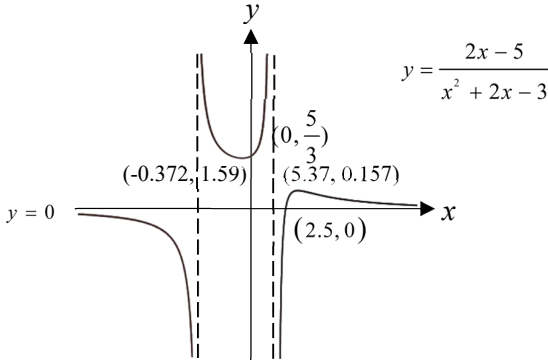
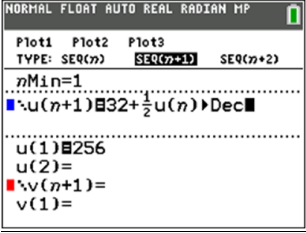
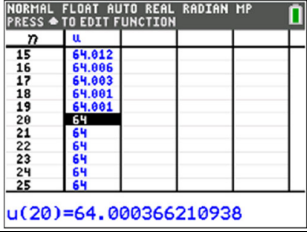


Q1	Suggested Answers
(a)	$y = \frac{a}{x^2} + be^{2x} + c$ <p>Sub $x=1, y=2e^2 - 1$</p> $a + be^2 + c = 2e^2 - 1 \text{ ---(1)}$ <p>After scaling,</p> $y = \frac{a}{\left(\frac{x}{2}\right)^2} + be^{2\left(\frac{x}{2}\right)} + c = \frac{4a}{x^2} + be^x + c$ <p>Sub $x=-1, y=8 + \frac{2}{e}$</p> $4a + be^{-1} + c = 8 + \frac{2}{e} \text{ ---(2)}$ <p>After translation</p> $y = \frac{a}{x^2} + be^{2x} + c - 1$ <p>Sub</p> $x = \sqrt{3}, y = 2e^{2\sqrt{3}} - 4$ $\frac{a}{3} + be^{2\sqrt{3}} + c = 2e^{2\sqrt{3}} - 3 \text{ ---(3)}$ <p>Using GC,</p> $a = 3, b = 2, c = -4$

Q2	Suggested Answers
(a)	<p>Method 1:</p> $x^2 + 4x + 9 = (x + 2)^2 + 5$ <p>Since $(x + 2)^2 \geq 0$, $(x + 2)^2 + 5 > 0$.</p> <p>Therefore, $x^2 + 4x + 9$ is always positive for all real values of x.</p>
	<p>Method 2:</p> $b^2 - 4ac = 4^2 - 4(1)(9) = -20$ <p>Since the discriminant < 0 and that the coefficient of x^2 is positive, therefore, $x^2 + 4x + 9$ is always positive for all real values of x.</p>
(b)	$\frac{(x^2 + 4x + 9)(x + 2)^2}{x^2 - 6x + 7} \leq 0$ <p>Since $x^2 + 4x + 9 > 0$</p> $\frac{(x + 2)^2}{x^2 - 6x + 7} \leq 0$ $\frac{(x + 2)^2}{(x - 3)^2 - 2} \leq 0$ $\frac{(x + 2)^2}{(x - 3 + \sqrt{2})(x - 3 - \sqrt{2})} \leq 0$ <div style="text-align: center;"> $\begin{array}{ccccccc} & + & & + & & - & & + \\ & \bullet & & \oplus & & & & \oplus \\ & -2 & & 3 - \sqrt{2} & & & & 3 + \sqrt{2} \end{array}$ </div> <p>$\therefore x = -2$ or $3 - \sqrt{2} < x < 3 + \sqrt{2}$</p>

Q3	Suggested Answers
(a)	
(b)	$(x+3)^2 + \left(\frac{2x-5}{x^2+2x-3}\right)^2 = k^2$ $(x+3)^2 + y^2 = k^2$ $k = \sqrt{\left(\frac{5}{3} - 0\right)^2 + (0 - (-3))^2}$ $= \sqrt{\frac{25}{9} + 9}$ $= \sqrt{\frac{106}{9}}$ $= \frac{\sqrt{106}}{3}$ $\therefore k > \frac{\sqrt{106}}{3}$

Q4	Suggested Answers
(a)	$U_4 = p + qU_3 \Rightarrow 76 = p + 88q \text{ --- (1)}$ $U_5 = p + qU_4 \Rightarrow 70 = p + 76q \text{ --- (2)}$ <p>Solving equation (1) and (2): $p = 32, q = 0.5$</p>
(b)	<p>Method 1:</p> $U_3 = p + qU_2 \Rightarrow 88 = 32 + (0.5)U_2 \Rightarrow U_2 = 112$ $U_2 = p + qU_1 \Rightarrow 112 = 32 + (0.5)U_1 \Rightarrow U_1 = 160$ $U_1 = p + qU_0 \Rightarrow 160 = 32 + (0.5)U_0 \Rightarrow U_0 = 256$

(b)	<p>Method 2:</p> $U_3 = 32 + \frac{1}{2}U_2$ $= 32 + \frac{1}{2}\left(32 + \frac{1}{2}U_1\right)$ $= 32 + \frac{1}{2}\left(32 + \frac{1}{2}\left(32 + \frac{1}{2}U_0\right)\right)$ $88 = 32 + \frac{1}{2}\left(32 + \frac{1}{2}\left(32 + \frac{1}{2}U_0\right)\right)$ $\therefore U_0 = 256$
(c)	<p>Method 1: Using GC to get 64</p> <div style="display: flex; justify-content: space-around;">   </div> <p>Method 2:</p> <p>As $t \rightarrow \infty, C_t \rightarrow L, C_{t+1} \rightarrow L$</p> $L = 32 + \frac{1}{2}L$ $2L = 64 + L$ $L = 64$ <p>The readings decreases and converges to 64.</p>

Q5	Suggested Answers
(a)	$\mathbf{a} \times \mathbf{b} = \begin{pmatrix} 3 \\ 2 \\ -1 \end{pmatrix} \times \begin{pmatrix} 4 \\ -3 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix}$ <p>Area of $\triangle AOB$</p> $= \frac{1}{2} \mathbf{a} \times \mathbf{b} $ $= \frac{1}{2} \left \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix} \right $ $= \frac{1}{2} \sqrt{1 + 100 + 289}$ $= \frac{1}{2} \sqrt{390} \text{ units}^2$

(b)

Method 1:

Perpendicular ht of tetrahedron =

$$\frac{1}{\sqrt{1+100+289}} \left| \overrightarrow{OC} \cdot \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix} \right| = \frac{1}{\sqrt{390}} \left| \begin{pmatrix} 3 \\ -1 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix} \right| = \frac{30}{\sqrt{390}}$$

$$\text{Vol of tetrahedron OABC} = \frac{1}{3} \left(\frac{\sqrt{390}}{2} \right) \left(\frac{30}{\sqrt{390}} \right) = 5 \text{ units}^3$$

Method 2

Let X be the foot of perpendicular from C to plane OAB .

$$\overrightarrow{OX} = \begin{pmatrix} 3 \\ -1 \\ -1 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix}, \text{ for some } \mu \in \mathbb{R}$$

$$\mathbf{r} \cdot \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix} = 0$$

Equation of plane OAB :

Since the point X also lies on the plane OAB ,

$$\left(\begin{pmatrix} 3 \\ -1 \\ -1 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix} \right) \cdot \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix} = 0$$

$$3 + \mu + 10 + 100\mu + 17 + 289\mu = 0$$

$$390\mu = -30$$

$$\mu = -\frac{1}{13}$$

$$\overrightarrow{CX} = \overrightarrow{OX} - \overrightarrow{OC}$$

$$= \begin{pmatrix} 3 \\ -1 \\ -1 \end{pmatrix} - \frac{1}{13} \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix} - \begin{pmatrix} 3 \\ -1 \\ -1 \end{pmatrix}$$

$$= -\frac{1}{13} \begin{pmatrix} 1 \\ -10 \\ -17 \end{pmatrix}$$

$$\begin{aligned} \text{perpendicular height, } |\overrightarrow{CX}| &= \frac{1}{13} \sqrt{1 + (-10)^2 + (-17)^2} \\ &= \frac{\sqrt{390}}{13} \\ &= \frac{30}{\sqrt{390}} \end{aligned}$$

(c)	<p>Method 1</p> <p>Perpendicular distance from B to line OA</p> $= \mathbf{b} \times \hat{\mathbf{a}} $ $= \frac{\sqrt{390}}{\sqrt{9+4+1}}$ $= \sqrt{\frac{195}{7}} \text{ or } 5.28$
	<p>Method 2</p> <p>Area of $OAB = \frac{1}{2}\sqrt{390} = \frac{1}{2}OA(h)$</p> <p>Thus, perpendicular distance from B to line $OA = h = \sqrt{\frac{390}{14}} = \sqrt{\frac{195}{7}}$</p>

Q6	Suggested Answers
(a)	<p>NEW</p> $S_n = n^2 + 2n$ $S_n = n^2 + 2n$ $u_n = S_n - S_{n-1}$ $= (n^2 + 2n) - ((n-1)^2 + 2(n-1))$ $= n^2 + 2n - n^2 + 2n - 1 - 2n + 2$ $= 2n + 1$ $u_{n+1} - u_n = (2(n+1) + 1) - (2n + 1)$ $= 2n + 3 - 2n - 1$ $= 2$ <p>Since $u_{n+1} - u_n = 2$ is a constant, it is an arithmetic series.</p> <p>$\therefore d = 2$</p> $u_n = 2n + 1$ $a + (n-1)2 = 2n + 1$ $a + 2n - 2 = 2n + 1$ $a = 3$
(b)	$a = 12$ $u_6 = -\frac{3}{8}$ $\Rightarrow ar^5 = -\frac{3}{8}$ $\Rightarrow r^5 = -\frac{1}{32}$ $\Rightarrow r = -\frac{1}{2}$

$$S_n = \frac{a(1-r^n)}{1-r}$$

$$= \frac{12 \left(1 - \left(-\frac{1}{2} \right)^n \right)}{1 - \left(-\frac{1}{2} \right)}$$

$$= 8 \left(1 - \left(-\frac{1}{2} \right)^n \right)$$

$$S = \frac{a}{1-r}$$

$$= \frac{12}{1 - \left(-\frac{1}{2} \right)}$$

$$= 8$$

$$|S_n - S| < 0.001$$

$$\left| 8 \left(1 - \left(-\frac{1}{2} \right)^n \right) - 8 \right| < 0.001$$

$$\left| 8 \left(1 - \left(-\frac{1}{2} \right)^n \right) - 8 \right| - 0.001 < 0$$

From GC,

n	$\left 8 \left(1 - \left(-\frac{1}{2} \right)^n \right) - 8 \right - 0.001$
12	$9.53 \times 10^{-4} > 0$
13	$-2.34 \times 10^{-5} < 0$

Therefore, the least value of n is 13.

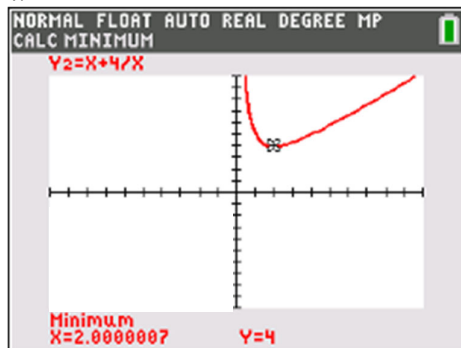
Q7	Suggested Answers
(a)	<div data-bbox="337 226 794 569" data-label="Figure"> </div> <p> $R_f = [0, \infty)$ $D_g = \mathbb{R}^+$ $R_f \not\subseteq D_g$ Thus gf does not exist. </p>
(b)	<p>Method 1:</p> <p>Consider the different scenarios:</p> <div data-bbox="337 932 1227 1140" data-label="Figure"> </div> <p> If $\alpha > 0$, g will have a turning point at $x = \sqrt{\alpha}$, making g not an one-one function and g^{-1} will not exist. Hence, $\alpha \leq 0$. </p> <p>Method 2:</p> <p>We need $g'(x) = 1 - \frac{\alpha}{x^2} > 0$ for g^{-1} to exist.</p> <p>Since $x^2 > 0, \alpha < 0$</p> <p>Also, when $\alpha = 0$, $g(x) = x$ is also an one-one function.</p> <p>Hence, $\alpha \leq 0$</p>

(c)

$$g(x) = x + \frac{4}{x}$$

$$g'(x) = 1 - \frac{4}{x^2} = 0$$

$$x = \pm 2$$



From graph, least $\beta = 2$ since we need g to be one-one function.

(or since $x > 0$, $\beta = 2$)

$$y = x + \frac{4}{x}$$

$$xy = x^2 + 4$$

$$x = \frac{y \pm \sqrt{y^2 - 4(1)(4)}}{2}$$

$$\text{since } x \geq 2, x = \frac{y + \sqrt{y^2 - 16}}{2}$$

$$g^{-1}(x) = \frac{1}{2}(x + \sqrt{x^2 - 16})$$

$$D_{g^{-1}} = R_g = [4, \infty)$$

Q8 Suggested Answers

(a)

$$y = \sqrt{\ln(x + e)} \Rightarrow y^2 = \ln(x + e) \Rightarrow e^{y^2} = x + e$$

$$2ye^{y^2} \frac{dy}{dx} = 1 \Rightarrow 2y \frac{dy}{dx} = e^{-y^2} \text{ (shown)}$$

OR

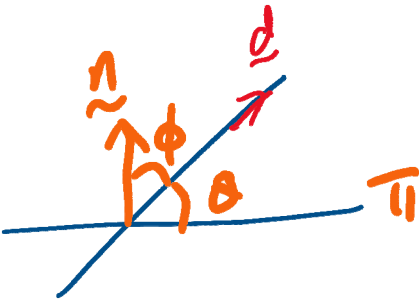
Differentiate w.r.t. x gives

$$2y \frac{dy}{dx} = \frac{1}{x + e} = \frac{1}{e^{y^2}} \text{ since } y^2 = \ln(x + e) \Rightarrow x + e = e^{y^2}$$

$$\text{That is, } 2y \frac{dy}{dx} = e^{-y^2}.$$

Differentiate w.r.t. x gives

	$2 \left[y \frac{d^2 y}{dx^2} + \left(\frac{dy}{dx} \right)^2 \right] = -2y \frac{dy}{dx} e^{-y^2}$ $y \frac{d^2 y}{dx^2} + \left(\frac{dy}{dx} \right)^2 = -y \frac{dy}{dx} e^{-y^2}$ <p>When $x=0$, $y=1$, $\frac{dy}{dx} = \frac{1}{2e}$, $\frac{d^2 y}{dx^2} = -\frac{3}{4e^2}$.</p> $y = 1 + \frac{1}{2e}x + \frac{1}{2!} \left(-\frac{3}{4e^2} \right) x^2 + \dots = 1 + \frac{1}{2e}x - \frac{3}{8e^2}x^2 + \dots$
(b)	$\ln(x+e) = \ln e \left(1 + \frac{x}{e} \right)$ $= 1 + \ln \left(1 + \frac{x}{e} \right)$ $= 1 + \frac{x}{e} - \frac{1}{2} \left(\frac{x}{e} \right)^2 + \dots$ $= 1 + \left(\frac{x}{e} - \frac{x^2}{2e^2} + \dots \right)$ $y = \sqrt{\ln(x+e)}$ $= \left[\ln(x+e) \right]^{\frac{1}{2}}$ $= \left[1 + \left(\frac{x}{e} - \frac{x^2}{2e^2} + \dots \right) \right]^{\frac{1}{2}}$ $= 1 + \frac{1}{2} \left(\frac{x}{e} - \frac{x^2}{2e^2} + \dots \right) + \frac{\left(\frac{1}{2} \right) \left(-\frac{1}{2} \right)}{2!} \left(\frac{x}{e} - \frac{x^2}{2e^2} + \dots \right)^2 + \dots$ $= 1 + \frac{1}{2e}x - \frac{3}{8e^2}x^2 + \dots$ <p>which agrees with the expansion in (a).</p>
(c)	$\sqrt{\ln \left(\frac{1+10e}{10} \right)} = \sqrt{\ln \left(\frac{1}{10} + e \right)}$ $\approx 1 + \frac{1}{2e} \left(\frac{1}{10} \right) - \frac{3}{8e^2} \left(\frac{1}{10} \right)^2$ $= 1 + \frac{1}{20e} - \frac{3}{800e^2}$ $= \frac{800e^2 + 40e - 3}{800e^2}$

Q9	Suggested Answers
(a)	$\mathbf{n}_1 = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} \times \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ -6 \\ 3 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$ $\cos \theta = \frac{\begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -4 \\ 5 \end{pmatrix}}{\sqrt{1+4+1}\sqrt{1+16+25}} = \frac{14}{\sqrt{6}\sqrt{42}}$ $\theta = 28.1^\circ$
(b)	$\Pi_1 : \mathbf{r} \cdot \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} = 4$ $\Pi_1 : x - 2y + z = 4$ $\Pi_2 : x - 4y + 5z = 12$ <p>Using GC, Line of intersection has equation</p> $\mathbf{r} = \begin{pmatrix} -4 \\ -4 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}, \lambda \in \mathbb{R}$
(c)	$l : \mathbf{r} = \begin{pmatrix} m \\ 2m+1 \\ -3 \end{pmatrix} + \lambda \begin{pmatrix} 3n \\ -3 \\ n \end{pmatrix}$ $\theta = \sin^{-1} \frac{2}{\sqrt{6}}$ $\sin \theta = \frac{2}{\sqrt{6}}$ $\cos\left(\frac{\pi}{2} - \theta\right) = \frac{2}{\sqrt{6}}$ $\cos \phi = \frac{2}{\sqrt{6}}$ 

$$\frac{\begin{pmatrix} 3n \\ -3 \\ n \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}}{\sqrt{(3n)^2 + 9 + n^2} \sqrt{6}} = \frac{2}{\sqrt{6}}$$

$$\frac{3n + 6 + n}{\sqrt{10n^2 + 9}} = 2$$

$$(2n + 3)^2 = 10n^2 + 9$$

$$n = 0 \text{ (rej, } n > 0) \text{ or } n = 2$$

Using distance of point to plane formula $\frac{|\mathbf{b} \cdot \mathbf{n} - D|}{|\mathbf{n}|}$

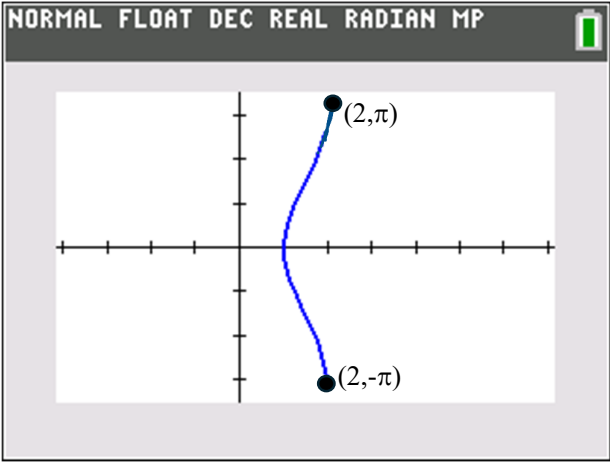
$$\text{Perpendicular distance from } A \text{ to plane } \Pi_1 = \frac{15}{\sqrt{6}}$$

$$\frac{\left| \begin{pmatrix} m \\ 2m+1 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} - 4 \right|}{\sqrt{6}} = \frac{15}{\sqrt{6}}$$

$$\frac{|m - 4m - 2 - 3 - 4|}{\sqrt{6}} = \frac{15}{\sqrt{6}}$$

$$-3m - 9 = \pm 15$$

$$m = -8 \text{ (rej, } m > 0) \text{ or } m = 2$$

Q10	Suggested Answers
(a)	
(b)	<p> $x = 1 + t^2, \quad y = 2 \sin^{-1} t \quad \text{for } t \leq 1.$ </p> $\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}}$ $= \frac{2}{2t\sqrt{1-t^2}}$ $= \frac{1}{t\sqrt{1-t^2}}$
(c)	<p>At P, $y = 0 \Rightarrow 2 \sin^{-1} t = 0 \Rightarrow t = 0$.</p> <p>When $t = 0$, $x = 1$ which gives the x-coordinate of P.</p> <p>Since $\left. \frac{dy}{dx} \right _{x=1} = \left. \frac{1}{t\sqrt{1-t^2}} \right _{t=0}$ is undefined, the robot is moving in a direction parallel to the y-axis.</p> <p>So the equation of the line is $x = 1$.</p>
(d)	<p> $y = \frac{\pi}{3} \Rightarrow 2 \sin^{-1} t = \frac{\pi}{3} \Rightarrow \sin^{-1} t = \frac{\pi}{6} \Rightarrow t = \frac{1}{2}.$ </p> $\left. \frac{dy}{dx} \right _{t=\frac{1}{2}} = \frac{1}{\frac{1}{2}\sqrt{1-\left(\frac{1}{2}\right)^2}} = \frac{4}{\sqrt{3}}.$ <p>The angle θ which the direction of motion of the robot makes with the positive x-axis is given by</p>

	$\tan \theta = \frac{4}{\sqrt{3}} \Rightarrow \theta \approx 66.6^\circ . \text{ (or 1.16 rad)}$
(e)	$s = \sqrt{(1+t^2-2)^2 + (2\sin^{-1}t-2)^2}$ $= \sqrt{(t^2-1)^2 + [2(\sin^{-1}t-1)]^2}$ $= \sqrt{(t^2-1)^2 + 4(\sin^{-1}t-1)^2}$
(f)	$s^2 = (t^2-1)^2 + 4(\sin^{-1}t-1)^2 .$ <p>Differentiate w.r.t. t gives</p> $s^2 = (t^2-1)^2 + 4(\sin^{-1}t-1)^2$ $2s \frac{ds}{dt} = 4t(t^2-1) + \frac{8(\sin^{-1}t-1)}{\sqrt{1-t^2}}$ <p>For least s, $\frac{ds}{dt} = 0$</p> $\Rightarrow 4t(t^2-1) + \frac{8(\sin^{-1}t-1)}{\sqrt{1-t^2}} = 0$ $\Rightarrow t(t^2-1) + \frac{2(\sin^{-1}t-1)}{\sqrt{1-t^2}} = 0$ <p>By GC, $t = 0.86879$.</p> <p>Minimum distance</p> $s = \sqrt{(0.86879^2-1)^2 + 4(\sin^{-1} 0.86879-1)^2} \approx 0.267$ <p>Since $s > 0.25$, the robot will not be attracted by the magnet.</p>