DAY 42: Monday, December 3rd

Fact 1.16. Let W be a subspace of \mathbb{R}^n . Then

- (a) $(W^{\perp})^{\perp} = W$
- (b) A vector \vec{z} is in W^{\perp} if and only if \vec{z} is orthogonal to every vector in a set that spans W.
- (c) W^{\perp} is a subspace of \mathbb{R}^n .

Theorem 1.17. Let A be an $m \times n$ matrix. Then

$$(\operatorname{Row}(A))^{\perp} = \operatorname{Nul}(A)$$
 and $(\operatorname{Col}(A))^{\perp} = \operatorname{Nul}(A^T)$

Example 1.18. Let $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ and $\vec{v}_2 = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$ be vectors in \mathbb{R}^3 , and let $W = \operatorname{Span}(\vec{v}_1, \vec{v}_2)$ be a subspace

of \mathbb{R}^3 . Give an explicit description (a parametric form) of the elements of W^{\perp} .

Solution

By Fact 1.16 (b), a vector $\vec{z}=\left[\begin{array}{c}z_1\\z_2\\z_3\end{array}\right]$ is in W^\perp if and only if

$$\begin{cases} \vec{z} \cdot \vec{v_1} = 0 \\ \vec{z} \cdot \vec{v_2} = 0 \end{cases}$$
 which is equivalent to
$$\begin{cases} z_1 - z_3 = 0 \\ 2z_1 - z_2 + z_3 = 0 \end{cases}$$

So, we solve this linear system to find an explicit description of the vector \vec{z} . The augmented matrix of this system is given by

$$\left[
\begin{array}{ccccc}
1 & 0 & -1 & 0 \\
2 & -1 & 1 & 0
\end{array}
\right]$$

This matrix is row reduced to

$$\left[
\begin{array}{cccc}
1 & 0 & -1 & 0 \\
0 & -1 & 3 & 0
\end{array}
\right]$$

So a solution \vec{z} of the system is of the form

$$ec{z} = \left[egin{array}{c} z_1 \ z_2 \ z_3 \end{array}
ight] = \left[egin{array}{c} z_3 \ 3z_3 \ z_3 \end{array}
ight] = z_3 \left[egin{array}{c} 1 \ 3 \ 1 \end{array}
ight], \;\; z_3 \in \mathbb{R}.$$

2 Orthogonal Sets and The Gram-Schmidt Process

Definition 2.1. A set of vectors $\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_p\}$ in \mathbb{R}^n is said to be an orthogonal set if each pair of distinct vectors from the set is orthogonal, i.e. $\vec{u}_i \cdot \vec{u}_j = 0$ for every $i \neq j$.

4

Example 2.2. Show that the set
$$\left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} \right\}$$
 is orthogonal.

Solution

We have

$$\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = (1)(0) + (-2)(1) + (1)(2) = 0$$

$$\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} = (1)(-5) + (-2)(-2) + (1)(1) = 0$$

$$\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} = (0)(-5) + (1)(-2) + (2)(1) = 0$$

Theorem 2.3. If the set $S = {\vec{u}_1, \vec{u}_2, \dots, \vec{u}_p}$ is an orthogonal set of nonzero vectors in \mathbb{R}^n , then S is linearly independent. Hence, it is a basis for the subspace that it spans.

Definition 2.4. An **orthogonal basis** for a subspace W of \mathbb{R}^n is a basis for W which is an orthogonal set.

Theorem 2.5. Let W be a subspace of \mathbb{R}^n and let $\mathcal{B} = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_p\}$ be an orthogonal basis for W. Then, for every \vec{u} in W, the weights in the linear combination

$$\vec{u} = c_1 \vec{b}_1 + c_2 \vec{b}_2 + \dots + c_p \vec{b}_p$$

is given by

$$c_j = \frac{\vec{u} \cdot \vec{b}_j}{\vec{b}_j \cdot \vec{b}_j}, \quad \text{for } j = 1, 2, \cdots, p.$$

Definition 2.6.

- (a) A set $S = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_p\}$ is an **orthonormal set** if it is orthogonal and $||\vec{u}_i|| = 1$ for $i = 1, 2, \dots, p$ (i.e. each vector \vec{u}_i in S is a unit vector).
- (b) An **orthonormal basis** for a subspace W of \mathbb{R}^n is a basis for W which is orthonormal (orthogonal set and each element is a unit vector).
- (c) If S is an orthonormal set in \mathbb{R}^n , then it is an orthonormal basis for the subspace that it spans.

Example 2.7. The standard basis $\{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$ for \mathbb{R}^n is an orthonormal basis for \mathbb{R}^n .

Theorem 2.8. An $m \times n$ matrix U has orthonormal columns if and only if $U^T U = I_m$.

The Gram-Schmidt Process

The Gram-Schmidt algorithm consists to constructing an orthogonal or orthonormal basis for a subspace W of \mathbb{R}^n starting with any basis \mathcal{B} for W.

Theorem 2.9 (Gram-Schmidt Process). Let W be a subspace of \mathbb{R}^n and let $\mathcal{B} = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_p\}$ be a basis for W. Then, the set $\mathcal{O} = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}$ such that

$$\begin{array}{rcl} \vec{v}_1 & = & \vec{b}_1 \\ \vec{v}_2 & = & \vec{b}_2 - \frac{\vec{b}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 \\ \\ \vec{v}_3 & = & \vec{b}_3 - \frac{\vec{b}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{b}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 \\ \\ & \vdots \\ \\ \vec{v}_p & = & \vec{b}_p - \frac{\vec{b}_p \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{b}_p \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 - \dots - \frac{\vec{b}_p \cdot \vec{v}_{p-1}}{\vec{v}_{p-1} \cdot \vec{v}_{p-1}} \vec{v}_{p-1} \end{array}$$

is an orthogonal basis for W. In addition,

$$\operatorname{Span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k) = \operatorname{Span}(\vec{b}_1, \vec{b}_2, \dots, \vec{b}_k) \quad \text{for } 1 \le k \le p.$$

Note 2.10. To find an orthonormal basis for W, simply normalize each vector $\vec{v_i}$ constructed in Theorem 2.9.

Example 2.11. Let $\vec{b}_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ and $\vec{b}_2 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$ be vectors in \mathbb{R}^3 and let $W = \operatorname{Span}(\vec{b}_1, \vec{b}_2)$. Find an orthogonal basis, and then an orthonormal basis for W.

Solution

We use Gram-Schmidt algorithm to find an orthogonal basis for W. We have

$$\vec{v}_{1} = \vec{b}_{1} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{v}_{2} = \vec{b}_{1} - \frac{\vec{b}_{2} \cdot \vec{v}_{1}}{\vec{v}_{1} \cdot \vec{v}_{1}} \vec{v}_{1} = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} - \frac{-2}{2} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Then the set $\mathcal{O}_1 = \{\vec{v}_1, \vec{v}_2\}$ is an orthogonal basis for W. Clearly, \mathcal{O}_1 is linearly independent and $\vec{v}_1 \cdot \vec{v}_2 = 0$. To find an orthonormal basis for W, we simply normalize each vector in \mathcal{O}_1 . We have

$$||\vec{v}_1|| = \sqrt{\vec{v}_1 \cdot \vec{v}_1} = \sqrt{2}$$

$$||\vec{v}_2|| = \sqrt{\vec{v}_2 \cdot \vec{v}_2} = \sqrt{3}$$

Let
$$\vec{u}_1 = \frac{1}{||\vec{v}_1||} \vec{v}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$
 and $\vec{u}_2 = \frac{1}{||\vec{v}_2||} \vec{v}_2 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$. Then $\mathcal{O}_2 = \{\vec{u}_1, \vec{u}_2\}$ is orthonormal basis for W .