ln(B) \right]}{2} \\ & \overline{\left[\overline{G}_{c} \right]_{\parallel} = \\ & - i \left[\nabla_{\parallel} \ln(u_{e\theta 1}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & \overline{\left[\overline{G}_{c} \right]_{\parallel} = \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[\nabla_{\perp} \ln(p_{c0}) \right] \omega_{cc} \rho_{c}^{2} k_{\theta} + 5i \omega_{cc} \rho_{c}^{2} k_{\theta} \left[\nabla_{\perp} \ln(B) \right] \\ & - i \left[$$

From here, we can input these results in the electron momentum equation.

Section II: Derivation of the electron equations

Warm, magnetized electrons are described by their continuity and momentum equations, which read:

$$rac{\partial n_e}{\partial t} +
abla \cdot (n_e \mathbf{u}_e) =
u_p n_e,$$

$$rac{\partial \mathbf{u}_e}{\partial t} + \mathbf{u}_e \cdot
abla \mathbf{u}_e = -rac{
abla \cdot ar{\overline{p}}_e}{m_e n_e} - rac{e}{m_e} (-
abla \phi + \mathbf{u}_e imes \mathbf{B}) -
u_e \mathbf{u}_e,$$

represents the particle production rate, ϕ the electrostatic potential, ν_e is used to model dissipative forces on the electrons coming from collisional phenomena,

and \overline{p}_e the complete electron pressure tensor including the gyroviscous contribution. The system has to be completed with the energy equation, which we are not going to consider in the perturbation problem since we are neglecting temperature perturbations, i.e., $T_{e1}=0$. This assumption is reasonable for low frequency oscillations [Ref.5 \cite{bell21a}].

The cell below computes and displays the continuity and momentum equations for electrons, yielding the same expressions shown in Eqs. C.3-6 of the manuscript.

```
In [220... # Cell 3
         # THIS CELL COMPUTES AND DISPLAYS THE CONTINUITY EQUATION FOR THE ELECTRONS
         # Continuity Equation
         def continuity eq(u0,u1):
             lhs 0 = -1j * w * small * hel
             lhs_1 = scal_prod_vect(u0, grad scal(he1))
             lhs 2 = div vect(u1)
             x = [x pe, x th, x pa]
             lhs 3 = 0
             for i in [0,1,2]:
                 lhs_3 += u1[i] * small * diff(n0, x[i]) / n 0
             lhs = lhs_0 + lhs_1 + lhs_2 + lhs_3
             return lhs
         def display continuity eq(u0,u1):
             lhs = continuity eq(u0,u1)
             lhs1 = complete subs(lhs)
             print('Continuity equation:')
             display(nsimplify(lhs1).subs(small**2,0).subs(small,1))
             print('= 0')
             display(Latex('(Eq. C.3)'))
             print('----
             return lhs
         # THIS CELL COMPUTES AND DISPLAYS THE MOMENTUM EQUATION FOR THE ELECTRONS
         nue = symbols('\\nu e')
         # The momentum equation is given by:
         def momentum eq(u0,u1):
             lhs 0 = scal vect(-1j*small*(w+1j*nue), u1)
             lhs 1 = vect matr(u0, grad vect(u1))
             lhs 2 = matr vect(Ge, u1)
             lhs 2 = scal vect(-1, lhs 2)
             lhs 3 = \text{prod vect(scal vect(-w ce,[0,0,1]), (u1))}
             lhs = sum \ vect(lhs 0, lhs 1)
             lhs = sum vect(lhs, lhs 2)
```

```
lhs = sum \ vect(lhs, lhs 3)
    rhs 0 = scal vect(- c e**2, grad scal(hel))
    rhs 1 = grad scal(phi1)
    rhs = sum vect(rhs 0, rhs 1)
    return lhs, rhs
def display momentum eq(u0,u1):
   lhs, rhs = momentum eq(u0,u1)
   lhs1 = complete subs(lhs)
    rhs1 = complete subs(rhs)
   display(Latex(r'Momentum in the $x \perp$ direction:'))
   display(nsimplify(lhs1[0].subs(small**2,0)).subs(small,1))
   print('=')
   display(nsimplify(rhs1[0].subs(small**2,0)).subs(small,1))
   display(Latex('(Eq. C.4)'))
   print('-----
   display(Latex(r'Momentum in the $x \theta$ direction:'))
   display(nsimplify(lhs1[1].subs(small**2,0)).subs(small,1))
   print('=')
   display(nsimplify(rhs1[1].subs(small**2,0)).subs(small,1))
   display(Latex('(Eq. C.5)'))
   print('-----
   display(Latex(r'Momentum in the $x \parallel$ direction:'))
   display(nsimplify(lhs1[2].subs(small**2,0)).subs(small,1))
   print('=')
   display(nsimplify(rhs1[2].subs(small**2,0)).subs(small,1))
   display(Latex('(Eq. C.6)'))
    return lhs, rhs
lhs continuity = display continuity eq(ue0, ue1)
lhs momentum, rhs momentum = display momentum eq(ue0, ue1)
# Compute matrix Ae
A e = [[0,0,0,0],
      [0,0,0,0],
       [0,0,0,0],
      [0,0,0,0]
def subs ue(expr,i):
   ind = [[1,0,0,0],
          [0,1,0,0],
          [0,0,1,0]
   exp new = expr.subs(u pel sym, ind[0][i]).subs(u thl sym, ind[1][i]).sub
   return exp new
def subs he(expr,i):
   ind = [0,0,0,1]
   exp new = expr.subs(hel sym, ind[i]).subs(phil sym,0)
    return exp new
new lhs = [lhs momentum[0], lhs momentum[1], lhs momentum[2], lhs continuity
new rhs = [rhs momentum[0], rhs momentum[1], rhs momentum[2], w-w]
for i in [0,1,2,3]:
   for j in [0,1,2,3]:
        LHS = new lhs[i]
        RHS = new rhs[i]
       if j < 3:
            a_e = subs_ue(LHS,j)
       else:
            if i < 3:
                a e = -subs he(RHS,j)
            else:
```

```
a e = LHS.subs(hel sym,1).subs(phil sym,0).subs(u pel sym,0)
                   A e[i][j] = a e.subs(u pe0 sym,0).subs(u pa0 sym,0)
   Ae sym = [[0,0,0,0],
                        [0,0,0,0],
                        [0,0,0,0],
                        [0,0,0,0]
   # Additional symbols
   we, wMe, wBe, uNa, uTa, varka pe, varka th, varka pa, wNe, k, lambda pa, kTa
               symbols('\omega e, \omega {Me}, \omega {Be}, u {n\parallel}, u {T\para
                                 '\hat\\varkappa \parallel, \omega {Ne}, k, \hat\lambda {\paral
   # Compute symbolic Ae
   Ae sym[0+1][0+1] = -1j * small * (we + wMe/2 - wBe/2)
   Ae sym[0+1][1+1] = -1j * small * k pe *(wMe/(2*k th) - wBe/(2*k th) - w ce *
   Ae sym[0+1][2+1] = small * k th * 1j * w ce * rho e**2 * (kTa + lambda pa)#
   Ae sym[0+1][3-3] = c e^{**2} * (1j * k pe + small * Dpe lnhe1)
   Ae sym[1+1][0+1] = 1j * small * k pe *(wMe/(2*k th) - wBe/(2*k th) - w ce *
   Ae sym[1+1][1+1] = -1j * small * (we + wMe/2 - wBe/2)
   Ae_sym[1+1][2+1] = - small * k_pe * 1j * w_ce * rho_e**2 * (kTa + lambda_pa)
   Ae sym[1+1][3-3] = c e^{**2} * (1j * k th)
   Ae sym[2+1][0+1] = - small * k th * w ce * rho e**2 * (1j * varka pe)# - k k
   Ae sym[2+1][1+1] = - small * k pe * w ce * rho e**2 * (-1j * varka th)# + k
   Ae sym[2+1][2+1] = -1j * small * (we + wMe - 3*wBe)
   Ae sym[2+1][3-3] = small * c e**2 * eHa#(1j * k pa + Dpa lnhe1)
   Ae sym[3-3][0+1] = 1j * k pe + small * (Dpe lnu pe + w ce/c e**2 * (wBe - w
   Ae sym[3-3][1+1] = 1j * k th
   Ae_sym[3-3][2+1] = small * (lambda_pa)# + 1j * k pa)
   Ae sym[3-3][3-3] = -1j * small * we
   # THIS CELL THE SYMBOLIC MATRIX OF COEFFICENTS Ae
   w pe, w pa = symbols('\\omega {\perp}, \\omega {\parallel}')
   Ae sym[0+1][0+1] = -1j * small * (w pe)
   Ae sym[1+1][1+1] = -1j * small * (w pe)
   Ae sym[2+1][2+1] = -1j * small * (w pa)
   Ae sym1 = [[0,0,0,0],
                          [0,0,0,0],
                          [0,0,0,0],
                          [0,0,0,0]
   for i in range(4):
           for j in range(4):
                   Ae sym1[i][j] = Ae sym[i][j]
   Ae print = Matrix(Ae sym1)
Continuity equation:
[
abla_{\parallel} \ln(n_0)]u_{e\parallel 1} + [
abla_{\parallel} \ln(u_{e\parallel 1})]u_{e\parallel 1} + [
abla_{\perp} \ln(n_0)]u_{e\perp 1} + [
abla_{\perp} \ln(u_{e\perp 1})]u_{e\perp 1} - i\omega h_{e1} + ih_{e1}k_{	heta}u_{e	heta 0} + ik_{	heta}u_{e1} + ih_{e1}k_{	heta}u_{e2} + ik_{	heta}u_{e2} + ik_{	heta}u_{e2} + ih_{e2}u_{e2} + ik_{	heta}u_{e2} + ih_{e2}u_{e2} + ik_{	heta}u_{e2} + ih_{e2}u_{e2} + ih_{e2}u_{e
```

```
= 0
(Eq. C.3)
```

Momentum in the x_{\perp} direction:

$$\omega_{ce}u_{e\theta1} + ik_{\theta}u_{e\perp1}u_{e\theta0} - u_{e\parallel1} \left(-i[\nabla_{\parallel} \ln(p_{e0})]\omega_{ce}\rho_{e}^{2}k_{\theta} - i[\nabla_{\parallel} \ln(u_{e\parallel1})]\omega_{ce}\rho_{e}^{2}k_{\theta} + \omega_{ce}\rho_{e}^{2}k_{\parallel}k_{\theta} + \frac{7i\omega_{ce}\rho_{e}^{2}k}{2} - u_{e\theta1} \left(-\frac{i[\nabla_{\perp} \ln(p_{e0})]\omega_{ce}\rho_{e}^{2}k_{\perp}}{2} - i[\nabla_{\perp} \ln(u_{e\theta1})]\omega_{ce}\rho_{e}^{2}k_{\perp} + \frac{\omega_{ce}\rho_{e}^{2}k_{\perp}^{2}}{2} + \frac{3i\omega_{ce}\rho_{e}^{2}k_{\perp}[\nabla_{\perp} \ln(B)]}{2} + \frac{\omega_{ce}\mu_{e}^{2}k_{\perp}}{2} \right) = \left[\nabla_{\perp} \ln(\phi_{e1}) \right] e\phi_{e1}/m_{e} - c_{e}^{2} \left(\left[\nabla_{\perp} \ln(h_{e1})\right]h_{e1} + ih_{e1}k_{\perp} \right) + ie\phi_{e1}/m_{e}k_{\perp} \right]$$
(Eq. C.4)

Momentum in the x_{θ} direction:

$$-\omega_{ce}u_{e\perp 1} + ik_{\theta}u_{e\theta 0}u_{e\theta 1} - u_{e\parallel 1}\left(i[\nabla_{\parallel}\ln(p_{e0})]\omega_{ce}\rho_{e}^{2}k_{\perp} + i[\nabla_{\parallel}\ln(u_{e\parallel 1})]\omega_{ce}\rho_{e}^{2}k_{\perp} - \omega_{ce}\rho_{e}^{2}k_{\parallel}k_{\perp} - \frac{7i\omega_{ce}\rho_{e}^{2}k_{\perp}}{2} - u_{e\perp 1}\left(\frac{i[\nabla_{\perp}\ln(p_{e0})]\omega_{ce}\rho_{e}^{2}k_{\perp}}{2} + i[\nabla_{\perp}\ln(u_{e\perp 1})]\omega_{ce}\rho_{e}^{2}k_{\perp} - \frac{\omega_{ce}\rho_{e}^{2}k_{\perp}^{2}}{2} - \frac{3i\omega_{ce}\rho_{e}^{2}k_{\perp}[\nabla_{\perp}\ln(B)]}{2} - \frac{\omega_{ce}\rho_{e}^{2}k_{\perp}}{2} - \frac{\omega_{ce}\rho_{e}^{2}k_{\perp}}{2} - \frac$$

Momentum in the x_{\parallel} direction:

$$\begin{split} ik_{\theta}u_{e\parallel 1}u_{e\theta 0} - iu_{e\parallel 1}\left(i\nu_{e} + \omega\right) - u_{e\parallel 1}\left(-i\left[\nabla_{\perp}\ln(p_{e0})\right]\omega_{ce}\rho_{e}^{2}k_{\theta} + 5i\omega_{ce}\rho_{e}^{2}k_{\theta}\left[\nabla_{\perp}\ln(B)\right]\right) - u_{e\perp 1}\left(i\left[\nabla_{\parallel}\ln(u_{e\theta 1})\right]\omega_{ce}\rho_{e}^{2}k_{\perp} + \omega_{ce}\rho_{e}^{2}k_{\parallel}k_{\perp} - \frac{i\omega_{ce}\rho_{e}^{2}k_{\perp}\left[\nabla_{\parallel}\ln(B)\right]}{2}\right) \\ = \\ \left[\nabla_{\parallel}\ln(\phi_{e1})\right]e\phi_{e1}/m_{e} - c_{e}^{2}\left(\left[\nabla_{\parallel}\ln(h_{e1})\right]h_{e1} + ih_{e1}k_{\parallel}\right) + ie\phi_{e1}/m_{e}k_{\parallel} \end{split}$$
(Eq. C.6)

Section III: Expression and determinant of A_e

Now, we can make some proper symbolic substitutions to render the expressions more manageable. We define the following frequencies:

$$egin{aligned} \omega_{Ne} &\equiv -rac{c_e^2}{\omega_{ce}}
abla_ot \ln n_0, & \omega_{Be} &\equiv -rac{c_e^2}{\omega_{ce}}
abla_ot \ln B_0, & \omega_{Te} &\equiv -rac{c_e^2}{\omega_{ce}}
abla_ot \ln T_e, \ & \omega_e &\equiv \omega - k_ heta u_{ heta e}, & \omega_ot &\equiv \omega_e - rac{\omega_{Me} + \omega_{Be}}{2}, & \omega_\| &\equiv \omega_e - \omega_{Me} - 3\omega_{Be}, \end{aligned}$$

which correspond to the definitions found in the list of symbols Eq. A.1. The first three definitions are drift frequencies, due to gradients in the equilibrium electron density, magnetic field and electron temperature, respectively. ω_e is the Doppler-shifted wave frequency as seen by an observer moving with the electron refernce frame, ω_\perp is the same Doppler-shifted frequency corrected with the leading terms coming from the projection of the gyroviscous tensor on the plane perpendicular to ${\bf B}$, while ω_\parallel is analogous to ω_\perp but with the correction coming from the projection of $\nabla \cdot \Pi_{e1}$ in the parallel direction.

We further define the following parallel gradients of zeroth-order quantities, as shown in Eq. C.9 of the manuscript,

$$arkappa_n \equiv
abla_\parallel \ln rac{n_0}{\sqrt{B}}, \qquad arkappa_T \equiv
abla_\parallel \ln rac{T_e}{\sqrt{B^5}},$$

and the parallel gradients of first-order quantities, defined as in Eq. C.10,

$$m{arkappa}_{\perp} \equiv
abla_{\parallel} \ln(\sqrt{B}u_{\perp e1}), \qquad m{arkappa}_{\perp} \equiv
abla_{\parallel} \ln(\sqrt{B}u_{ heta e1}), \qquad m{arkappa}_{\parallel} \equiv
abla_{\parallel} \lnigg(rac{u_{\parallel e1}}{\sqrt{B}}igg).$$

To aid us in the symbolic manipulation of the determinant of the matrix of coefficients A_e , we will make use of the following additional definitions:

$$\hat{m{arkappa}}_{\perp} \equiv m{arkappa}_{\perp} + i k_{\parallel}, \qquad \hat{m{arkappa}}_{ heta} \equiv m{arkappa}_{ heta} + i k_{\parallel}, \qquad \hat{m{\lambda}}_{\parallel} \equiv \hat{m{arkappa}}_{\parallel} + m{arkappa}_{n},$$

The cell below displays the matrix of coefficients A_e , adopting the above definitions.

$$egin{aligned} -i\omega_e & [
abla_ot \ln(u_{e\perp 1})] + rac{\omega_{ce}(\omega_{Be}-\omega_{Ne})}{c_e^2k_ heta} + ik_ot \ c_e^2\left([
abla_ot \ln(h_{e1})] + ik_ot
ight) & -i\left(i
u_e + \omega_ot
ight) & \omega_{ce}\left(-rac{i}{2}\omega_{ee}k_ heta + ik_ot
ight) \ \hat{\eta}_\parallel c_e^2 & -i\hat{oldsymbol{arkappa}}_ot\omega_{ce}
ho_e^2k_ heta \ & -i\hat{oldsymbol{arkappa}}_ot\omega_{ce}
ho_e^2k_ heta \end{aligned}$$

Next, we calculate the inverse of the determinant of A_e , which we refer to as $D_e \equiv -\det(A_e)$.

At the leading order in ϵ , D_e can be subdivided in two terms, the first depending solely on the perpendicular dynamics of the electrons, the second only on the parallel dynamics. We express the first term as $D_{e\perp}\equiv D_e|_{k_\parallel,\nabla_\parallel=0}$, where $k_\parallel,\nabla_\parallel=0$ symbolically indicates the complete neglect of electron dynamics along the parallel direction. We express the remaining term of D_e through the parallel gradient drift frequency Ω_\parallel defined as

$$\Omega_\parallel^2 \equiv -rac{D_e-D_{e\perp}}{\omega_{ce}^2}.$$

The cell below computes and displays both $D_{e\perp}$ and $\Omega_{||}^2$

```
In [176... # Cell 4
                                          # THIS CELL COMPUTES THE DETERMINANT OF THE SYMBOLIC MATRIX AE UP TO THE SEC
                                          De = det4(Ae sym)
                                          De = De.subs(u pe0,0).subs(u pa0,0).subs(u th0,u th0 sym)
                                          De = De.subs(x pe,0).subs(x th,0).subs(x pa,0)
                                          PolyDe = Poly(De, small)
                                          degree De = degree(PolyDe, gen=small)
                                          order De = len(PolyDe.all coeffs())
                                          De 0 = PolyDe.all coeffs()[order De-3]
                                          # THIS CELL ONLY PRINTS THE PART OF THE DETERMINANT THAT DEPENDS ON THE PERF
                                          De 0 pe = De 0.subs(varka pe,0).subs(varka th,0).subs(varka pa,0).subs(uNa,6
                                                             .subs(Dpa_lnu_pa,0).subs(Dpa_lnu_pe,0).subs(Dpa_lnu_th,0).subs(Dpa_lnhe1
                                          display(Latex(r'$\displaystyle-\frac{{D e} \perp}{\omega \parallel+i\nu e}=$
                                          display(nsimplify(simplify(De_0_pe).subs(c_e,rho_e*w_ce).subs(w_pe,w_pe+1j*r
                                          De_0_pa = De_0.subs(w_pa,0)
                                          print('-----
                                          display(Latex(r'$\displaystyle\frac{\Omega^2 \parallel}{c e^2}=$'))
                                          display(nsimplify(simplify(De 0 pa).subs(k pa,0).subs(c e,rho e*w ce)/w ce**
                                  -rac{D_{e\perp}}{\omega_{\shortparallel}+i
u_{e}}=
                                   rac{\left[
abla_{\perp} \ln(h_{e1})
ight]\omega_{ce}^3
ho_e^4k^2k_{	heta}}{2}-\left[
abla_{\perp} \ln(h_{e1})
ight]\omega_{ce}^3
ho_e^2k_{	heta}-rac{\left[
abla_{\perp} \ln(u_{e\perp1})
ight]\omega_{ce}^3
ho_e^4k^2k_{	heta}}{2}+\left[
abla_{\perp} \ln(u_{e\perp1})
ight]\omega_{ce}^3
ho_e^4k_{\perp}^2k_{	heta}+\left[
abla_{\perp} \ln(u_{e\perp1})
ight]\omega_{ce}^3
ho_e^4k_{\perp}^2k_{	heta}
                                    -rac{\omega_{Be}\omega_{ce}^2
ho_e^2k^2}{2}+\omega_{Be}\omega_{ce}^2+rac{\omega_{Ne}\omega_{ce}^2
ho_e^2k^2}{2}-\omega_{Ne}\omega_{ce}^2-\omega_{ce}^2
ho_e^2k_\perp^2\left(i
u_e+\omega_\perp
ight)-\omega_{ce}^2
ho_e^2k_	heta^2\left(i
u_e+\omega_\perp
ight)
                                      ______
                                  -\frac{\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{4}k^{4}}{4}+\frac{\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{4}k^{2}k_{\perp}^{2}}{2}+\frac{\hat{\eta}_{\|}\ddot{\lambda}_{\|}\rho_{e}^{4}k^{2}k_{\theta}^{2}}{2}+\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\perp}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{\theta}^{2}-\hat{\eta}_{\|}\hat{\lambda}_{\|}\rho_{e}^{2}k_{
                                  -\hat{\kappa}_{\perp}\hat{\lambda}_{\parallel}
ho_e^2k_{	heta}^2-\hat{\kappa}_{\perp}\kappa_T
ho_e^4k_{\perp}^2k_{	heta}^2-\hat{\kappa}_{\perp}\kappa_T
ho_e^4k_{	heta}^4+rac{\hat{\kappa}_{	heta}\hat{\lambda}_{\parallel}
ho_e^4k^2k_{\perp}^2}{2}-\hat{\kappa}_{	heta}\hat{\lambda}_{\parallel}
ho_e^4k_{\perp}^4-\hat{\kappa}_{	heta}\hat{\lambda}_{\parallel}
ho_e^4k_{\perp}^2k_{	heta}^2-\hat{\kappa}_{	heta}\hat{\lambda}_{\parallel}
ho_e^2k_{\perp}^2-\hat{\kappa}_{	heta}
```

Recalling the definitions of ω_e and ω_\perp , $D_{e\perp}$ can be rewritten as

$$D_{e\perp} = \omega_{ce}^2(\omega_\parallel + i
u_e) \left[\omega_e igg(1 - rac{
ho_e^2 k^2}{2}igg)^2 + k^2
ho_e^2(\omega_\perp + i
u_e) + -rac{k_ heta c_e^2}{\omega_{ce}}
abla_\perp \ln rac{n_0 u_{\perp\epsilon}}{B h_{e1}}
ight.$$

On theother hand, remembering the definitions of $\hat{\lambda}_{\parallel}$, $\hat{\eta}_{\parallel}$, $\hat{\varkappa}_{\perp}$ and $\hat{\varkappa}_{\theta}$, the expression of Ω^2_{\parallel} can be simplified as

$$egin{aligned} rac{\Omega_{\parallel}^2}{c_e^2} &= -\left[\hat{\lambda}_{\parallel}\left(1+rac{k^2
ho_e^2}{2}
ight) + arkappa_T
ho_e^2k^2
ight]\left[\hat{\eta}_{\parallel}\left(1-rac{k^2
ho_e^2}{2}
ight) + \hat{arkappa}_{\perp}
ho_e^2k_{ heta}^2 + \hat{arkappa}_{ heta}
ho_e^2k_{\perp}^2
ight] \ &= -\left[\left(ik_{\parallel}+arkappa_n+arkappa_{\parallel}
ight)\left(1+rac{k^2
ho_e^2}{2}
ight) + arkappa_T
ho_e^2k^2
ight]\left[\left(ik_{\parallel}+
abla_{\parallel}h_{e1}
ight)\left(1-rac{k^2
ho_e^2}{2}
ight)
ight] \end{aligned}$$

which corresponds to Eq. C.8 of the manuscript.

Summing the expressions for $D_{e\perp}$ and $-\omega_{ce}^2\Omega_{\parallel}^2$ returns the full expression of D_e from Eq. C.7 of the manuscript.

First-order gradients and closure of the electron system of equations

As a final step, we compute the gradients of the first-order plasma quantities as functions of the gradients of the zeroth-order quantities.

The expression for h_{e1} is quite trivial to recover using Kramer's rule,

$$\det(A_e)h_{e1} = rac{1}{c_e^2}\det(A_e)igg|_{\substack{\omega_e=0\h_{e1} o\phi_1}} \ = -rac{D_e}{c_e^2}igg\{1-rac{\omega_{ce}^2}{D_e}igg(1-rac{k^2
ho_e^2}{2}igg)\left(\omega_\parallel+i
u_e
ight)igg[\omega_e\left(1-rac{k^2
ho_e^2}{2}
ight)+rac{k_ heta c_e^2}{\omega_{ce}}
abla_\perp\lnrac{h_{e1}}{\phi_1}igg]$$

which corresponds to Eq. C.11 of the manuscript. Here, the subscript $h_{e1} \to \phi_1$ indicates the substitution of the terms $\nabla \ln h_{e1}$ with gradients of the electric potential $\nabla \ln \phi_1$.

Derivating in space the above relation yields, neglecting $abla^2 \ln Q_0$ and $abla^2 \ln Q_1$ terms,

$$abla \ln h_{e1} =
abla \ln rac{\phi_1}{T_e}$$

which is Eq. C.13 of the manuscript. We will feed this information to the symbolic manipulator at the next cell, in order to facilitate the computaions of the velocities, with the assumption $\nabla_{\parallel} \ln h_{e1} \simeq \nabla_{\parallel} \ln \phi_1$, being $\nabla_{\parallel} \ln T_e$ negligible

with respect to $abla_{\parallel} \ln p_{e0}$. This assumptions is justified by the available simulation data, as presented in Table V.I of the manuscript.

Using this and considering $|
abla_\| \ln T_e/
abla_\| \ln p_{e0}| \ll 1$ allow us to simplify the expression of h_{e1} as (Eq. C.14)

$$rac{h_{e1}}{e\phi_1/m_e} = rac{1}{c_e^2} - rac{\omega_{ce}^2}{c_e^2 D_e}igg(1-rac{k^2
ho_e^2}{2}igg)^2igg(\omega_\parallel+i
u_eigg)igg(\omega_e+rac{\omega_{Te}}{1-k^2
ho_e^2/2}igg)\,.$$

The velocities can be similarly computed. The cell below computes and displays $\mathbf{u}_{e1}(e\phi_1/m_e)^{-1}$ at the leading order in ϵ .

```
In [221... # Cell 5
                                      # THIS CELL COMPUTES u {e1} TO THE LEADING ORDER IN \varepsilon
                                      Dpe lnT, Dpa lnT, wTe = symbols(' [\n {\perp}\ln(T {e})], [\n {\pa
                                      k phi = grad scal(phi1)
                                      k phi = [0*phi1 sym, k phi[0], k phi[1], k phi[2]]
                                      # Computing u pel
                                      Ae sym pe = [[0,0,0,0]],
                                                                                         [0,0,0,0],
                                                                                          [0,0,0,0],
                                                                                           [0,0,0,0]
                                      for i in range(4):
                                                      for j in range(4):
                                                                      Ae_{sym_pe[i][j]} = Ae_{sym[i][j]}
                                      for i in range(4):
                                                      Ae_sym_pe[i][1] = k_phi[i].subs(phil_sym,1).subs(x pe,0).subs(x th,0).subs(x th,0
                                                      .subs(Dpa lnphi1+1j*k pa, eHa)
                                      Upe = det4(Ae sym pe)
                                      Upe = expand(Upe, small)
                                      Upe = Upe.subs(small**3,0).subs(small**4,0).subs(w pa,w pa+1j*nue)
                                      display(Latex(r'$\displaystyle - D e \frac{u {\perp e1}}{e\phi 1/m e}=$'))
                                      display(nsimplify(Upe.subs(small,1)))
                                      display(Latex('(Eq. C.15)'))
                                      print('-----
                                      # Computing u th1
                                      Ae sym th = [[0,0,0,0]],
                                                                                         [0,0,0,0],
                                                                                          [0,0,0,0],
                                                                                          [0,0,0,0]
                                      for i in range(4):
                                                      for j in range(4):
                                                                      Ae sym th[i][j] = Ae sym[i][j]
                                      for i in range(4):
                                                      Ae_sym_th[i][2] = k_phi[i].subs(phil_sym,1).subs(x_pe,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0).subs(x_th,0
                                                       .subs(Dpa lnphi1+1j*k pa, eHa)
                                      Uth = det4(Ae sym th)
                                      Uth = expand(Uth, small)
                                      Uth = Uth.subs(small**3,0).subs(small**4,0).subs(w pa,w pa+1j*nue)
                                      display(Latex(r'$\displaystyle - D e \frac{u {\theta e1}}{e\phi 1/m e}=$'))
                                      display(nsimplify(Uth.subs(small,1)))
                                      display(Latex('(Eq. C.16)'))
                                      print('-----
```

```
# Computing u pal
       Ae sym pa = [[0,0,0,0],
                                                                     [0,0,0,0],
                                                                     [0,0,0,0],
                                                                     [0,0,0,0]
       for i in range(4):
                          for j in range(4):
                                             Ae_sym_pa[i][j] = Ae_sym[i][j]
       for i in range(4):
                          Ae sym pa[i][3] = k phi[i].subs(phi1 sym,1).subs(x pe,0).subs(x th,0).subs(x th,0
                           .subs(Dpa lnphi1+1j*k pa, eHa)
       Upa = det4(Ae sym pa)
       Upa = expand(Upa, small)
       Upa = Upa.subs(small**3,0).subs(small**4,0).subs(w pa,w pa+1j*nue)
       display(Latex(r'$\displaystyle - D_e \frac{u_{\parallel e1}}{e\phi 1/m e}=$'
       display(nsimplify(Upa.subs(small,1)))
-D_e \frac{u_{\perp e1}}{e\phi_1/m_e} =
-rac{i\omega_{e}\omega_{ce}
ho_{e}^{2}k^{2}k_{	heta}\left(i
u_{e}+\omega_{\parallel}
ight)}{2}+i\omega_{e}\omega_{ce}k_{	heta}\left(i
u_{e}+\omega_{\parallel}
ight)+i\omega_{Te}\omega_{ce}k_{	heta}\left(i
u_{e}+\omega_{\parallel}
ight)
(Eq. C.15)
                                _____
-D_e \frac{u_{\theta e 1}}{e \phi_1 / m_e} =
rac{i\omega_{e}\omega_{ce}
ho_{e}^{2}k^{2}k_{\perp}\left(i
u_{e}+\omega_{\parallel}
ight)}{2}-i\omega_{e}\omega_{ce}k_{\perp}\left(i
u_{e}+\omega_{\parallel}
ight)-i\omega_{Te}\omega_{ce}k_{\perp}\left(i
u_{e}+\omega_{\parallel}
ight)
(Eq. C.16)
-D_e \frac{u_{\parallel e1}}{e\phi_1/m_e} =
-\frac{i\hat{\eta}_{\parallel}\omega_{e}\omega_{ce}^{2}\rho_{e}^{4}k^{4}}{4}+i\hat{\eta}_{\parallel}\omega_{e}\omega_{ce}^{2}\rho_{e}^{2}k^{2}-i\hat{\eta}_{\parallel}\omega_{e}\omega_{ce}^{2}+\frac{i\hat{\eta}_{\parallel}\omega_{Te}\omega_{ce}^{2}\rho_{e}^{2}k^{2}}{2}-i\hat{\eta}_{\parallel}\omega_{Te}\omega_{ce}^{2}+\frac{i\hat{\varkappa}_{\perp}\omega_{e}\omega_{ce}^{2}\rho_{e}^{4}k^{2}k_{\theta}^{2}}{2}-i\hat{\varkappa}_{\perp}\omega_{e}\omega_{ce}^{2}\rho_{e}^{4}k^{2}k_{\theta}^{2}}
```

The first two relations don't need further simplification. The last can be rearranged as

$$-D_erac{u_{\parallel e1}}{e\phi_1/m_e}=-i\omega_{ce}^2\left[\hat{\eta}_\parallel\left(1-rac{
ho_e^2k^2}{2}
ight)+\hat{m{arkappi}}_\perp
ho_e^2k_ heta^2+\hat{m{arkappi}}_ heta
ho_e^2k_\perp^2
ight]\left[\omega_e\left(1-rac{
ho_e^2k^2}{2}
ight)$$

$$=-i\omega_{ce}^2\left[\left(ik_\parallel+
abla_\parallel\ln\phi_1
ight)\left(1-rac{
ho_e^2k^2}{2}
ight)+ik_\parallel k^2
ho_e^2+arkappa_\perp
ho_e^2k_ heta^2+arkappa_e
ho_e^2k_\perp^2
ight]\left[\omega_e\left(1-rac{
ho_e^2k^2}{2}
ight)+ik_\parallel k^2
ho_e^2+arkappa_\perp
ho_e^2k_ heta^2+arkappa_e^2k_\perp^2
ight]$$

which corresponds to Eq. C.17 of the manuscript. Derivating in space allows us to obtain Eqs. C.18 and C.19:

$$abla \ln u_{ot e1} =
abla \ln u_{ heta e1} =
abla \ln rac{\phi_1}{B}, \qquad
abla \ln u_{\|e1} =
abla \ln \phi_1.$$

We can now feed allof these relations to the symbolic manipulator, and recompute $D_{e\perp}$ and Ω_{\parallel}^2 as functions of $\nabla \ln \phi_1$. We define \$= $reformulateheretheexpressions of the parallel gradients for convenience, <math>\hat{\varkappa}_{\perp}=\$$ The cell below recomputes and displays the aforementioned terms.

Bibliography

Ref.1 -

Ref.2 -

Ref.3 -

Ref.4 - \