Output Port	Port Direction	Туре	Description
aircraft_state	External Input	message_aircraft_state_t	Input of the current position, angle, and velocity of the helicopter
cancel_hover	Internal Couple	bool	Signals to cancel current hover sequence
control_yielded	External Output	bool	Signals that the pilot has control
fcc_command_hover	External Output	message_fcc_command_t	Outputs a command to the FCC to hover
fcc_command_velocity	External Output	message_fcc_command_t	Outputs a command to the FCC to change the velocity
hover_criteria_met	Internal Couple	bool	Signals to other models that the aircraft is hovering
land	Internal Couple	bool	Signals the landing sequence
land_requested	External Output	bool	Outputs a command to the FCC to start the landing process
landing_acheived	External Input	bool	Input that the landing sequence has been completed
lp_criteria_met	Internal Couple	message_mavlink_mission_item_t	Signals the the landing point criteria has been met
lp_expired	External Output	message_mavlink_mission_item_t	Outputs that the lp has expired
lp_new	Internal Couple	message_mavlink_mission_item_t	Signals that the supervisor has received a new lp
lp_recv	External Input	message_mavlink_mission_item_t	Input of a new landing point
mission_complete	External Output	bool	Outputs that the mission is complete
notify_pilot	External Output	bool	Outputs to the pilot that they are required to take over
pilot_handover	Internal Couple	message_mavlink_mission_item_t	Signals that the supervisor is giving control to the pilot
pilot_takeover	External Input	bool	Input of the pilot forcibly taking control of the helicopter
plp_ach	External Input	message_mavlink_mission_item_t	Input of the helicopter achieving the planned landing point
request_reposition	Internal Couple	message_mavlink_mission_item_t	Signals to the other models to reposition the helicopter
stabilize	Internal Couple	message_hover_criteria_t	Signal to start the stabilize sequence
start_lze_scan	External Output	bool	Output to the perception control system to scan the landing zone

Message_aircraft_state_t Used to send messages involving the current state of the aircraft. Used to send message involving the current state of the aircraft. In the current state of the current state of the current state. In the current state.	Message Type	Brief	Variables	Data type	Description
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