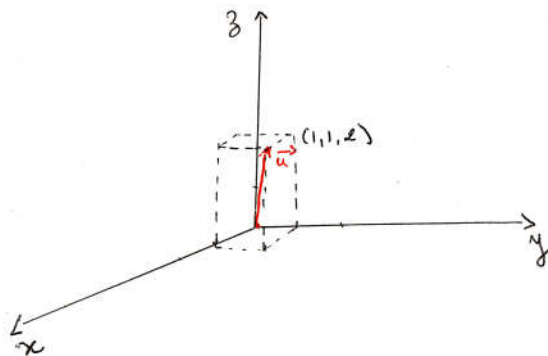


DAY 5: AUGUST 31st

(VECTOR EQUATIONS: continued)

Vectors in \mathbb{R}^3

A point with coordinate (a, b, c) in \mathbb{R}^3 corresponds to the vector $\vec{u} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$



Theorem 3.9. Let $\vec{u}, \vec{v}, \vec{w} \in \mathbb{R}^n$ and $c, d \in \mathbb{R}$.

- (1) $\vec{u} + \vec{v} = \vec{v} + \vec{u}$.
- (2) $(\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w})$.
- (3) $(\vec{u} + \vec{0}) = \vec{0} = \vec{0} + \vec{u}$
- (4) $\vec{u} + (-\vec{u}) = \vec{0} = -\vec{u} + \vec{u}$.
- (5) $c(\vec{u} + \vec{v}) = c\vec{u} + c\vec{v}$.
- (6) $(c + d)\vec{u} = c\vec{u} + d\vec{u}$.
- (7) $c(d\vec{u}) = (cd)\vec{u}$.
- (8) $1\vec{u} = \vec{u}$.

Linear Combination and spanning

Definition 3.10 (Linear Combination). Given vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p \in \mathbb{R}^n$ and scalars c_1, c_2, \dots, c_p the vector

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_p\vec{v}_p$$

is called a linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$.

Example 3.11. We have

$$2 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ -1 \end{bmatrix}$$

The vector $\vec{w} = \begin{bmatrix} 1 \\ -2 \\ -1 \end{bmatrix}$ is a linear combination of the vectors $\vec{u} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$ (as $\vec{w} = 2\vec{u} - \vec{v}$).

Suppose that we have the following linear combination:

$$x_1 \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} + x_2 \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} + x_3 \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix}$$

This is the same as

$$\begin{bmatrix} a_1x_1 + b_1x_2 + c_1x_3 \\ a_2x_1 + b_2x_2 + c_2x_3 \\ a_3x_1 + b_3x_2 + c_3x_3 \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix}$$

By the equality of two vectors, we have the following equalities:

$$a_1x_1 + b_1x_2 + c_1x_3 = d_1$$

$$a_2x_1 + b_2x_2 + c_2x_3 = d_2$$

$$a_3x_1 + b_3x_2 + c_3x_3 = d_3$$

It follows that the vector $\begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix}$ is a linear combination of $\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$, $\begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$, $\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$ if the above linear system has solutions.

FACT:

A vector equation $x_1\vec{v}_1 + x_2\vec{v}_2 + \dots + x_p\vec{v}_p = \vec{b}$ has the same solutions as the system of linear equations corresponding to the augmented matrix

$$(A) \quad \left[\begin{array}{cccc|c} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_p & \vec{b} \end{array} \right]$$

In particular, \vec{b} can be written (or generated) as a linear combination of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ if and only if the linear system with augmented matrix (A) is consistent.

Example 3.12. Is $\vec{b} = \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix}$ a linear combination of $\vec{v}_1 = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}$ and $\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$?

The vector equation is

$$x \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix}$$

The augmented matrix of the corresponding linear system is given by

$$(B) \quad \begin{bmatrix} 1 & 0 & 2 \\ -2 & 1 & -1 \\ 0 & 2 & 6 \end{bmatrix}$$

EXERCISE: Reduce the matrix (B) to reduced echelon form.

The echelon form of matrix (B) is given by

$$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

It follows that the system is consistent, and $x = 2$ and $y = 3$. Therefore $\vec{b} = 2\vec{v}_1 + 3\vec{v}_2$, so \vec{b} is a linear combination of \vec{v}_1 and \vec{v}_2 .

Definition 3.13 (Spanning). Let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p \in \mathbb{R}^n$. The subset of \mathbb{R}^n spanned (or generated) by $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ is the collection of all linear combinations of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$.

$$\text{Span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p) = \{c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_p\vec{v}_p : c_1, c_2, \dots, c_p \in \mathbb{R}\}.$$

NOTE:

- The span of $\vec{0}$ in \mathbb{R}^n is the single vector $\vec{0}$.
- The span of a single nonzero vector in \mathbb{R}^2 and \mathbb{R}^3 is a line through $\vec{0}$.
- The span of two nonzero vectors \vec{u} and \vec{v} in \mathbb{R}^3 , with $\vec{v} \neq c\vec{u}$, is a plane through $\vec{0}$.

Example 3.14. Let $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} 2 \\ 5 \\ -3 \end{bmatrix}$, and $\vec{b} = \begin{bmatrix} -9 \\ -30 \\ 31 \end{bmatrix}$

$\text{Span}(\vec{v}_1, \vec{v}_2)$ is a plane in \mathbb{R}^3 , is \vec{b} in that plane?

This question is the same as: is \vec{b} a linear combination of \vec{v}_1 and \vec{v}_2 . The approach to solve this is the same as in Example 3.12.