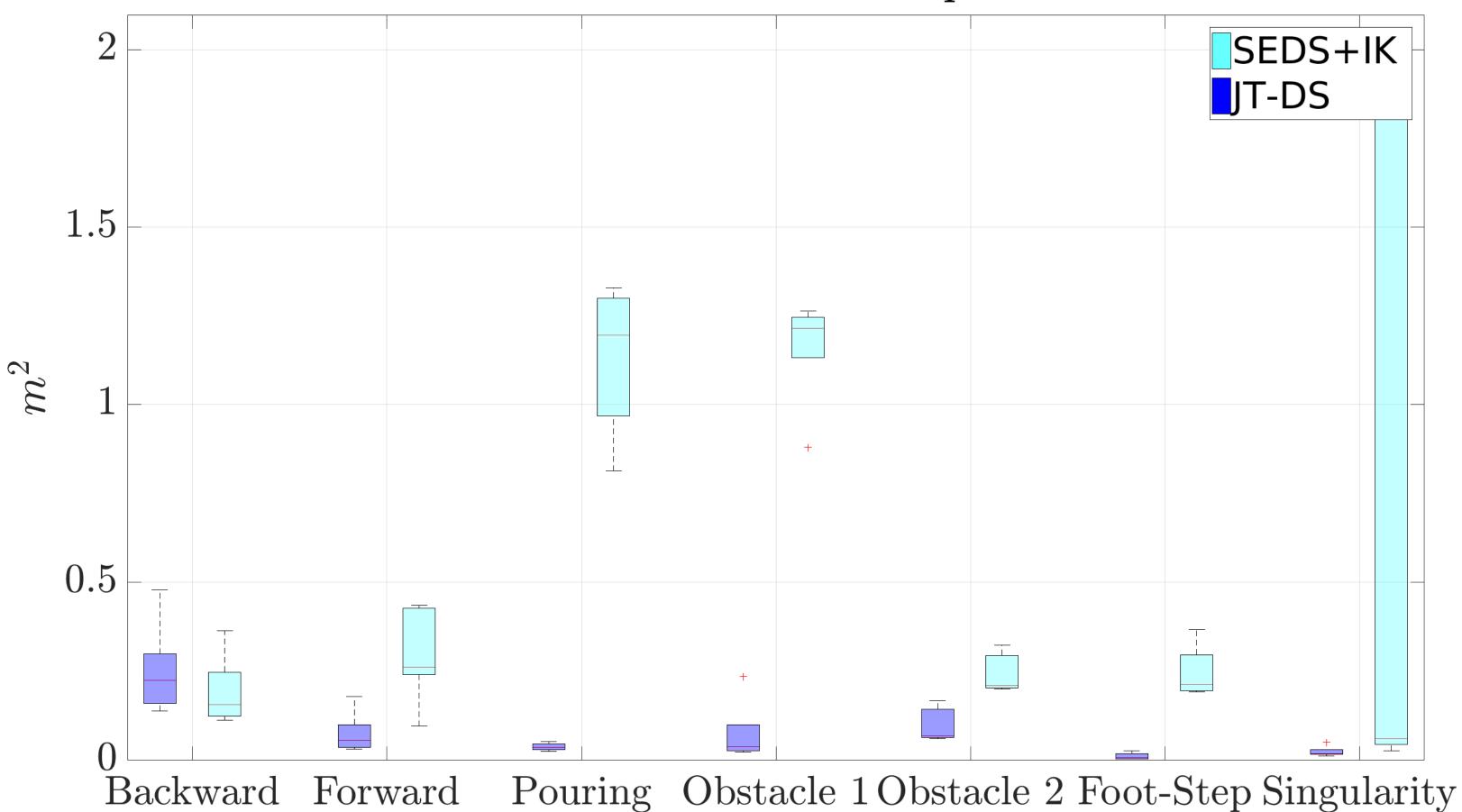
## Distance between the desired target and the final end-effector positions



Scenario