

Kernel Ridge Regression and the Kernel Trick

Machine Learning Course - CS-433
28 Oct 2025
Robert West
(Slide credits: Nicolas Flammarion)



Equivalent formulations for ridge regression

Objective

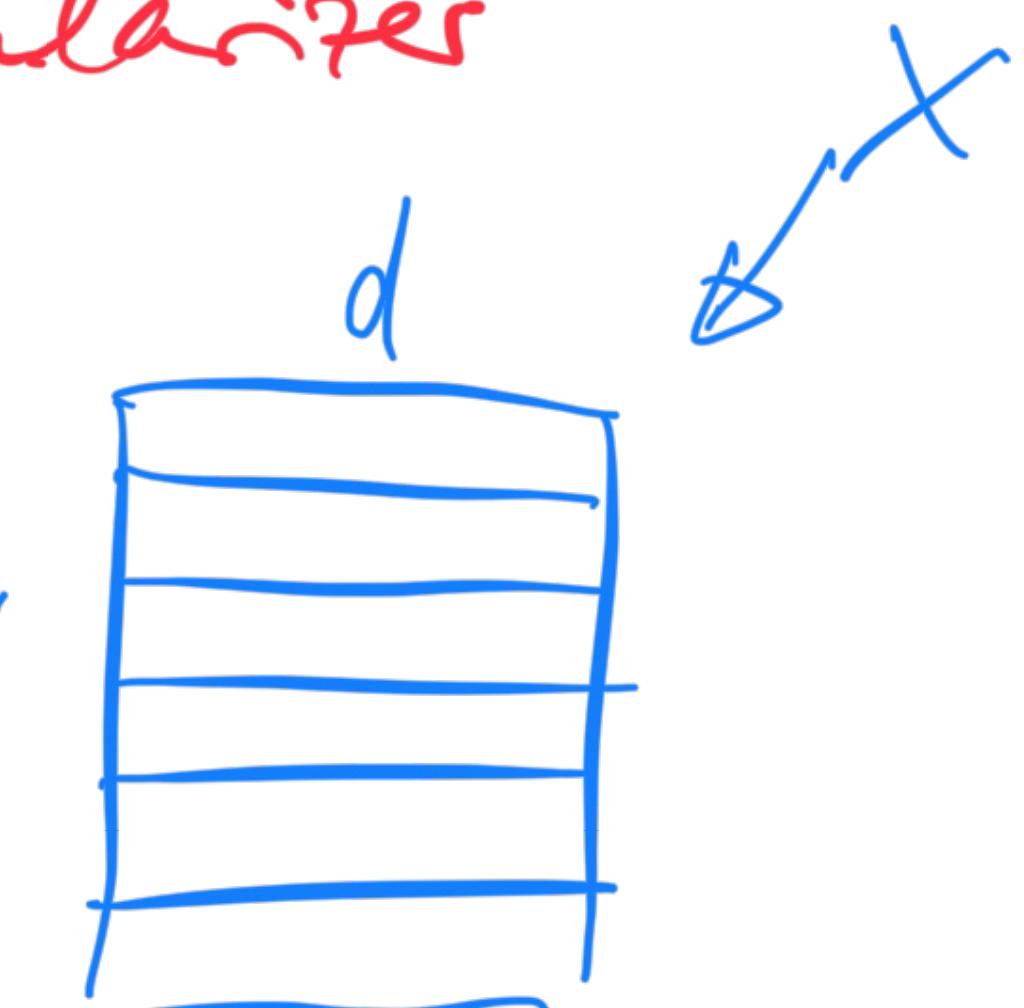
$$\min_w \frac{1}{2N} \sum_{n=1}^N (y_n - w^\top x_n)^2 + \frac{\lambda}{2} \|w\|^2$$

Squared loss *L₂ regularizer*

error

covariance matrix

N *d*



The solution is given by

$$w_* = \frac{1}{N} \left(\underbrace{\frac{1}{N} \mathbf{X}^\top \mathbf{X}}_{d \times d} + \lambda I_d \right)^{-1} \mathbf{X}^\top \mathbf{y}$$

$\mathbf{X}^\top \in \mathbb{R}^{d \times N} \rightarrow d \times d$

Alternatively, the solution can be written as *kernel matrix*

$$w_* = \frac{1}{N} \mathbf{X}^\top \left(\underbrace{\frac{1}{N} \mathbf{X} \mathbf{X}^\top}_{N \times N} + \lambda I_N \right)^{-1} \mathbf{y}$$

$\mathbf{X} \in \mathbb{R}^{N \times d} \rightarrow N \times N$

Proof: Let $P \in \mathbb{R}^{m \times n}$ and $Q \in \mathbb{R}^{n \times m}$

$$P(QP + I_n) = PQP + P = (PQ + I_m)P$$

Assuming that both $QP + I_n$ and $PQ + I_m$ are invertible

$$(PQ + I_m)^{-1}P = P(QP + I_n)^{-1}$$

We deduce the result with $P = \mathbf{X}^\top$ and $Q = \frac{1}{\lambda N} \mathbf{X}$

$$\mathbf{w}_* = \frac{1}{N} \left(\underbrace{\frac{1}{N} \mathbf{X}^\top \mathbf{X}}_{\mathbf{X}^\top \in \mathbb{R}^{d \times N} \rightarrow d \times d} + \lambda I_d \right)^{-1} \mathbf{X}^\top \mathbf{y}$$

But it can be alternatively written as

$$\mathbf{w}_* = \frac{1}{N} \mathbf{X}^\top \left(\underbrace{\frac{1}{N} \mathbf{X} \mathbf{X}^\top}_{\mathbf{X} \in \mathbb{R}^{N \times d} \rightarrow N \times N} + \lambda I_N \right)^{-1} \mathbf{y}$$

Usefulness of the alternative form

$$w_* = \frac{1}{N} \underbrace{\mathbf{X}^\top}_{d \times N} \underbrace{\left(\frac{1}{N} \mathbf{X} \mathbf{X}^\top + \lambda I_N \right)^{-1}}_{N \times N} \mathbf{y}$$

1. Computational complexity:

- For the original formulation $\frac{1}{N} \left(\frac{1}{N} \mathbf{X}^\top \mathbf{X} + \lambda I_d \right)^{-1} \mathbf{X}^\top \mathbf{y}$, $O(d^3 + Nd^2)$

- For the new formulation $\frac{1}{N} \mathbf{X}^\top \left(\frac{1}{N} \mathbf{X} \mathbf{X}^\top + \lambda I_N \right)^{-1} \mathbf{y}$, $O(N^3 + dN^2)$

→ Depending on d, N one formulation may be more efficient than the other
 $\alpha_* \in \mathbb{R}^N$

2. Structural difference:

$$w_* = \mathbf{X}^\top \alpha_* \quad \text{where } \alpha_* = \frac{1}{N} \left(\frac{1}{N} \mathbf{X} \mathbf{X}^\top + \lambda I_N \right)^{-1} \mathbf{y}$$

→ $w_* \in \text{span}\{x_1, \dots, x_N\}$

These two insights are fundamental to understanding the **kernel trick**

Representer Theorem

previous slide:
 $\ell(x^T w, y) = \frac{(y - x^T w)^2}{|y - x^T w|}$

Claim: For any loss function ℓ , and any minimizer

$$w_* \in \arg \min_w \frac{1}{N} \sum_{n=1}^N \ell(x_n^T w, y_n) + \frac{\lambda}{2} \|w\|^2$$

there exists $\alpha_* \in \mathbb{R}^N$ such that

$$w_* = \underline{\mathbf{X}^T \alpha_*}$$

Meaning: There exists an optimal solution within $\text{span}\{x_1, \dots, x_N\}$

Consequence: This is more general than LS, enabling the kernel trick to various problems, including Kernel SVM, Kernel LS, and Kernel Principal Component Analysis

Proof of the representer theorem

Let w_* be an optimal solution of $\min_w \frac{1}{N} \sum_{n=1}^N \ell(x_n^\top w, y_n) + \frac{\lambda}{2} \|w\|^2$

We can always rewrite w_* as $w_* = \sum_{n=1}^N \alpha_n x_n + u$ where $u^\top x_n = 0$ for all n

Let's define $w = w_* - u$

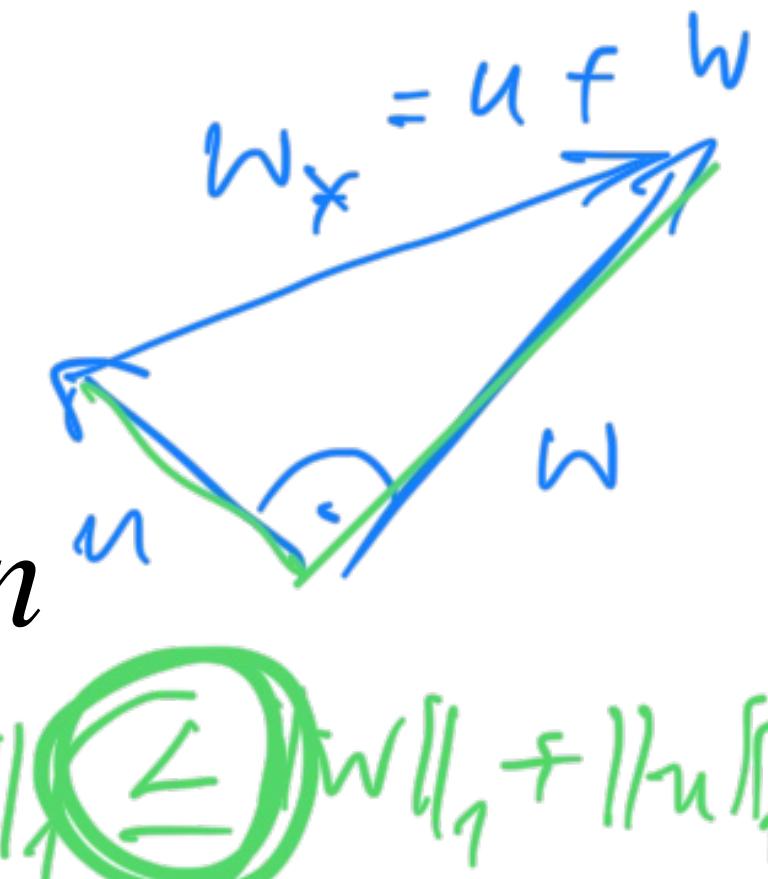
• $\|w_*\|^2 = \|w\|^2 + \|u\|^2$, thus $\|w\|^2 \leq \|w_*\|^2$

• For all n , $w^\top x_n = (w_* - u)^\top x_n = w_*^\top x_n$, thus $\ell(x_n^\top w, y_n) = \ell(x_n^\top w_*, y_n)$

Therefore $\frac{1}{N} \sum_{n=1}^N \ell(x_n^\top w, y_n) + \frac{\lambda}{2} \|w\|^2 \leq \frac{1}{N} \sum_{n=1}^N \ell(x_n^\top w_*, y_n) + \frac{\lambda}{2} \|w_*\|^2$

By definition of w_* , $\frac{1}{N} \sum_{n=1}^N \ell(x_n^\top w_*, y_n) + \frac{\lambda}{2} \|w_*\|^2 \leq \frac{1}{N} \sum_{n=1}^N \ell(x_n^\top w, y_n) + \frac{\lambda}{2} \|w\|^2$

Hence $\|w_*\|^2 = \|w\|^2$ and $u = 0$. Thus $w_* = w = \sum_{n=1}^N \alpha_n x_n$



Kernelized ridge regression

Classic formulation in w :

$$w_* = \arg \min_w \frac{1}{2N} \|y - Xw\|^2 + \frac{\lambda}{2} \|w\|^2$$

Alternative formulation in α :

$$\alpha_* = \arg \min_{\alpha} \frac{1}{2} \alpha^T \left(\frac{1}{N} \mathbf{X} \mathbf{X}^T + \lambda I_N \right) \alpha - \frac{1}{N} \alpha^T y$$

Claim: These two formulations are equivalent

Proof: Set the gradient to 0, to obtain $\alpha_* = \frac{1}{N} \left(\frac{1}{N} \mathbf{X} \mathbf{X}^T + \lambda I_N \right)^{-1} y$, and $w_* = \mathbf{X}^T \alpha_*$

Key takeaways:

- Computational complexity - depending on d, N
- The dual formulation only uses \mathbf{X} through the kernel matrix $\mathbf{K} = \mathbf{X} \mathbf{X}^T$

Kernel matrix

$$x_i^T x_j = x_j^T x_i$$

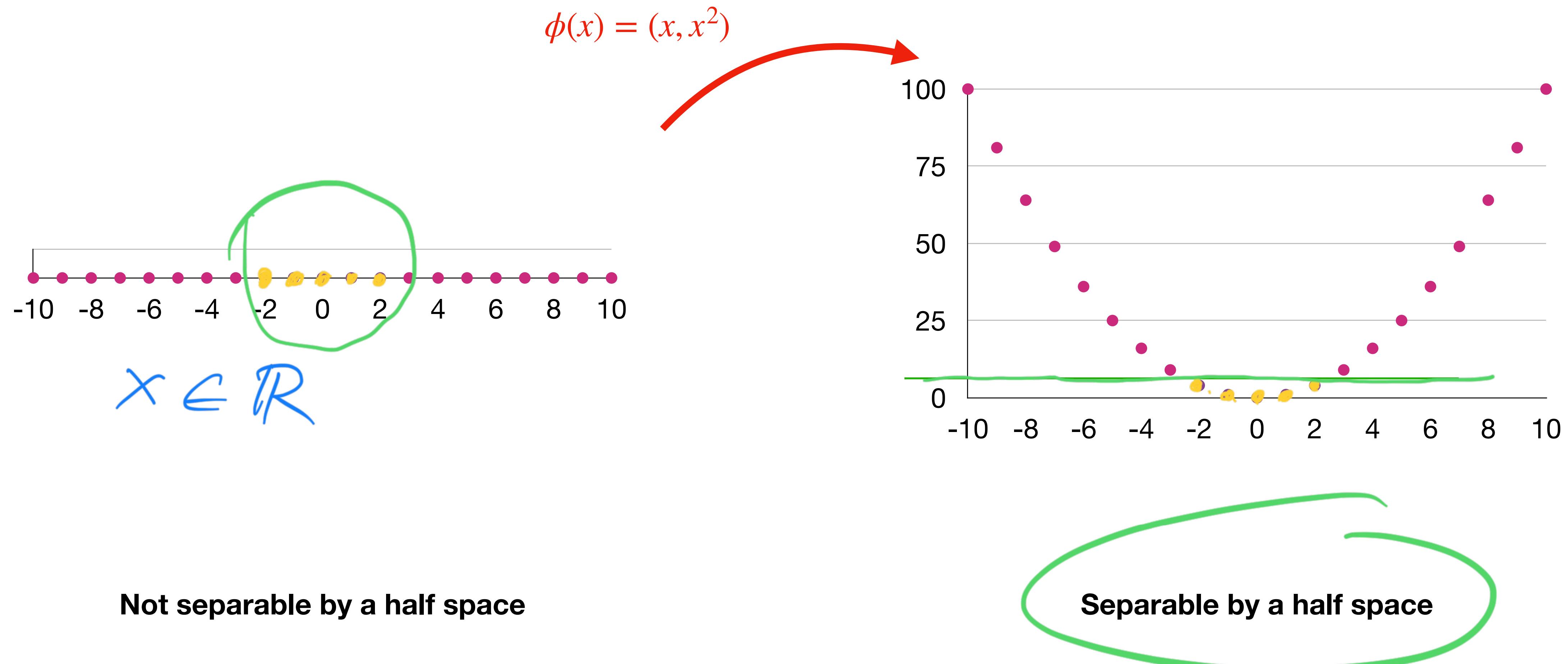


$$u^T v = \|u\| \cdot \|v\| \cdot \cos(\alpha)$$

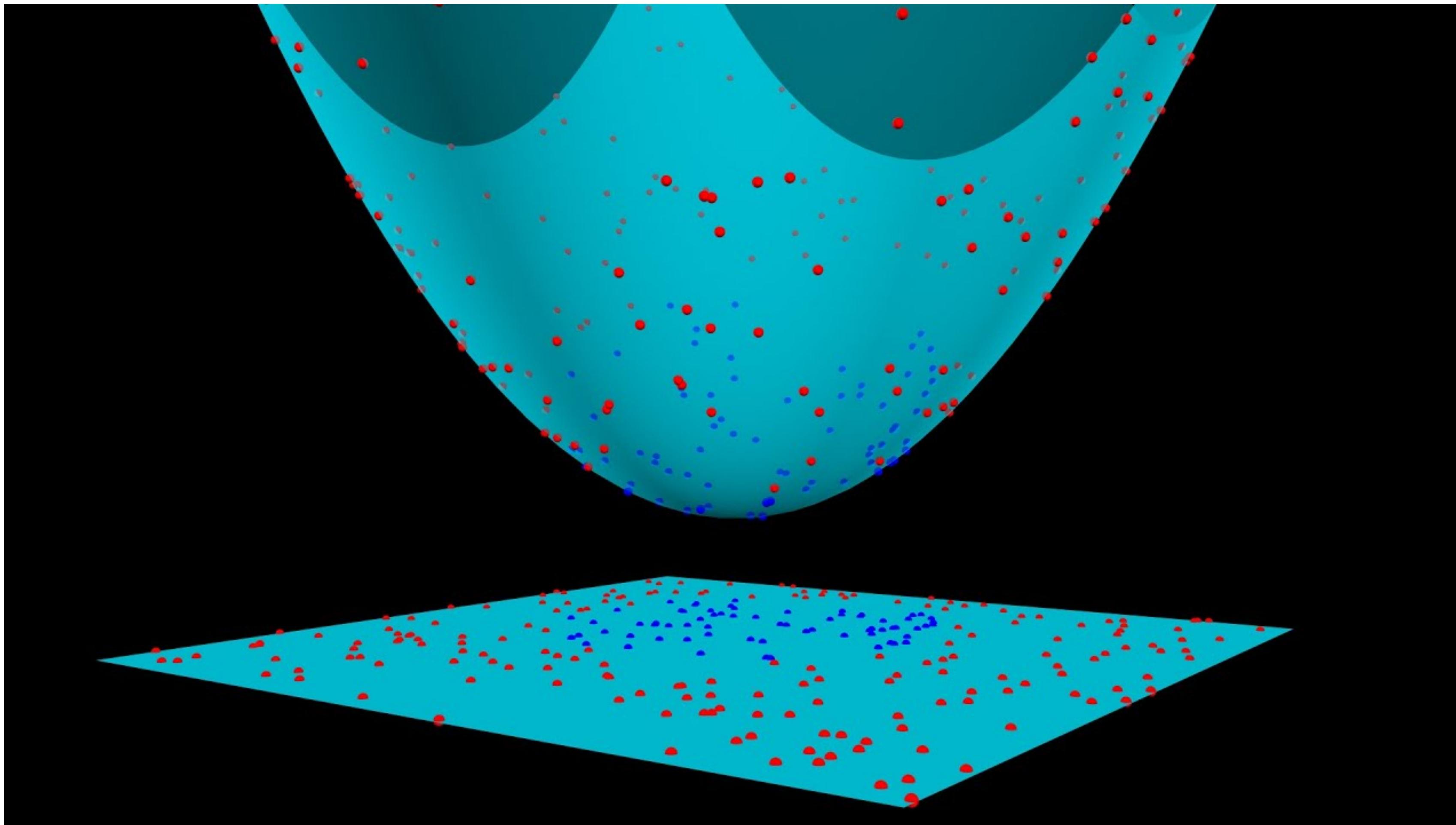
$$\mathbf{K} = \mathbf{X} \mathbf{X}^T = \begin{pmatrix} x_1^T x_1 & x_1^T x_2 & \cdots & x_1^T x_N \\ x_2^T x_1 & x_2^T x_2 & \cdots & x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ x_N^T x_1 & x_N^T x_2 & \cdots & x_N^T x_N \end{pmatrix} = (x_i^T x_j)_{i,j} \in \mathbb{R}^{N \times N}$$



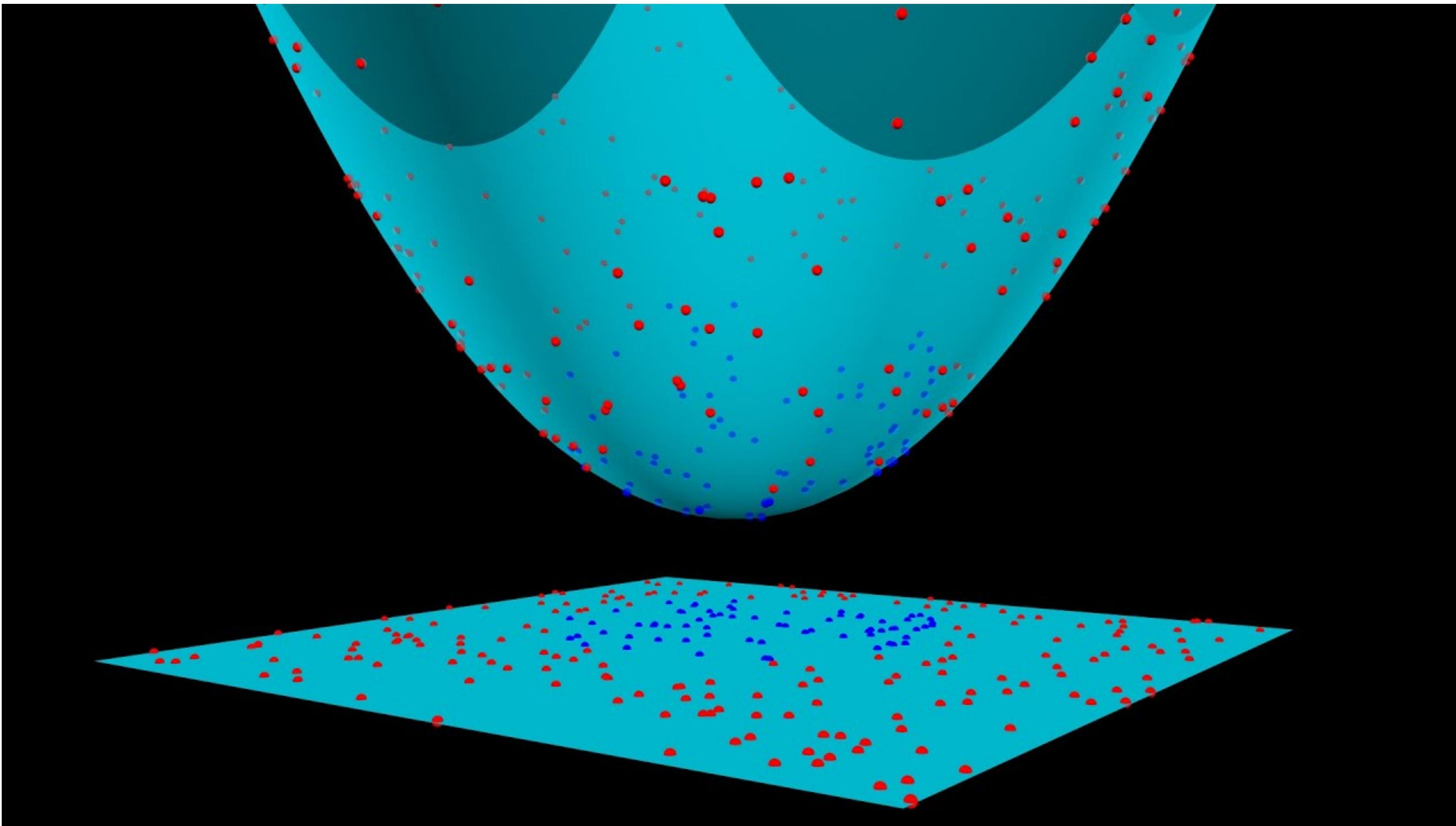
Embedding into feature spaces



Usefulness of feature spaces



Usefulness of feature spaces



Kernel matrix with feature spaces

When a feature map $\phi: \mathbb{R}^d \rightarrow \mathbb{R}^{\tilde{d}}$ is used,

$$(x_n)_{n=1}^N \hookrightarrow (\phi(x_n))_{n=1}^N$$

The associated kernel matrix is

$$\mathbf{K} = \Phi\Phi^\top = \begin{pmatrix} \phi(x_1)^\top \phi(x_1) & \phi(x_1)^\top \phi(x_2) & \cdots & \phi(x_1)^\top \phi(x_N) \\ \phi(x_2)^\top \phi(x_1) & \phi(x_2)^\top \phi(x_2) & \cdots & \phi(x_2)^\top \phi(x_N) \\ \vdots & \vdots & \ddots & \vdots \\ \phi(x_N)^\top \phi(x_1) & \phi(x_N)^\top \phi(x_2) & \cdots & \phi(x_N)^\top \phi(x_N) \end{pmatrix} \in \mathbb{R}^{N \times N}$$

Problem: when $d \ll \tilde{d}$ computing $\phi(x)^\top \phi(x')$ costs $O(\tilde{d})$ - too expensive

Kernel trick

Kernel function: $\kappa(x, x')$ such that

$$\kappa(x, x') = \phi(x)^\top \phi(x')$$

Similarity between x and x'

Similarity realized as an inner product in the feature space

It is equivalent to

- Directly compute $\kappa(x, x')$
- First map the features to $\phi(x)$, then compute $\phi(x)^\top \phi(x')$

Kernel trick

Kernel function: $\kappa(x, x')$ such that

$$\kappa(x, x') = \phi(x)^\top \phi(x')$$

Similarity between x and x'

Similarity realized as an inner product in the feature space

It is equivalent to

- Directly compute $\kappa(x, x')$
- First map the features to $\phi(x)$, then compute $\phi(x)^\top \phi(x')$

Purpose: enable computation of linear classifiers in high-dimensional space without performing computations in this high-dimensional space directly.

Predicting with kernels

$$\phi(x) = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$$

Problem: The prediction is $y = \phi(x)^T w_*$ but computing $\phi(x)$ can be expensive

Question: How can we make predictions using only the kernel function, without the need to compute $\phi(x)$?

$$\text{Answer: } \phi(x)^T w_* = \phi(x)^T \phi(X)^T \alpha_* = \sum_{n=1}^N \kappa(x, x_n) \alpha_{*n}$$

$$w_* = \phi(X)^T \alpha_*$$

We can do a prediction only using the kernel function

Important remark:

$$y = \phi(x)^T w_* = f_{w_*}(x)$$

Linear prediction
in the feature space

Non linear prediction
in the \mathcal{X} space

Examples of kernel (easy)

1. Linear kernel: $\kappa(x, x') = x^T x'$

→ Feature map is $\phi(x) = x$

2. Quadratic kernel: $\kappa(x, x') = \underline{(xx')^2}$ for $x, x' \in \mathbb{R}$

→ Feature map is $\phi(x) = x^2$

$$\phi(x)^T \phi(x') = x^2 \cdot x'^2 = (x \cdot x')^2 = \kappa(x, x')$$

3. Polynomial kernel

$$\begin{aligned}(x^T x')^d \\ (x^T x' + 1)^d\end{aligned}$$

Let $x, x' \in \mathbb{R}^3$

$$\kappa(x, x') = \underbrace{(x_1 x'_1 + x_2 x'_2 + x_3 x'_3)^2}_{x^T x'}^d$$

Feature map:

$$\phi(x) = [x_1^2, x_2^2, x_3^2, \sqrt{2}x_1x_2, \sqrt{2}x_1x_3, \sqrt{2}x_2x_3] \in \mathbb{R}^6$$

Proof:

$$\underline{\kappa(x, x')} = \underline{\phi(x)^T \phi(x')}$$

$$\begin{aligned}\kappa(x, x') &= \underline{(x_1 x'_1 + x_2 x'_2 + x_3 x'_3)^2} \\ &= (x_1 x'_1)^2 + (x_2 x'_2)^2 + (x_3 x'_3)^2 + 2x_1 x_2 x'_1 x'_2 + 2x_1 x_3 x'_1 x'_3 + 2x_2 x_3 x'_2 x'_3 \\ &= (x_1^2, x_2^2, x_3^2, \sqrt{2}x_1x_2, \sqrt{2}x_1x_3, \sqrt{2}x_2x_3)^T (x'_1^2, x'_2^2, x'_3^2, \sqrt{2}x'_1 x'_2, \sqrt{2}x'_1 x'_3, \sqrt{2}x'_2 x'_3)\end{aligned}$$

We obtain ϕ by identification

4. Radial basis function (RBF) kernel

Let $x, x' \in \mathbb{R}^d$

For $x, x' \in \mathbb{R}$

Feature map:

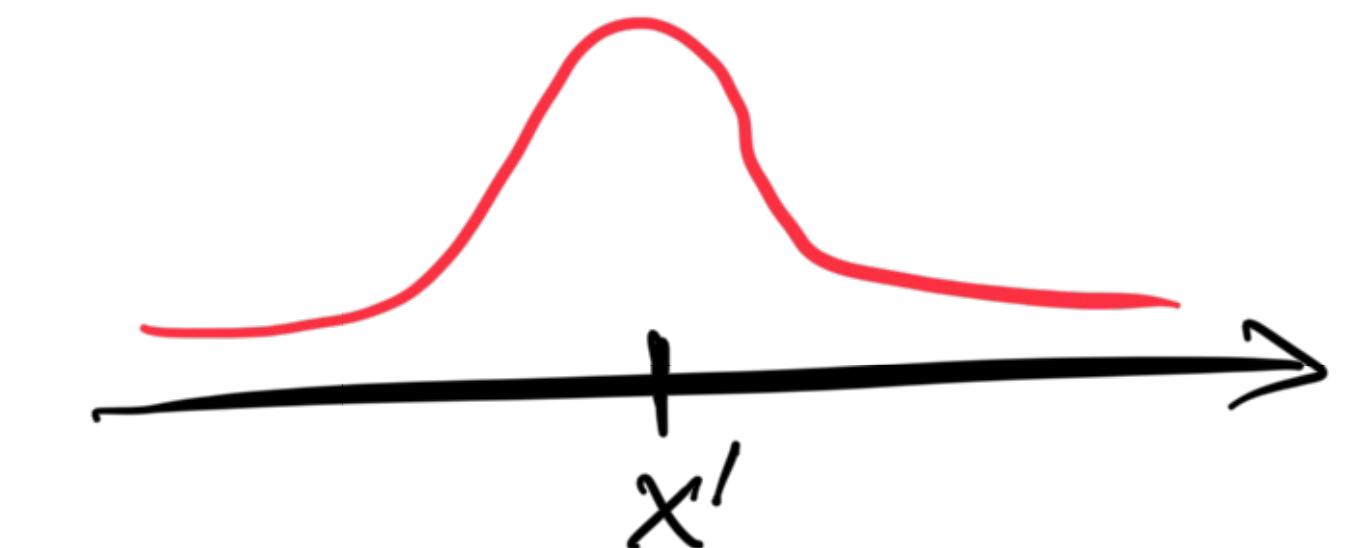
$$\text{Proof: } \kappa(x, x') = e^{-x^2 - x'^2 + 2xx'} = e^{-x^2} e^{-x'^2} \sum_{k=0}^{\infty} \frac{2^k x^k x'^k}{k!} \quad \text{by the Taylor expansion of } \exp$$

$$\phi(x) = e^{-x^2} \left(\dots, \frac{2^{k/2} x^k}{\sqrt{k!}}, \dots \right) \implies \phi(x)^\top \phi(x') = \kappa(x, x')$$

$$\kappa(x, x') = e^{-\frac{(x-x')^\top (x-x')}{\|x-x'\|^2}}$$

$$\kappa(x, x') = e^{-\frac{(x-x')^2}{2}}$$

$$e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$$



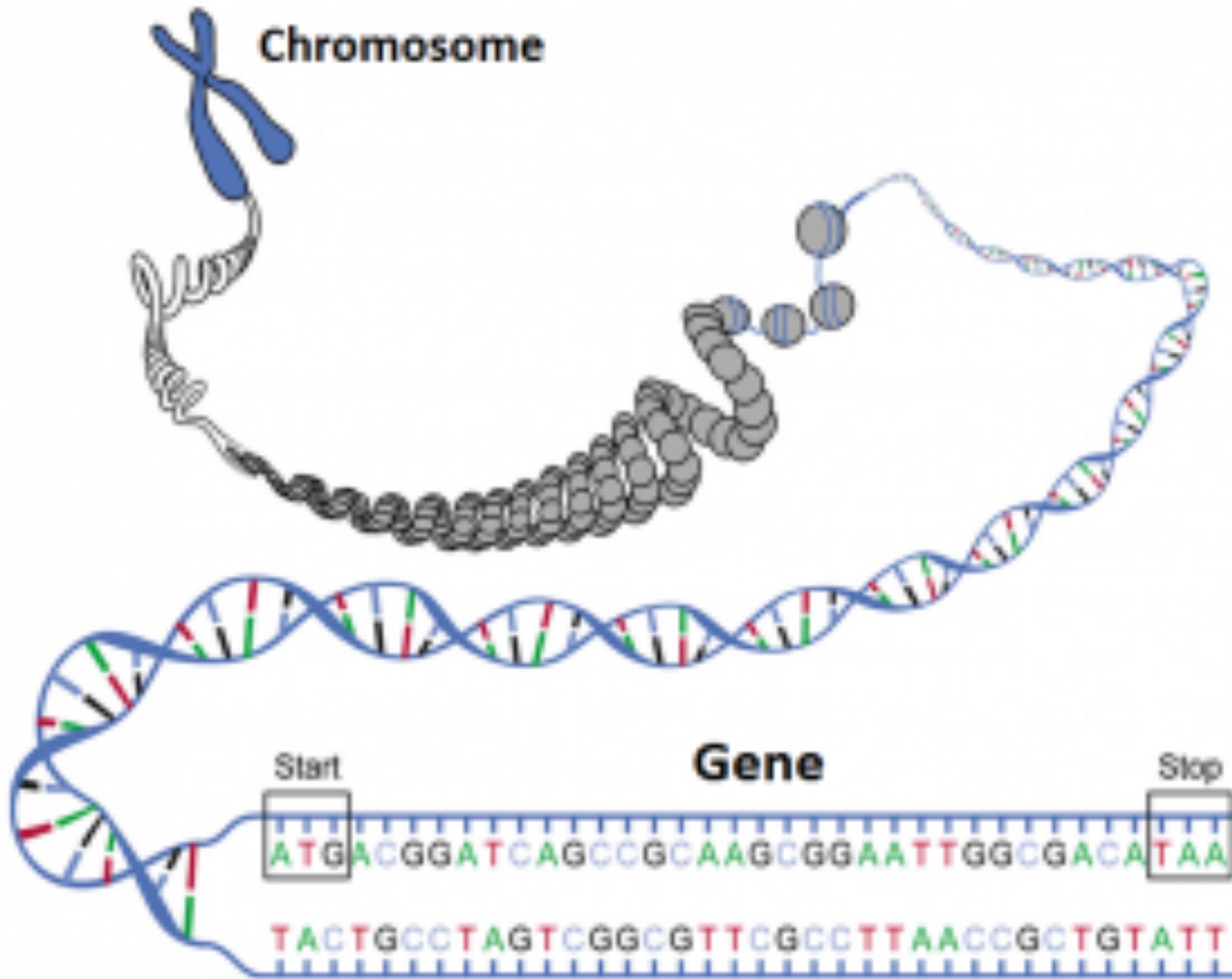
$$\phi(x) = e^{-x^2} \left(\dots, \frac{2^{k/2} x^k}{\sqrt{k!}}, \dots \right)$$

$$e^{2xx'} = \sum_{k=0}^{\infty} \frac{2^k x^k x'^k}{k!} = \sum_{k=0}^{\infty} \frac{2^k x^k}{\sqrt{k!}} \cdot \frac{2^{\frac{k}{2}} x'^k}{\sqrt{k!}}$$

Infinite dimensional vector

Interest: it cannot be represented as an inner product in a finite-dimensional space

4. String kernels



$$\varphi_u : \begin{cases} \Sigma^n \rightarrow \mathbb{R}^{\Sigma^n} \\ s \mapsto \sum_{i: u=s_i} \lambda^{l(i)} \end{cases}$$

Building new kernels from existing kernels

Let κ_1, κ_2 be two kernel functions and ϕ_1, ϕ_2 the corresponding feature maps

Claim 1: Positive linear combinations of kernel are kernels

$$\kappa(x, x') = \alpha\kappa_1(x, x') + \beta\kappa_2(x, x') \text{ for } \alpha, \beta \geq 0$$

Claim 2: Products of kernels are kernels

$$\kappa(x, x') = \kappa_1(x, x')\kappa_2(x, x')$$

Objective: To provide building blocks for deriving new kernels

Proof 1:

$$\begin{aligned}\kappa(x, x') &= \alpha\kappa_1(x, x') + \beta\kappa_2(x, x') \\ &= \alpha\phi_1(x)^\top\phi_1(x') + \beta\phi_2(x)^\top\phi_2(x') \\ &= \phi(x)^\top\phi(x')\end{aligned}$$

where $\phi(x) = \begin{pmatrix} \sqrt{\alpha}\phi_1(x) \\ \sqrt{\beta}\phi_2(x) \end{pmatrix} \in \mathbb{R}^{d_1+d_2}$

kernels from old kernel

is and ϕ_1, ϕ_2 the corresponding feature maps

Claim 1: Positive linear combinations of kernel are kernel

$$\kappa(x, x') = \alpha\kappa_1(x, x') + \beta\kappa_2(x, x')$$

Claim 2: Products of kernels are kernel

$$\kappa(x, x') = \kappa_1(x, x')\kappa_2(x, x')$$

Proof 2:

$$\begin{aligned}\kappa(x, x') &= \kappa_1(x, x')\kappa_2(x, x') \\ &= \phi_1(x)^\top \phi_1(x') \phi_2(x)^\top \phi_2(x')\end{aligned}$$

Let

$$\begin{aligned}\phi(x) &= ((\phi_1(x))_i(\phi_2(x))_j)_{1 \leq i \leq d_1, 1 \leq j \leq d_2} \in \mathbb{R}^{d_1 d_2} \\ &= ((\phi_1(x))_1(\phi_2(x))_1, \dots, (\phi_1(x))_1(\phi_2(x))_{d_2}, \dots, (\phi_1(x))_{d_1}(\phi_2(x))_1, \dots, (\phi_1(x))_{d_1}(\phi_2(x))_{d_2})^\top\end{aligned}$$

then

$$\begin{aligned}\phi(x)^\top \phi(x') &= \sum_l (\phi(x))_l (\phi(x'))_l \\ &= \sum_{i,j} (\phi_1(x))_i (\phi_2(x))_j (\phi_1(x'))_i (\phi_2(x'))_j \\ &= \sum_i (\phi_1(x))_i (\phi_1(x'))_i \sum_j (\phi_2(x))_j (\phi_2(x'))_j \\ &= \phi_1(x)^\top \phi_1(x') \phi_2(x)^\top \phi_2(x') = \kappa(x, x')\end{aligned}$$

Claim 2: Products of kernels are kernel

$$\kappa(x, x') = \kappa_1(x, x')\kappa_2(x, x')$$

Mercer's condition

Question: Given a kernel function κ , how can we ensure the existence of a feature map ϕ such that

$$\kappa(x, x') = \phi(x)^\top \phi(x')$$

Answer: It is true if and only if the following Mercer's conditions are fulfilled:

- The kernel function is symmetric:

$$\forall x, x', \kappa(x, x') = \kappa(x', x)$$

- The kernel matrix is psd for all possible input sets:

$$\forall N \geq 0, \forall (x_n)_{n=1}^N, \mathbf{K} = (\kappa(x_i, x_j))_{i,j=1}^N \succeq 0$$

Recap

- Many algorithms (SVM, Least Squares, PCA, etc) can be rewritten so that they rely only on inner products between data points ($\mathbf{X}\mathbf{X}^T$)
- This motivates to generalize the inner products with **kernels** to make the model non-linear in the input space
- This can improve efficiency by avoiding a direct computation of feature maps $\phi(x)$ of a potentially high-dimensional space
- To predict with kernels, you need to compute the similarity $k(x, x_i)$ of a new point x with every training point x_i
- You can derive new kernels using a certain set of properties

Bonus: proof of Mercer theorem

- If κ represents an inner product then it is symmetric and the kernel matrix is psd:

$$v^\top \mathbf{K} v = \sum_{i,j} v_i v_j \phi(x_i)^\top \phi(x_j) = \left\| \sum_i v_i \phi(x_i) \right\|^2$$

- Define $\phi(x) = \kappa(\cdot, x)$. Define a vector space of functions by considering all linear combinations $\{ \sum_i \alpha_i \kappa(\cdot, x_i) \}$. Define an inner product on this vector space by

$$\langle \sum_i \alpha_i \kappa(\cdot, x_i), \sum_j \beta_j \kappa(\cdot, x'_j) \rangle = \sum_{i,j} \alpha_i \beta_j \kappa(x_i, x'_j)$$

This is a valid inner product (symmetric, bilinear and positive definite, with equality holding only if $\phi(x)$ is the zero function)

Consequently

$$\langle \phi(x), \phi(x') \rangle = \langle \kappa(\cdot, x), \kappa(\cdot, x') \rangle = \kappa(x, x')$$