

7 Change of Basis

Recall that if V is a vector space with a basis $\mathcal{B} = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\}$ and if $\vec{u} = c_1\vec{b}_1 + c_2\vec{b}_2 + \dots + c_n\vec{b}_n$ is a vector in V , then the coordinates of \vec{u} relative to \mathcal{B} is given by

$$[\vec{u}]_{\mathcal{B}} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$

and the coordinate mapping $T : V \rightarrow \mathbb{R}^n$, defined by $T(\vec{u}) = [\vec{u}]_{\mathcal{B}}$ is a one-to-one linear transformation onto \mathbb{R}^n .

Example 7.1. Let V be a 2-dimensional vector space and let $\mathcal{B} = \{\vec{b}_1, \vec{b}_2\}$ and $\mathcal{C} = \{\vec{c}_1, \vec{c}_2\}$ be bases for V . Suppose

$$\vec{b}_1 = 4\vec{c}_1 + \vec{c}_2 \quad \text{and} \quad \vec{b}_2 = -6\vec{c}_1 + \vec{c}_2$$

Let $\vec{x} = 3\vec{b}_1 + \vec{b}_2$, i.e. $[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$. Find $[\vec{x}]_{\mathcal{C}}$.

Solution

Consider the coordinate mapping $\vec{u} \mapsto T(\vec{u}) = [\vec{u}]_{\mathcal{C}}$. Since T is linear, we have

$$\begin{aligned} [\vec{x}]_{\mathcal{C}} &= [3\vec{b}_1 + \vec{b}_2]_{\mathcal{C}} \\ &= 3[\vec{b}_1]_{\mathcal{C}} + [\vec{b}_2]_{\mathcal{C}} \end{aligned}$$

This a vector equation (in \mathbb{R}^2) which is equivalent to the matrix equation

$$(vi) \quad [\vec{x}]_{\mathcal{C}} = \begin{bmatrix} [\vec{b}_1]_{\mathcal{C}} & [\vec{b}_2]_{\mathcal{C}} \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

Since $[\vec{b}_1]_{\mathcal{C}} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$ and $[\vec{b}_2]_{\mathcal{C}} = \begin{bmatrix} -6 \\ 1 \end{bmatrix}$, the equation (vi) becomes

$$[\vec{x}]_{\mathcal{C}} = \begin{bmatrix} 4 & -6 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 4 \end{bmatrix}$$

Hence $[\vec{x}]_{\mathcal{C}} = \begin{bmatrix} 6 \\ 4 \end{bmatrix}$, that is $\vec{x} = 6\vec{c}_1 + 4\vec{c}_2$.

Theorem 7.2. Let $\mathcal{B} = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\}$ and $\mathcal{C} = \{\vec{c}_1, \vec{c}_2, \dots, \vec{c}_n\}$ be bases of an n -dimensional vector space V . Then there is a unique matrix $P_{\mathcal{C} \leftarrow \mathcal{B}}$ such that

$$[\vec{x}]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}} [\vec{x}]_{\mathcal{B}}$$

The columns of $P_{\mathcal{C} \leftarrow \mathcal{B}}$ are the \mathcal{C} -coordinate vectors of the vectors in the basis \mathcal{B} . That is

$$(vii) \quad P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} [\vec{b}_1]_{\mathcal{C}} & [\vec{b}_2]_{\mathcal{C}} & \cdots & [\vec{b}_n]_{\mathcal{C}} \end{bmatrix}$$

Note 7.3. The columns of $P_{\mathcal{C} \leftarrow \mathcal{B}}$ are linearly independent, hence $P_{\mathcal{C} \leftarrow \mathcal{B}}$ is invertible. Multiplying the equality (vi) by $(P_{\mathcal{C} \leftarrow \mathcal{B}})^{-1}$ yields

$$(P_{\mathcal{C} \leftarrow \mathcal{B}})^{-1}[\vec{x}]_{\mathcal{C}} = [\vec{x}]_{\mathcal{B}}$$

Thus the matrix $(P_{\mathcal{C} \leftarrow \mathcal{B}})^{-1}$ is the matrix that convert \mathcal{C} -coordinates to \mathcal{B} -coordinates, that is

$$P_{\mathcal{B} \leftarrow \mathcal{C}} = (P_{\mathcal{C} \leftarrow \mathcal{B}})^{-1}$$

Change of Basis in \mathbb{R}^n

Recall that the set $\mathcal{E} = \{\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n\}$, where $\vec{e}_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$, is called the standard basis for \mathbb{R}^n . Let $\mathcal{B} = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\}$ be a nonstandard basis for \mathbb{R}^n . We have seen from Section 4 that matrix $P_{\mathcal{B}} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \cdots & \vec{b}_n \end{bmatrix}$, called the change-of-coordinates matrix, converts \mathcal{B} -coordinates to \mathcal{E} -coordinates. If \vec{x} is in \mathbb{R}^n , then

$$\vec{x} = P_{\mathcal{B}}[\vec{x}]_{\mathcal{B}}.$$

That is $P_{\mathcal{B}} = P_{\mathcal{E} \leftarrow \mathcal{B}}$.

Example 7.4. Let $\vec{b}_1 = \begin{bmatrix} -9 \\ 1 \end{bmatrix}$, $\vec{b}_2 = \begin{bmatrix} -5 \\ 1 \end{bmatrix}$, $\vec{c}_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$, and $\vec{c}_2 = \begin{bmatrix} 3 \\ -5 \end{bmatrix}$. Let $\mathcal{B} = \{\vec{b}_1, \vec{b}_2\}$ and $\mathcal{C} = \{\vec{c}_1, \vec{c}_2\}$ be bases for \mathbb{R}^2 . Find the change of coordinates matrix $P_{\mathcal{C} \leftarrow \mathcal{B}}$.

Solution

By Theorem 7.2, $P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} [\vec{b}_1]_{\mathcal{C}} & [\vec{b}_2]_{\mathcal{C}} \end{bmatrix}$. Hence we need to compute $[\vec{b}_1]_{\mathcal{C}}$ and $[\vec{b}_2]_{\mathcal{C}}$. So we solve the following equations

$$\begin{aligned} \vec{b}_1 &= \alpha_1 \vec{c}_1 + \alpha_2 \vec{c}_2 = \begin{bmatrix} \vec{c}_1 & \vec{c}_2 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} \\ \vec{b}_2 &= \beta_1 \vec{c}_1 + \beta_2 \vec{c}_2 = \begin{bmatrix} \vec{c}_1 & \vec{c}_2 \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} \end{aligned}$$

We solve these equations simultaneously by augmenting the coefficient matrix with \vec{b}_1 and \vec{b}_2 and row reducing it to reduced row echelon form.

$$\left[\begin{array}{cc|cc} 1 & 3 & -9 & -5 \\ -4 & -5 & 1 & -1 \end{array} \right] \xrightarrow{R_2 + 4R_1 \rightarrow R_2} \left[\begin{array}{cc|cc} 1 & 3 & -9 & -5 \\ 0 & 7 & -35 & -21 \end{array} \right] \xrightarrow{1/7 R_2 \rightarrow R_2} \left[\begin{array}{cc|cc} 1 & 3 & -9 & -5 \\ 0 & 1 & -5 & -3 \end{array} \right] \xrightarrow{R_1 - 3R_2 \rightarrow R_1} \left[\begin{array}{cc|cc} 1 & 0 & 6 & 4 \\ 0 & 1 & -5 & -3 \end{array} \right]$$

Therefore $[\vec{b}_1]_{\mathcal{C}} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} 6 \\ -5 \end{bmatrix}$ and $[\vec{b}_2]_{\mathcal{C}} = \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$. So $P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} 6 & 4 \\ -5 & -3 \end{bmatrix}$

Note 7.5. Note from the previous example that

$$\left[\begin{array}{cc|cc} \vec{c}_1 & \vec{c}_2 & \vec{b}_1 & \vec{b}_2 \end{array} \right] \sim \left[\begin{array}{cc|cc} I_2 & & P_{\mathcal{C} \leftarrow \mathcal{B}} & \end{array} \right]$$

Fact 7.6. Let $\mathcal{B} = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\}$ and $\mathcal{C} = \{\vec{c}_1, \vec{c}_2, \dots, \vec{c}_n\}$ be nonstandard bases for \mathbb{R}^n . For each \vec{x} in \mathbb{R}^n , we have

$$\vec{x} = P_{\mathcal{B}}[\vec{x}]_{\mathcal{B}}$$

$$\vec{x} = P_{\mathcal{C}}[\vec{x}]_{\mathcal{C}}$$

with $P_{\mathcal{B}} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \dots & \vec{b}_n \end{bmatrix}$ and $P_{\mathcal{C}} = \begin{bmatrix} \vec{c}_1 & \vec{c}_2 & \dots & \vec{c}_n \end{bmatrix}$. Therefore

$$[\vec{x}]_{\mathcal{C}} = P_{\mathcal{C}}^{-1}\vec{x} = P_{\mathcal{C}}^{-1}P_{\mathcal{B}}[\vec{x}]_{\mathcal{B}}$$

So

$$P_{\mathcal{C} \leftarrow \mathcal{B}} = P_{\mathcal{C}}^{-1}P_{\mathcal{B}}$$

$$P_{\mathcal{C} \leftarrow \mathcal{B}}[\vec{x}]_{\mathcal{B}}$$