

Transformers

Machine Learning Course - CS-433

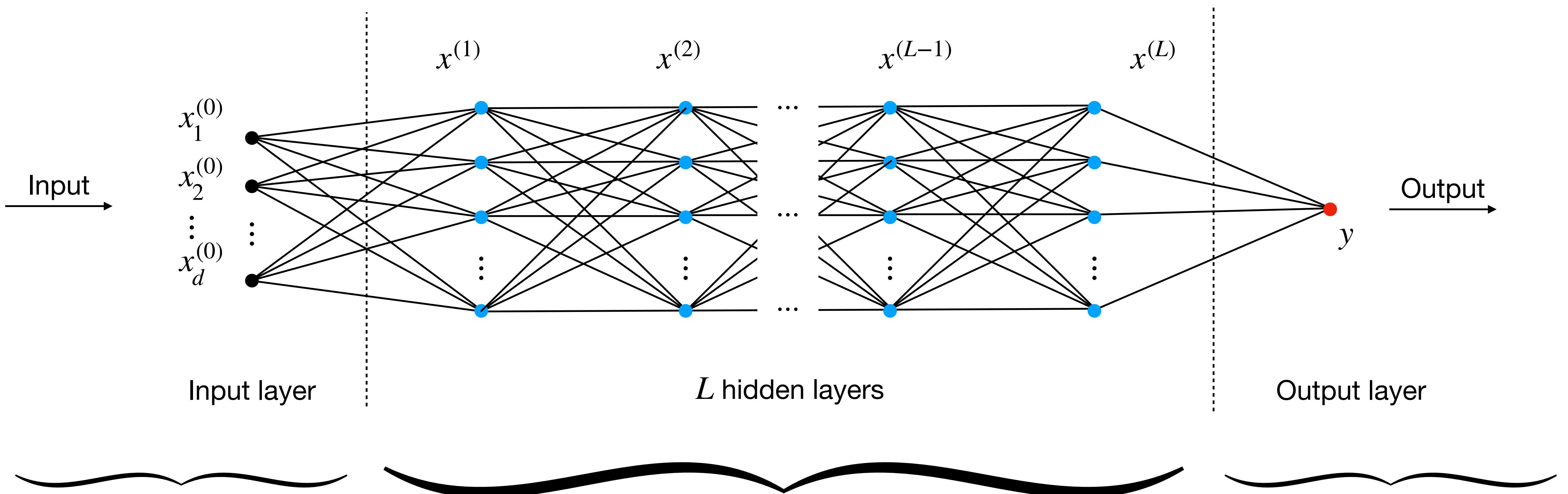
11 Nov 2025

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(Slide credits: Nicolas Flammarion)



So far in this class...



Single datapoint x

Feature extractor:
maps input x
to high-dimensional
feature vector $f(x)$

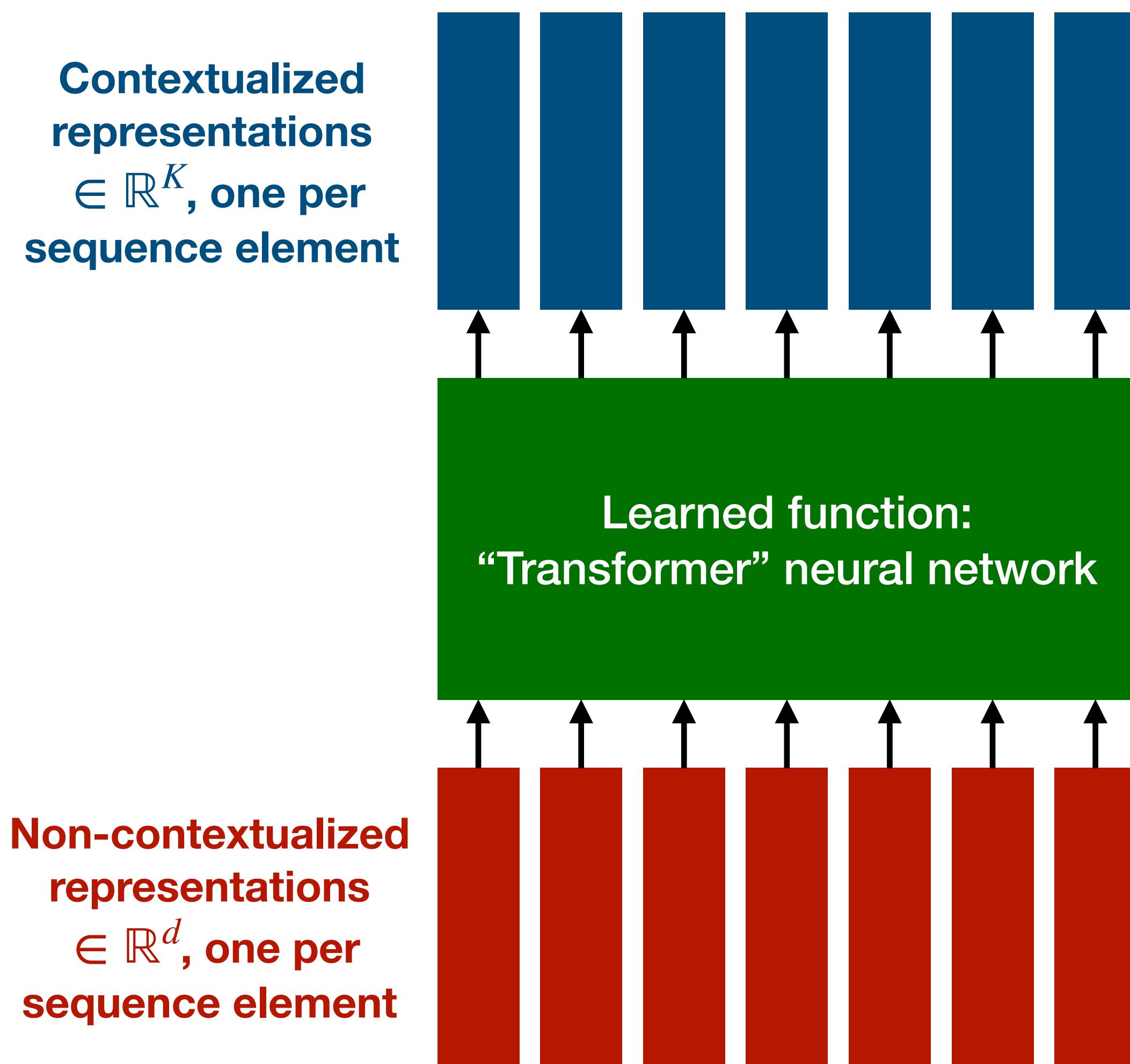
Linear model:
maps feature vector $f(x)$
to one-dimensional
score $f(x)^T w$

Towards richer inputs & outputs

Instead of single-datapoint inputs and 1-dimensional outputs, we may want to ingest and produce richer objects, e.g.,

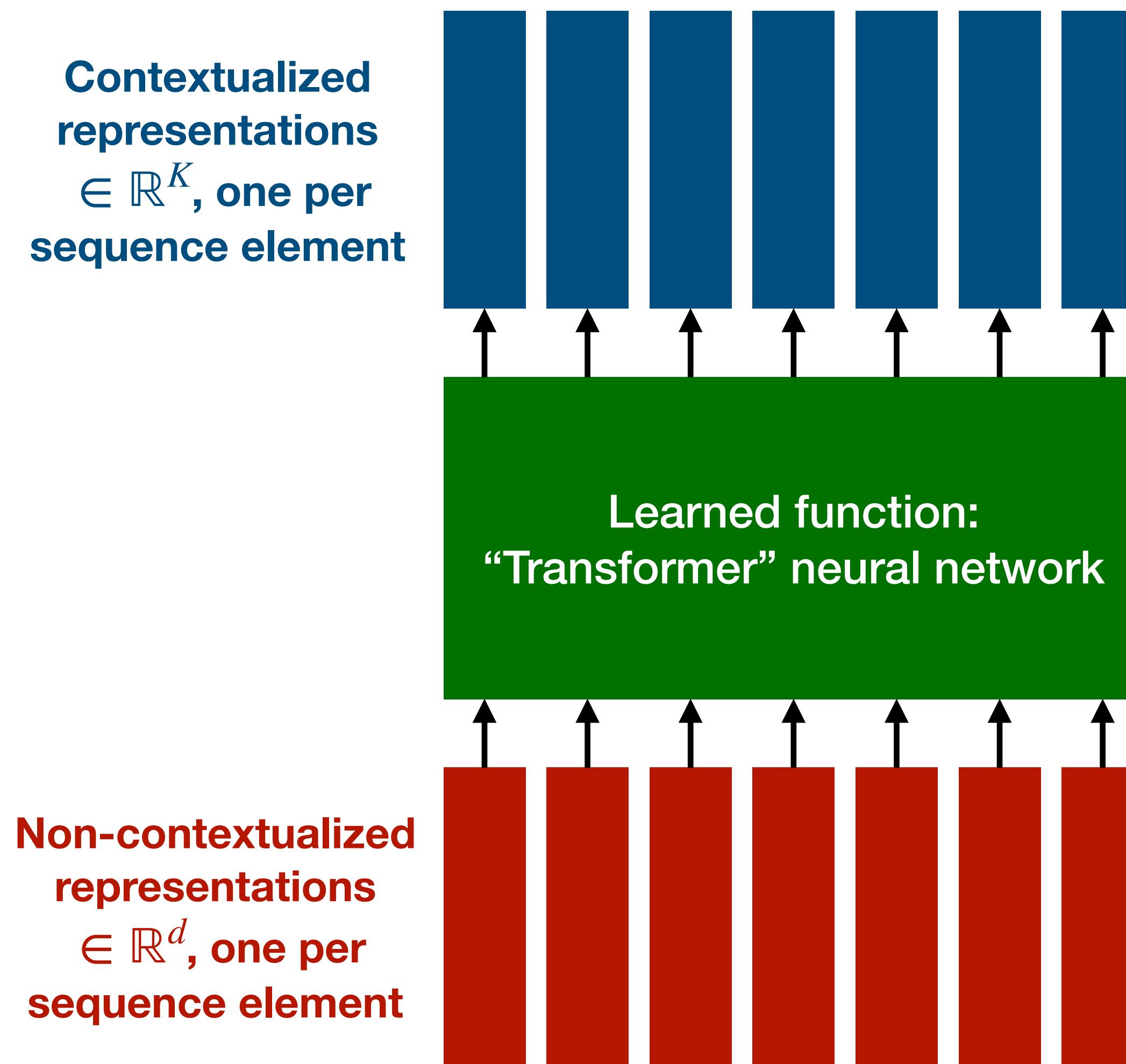
- **Tagging:** for each element in an input *sequence* (or set), make one prediction (not independent of predictions for other elements); e.g., part-of-speech tagging, gene-structure annotation, ...
- **Sequence-to-sequence transduction:** machine translation, question answering, summarization, image-to-text, text-to-image, ...

Basis: contextualized representations



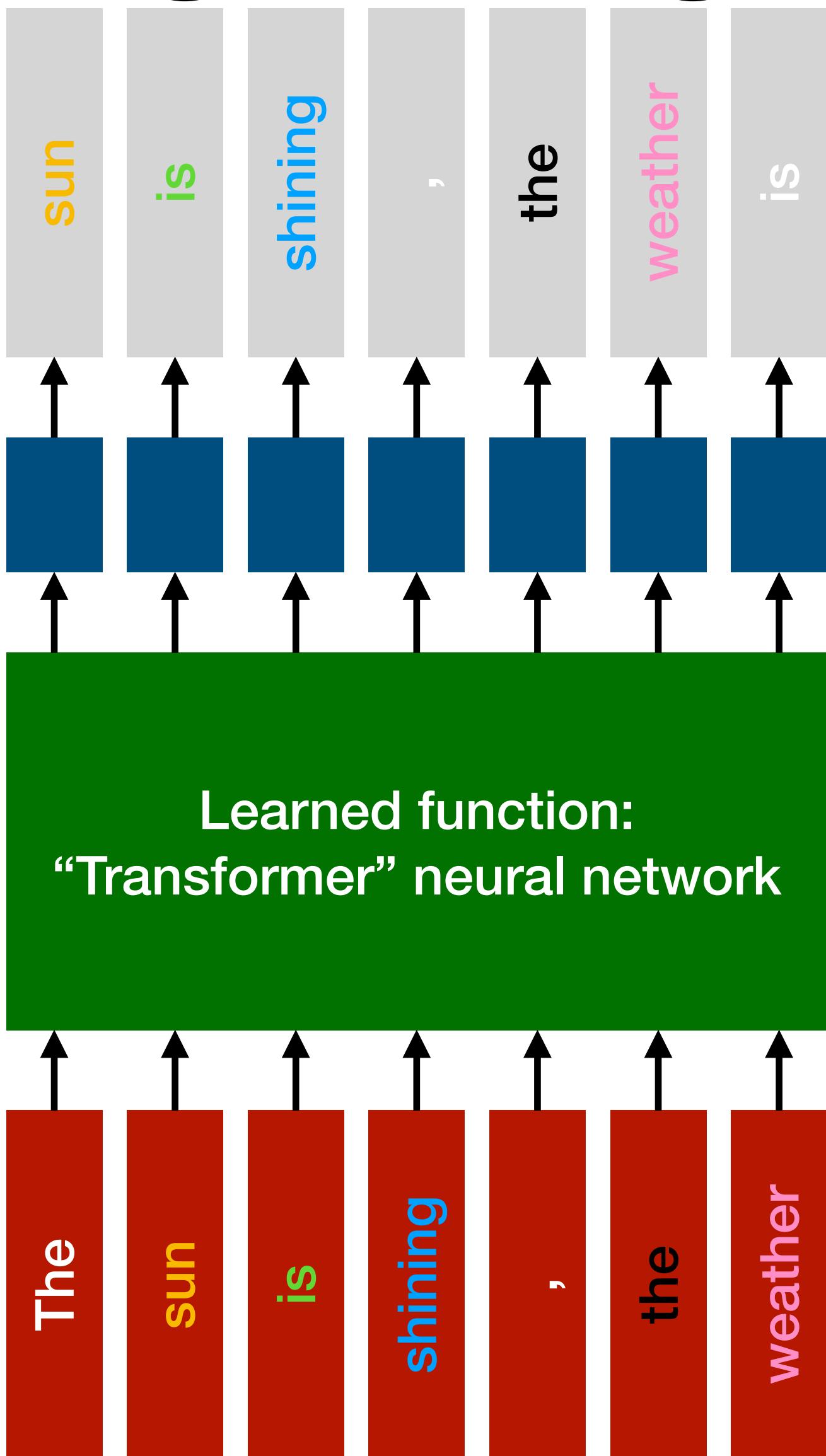
- **Tagging:** linear classifier on top of each contextualized representation, learned together with other params
- **Sequence-to-sequence transduction:** learn function for mapping seq of contextualized representations to seq of outputs (e.g., via next-token prediction, see next slides)
- **Classification** also straightforward: use representation of final seq element as feature vector for entire seq; feed to logistic regression layer (trained together with other params)

LOSS



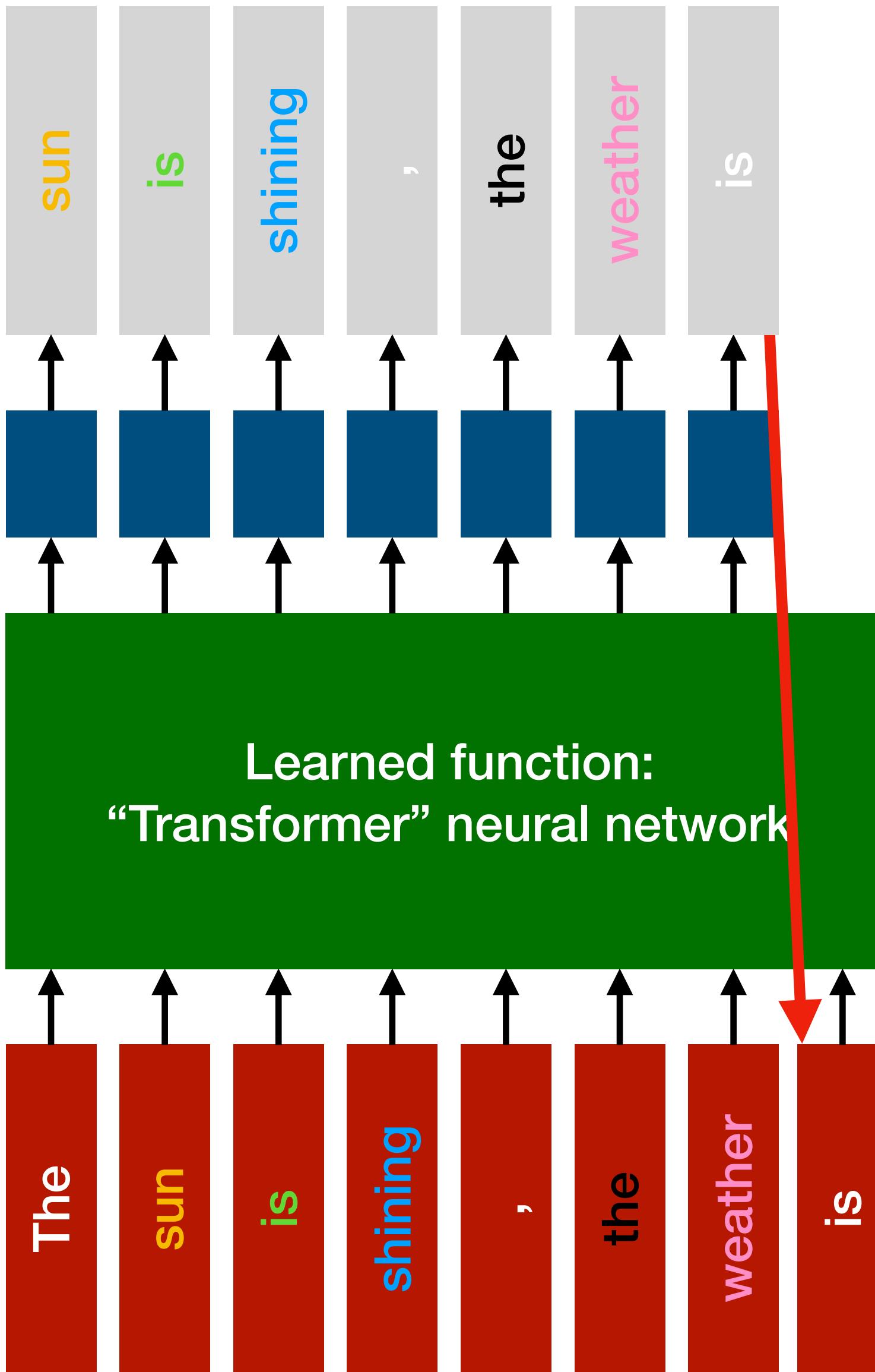
- Depending on your task, feed contextualized representations into an appropriate loss function; minimize via backprop
- Tagging: e.g., one logistic loss per element
- Classification: e.g., logistic loss on final sequence element

Large language models: training



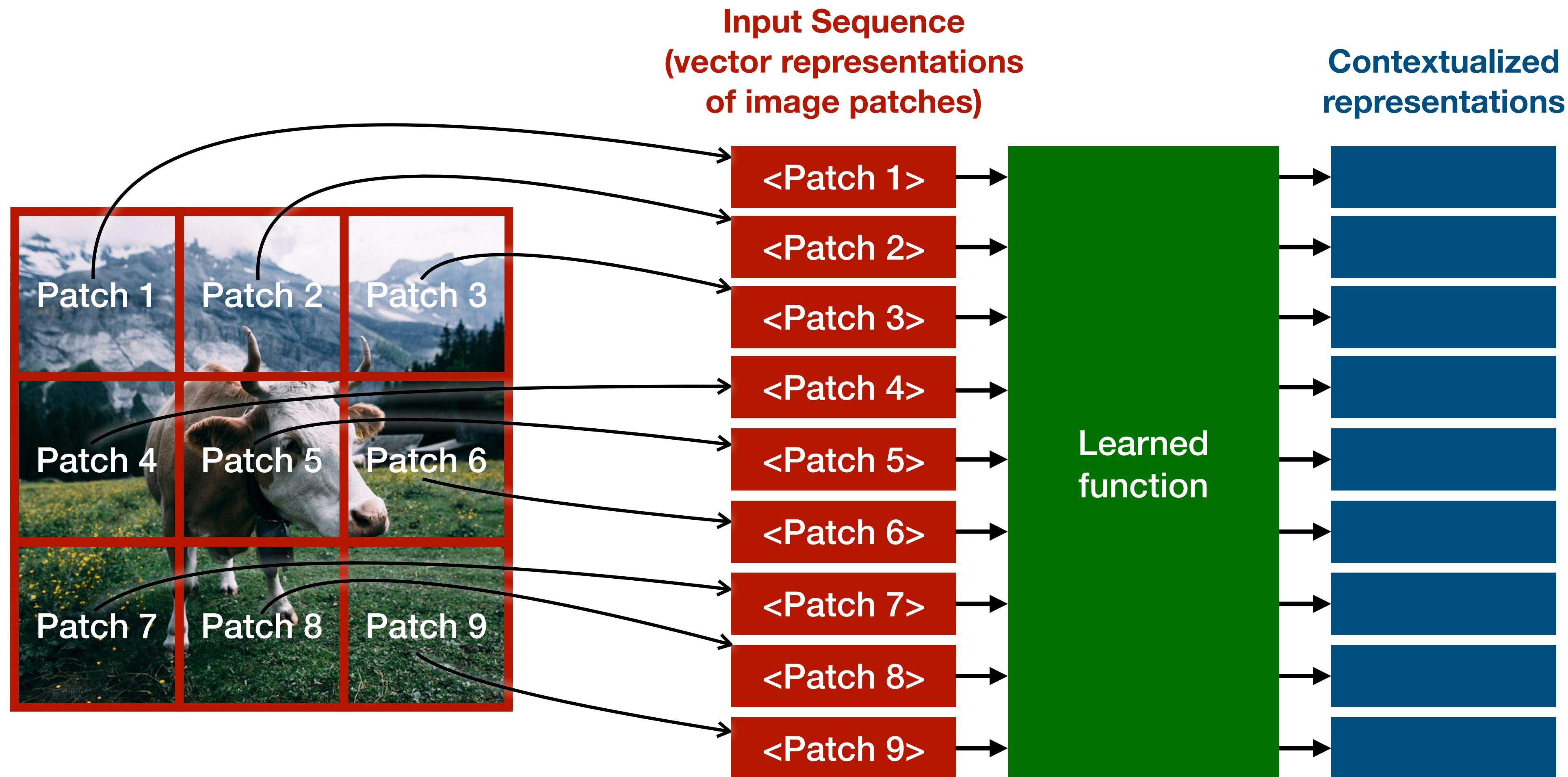
- **Next-word prediction:** train the network to tag every element with the word that comes next
- **Via logistic regression:** contextualized representation of word i is used to predict word $i + 1$ (#classes = #words in vocabulary)
- **Masking:** To avoid “cheating”, next-word prediction for word i can only see words $1, \dots, i$

Large language models: inference



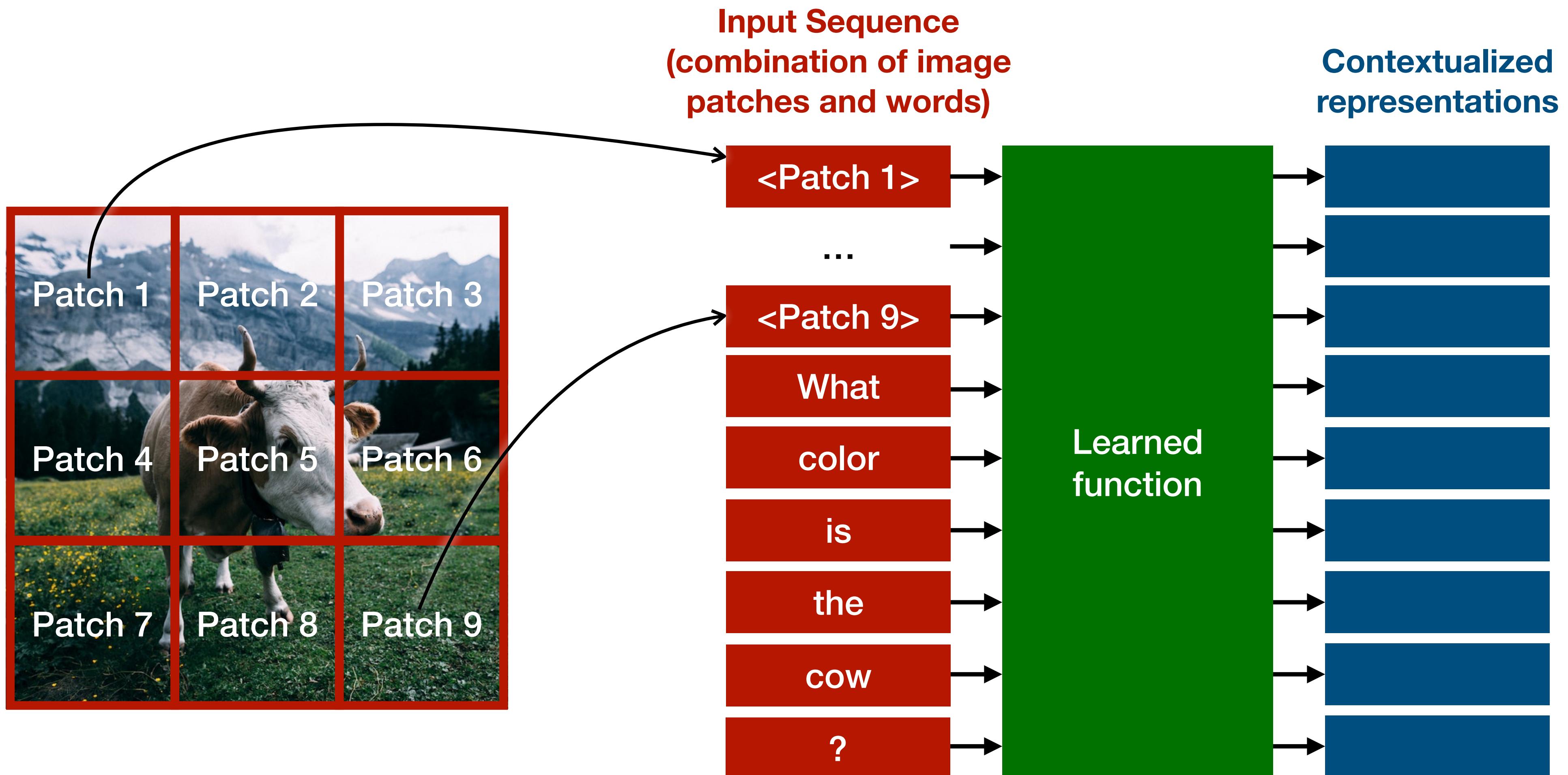
- Obtain contextualized representation of last input element
- Make prediction for next word
- Add it to input
- Repeat

Images can also be represented as sequences

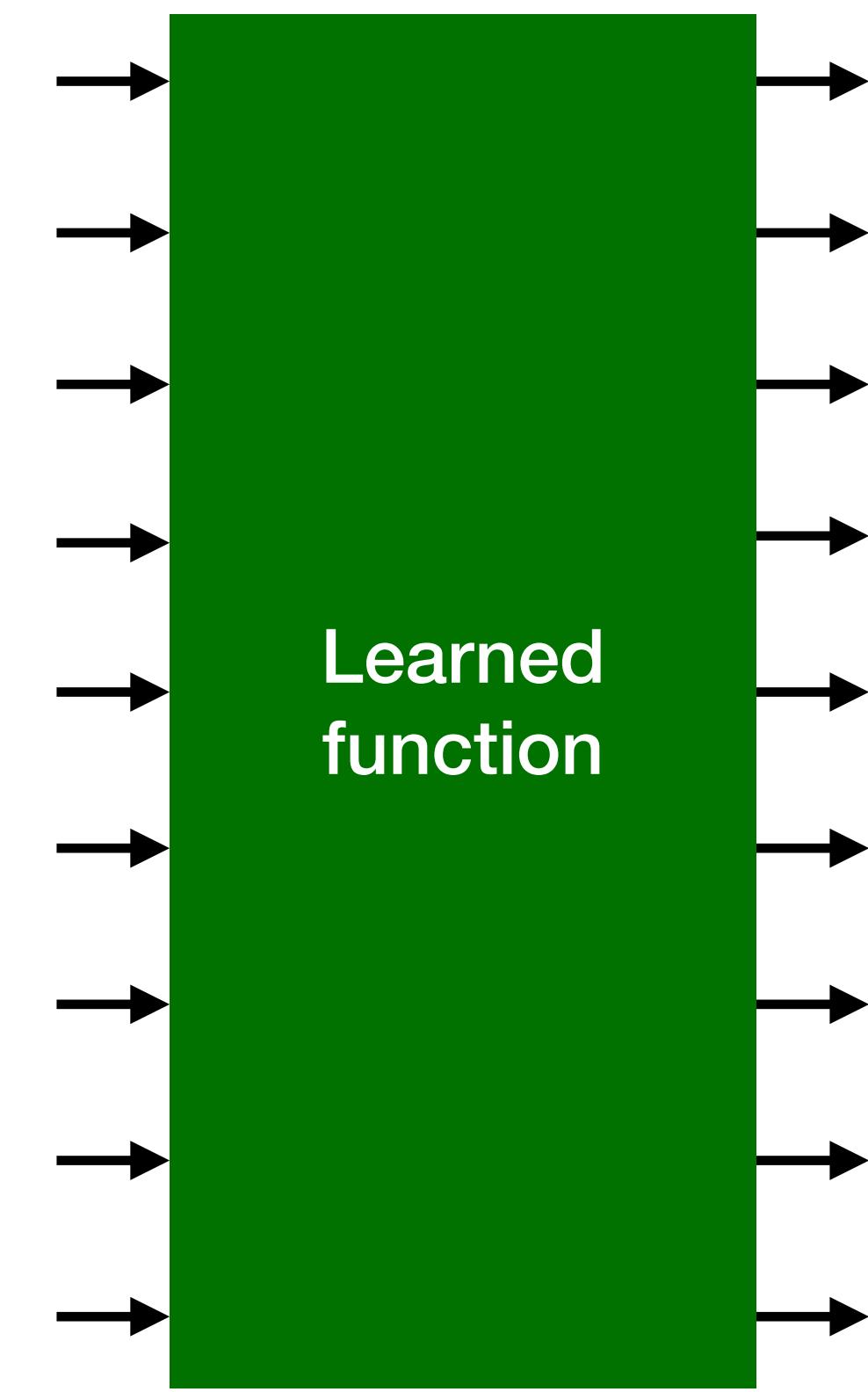


Note: In practice the patches
are typically much smaller

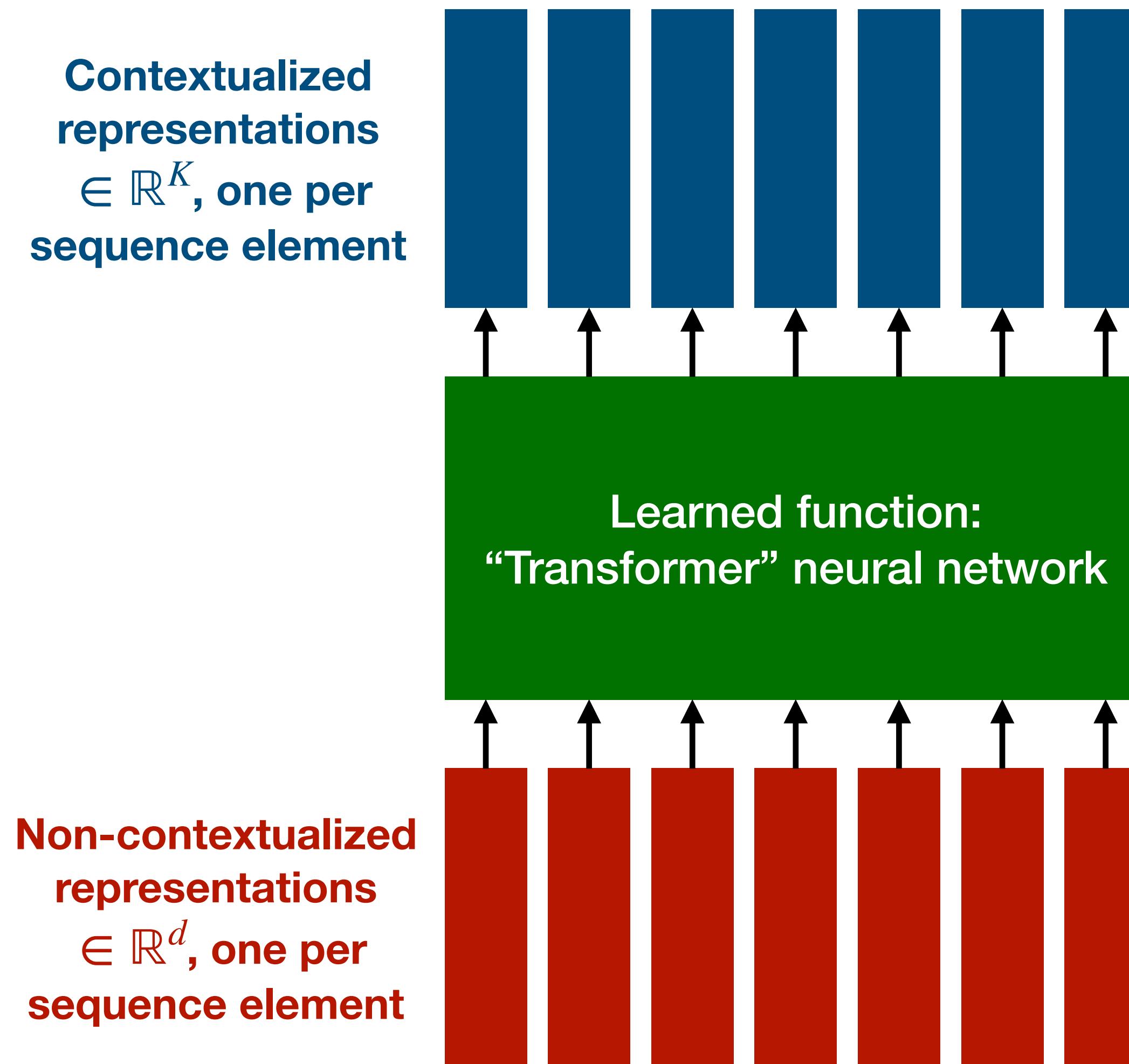
Sequences can be multimodal (image + text)



Transformers



What is a Transformer?

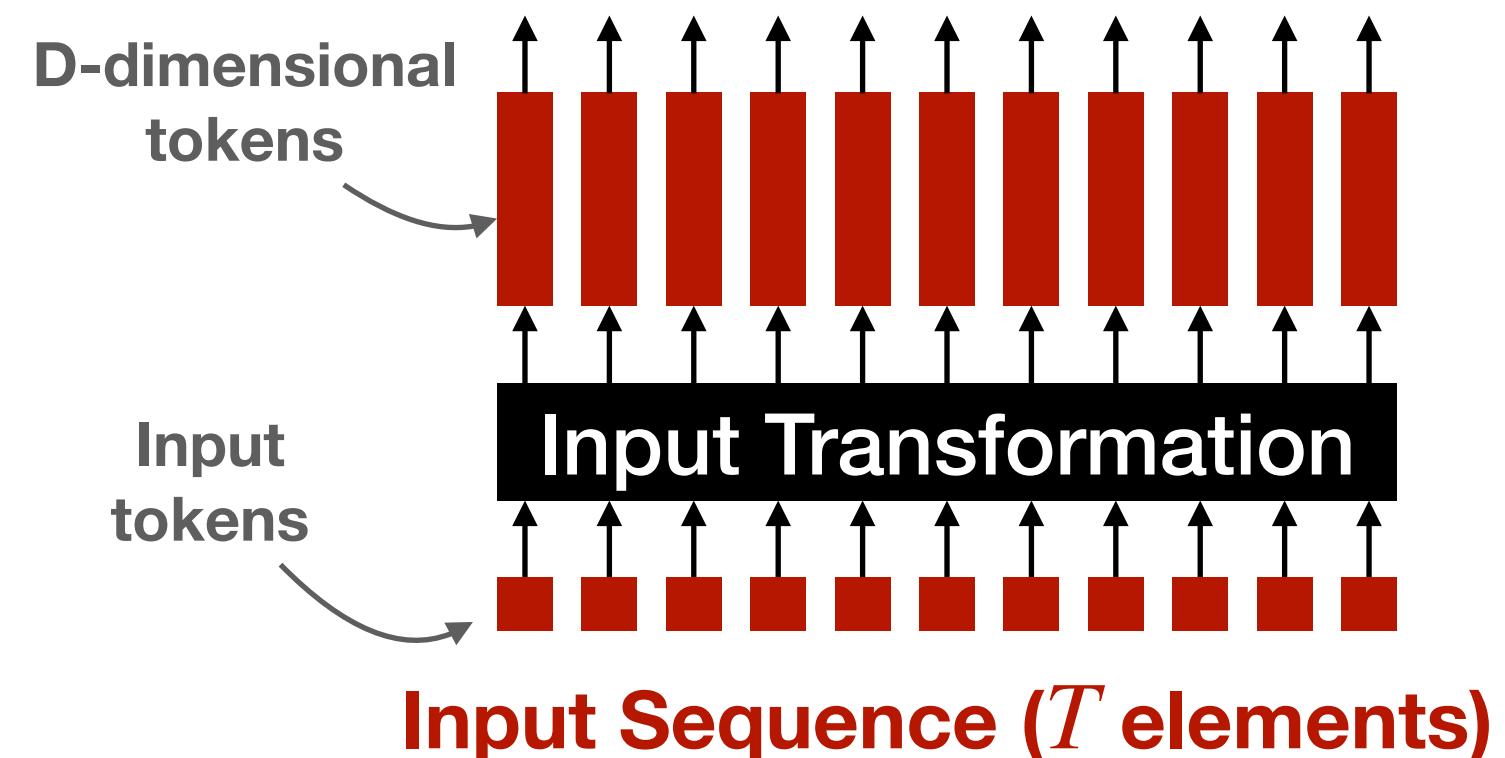


- Iteratively transforms sequence of **non-contextualized** representations into a sequence of **contextualized** representations
- Mixes information between sequence elements via **self-attention**

Overview of Transformer architecture

Input transformation: converts raw input sequence elements (“**tokens**”) into real-valued vector representations:

- **Text:** every word is replaced with a (fixed, non-contextualized) vector representing the word
- **Images:** each image patch is flattened into a vector

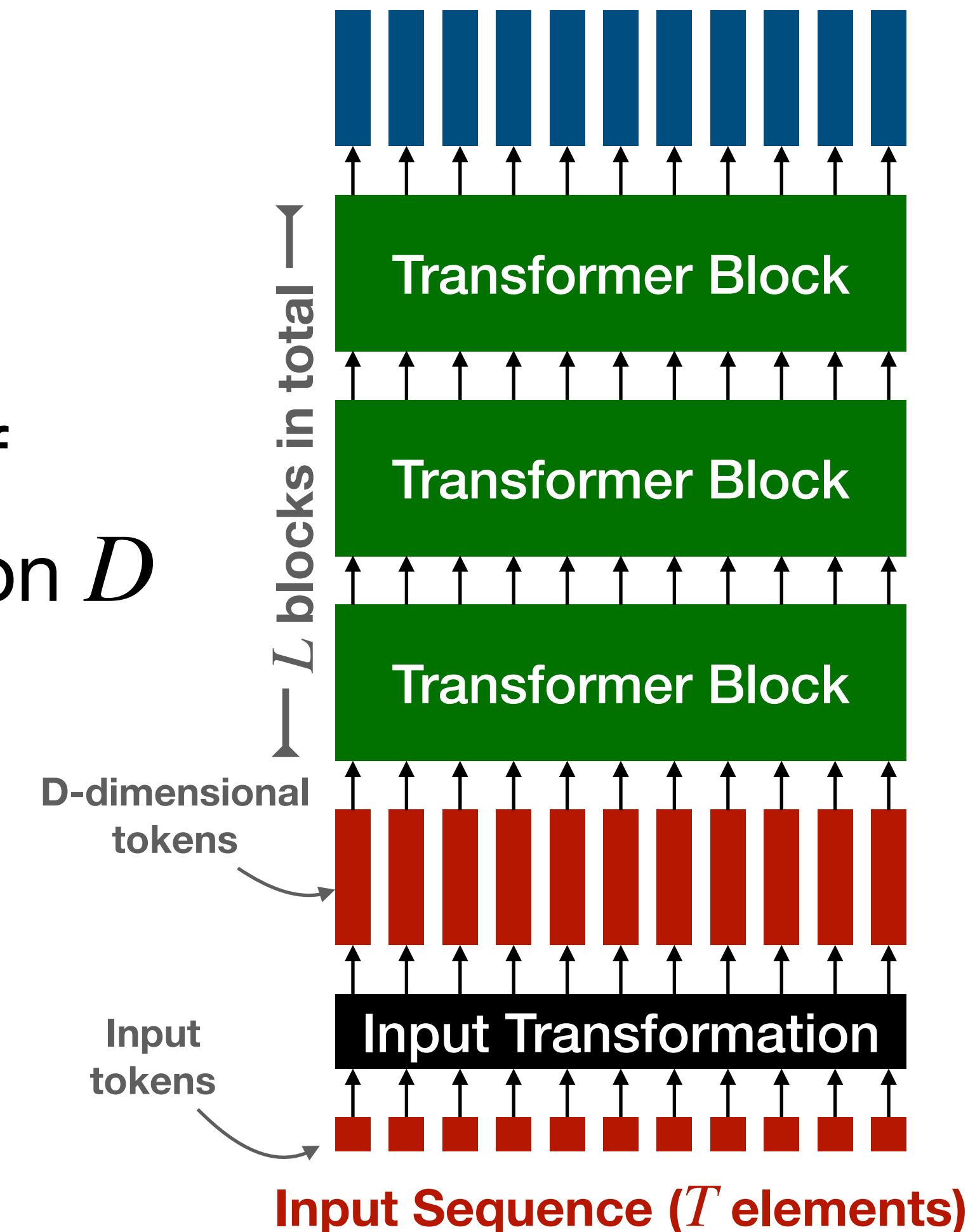


Overview of Transformer architecture

Input transformation: converts raw input sequence elements (“**t**okens”) into real-valued vector representations:

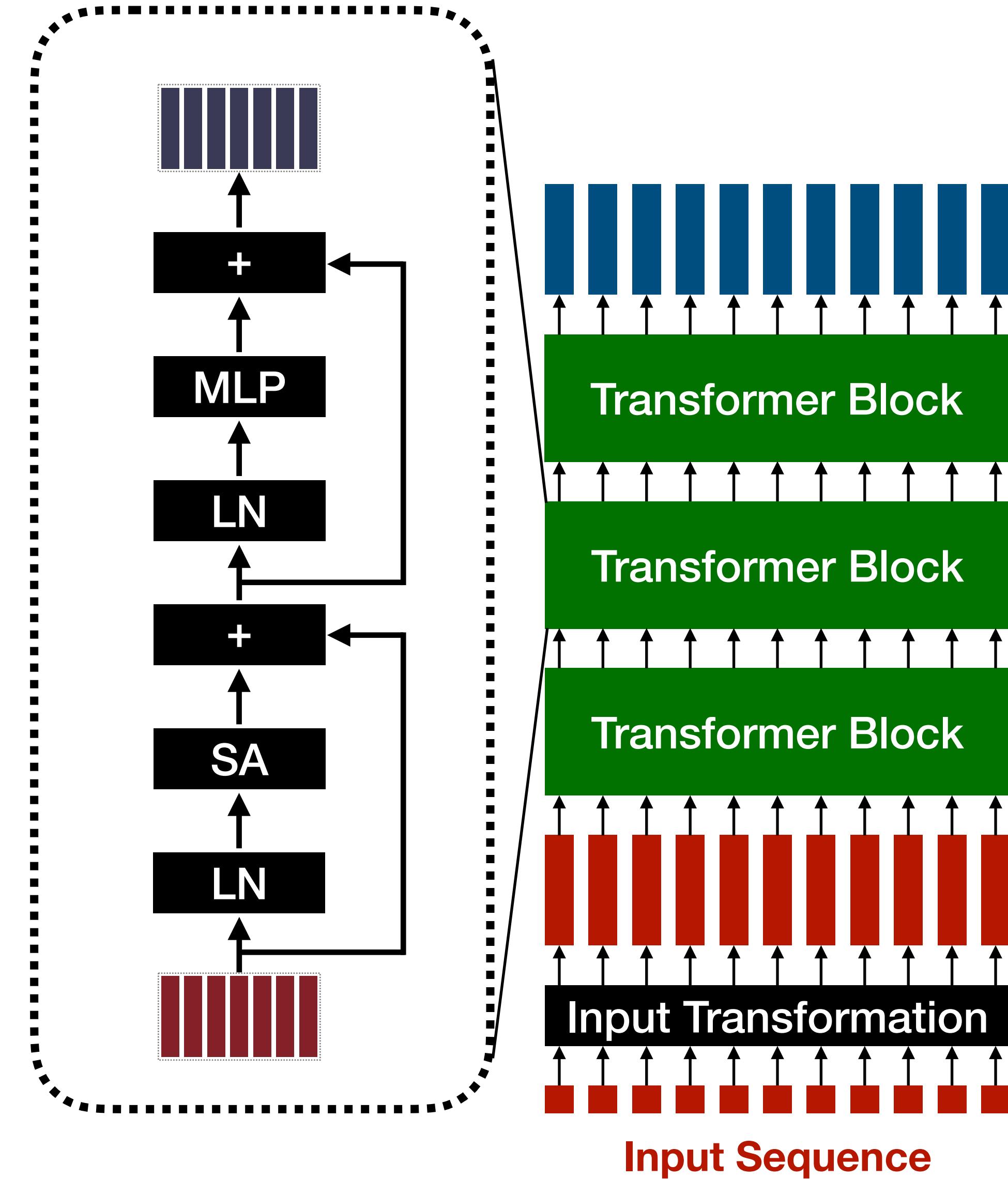
- **Text:** every word is replaced with a (fixed, non-contextualized) vector representing the word
- **Images:** each image patch is flattened into a vector

Transformer block: transforms a sequence of T vectors of dimension D into a new sequence of T vectors of dimension D using **self-attention** and **MLP sub-blocks**



Transformer block

- **Self-Attention (SA):** mixes information **between** tokens
- **Multi-Layer Perceptron (MLP):** mixes information **within** each token
- Other standard components:
 - Skip connections are widely used
 - Layer normalization (LN) is usually placed at the start of a residual branch



Input transformations

Text token embeddings

Tokenization: split the input text into a sequence of *input tokens* (typically word fragments + some special symbols) according to some predefined *tokenizer procedure*:

- Text: "Transformers are awesome!"
- Tokens: ["Trans", "form", "ers_", "are_", "awe", "some", "!"]
- Token IDs: [5124, 1029, 645, 3001, 6931, 7330, 10] (each token corresponds to some number $i \in \{1, \dots, N_{vocab}\}$)

Token embedding: maps each token ID $i \in \{1, \dots, N_{vocab}\}$ into a real-valued vector $\mathbf{w}_i \in \mathbb{R}^D$:

- Token embeddings: [$\mathbf{w}_{5124}, \mathbf{w}_{1029}, \mathbf{w}_{645}, \mathbf{w}_{3001}, \mathbf{w}_{6931}, \mathbf{w}_{7330}, \mathbf{w}_{10}$]

► The whole input sequence of T tokens leads to an input matrix $X =$

$$\begin{bmatrix} \mathbf{w}_{5124} \\ \mathbf{w}_{1029} \\ \vdots \\ \mathbf{w}_{10} \end{bmatrix} \in \mathbb{R}^{T \times D}$$

Notation: Throughout this lecture, all vectors will be treated as row vectors.

Text token embeddings: learning

- The matrix $W_{\text{emb}} = \begin{bmatrix} \mathbf{w}_1 \\ \vdots \\ \mathbf{w}_{N_{\text{vocab}}} \end{bmatrix} \in \mathbb{R}^{N_{\text{vocab}} \times D}$ is learned via backpropagation, along with all other transformer parameters
- Token embeddings of concrete input sequence obtained via matrix multiplication:

$$X = \begin{bmatrix} \mathbf{e}_{i_1} \\ \vdots \\ \mathbf{e}_{i_T} \end{bmatrix} W_{\text{emb}} \quad (\text{since } \mathbf{e}_i W_{\text{emb}} = (W_{\text{emb}})_{i,:} = \mathbf{w}_i)$$

- The tokenizer procedure is typically fixed in advance and not learned

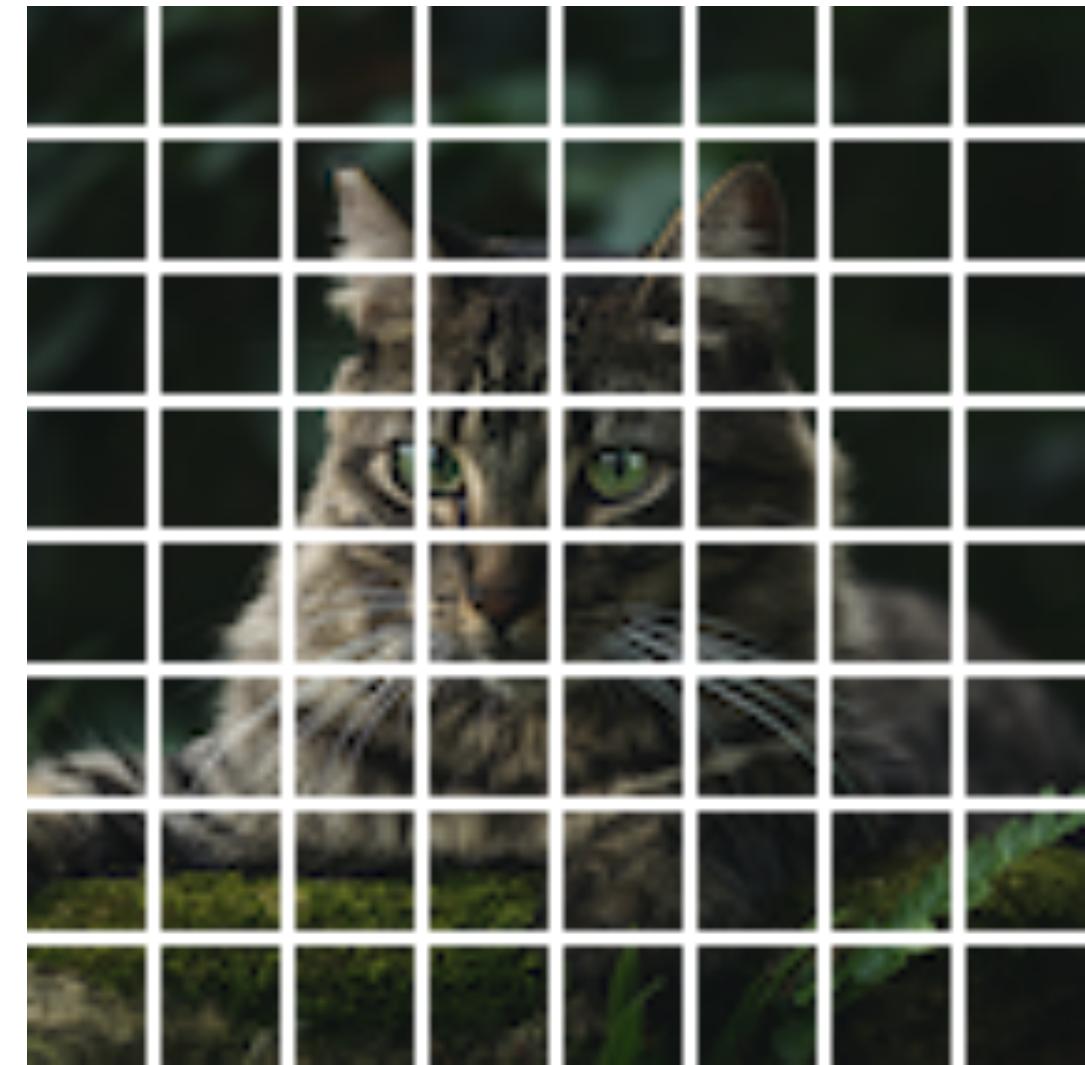
Image patch embeddings

- Divide image into patches of a given size
(typical choice: 16×16 pixels each)
- Flatten each patch into a vector of size
 $16 \cdot 16 \cdot 3 = 768$ (height*width*color channels)
- Multiply each resulting vector by an embedding matrix $W_{\text{emb}} \in \mathbb{R}^{768 \times D}$ which is shared for all inputs
- Learn W_{emb} through backpropagation, along with all other transformer parameters
- The whole input sequence of T embedded patches leads to an input matrix $X \in \mathbb{R}^{T \times D}$

Original (128×128)



Patches (16×16 each)



Single patch (16×16)

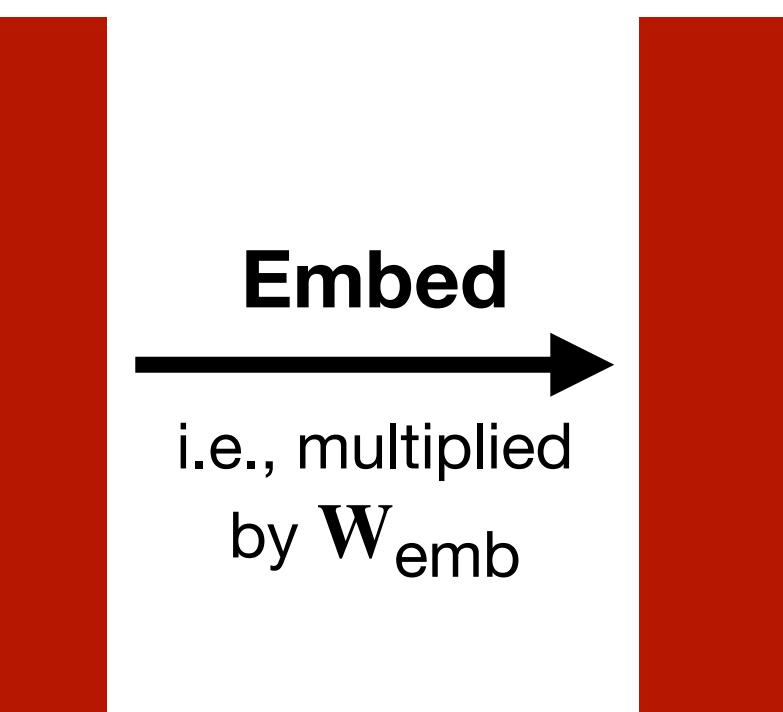


Dim 768



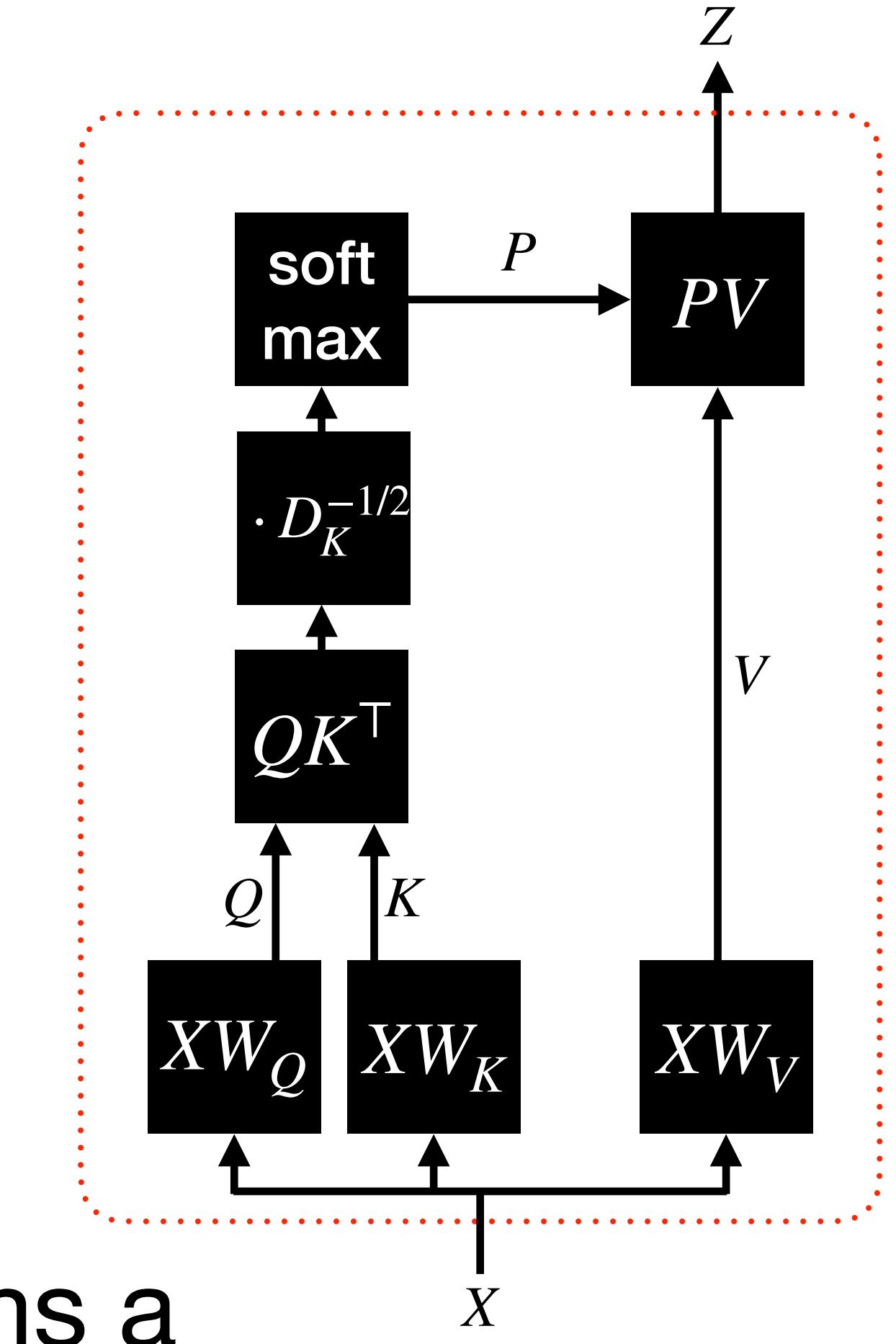
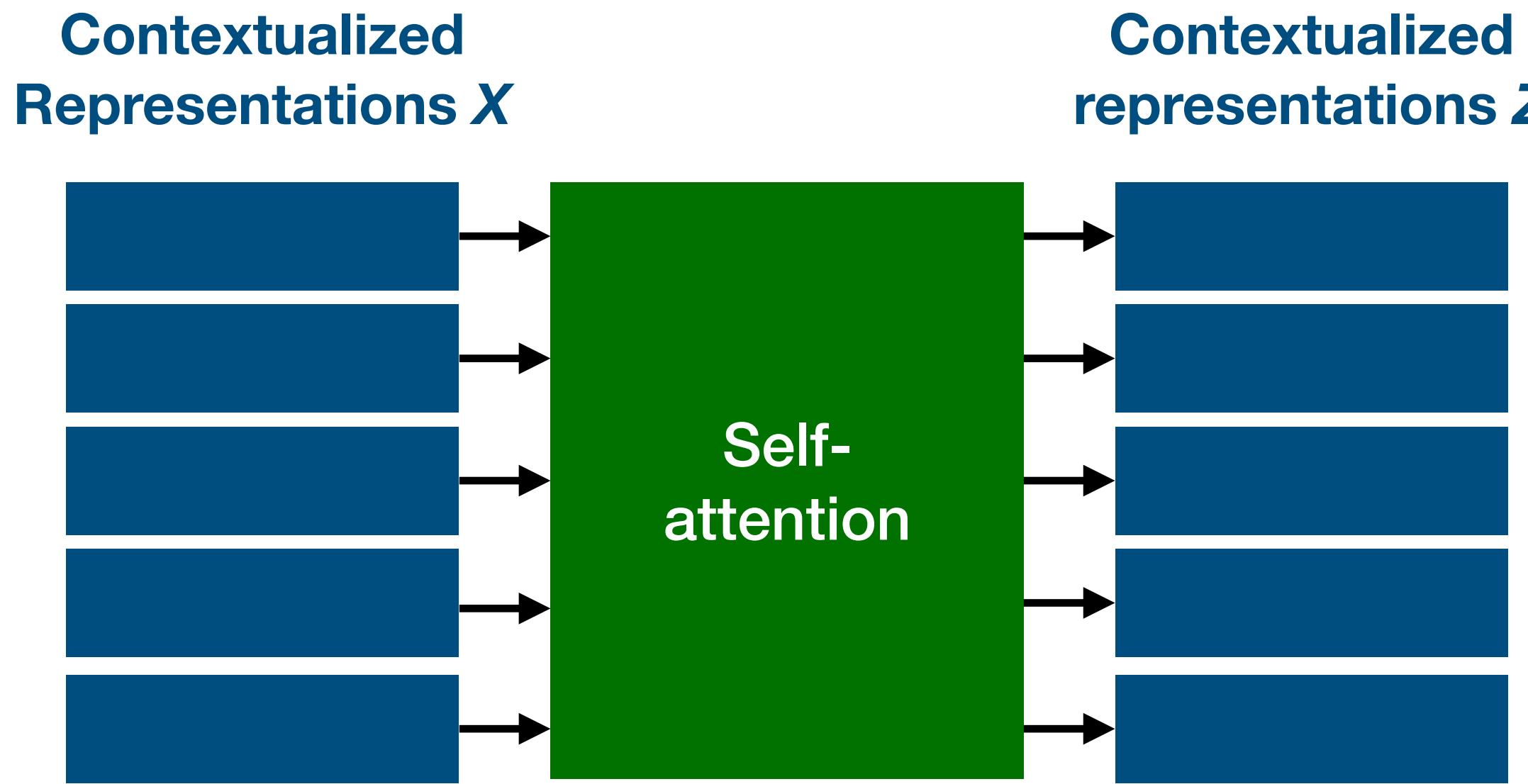
Embed
i.e., multiplied
by W_{emb}

Dim D



Self-attention

What is self-attention?



Self-attention is a function that transforms a sequence of contextualized representations (one per input token) into a new sequence of contextualized representations using learned input-dependent weighted averages

Attention as a weighted average

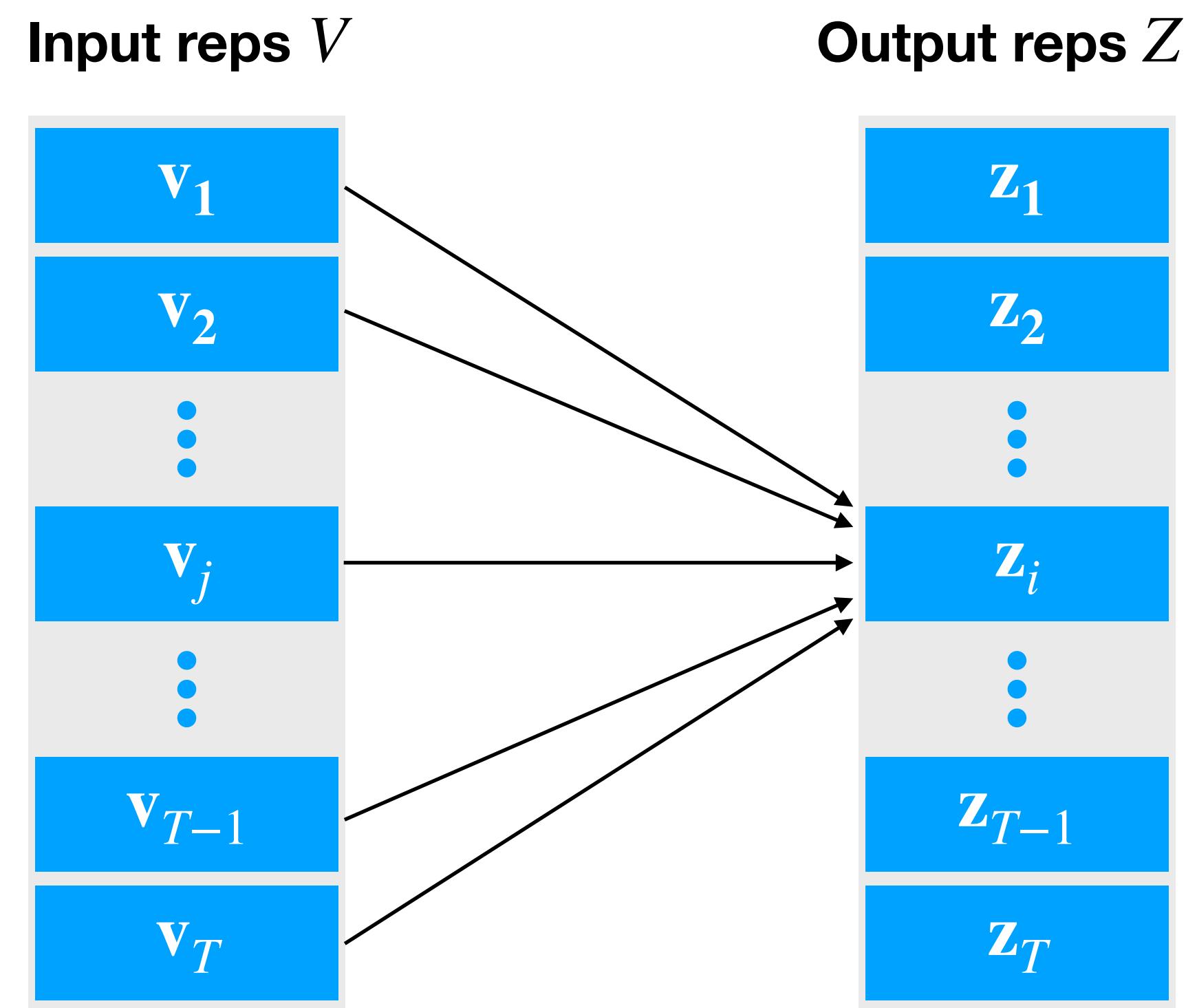
- T **input and output tokens**: $V \in \mathbb{R}^{T \times D_V}, Z \in \mathbb{R}^{T \times D_V}$
- Each output is a **weighted average** of the inputs:

$$\mathbf{z}_i = \sum_{j=1}^T p_{i,j} \mathbf{v}_j \quad \text{or in matrix form } Z = PV$$

- Weighting coefficients $P \in [0,1]^{T \times T}$ form valid probability distributions over the input tokens:

$$\rightarrow \sum_{j=1}^T p_{i,j} = 1 \text{ (i.e., each row sums to one)}$$

Notation: throughout this lecture, the j -th **rows** of V and Z are denoted by \mathbf{v}_j and \mathbf{z}_j



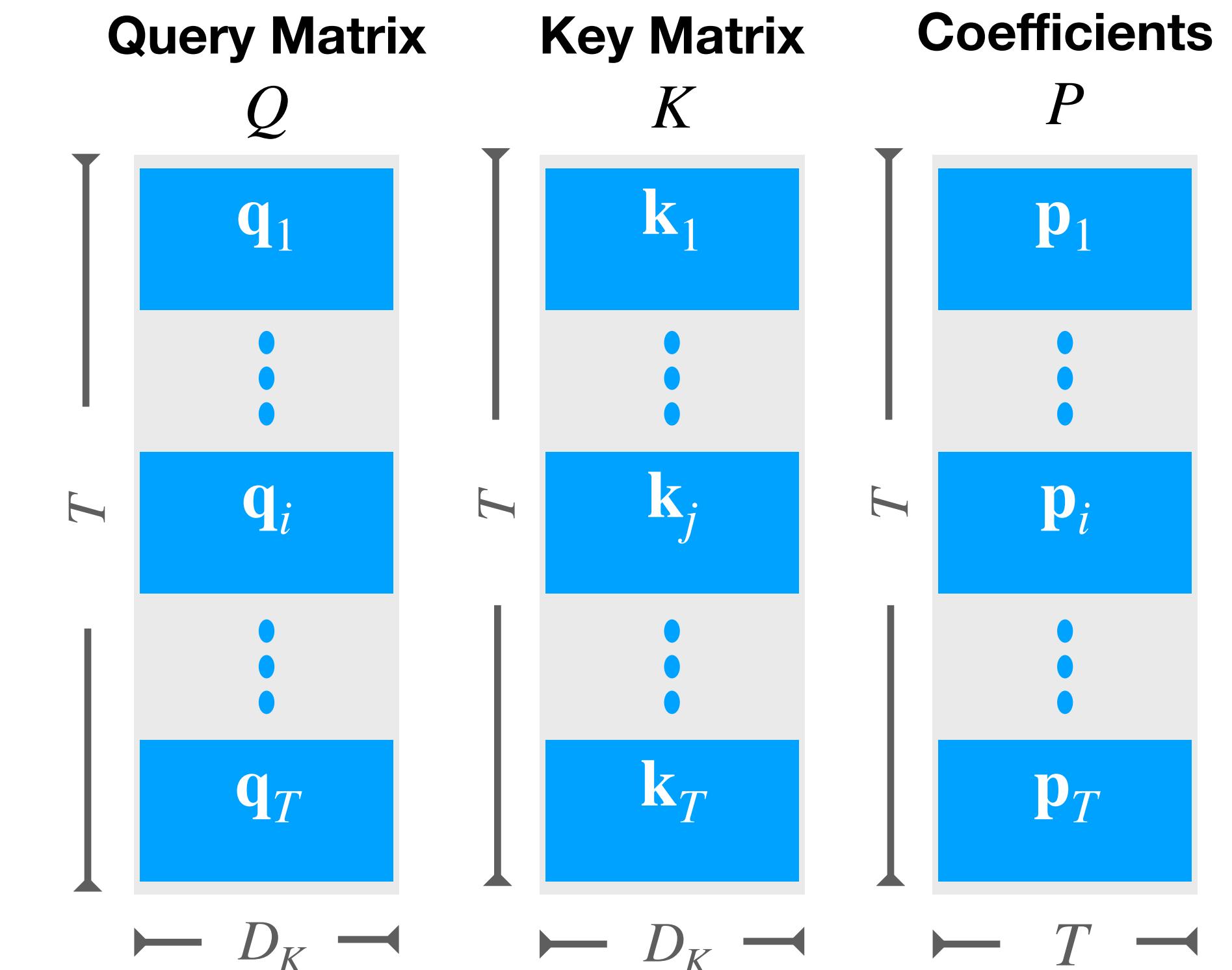
The weighting coefficients P

- **Query tokens** $Q \in \mathbb{R}^{T \times D_K}$ (one query per output token)
- **Key tokens** $K \in \mathbb{R}^{T \times D_K}$ (one key per input token)
- Determine weight $p_{i,j}$ based on **how similar** q_i and k_j are
 - Use inner product to obtain raw similarity scores
 - Normalize with **softmax** (scaled with “temperature” $\sqrt{D_K}$) to obtain a probability distribution
- This can be expressed as:

$$\text{Element-wise: } p_{i,j} = \frac{\exp\left(q_i k_j^\top / \sqrt{D_K}\right)}{\sum_{t=1}^T \exp\left(q_i k_t^\top / \sqrt{D_K}\right)}$$

$$\text{Matrix form: } P = \text{softmax}\left(\frac{QK^\top}{\sqrt{D_K}}\right)$$

The softmax is applied on each row *independently*



Computation complexity:
 $O(T \times T)$

The weighting coefficients P

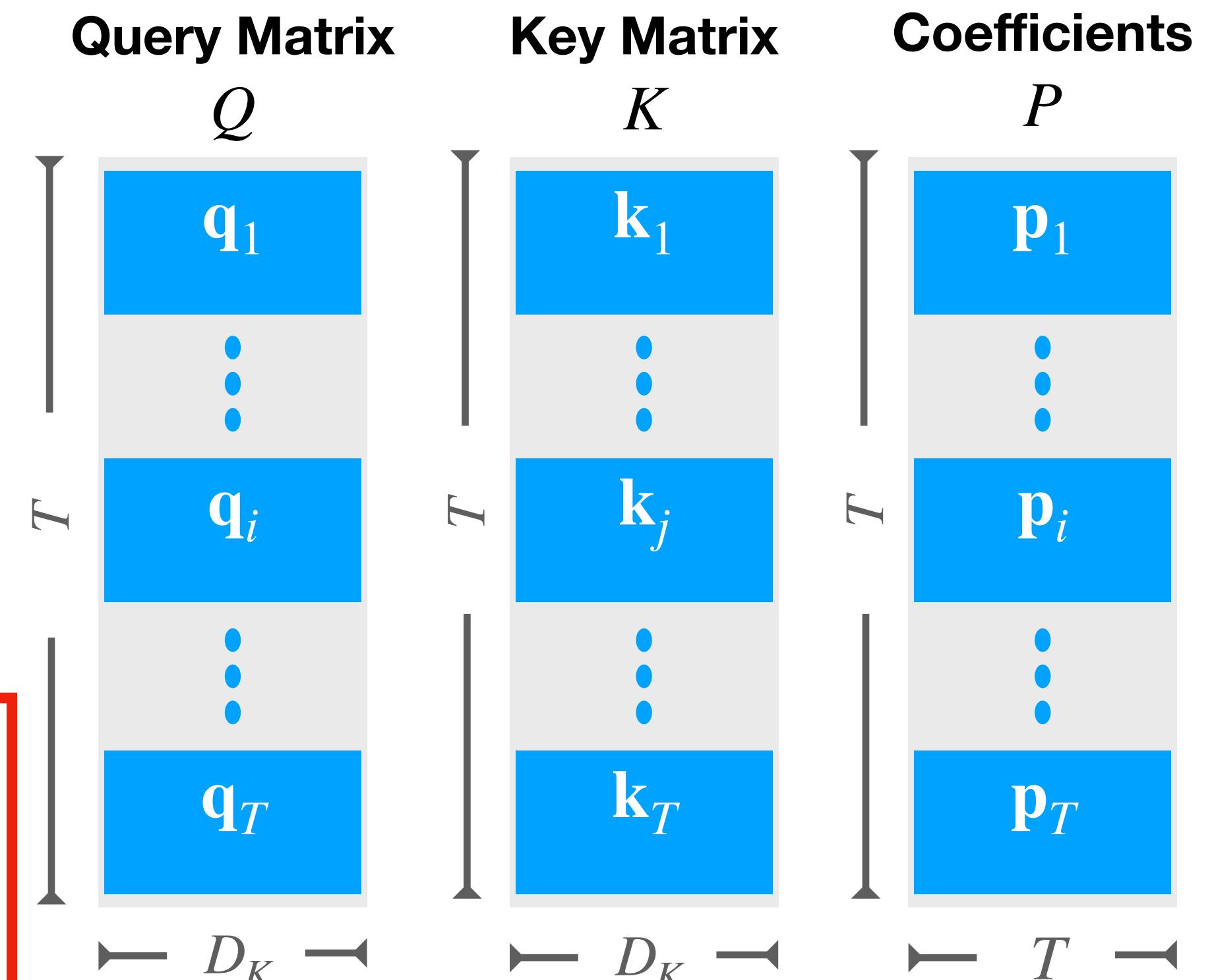
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- Determine weight $p_{i,j}$ based on **how similar** q_i and k_j are
 - Use inner product to obtain raw similarity scores
 - Normalize with softmax (scaled the temperature by $\sqrt{D_K}$) to obtain a probability distribution

In some applications, **causal masking** is used:

Sum until position i : $p_{i,j} = \frac{\exp(q_i k_j^\top / \sqrt{D_K})}{\sum_{t=1}^i \exp(q_i k_t^\top / \sqrt{D_K})}$ for $j \leq i$ and $p_{i,j} = 0$ otherwise

Mask before softmax: $P = \text{softmax}\left(\cancel{M} + \frac{QK^\top}{\sqrt{D_K}}\right)$

where $M \in \mathbb{R}^{T \times T}$ is the matrix $M_{ij} = -\infty$ for $j > i$ and $M_{i,j} = 0$ otherwise



Computation complexity:

$$O(T \times T)$$

Computing K, Q, V

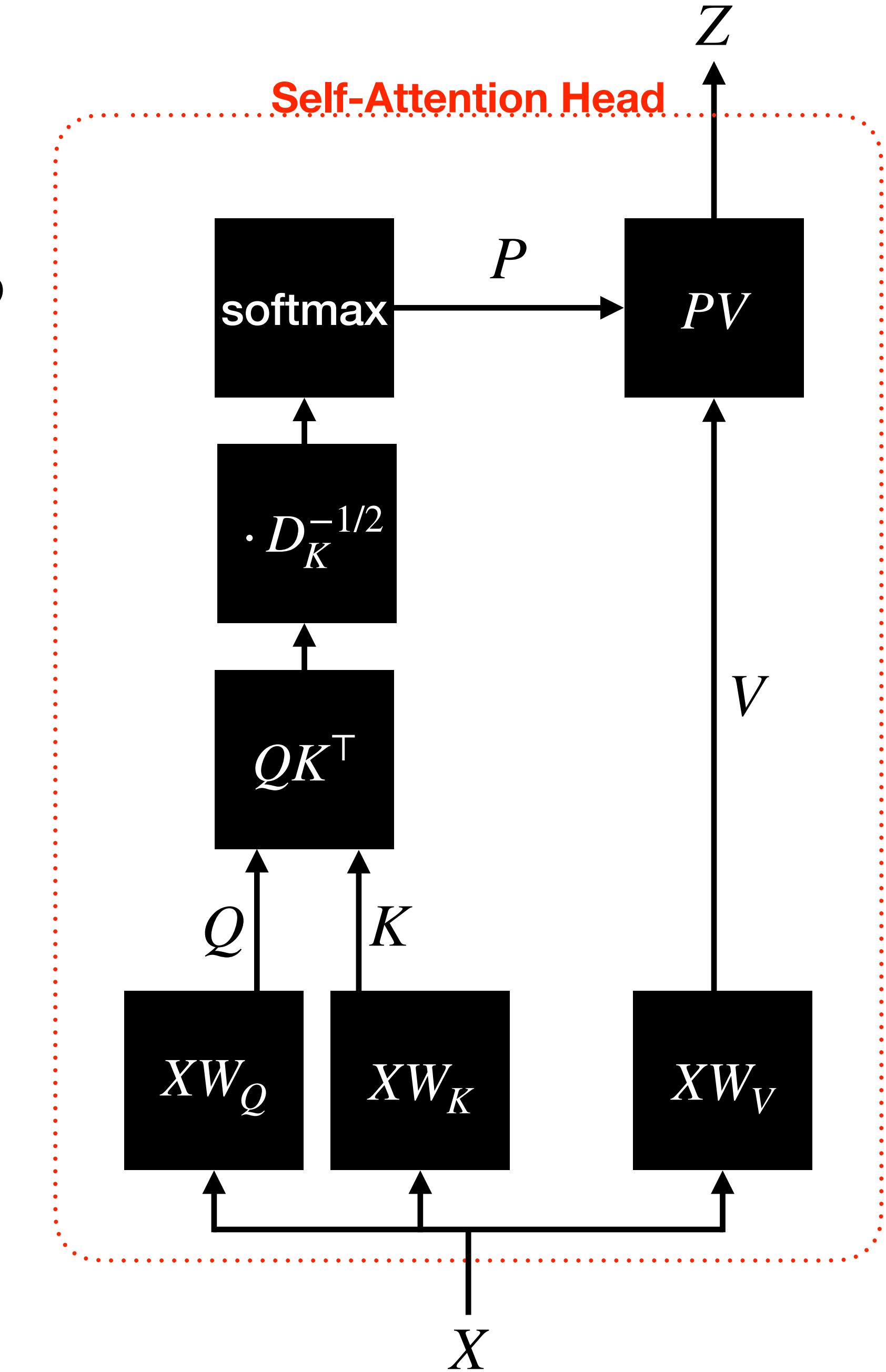
Define K, Q, V from the **same** input sequence $X \in \mathbb{R}^{T \times D}$

- **Keys:** $K = XW_K \in \mathbb{R}^{T \times D_K}$
- **Queries:** $Q = XW_Q \in \mathbb{R}^{T \times D_K}$
- **Values:** $V = XW_V \in \mathbb{R}^{T \times D_V}$
- $W_K, W_Q \in \mathbb{R}^{D \times D_K}, W_V \in \mathbb{R}^{D \times D_V}$ are parameters

The output of self-attention is then given by:

$$Z = \text{softmax} \left(\frac{QK^\top}{\sqrt{D_K}} \right) V \quad \text{softmax}(x_1, \dots, x_T) = \left(\frac{e^{x_i}}{\sum_{t=1}^T e^{x_t}} \right)_{i=1}^T$$

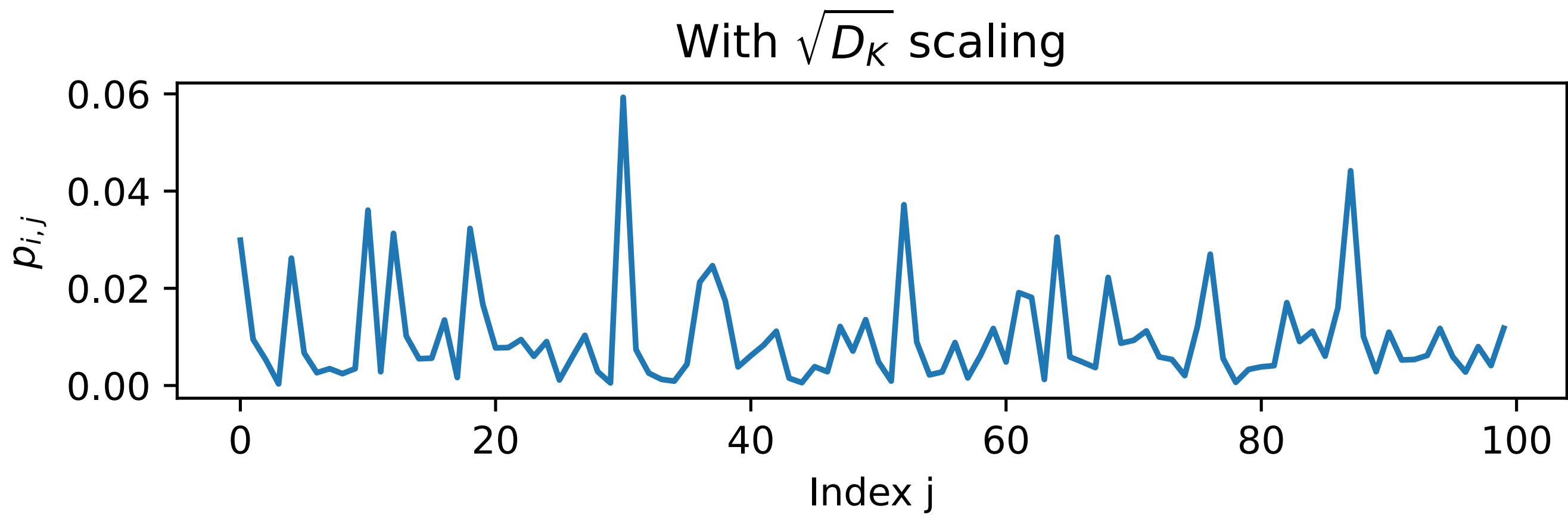
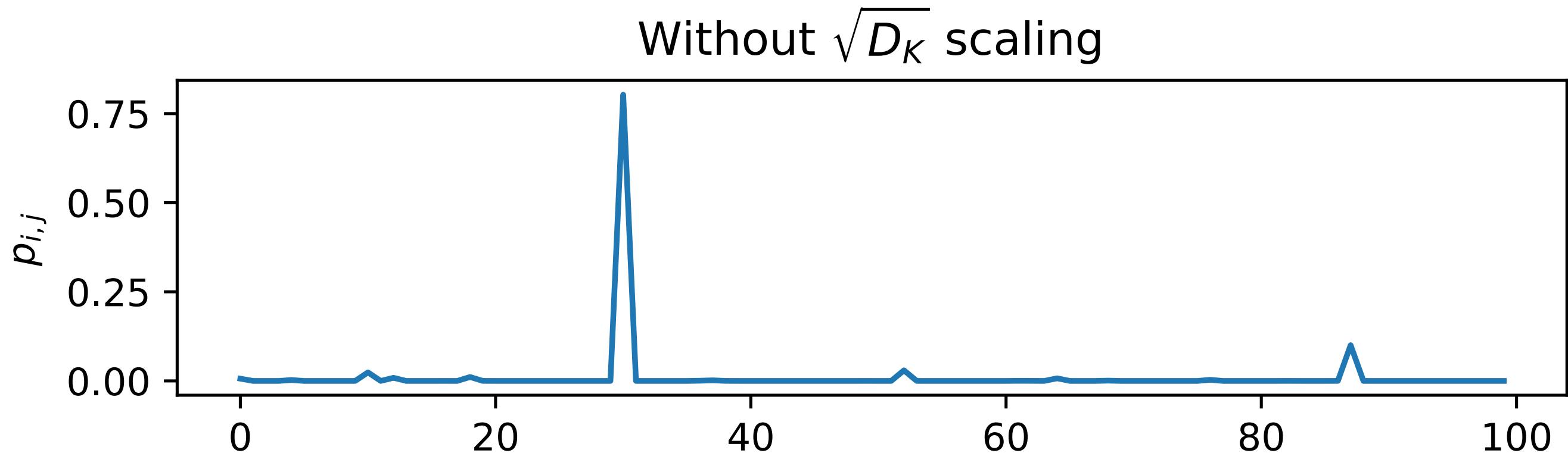
- $\text{softmax}(\cdot)$ is applied row-wise
- Quadratic computational complexity $O(T^2)$



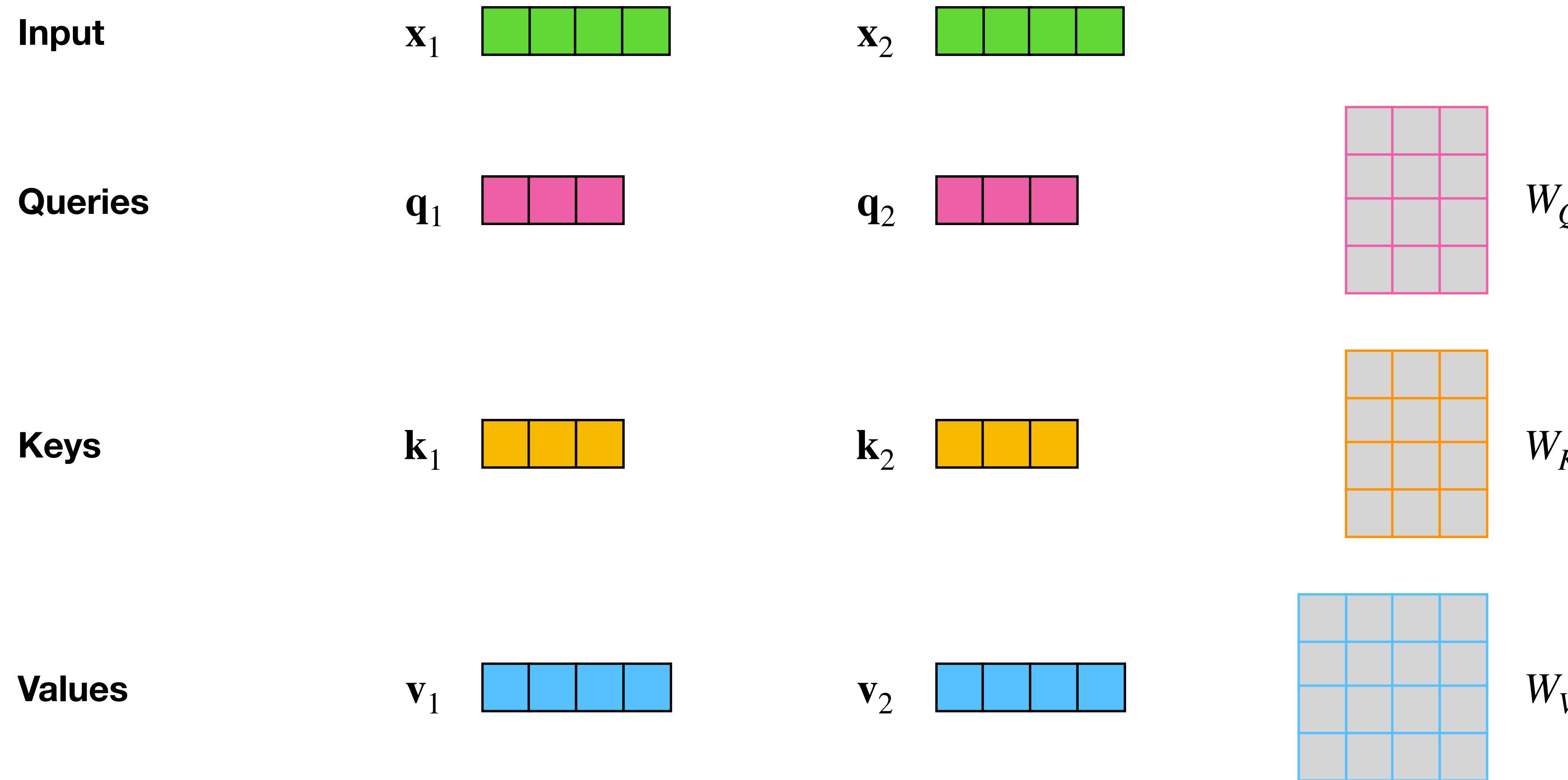
Why use $1/\sqrt{D_K}$ scaling?

$$P = \text{softmax} \left(\frac{QK^\top}{\sqrt{D_K}} \right)$$

- **Without scaling:** sharp distribution of the attention weights $p_{i,j}$ at random initialization
- The model takes much more time to adjust from the initial peak due to vanishing gradients
- The $1/\sqrt{D_K}$ scaling ensures uniformity at initialization and faster convergence



Self-Attention: Step-by-Step

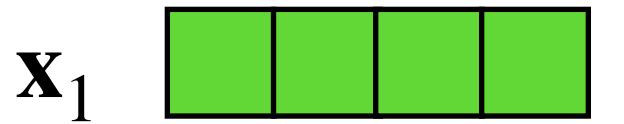


$$\begin{aligned} Q &= XW_Q \\ K &= XW_K \\ V &= XW_V \end{aligned}$$

Multiplying the input by the Q/K/V weight matrices, we create a query, a key and a value projection of each input of the input sequence

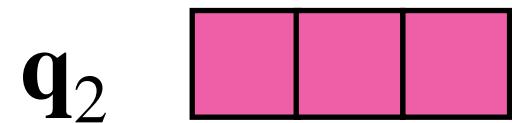
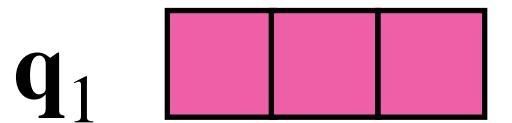
Self-Attention: Step-by-Step

Input

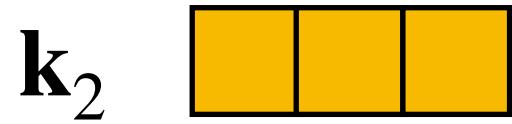
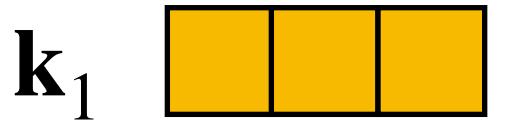


Step 1: create query, key and value vectors for each input token

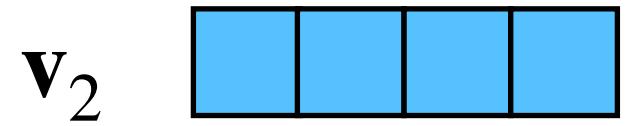
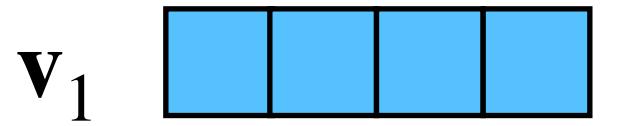
Queries



Keys

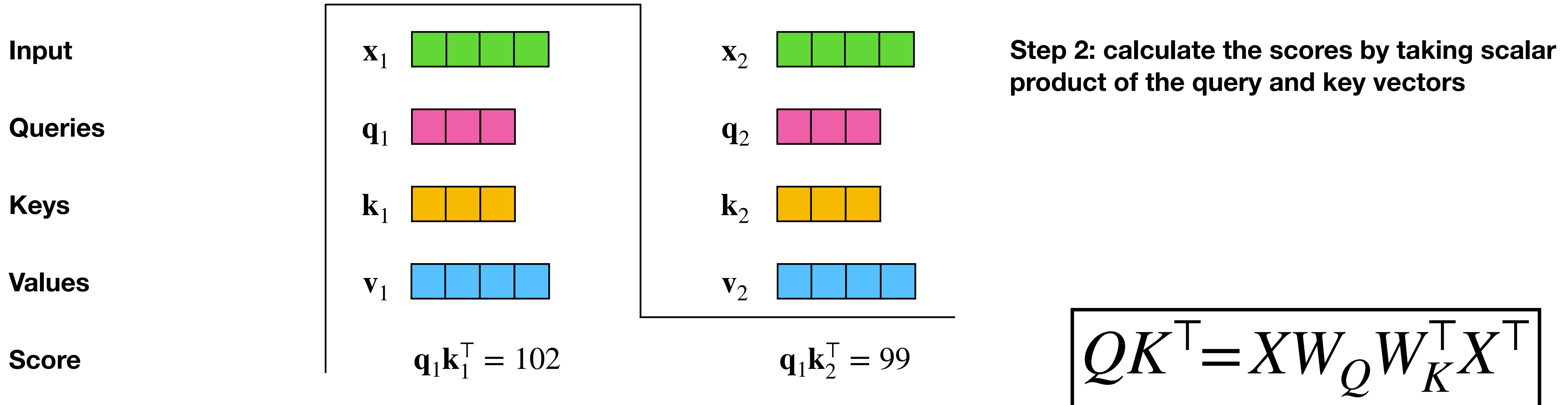


Values

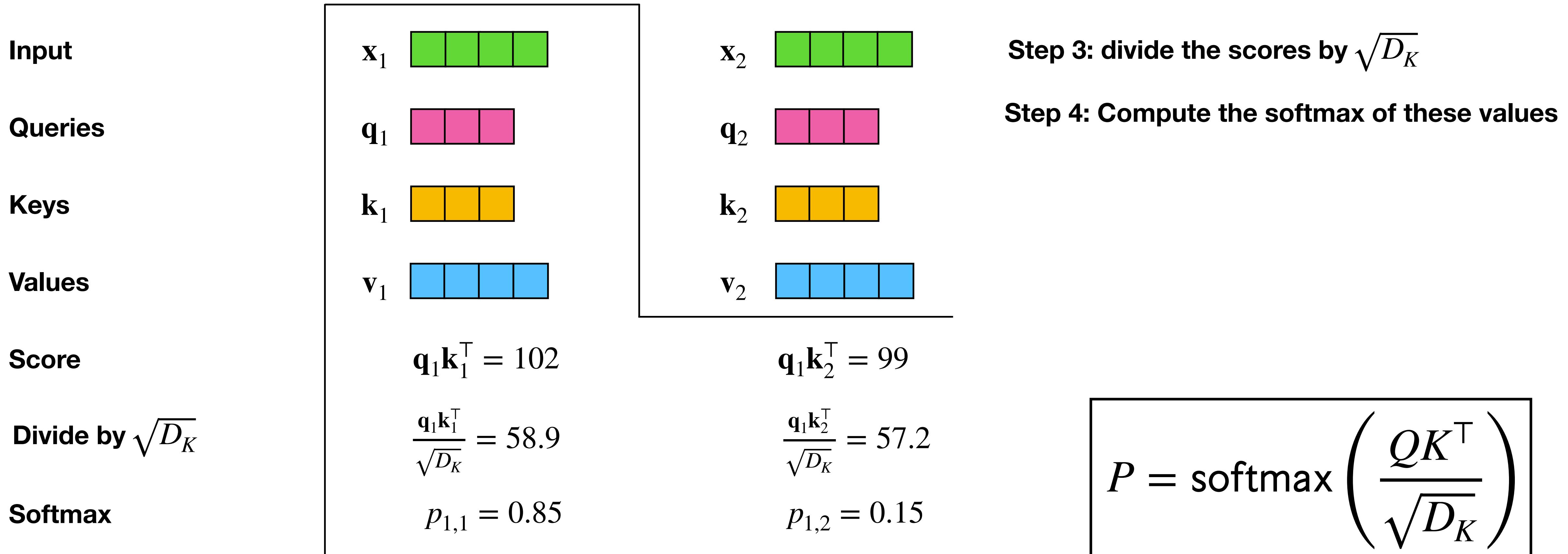


$$\begin{aligned} Q &= XW_Q \\ K &= XW_K \\ V &= XW_V \end{aligned}$$

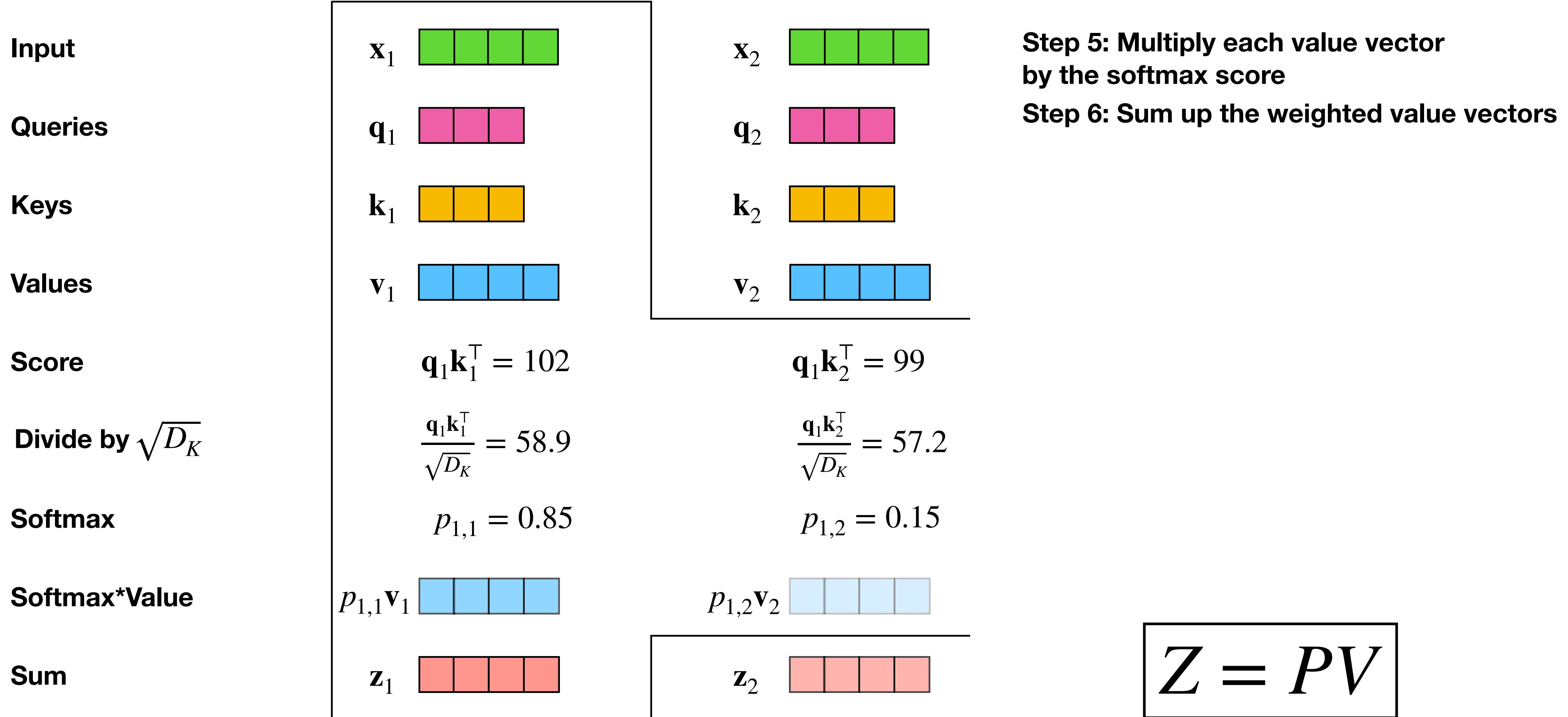
Self-Attention: Step-by-Step



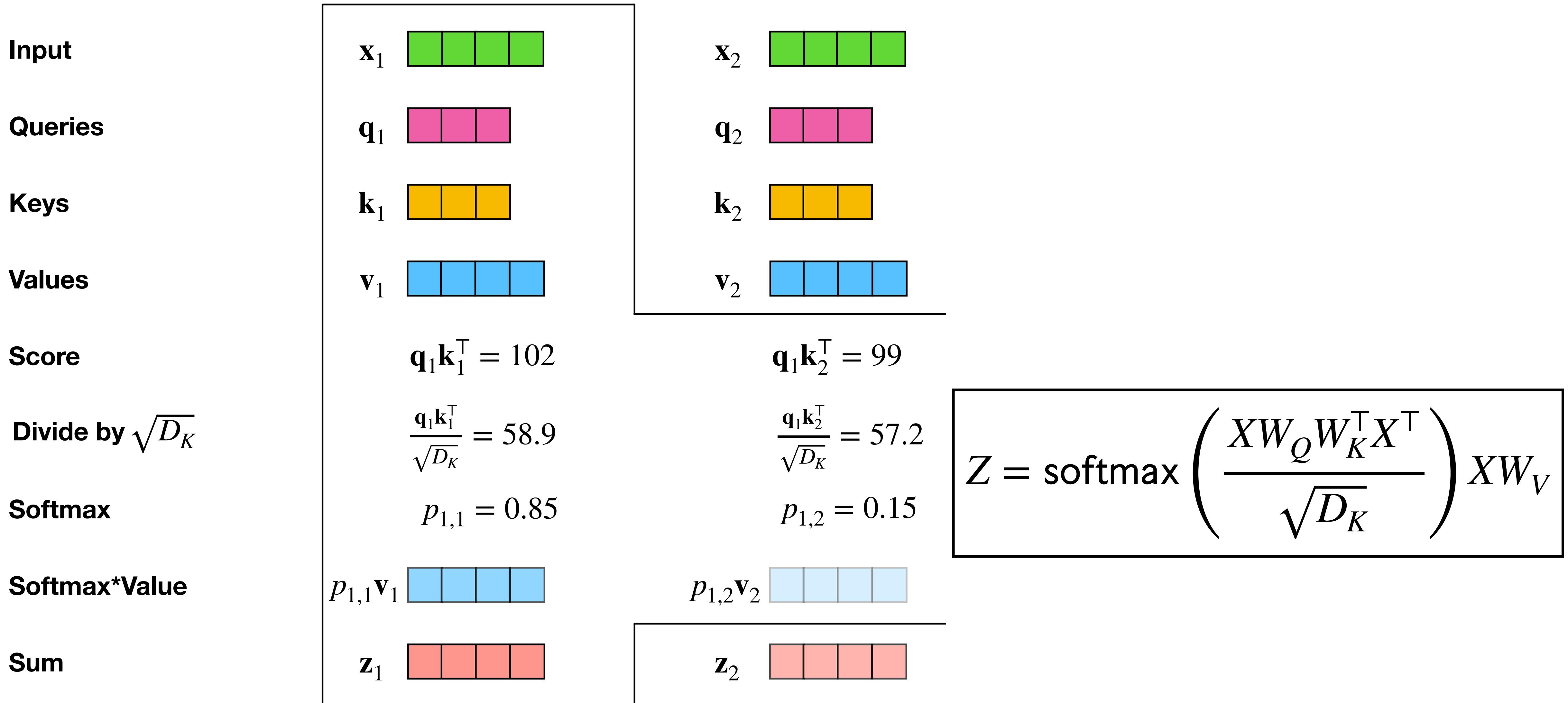
Self-Attention: Step-by-Step



Self-Attention: Step-by-Step



Self-Attention: Step-by-Step



Multi-Head Self-Attention

- It is desirable to have multiple attention patterns per layer, similar to having multiple output channels in a convolution layer

→ Run H self-attention “heads” in parallel

- The output of head h is given by:

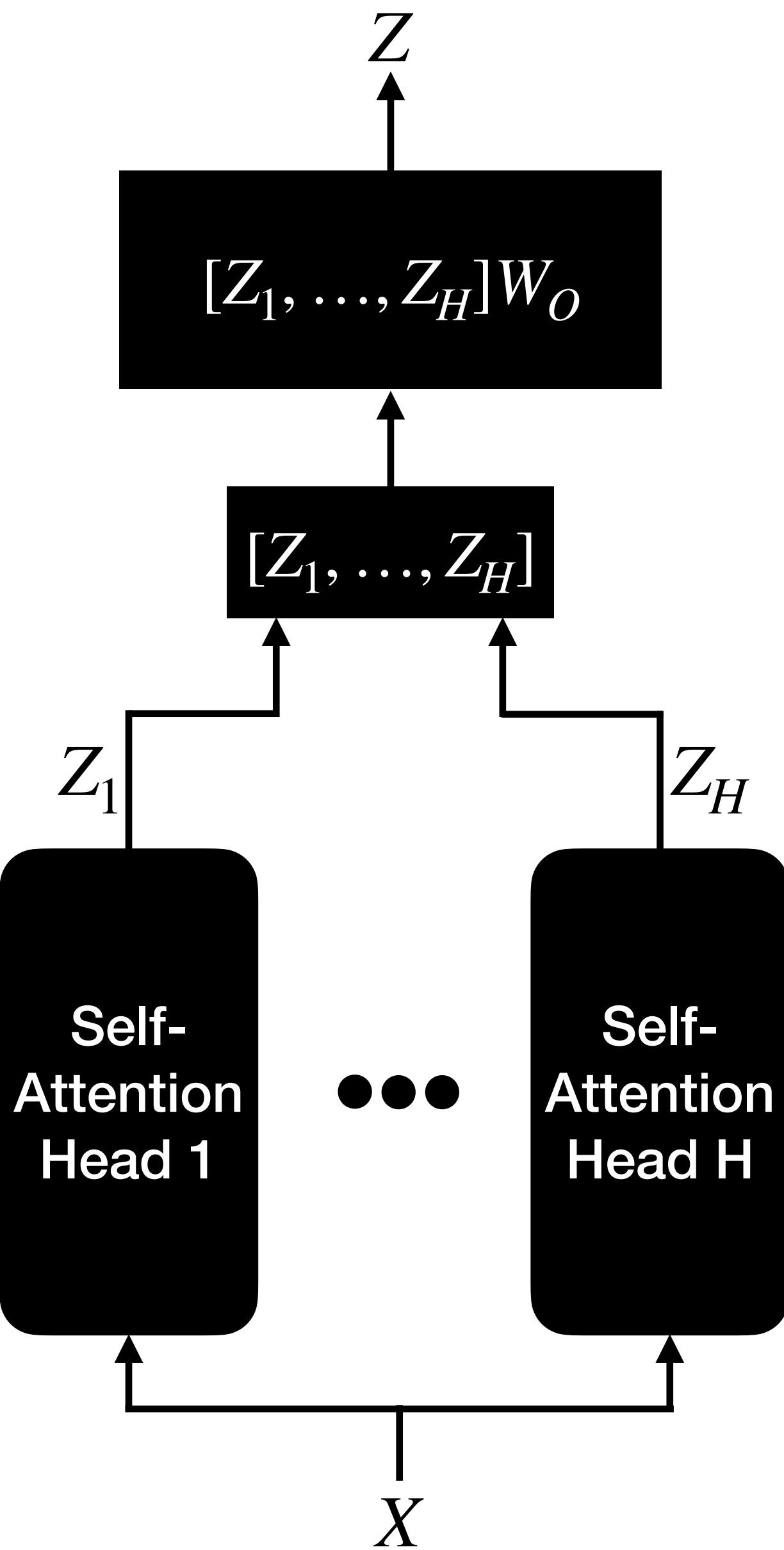
$$Z_h = \text{softmax} \left(\frac{XW_{Q,h}W_{K,h}^\top X^\top}{\sqrt{D_K}} \right) XW_{V,h}$$

$$W_{V,h} \in \mathbb{R}^{D \times D_V}, W_{K,h} \in \mathbb{R}^{D \times D_K}, W_{Q,h} \in \mathbb{R}^{D \times D_K}$$

- The final output is obtained by concatenating head-outputs and applying a linear transformation

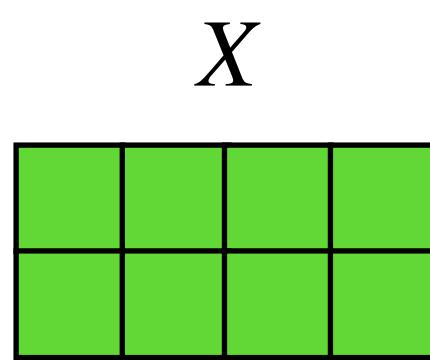
$$Z = [Z_1, \dots, Z_H]W_O$$

where $W_O \in \mathbb{R}^{HD_V \times D}$ is learned via backpropagation



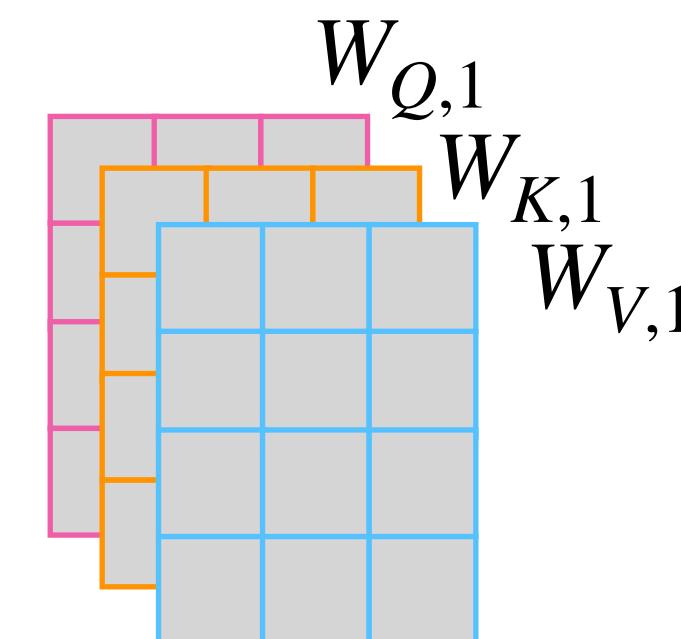
Multi-Head Self-Attention: recap

1) Input

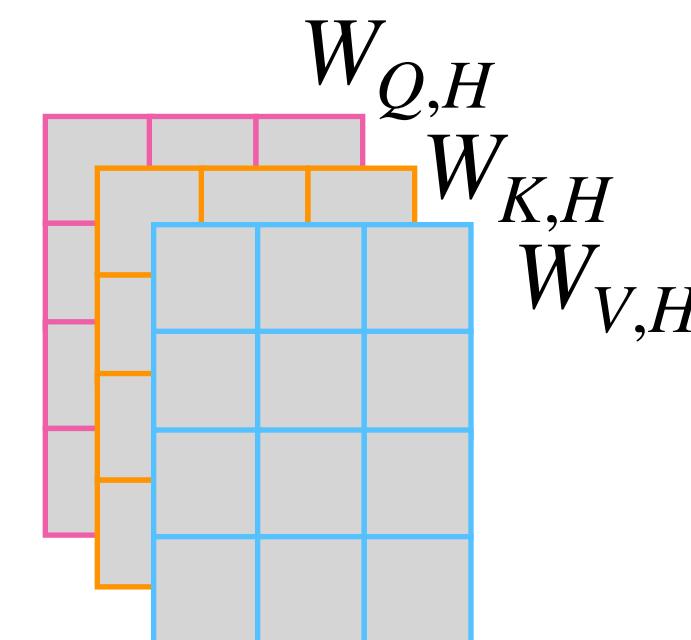


2) Split into H heads

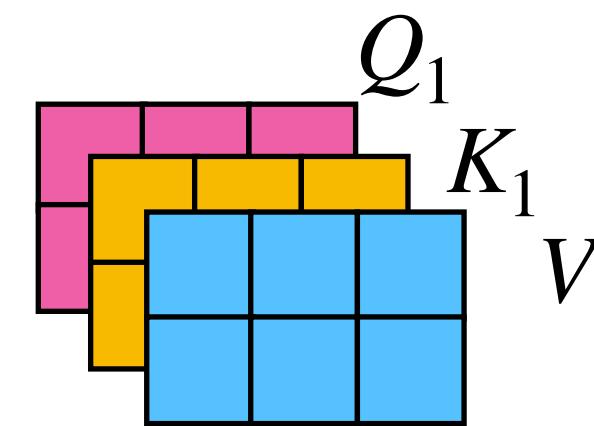
We multiply X by weight matrices



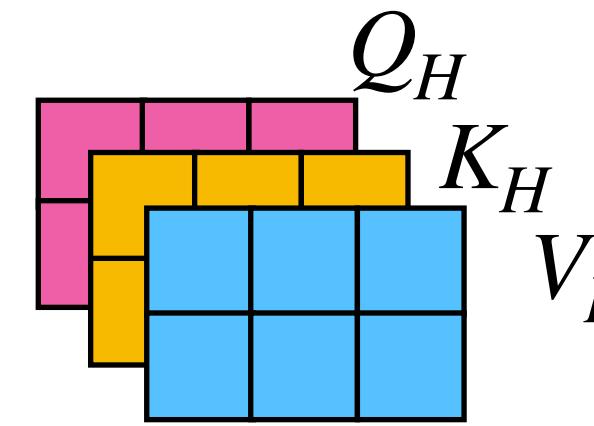
...



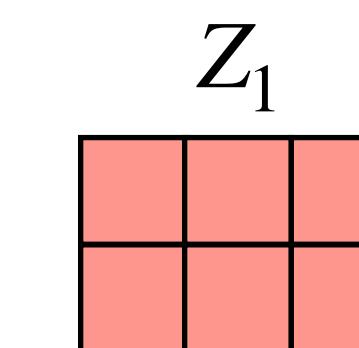
3) Calculate attention using
the resulting Q_h, K_h, V_h matrices



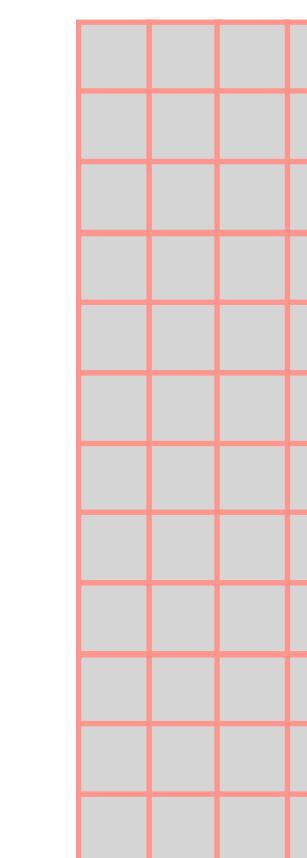
...



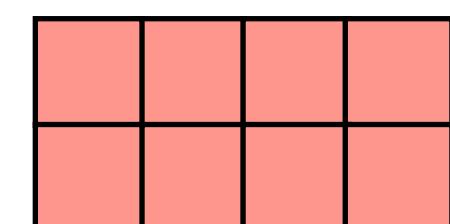
4) Concatenate the resulting matrices Z_h and multiply by W_0 to obtain the final output Z of the self-attention layer



W_0



Z



Positional information

Attention does not account for the order of input

For a permutation matrix $R \in \{0,1\}^{T \times T}$ we have:

$$Z_R = \text{softmax} \left(\frac{RXW_Q W_K^\top X^\top R^\top}{\sqrt{D_K}} \right) RXW_V \quad \text{Permute every } X \text{ in original formula}$$

$$= R \text{softmax} \left(\frac{XW_Q W_K^\top X^\top R^\top}{\sqrt{D_K}} \right) RXW_V \quad \text{Since softmax is computed row-wise}$$

$$= R \text{softmax} \left(\frac{XW_Q W_K^\top X^\top}{\sqrt{D_K}} \right) R^\top RXW_V \quad \text{Reordering the terms in the softmax sum does not affect the output}$$

$$= RPR^{-1}RXW_V \quad \text{For a permutation matrix: transpose=inverse}$$

$$= RPXW_V$$

Which is equivalent to a permutation of the original output $Z = PV$

Positional Information in Transformers

- **In practice, the input order matters:**
"She prefers cats to dogs" \neq "She prefers dogs to cats"
- **Solution:** incorporate a positional encoding in the network which is a function from the position to a feature vector $\text{pos} : \{1, \dots, T\} \rightarrow \mathbb{R}^D$
- **The most basic choice** is to add a positional embedding W_{pos} corresponding to each token's position t to the input embedding. $W_{\text{pos}} \in \mathbb{R}^{T \times D}$ is learned via backpropagation along with the other parameters:

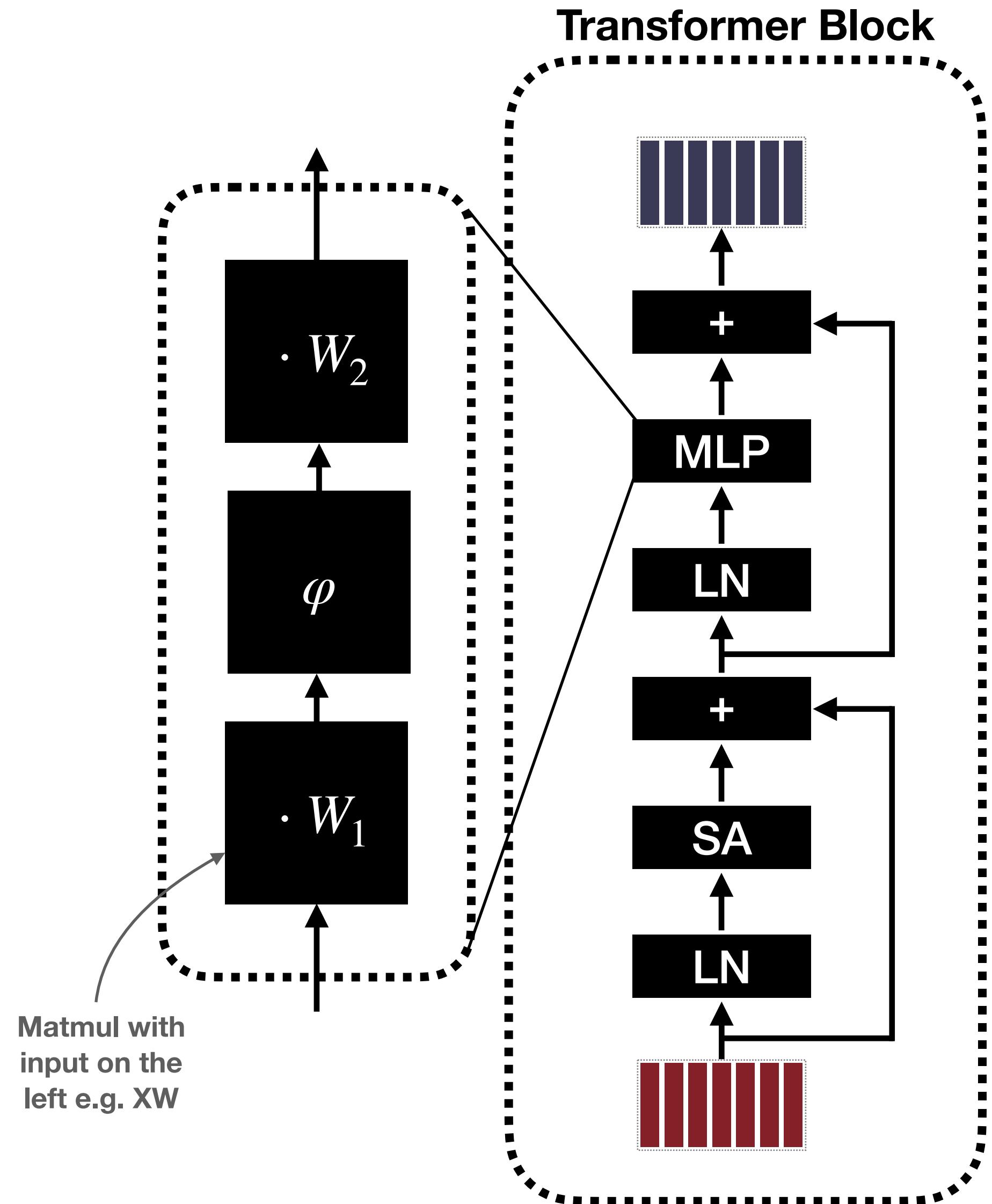
$$X = \begin{bmatrix} \mathbf{e}_{i_1} \\ \vdots \\ \mathbf{e}_{i_T} \end{bmatrix} W_{\text{emb}} + \begin{bmatrix} \mathbf{e}_1 \\ \vdots \\ \mathbf{e}_T \end{bmatrix} W_{\text{pos}}$$

- Numerous hand-crafted positional encodings exist (active area of research!)

MLP

Mixing Information within Tokens

- **MLP** mixes information within each token
- Apply the same transformation to each token independently:
$$MLP(X) = \varphi(XW_1)W_2$$
- Matrices $W_1, W_2 \in \mathbb{R}^{D \times D}$ learned via backprop
- Non-linearity φ in between (e.g., ReLU or GeLU)
- The model may also include learned bias terms



Mixing Information within Tokens

- MLP mixes information within each token

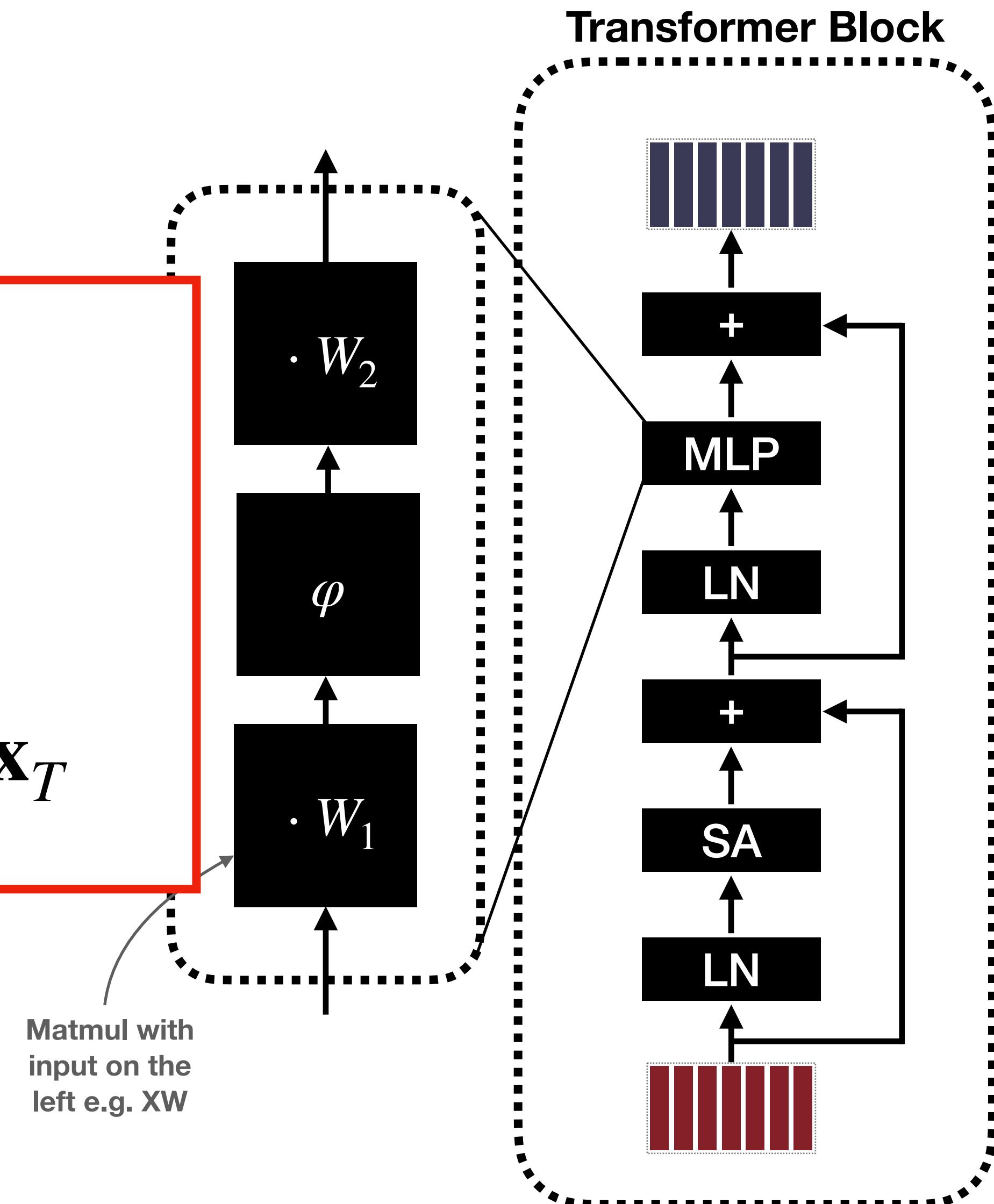
The same MLP is applied to each token:

$$MLP(X) = \varphi(XW_1)W_2$$

 \iff

$$MLP(\mathbf{x}_t) = \varphi(\mathbf{x}_t W_1)W_2, \text{ for each token } \mathbf{x}_1, \dots, \mathbf{x}_T$$

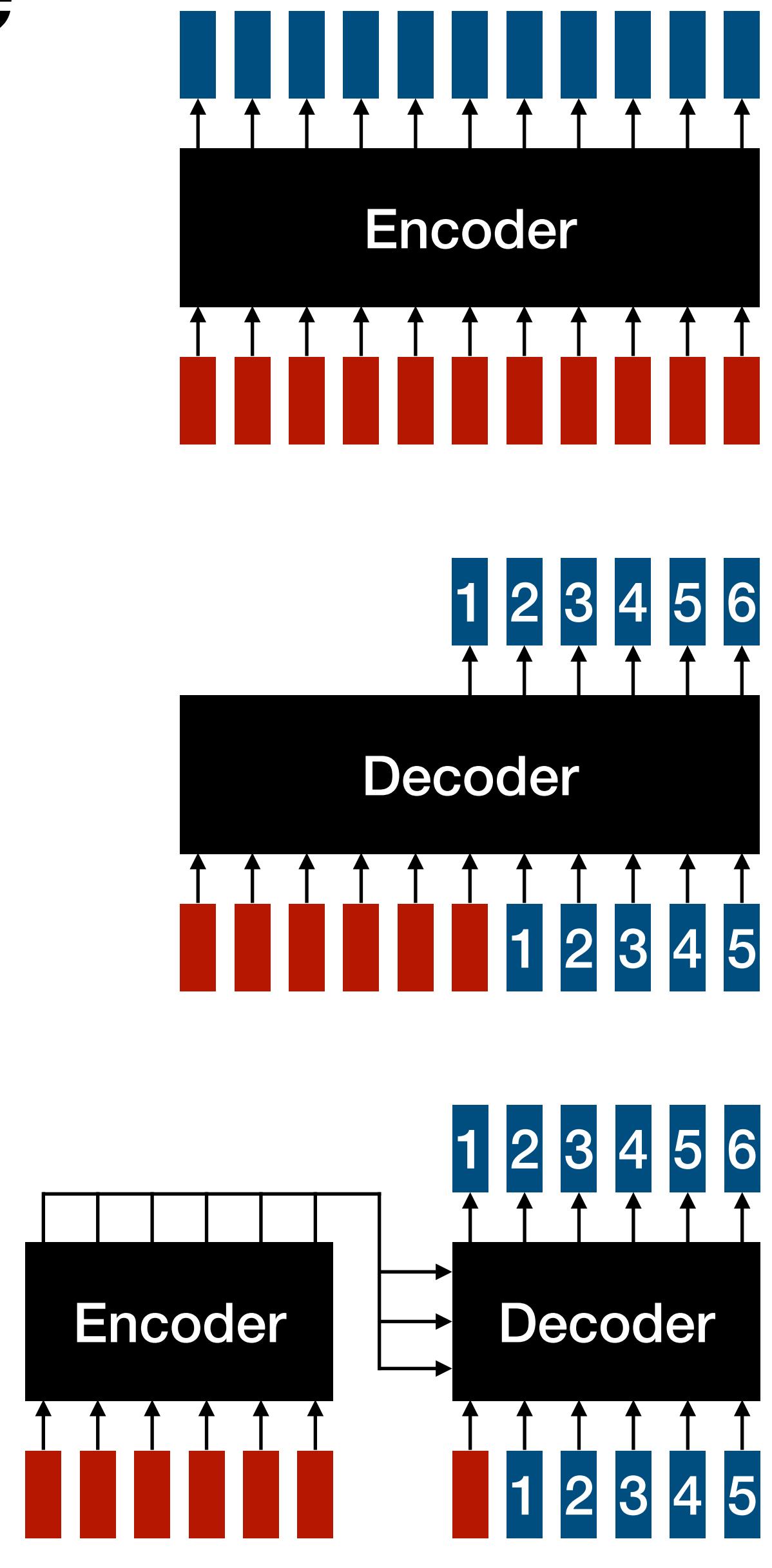
- Non-linearity φ in between (e.g., ReLU or GeLU)
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Big picture and takeaways

The transformer architecture can be used in different ways

- **Encoders** (e.g., element-level tagging, sequence-level classification):
 - They produce a fixed output size and process all inputs simultaneously
- **Decoders** (e.g., ChatGPT):
 - **Auto-regressively sample** the next token as $\mathbf{x}_{t+1} \sim \text{softmax}(f(\mathbf{x}_1, \dots, \mathbf{x}_t))$ and append it to the input as a **new token**; repeat
 - Capable of generating responses of arbitrary length
- **Encoder-decoder** (e.g., translation):
 - First encode the whole input (e.g., in one language) and then decode token by token (e.g., in a different language)



Transformers: big picture

- “**Tokenize everything**”: Everything can be seen as tokens, hence transformers are applicable across any modality
- **CNNs can also be used for text processing, but transformers excel at capturing long-range dependencies** (as an example, the latest GPT-4 model can process up to 128k input tokens, equivalent to ~300 pages of text).
- **Self-attention scales quadratically with sequence length**, making it computationally expensive for large volumes of text or numerous patches—active area of research
- **However, self-attention is highly parallelizable**, which is advantageous for multi-GPU or multi-node training setups
- Transformers are now the **preferred method** for both text and vision applications
- **Emergent abilities at scale**: few-shot learning (aka in-context learning from a few example) and zero-shot learning (e.g., you can ask ChatGPT any question without prior training on the task)

Recap

- **Transformers** iteratively map sequences to sequences using the self-attention mechanism
- The whole architecture is remarkably simple:
 - **Self-attention blocks** mix the information **between** tokens
 - **MLP blocks** mix the information **within** each token
- Transformers excel at modeling long-range dependencies
- Different architectures are possible (e.g., ChatGPT is decoder-only, but neural translation typically employs an encoder-decoder)
- Transformers have become a **universal architecture** for almost any type of data modality; they perform exceptionally well when given enough pretraining data

Additional Resources

If you want to learn more about attention and transformers:

- **The Illustrated Transformer:** <https://jalammar.github.io/illustrated-transformer/> (a good step-by-step guide with detailed illustrations)
- **The blog of Lillian Weng (OpenAI):** <https://lilianweng.github.io/posts/2018-06-24-attention/> (from 2018 but covers well the history of the attention mechanism and its different versions)
- **CS231n: Deep Learning for Computer Vision (Stanford):** http://cs231n.stanford.edu/slides/2023/lecture_9.pdf (more on positional encodings, masked self-attention, general attention, discussion of recurrent neural networks)
- **Minimal implementation of GPT-2:** <https://github.com/karpathy/nanoGPT/> (some things are just clearer in code)