Anderson Junior College Preliminary Examination 2011 H2 Mathematics Paper 1 (Solutions)

$$\int x \cos^{-1} x^{2} dx$$

$$= \frac{x^{2}}{2} \cos^{-1} x^{2} - \int \frac{x^{2}}{2} \left(\frac{-2x}{\sqrt{1 - x^{4}}} \right) dx$$

$$= \frac{x^{2}}{2} \cos^{-1} x^{2} - \frac{1}{4} \int \frac{-4x^{3}}{\sqrt{1 - x^{4}}} dx$$

$$= \frac{x^{2}}{2} \cos^{-1} x^{2} - \frac{1}{2} \sqrt{1 - x^{4}} + C$$

Let the price of a X-box console be \$x, a Kinect sensor be \$y and a Game DVD be \$z. x + y + z = 499

$$0.9x + 0.85y + 0.9z = 439.15$$

$$0.95x + 0.75y + 0.8z = 426.30$$

Aug matrix =
$$\begin{pmatrix} 1 & 1 & 1 & 499 \\ 0.9 & 0.85 & 0.9 & 439.15 \\ 0.95 & 0.75 & 0.8 & 426.30 \end{pmatrix} \Rightarrow \text{rref} = \begin{pmatrix} 1 & 0 & 0 & 247 \\ 0 & 1 & 0 & 199 \\ 0 & 0 & 1 & 53 \end{pmatrix}$$

$$x = 247$$
, $y = 199$, $z = 53$

Employees of Company P will pay [0.9(247)+0.8(199)+0.85(53)] = 426.55 > 426.30. No, it will not be more attractive for employees to purchase all the 3 items from own company.

$$\frac{3}{(x)(x-b)} < 0, \quad x \neq c, x \neq 0$$

Since
$$(x-c)^2 > 0$$
 as $x \neq c$,

$$\frac{(x+a)(x-b)}{x} < 0$$

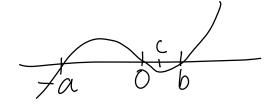
$$x(x+a)(x-b)<0$$

$$x < -a$$
 or $0 < x < b$ and $x \ne c$

Replace x by $\ln x$.

$$\ln x < -a$$
 or $0 < \ln x < b$ and $\ln x \neq c$

$$0 < x < e^{-a}$$
 or $1 < x < e^{b}$ and $x \neq e^{c}$



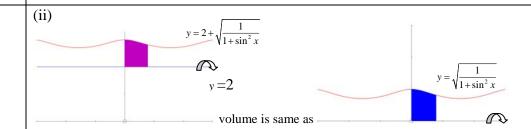
4 (i)
$$t = \tan x \Rightarrow \frac{dt}{dx} = \sec^2 x = 1 + t^2$$

$$= \int \frac{1}{1 + \frac{t^2}{1 + t^2}} \left(\frac{1}{1 + t^2}\right) dt$$

$$= \int \frac{1}{1 + 2t^2} dt$$

$$= \frac{1}{\sqrt{2}} \tan^{-1} \sqrt{2}t + c$$

$$= \frac{1}{\sqrt{2}} \tan^{-1} \sqrt{2} \tan x + c$$



Exact volume =
$$\pi \int_0^{\frac{\pi}{4}} \left(\sqrt{\frac{1}{1 + \sin^2 x}} \right)^2 dx$$

= $\pi \left[\frac{1}{\sqrt{2}} \tan^{-1} \sqrt{2} \tan x \right]_0^{\frac{\pi}{4}}$
= $\frac{\pi}{\sqrt{2}} \tan^{-1} \sqrt{2}$

- 5 Method 1:
- (a) $\int \sin 2x \cos x \, dx$ $= \frac{1}{2} \int \sin 3x + \sin x \, dx$ $= \frac{1}{2} \left(-\frac{\cos 3x}{3} \cos x \right) + C$ $= -\frac{1}{2} \left(\frac{\cos 3x}{3} + \cos x \right) + C$

Method 2: $\int \sin 2x \cos x \, dx$

$$= \int 2\sin x \cos^2 x \, dx \qquad [\text{use } \int f(x)[f(x)]^n \, dx = \frac{[f(x)]^{n+1}}{n+1} + c]$$
$$= -\frac{2}{3}\cos^3 x + C$$

$$= -\frac{2}{3}\cos^3 x + C$$
(b) (i) $\frac{dx}{dt} = \cos t + 1$, $\frac{dy}{dt} = 2\cos 2t$

$$\frac{dy}{dx} = \frac{dy}{dt}\frac{dt}{dx} = \frac{2\cos 2t}{\cos t + 1}$$

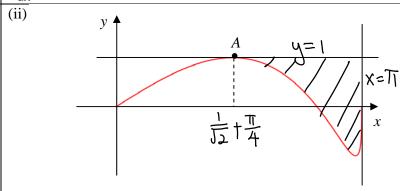
When
$$\frac{dy}{dx} = 0$$
, $\cos 2t = 0 \implies 2t = \frac{\pi}{2}, \frac{3\pi}{2} \implies t = \frac{\pi}{4}, \frac{3\pi}{4} \implies x = \frac{1}{\sqrt{2}} + \frac{\pi}{4}, \frac{1}{\sqrt{2}} + \frac{3\pi}{4}$
At point A , $x = \frac{1}{\sqrt{2}} + \frac{\pi}{4}$, $y = 1$

At point A,
$$x = \frac{1}{\sqrt{2}} + \frac{\pi}{4}$$
, $y = 1$

 \therefore y = 1 is the equation of the tangent to the curve at point A.

Or

Since $0 \le t \le \pi$, the maximum and minimum values of y (i.e. $y = \sin 2t$) is 1 and -1. The ycoordinate of point A is 1 and since the tangent to this max pt is a horizontal line $(\frac{dy}{dx} = 0)$, therefore the equation of the tangent to the curve at point A is y = 1.



$$= \frac{1}{2} \left(1 - \frac{1}{2} \left(2x - \frac{8x^3}{6} \right) + \frac{1}{4} (2x + ...)^2 - \frac{1}{8} (2x + ...)^3 + ... \right)$$

$$= \frac{1}{2} \left(1 - x + \frac{2x^3}{3} + x^2 - x^3 + ... \right)$$

$$= \frac{1}{2} - \frac{1}{2} x + \frac{1}{2} x^2 - \frac{1}{6} x^3 + ...$$

which is the same as the series obtained by using Maclaurin's theorem.

7 (i) 2y + 2z = 48, x + 2z = 18

Expressing z and x in terms of y,

$$z = 24 - y, x = 2y - 30$$

$$V = xyz = (2y - 30)y(24 - y)$$

$$= -2y^{3} + 78y^{2} - 720y$$

(ii) $\frac{dV}{dy} = 0$ $-6y^2 + 156y - 720 = 0$ $y^2 - 26y + 120 = 0$ Using G.C, y = 6 or y = 20 y = 6 is not a feasible solution as x will be negative. $\frac{d^2V}{dy^2} = -12y + 156$

When
$$y = 20$$
, $\frac{d^2V}{dy^2} = -84 < 0$

Hence, when y = 20,

Maximum volume = $20(2 \times 20 - 30)(24 - 20) = 800$

(iii) Let *t* be the time in seconds when robot A starts to move.

m = 2t and n = t-1

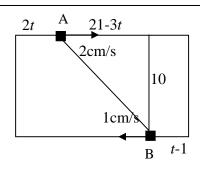
Distance between A and B = l,

$$l^2 = \left(21 - 3t\right)^2 + 10^2$$

Differentiating wrt t,

$$2l\frac{\mathrm{d}l}{\mathrm{d}t} = 2(21-3t)(-3)$$

At
$$n = 4$$
, $t = 5$



$$\frac{\mathrm{d}l}{\mathrm{d}t} = \frac{(6)(-3)}{\sqrt{6^2 + 10^2}} = -\frac{9}{\sqrt{34}}$$
 cm/s

Method 2:

$$l^2 = (20 - m - n)^2 + 10^2$$

Since m = 2n + 2,

$$l^2 = (18 - 3n)^2 + 10^2$$

Differentiating wrt n,

$$2l\frac{dl}{dn} = -6(18 - 3n)$$

At
$$n = 4$$
, $l^2 = 10^2 + 6^2$.

$$\frac{\mathrm{d}l}{\mathrm{d}n} = \frac{-18}{\sqrt{10^2 + 6^2}}$$

$$\frac{dl}{dt} = \frac{dl}{dn} \frac{dn}{dt} = \frac{-18}{\sqrt{10^2 + 6^2}} (1) = \frac{-18}{\sqrt{10^2 + 6^2}} = -\frac{9}{\sqrt{34}}$$
cm/s

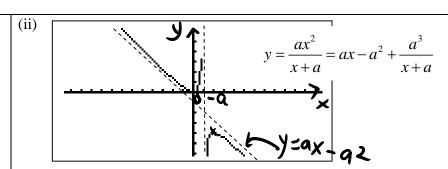
 $y = \frac{ax^2}{x+a}$

(i)
$$\frac{dy}{dx} = \frac{(x+a)2ax - ax^2}{(x+a)^2} = \frac{ax^2 + 2a^2x}{(x+a)^2}$$

Set
$$\frac{dy}{dx} = 0 \implies ax^2 + 2a^2x = 0 \implies ax(x+2a) = 0 \implies x = 0 \text{ or } x = -2a$$

For all negative values of a, there will be two distinct values of x thus two stationary pts. (shown)

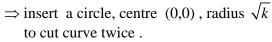
Or $B^2 - 4AC = 4a^2 > 0$ for all negative values of a.



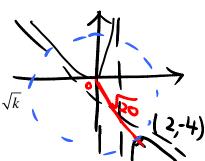
Max pt is (-2a, -4a²) Min pt is (0,0)

(iii)
$$x^4 = (k - x^2)(x-1)^2 \Rightarrow a = -1$$

$$\Rightarrow \left(\frac{-x^2}{x-1}\right)^2 = k - x^2 \Rightarrow y^2 = k - x^2$$



$$\Rightarrow$$
 0 < k < 20



9 (i)
$$\begin{pmatrix} \mu \\ 2\mu \\ 2\mu \end{pmatrix} = \begin{pmatrix} -\lambda \\ 2\lambda \\ -2+2\lambda \end{pmatrix} \Rightarrow \mu = \lambda \quad ---(1) \\ \Rightarrow \mu = \lambda \quad ---(2) \\ \mu = \lambda - 1 \quad ---(3)$$

The first and second equation has only 1 solution i.e. $\lambda=0$ and $\mu=0$ and it is obvious that equation (3) will be inconsistent for this solution; this implies that l_1 and l_2 are non-intersecting lines.

Since l_1 and l_2 are non-parallel lines as $\begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} \neq k \begin{pmatrix} -1 \\ 2 \\ 2 \end{pmatrix}$ where k is a scalar

Since l_1 and l_2 are non-parallel and non-intersecting lines, l_1 and l_2 are skew lines.

(ii) Let
$$\overrightarrow{OX} = \begin{pmatrix} -\lambda \\ 2\lambda \\ -2+2\lambda \end{pmatrix}$$
 and $\overrightarrow{OY} = \begin{pmatrix} \mu \\ 2\mu \\ 2\mu \end{pmatrix}$

$$\overline{OZ} = \frac{1}{2} \left(\overline{OX} + \overline{OY} \right) = \frac{1}{2} \begin{bmatrix} -\lambda \\ 2\lambda \\ -2 + 2\lambda \end{bmatrix} + \begin{pmatrix} \mu \\ 2\mu \\ 2\mu \end{bmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} + \lambda \begin{pmatrix} -\frac{1}{2} \\ 1 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} \frac{1}{2} \\ 1 \\ 1 \end{pmatrix}$$

Since λ and μ can be any real number, the locus of Z is a plane that passes through (0, 0, -1)

1) and parallel to both $-\frac{1}{2}i + j + k$ and $\frac{1}{2}i + j + k$,

Therefore
$$\begin{pmatrix} -\frac{1}{2} \\ 1 \\ 1 \end{pmatrix} \times \begin{pmatrix} \frac{1}{2} \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$
 is a normal to the plane p . The equation in scalar product

form is

$$p: \mathbf{r} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = 1$$

form is
$$p: \mathbf{r} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix} = 1$$
(iii) Let $\overrightarrow{OS} = \begin{pmatrix} -\lambda \\ 2\lambda \\ -2+2\lambda \end{pmatrix}$ and $\overrightarrow{OS}' = \begin{pmatrix} \mu \\ 2\mu \\ 2\mu \end{pmatrix}$

Method 1:

$$\overline{S'S} = \begin{pmatrix} -\lambda \\ 2\lambda \\ -2 + 2\lambda \end{pmatrix} - \begin{pmatrix} \mu \\ 2\mu \\ 2\mu \end{pmatrix} = \begin{pmatrix} -\lambda - \mu \\ 2\lambda - 2\mu \\ -2 + 2\lambda - 2\mu \end{pmatrix}$$

This vector will be parallel to the normal of p.

$$\overline{S'S} = \begin{pmatrix} -\lambda - \mu \\ 2\lambda - 2\mu \\ -2 + 2\lambda - 2\mu \end{pmatrix} = k \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = k \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \Rightarrow \begin{aligned} \lambda + \mu &= 0 \\ 2\lambda - 2\mu &= k \\ -2 + 2\lambda - 2\mu &= -k \end{aligned}$$

Solving,
$$\lambda = \frac{1}{4} \implies \overrightarrow{OS} = \begin{pmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix}$$

Coordinates of S is
$$\left(-\frac{1}{4}, \frac{1}{2}, -\frac{3}{2}\right)$$

Method 2:

Let F be the midpoint between S and S',

$$\overrightarrow{OF} = \frac{1}{2} \left(\overrightarrow{OS} + \overrightarrow{OS'} \right) = \frac{1}{2} \begin{pmatrix} -\lambda - \mu \\ 2\lambda - 2\mu \\ -2 + 2\lambda - 2\mu \end{pmatrix}$$

and

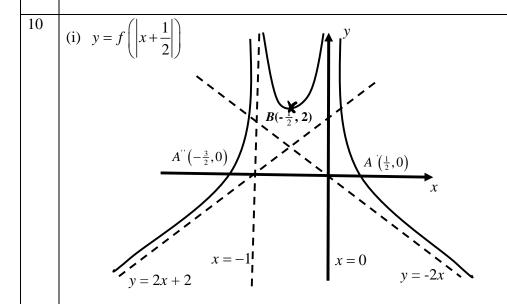
$$\overrightarrow{OF} = \overrightarrow{OS} + k \, \underline{n} = \begin{pmatrix} -\lambda \\ 2\lambda \\ -2 + 2\lambda \end{pmatrix} + k \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -\lambda \\ 2\lambda + k \\ -2 + 2\lambda - k \end{pmatrix}$$

Equating the position vector of point F,

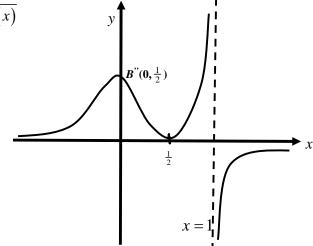
$$\frac{1}{2} \begin{pmatrix} -\lambda - \mu \\ 2\lambda - 2\mu \\ -2 + 2\lambda - 2\mu \end{pmatrix} = \begin{pmatrix} -\lambda \\ 2\lambda + k \\ -2 + 2\lambda - k \end{pmatrix} \Rightarrow \begin{aligned} \lambda + \mu &= 0 \\ 2\lambda - 2\mu &= k \\ -2 + 2\lambda - 2\mu &= -k \end{aligned}$$

Solving,
$$\lambda = \frac{1}{4} \implies \overrightarrow{OS} = \begin{pmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix}$$

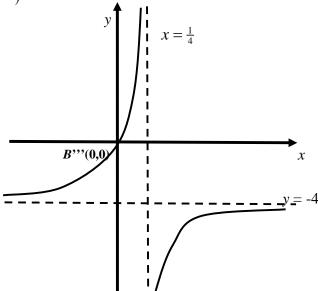
Coordinates of S is $\left(-\frac{1}{4}, \frac{1}{2}, -\frac{3}{2}\right)$







(iii)
$$y = f'(2x)$$



11 (i) Let P_n be the proposition: $u_n = na + (n-1)$ for $n \in \mathbb{Z}^+$.

When
$$n = 1$$
, LHS = $u_1 = a$

$$RHS = (1)a + 0 = a = LHS$$

Since LHS = RHS \therefore P₁ is true

Assume that P_k is true for some $k \in \mathbb{Z}^+$. i.e. $u_k = ka + (k-1)$

To prove that P_k is true $\Rightarrow P_{k+1}$ is true . i.e. to prove that $u_{k+1} = (k+1)a + (k+1) - 1$

RHS =
$$(k+1)a + (k+1) - 1 = (k+1)a + k$$

LHS =
$$u_{k+1} = \frac{k+1}{k}u_k + \frac{1}{k}$$

$$= \frac{k+1}{k}(ka+(k-1)) + \frac{1}{k}$$

$$= (k+1)a + \frac{(k+1)(k-1)}{k} + \frac{1}{k}$$

$$= (k+1)a + \frac{k^2 - 1}{k} + \frac{1}{k}$$

$$= (k+1)a + k - \frac{1}{k} + \frac{1}{k}$$

$$= (k+1)a + k = RHS$$

 $\therefore P_k$ is true $\Rightarrow P_{k+1}$ is true

As P_1 is true and P_k is true $\Rightarrow P_{k+1}$ is true, by the principle of mathematical induction P_n is true for all $n \in \mathbb{Z}^+$.

(ii)
$$a = 1$$
, $u_n = n + (n-1) = 2n - 1$, $u_{n-1} = 2(n-1) - 1 = 2n - 3$

$$\sum_{n=2}^{N} \frac{1}{u_n u_{n-1}}$$

$$= \sum_{n=2}^{N} \frac{1}{(2n-1)(2n-3)}$$

$$= \sum_{n=2}^{N} \left(\frac{1}{2(2n-3)} - \frac{1}{2(2n-1)}\right)$$

$$= \frac{1}{2} \sum_{n=2}^{N} \left(\frac{1}{(2n-3)} - \frac{1}{(2n-1)}\right)$$

$$= \frac{1}{2} \left[\frac{1}{1} - \frac{1}{3} + \frac{1}{3} - \frac{1}{5} + \frac{1}{2N-5} - \frac{1}{2N-3} + \frac{1}{2N-3} - \frac{1}{2N-1} + \frac{1}{2N-3} - \frac{1}{2N-1} + \frac{1}{2N-1} - \frac{1}{2N-1} + \frac{1}{2N-1} - \frac{1}{2N-1} + \frac{1}{2N-1} - \frac{1}{2N-1}$$
(Shown)

Since
$$\sum_{n=2}^{N} \frac{1}{(2n-1)(2n-3)} = \frac{1}{2} \left(1 - \frac{1}{2N-1} \right),$$

$$\sum_{n=2}^{N} \frac{1}{(2n+9)(2n+7)}$$

$$=\sum_{k=1}^{N+5} \frac{1}{(2k-1)(2k-3)}$$

$$=\sum_{k=2}^{N+5} \frac{1}{(2k-1)(2k-3)} - \sum_{k=3}^{6} \frac{1}{(2k-1)(2k-3)}$$

$$=\frac{1}{2} \left(1 - \frac{1}{2(N+5)-1}\right) - \frac{1}{2} \left[1 - \frac{1}{2(6)-1}\right]$$

$$=\frac{1}{2} \left(\frac{1}{11} - \frac{1}{2N+9}\right)$$

$$12 \quad \text{Given } S_n = \frac{1}{a} \left[1 - (a-1)^n\right],$$

$$T_n = S_n - S_{n-1}, \quad n \ge 2$$

$$=\frac{1}{a} \left[1 - (a-1)^n\right] - \frac{1}{a} \left[1 - (a-1)^{n-1}\right]$$

$$=-\frac{1}{a} (a-1)^n + \frac{1}{a} (a-1)^{n-1}$$

$$=\frac{1}{a} (a-1)^{n-1} (-a+1+1)$$

$$=\frac{1}{a} (a-1)^{n-1} (2-a)$$

$$T_n = \frac{1}{a} (a-1)^{n-1} (2-a), \quad n \in \mathbb{N}^+$$

$$\frac{T_n}{T_{n-1}} = \frac{1}{a} \frac{(a-1)^{n-1} (2-a)}{\frac{1}{a} (a-1)^{n-2} (2-a)} = (a-1) = \text{constant} \quad \text{(Shown)}$$

$$= (i) \text{ the total number of terms in the first } n \text{ brackets}$$

$$= 1 + 3 + 5 + \cdots (1 + (n-1)2)$$

$$= 1 + 3 + 5 + \cdots (2n-1)$$

$$= \frac{n}{2} (1 + (2n-1)) = n^2$$

$$= (ii) \text{ number of terms in the } 11^{th} \text{ bracket} = 1 + (11-1)2 = 21 \text{ terms}$$

$$\text{ (middle term will be the } 11^{th} \text{ term}$$

$$\text{Number of terms from } 1^{3t} \text{ bracket to } 10^{3t} \text{ bracket} = 10^2 = 100$$

$$T_{111} = \frac{1}{a} (a-1)^{1/10} (2-a)$$

$$\text{(iii)} \text{ For the sum to infinity of the series to exist, } |a-1| < 1$$

Method 1:

when
$$a = \frac{39}{20}$$
 (i.e. $|a-1|<1$),

sum to infinity of the series
$$=\frac{1}{a}[1-0] = \frac{1}{a}$$

For the sum of all the terms in the first n brackets to be within 0.1% of the sum to infinity of the series,

$$\left| \frac{S_{n^2} - S_{\infty}}{a} \right| < 0.1\% S_{\infty}$$

$$\left| \frac{1}{a} \left[1 - (a - 1)^{n^2} \right] - \frac{1}{a} \right| < 0.1\% \frac{1}{a}$$

$$\frac{1}{a} \left| -(a - 1)^{n^2} \right| < 0.001 (\frac{1}{a})$$

$$(a-1)^{n^2} < 0.001 \implies (\frac{19}{20})^{n^2} < 0.001$$

Using GC, n > 11.605

At least 12 brackets.

Method 2:

(iii) when
$$a = \frac{39}{20}$$
, first term $= \frac{2-a}{a} = \frac{1}{39}$, $r = (a-1) = \frac{19}{20}$

sum to infinity of the series
$$=$$
 $\frac{\frac{1}{39}}{1 - \frac{19}{20}} = \frac{20}{39}$

the sum of all the terms in the first n brackets

= the sum of n^2 terms in the GP

$$= \frac{1}{a} \left[1 - (a-1)^{n^2} \right] = \frac{20}{39} - \frac{20}{39} \left(\frac{19}{20} \right)^{n^2}$$

For the sum of all the terms in the first n brackets to be within 0.1% of the sum to infinity of the series,

$$\left| \frac{20}{39} - \frac{20}{39} \left(\frac{19}{20} \right)^{n^2} - \frac{20}{39} \right| < 0.1\% \frac{20}{39}$$

$$\left| -\frac{20}{39} \left(\frac{19}{20} \right)^{n^2} \right| < 0.001 \times \frac{20}{39}$$

$$\left(\frac{19}{20} \right)^{n^2} < 0.001$$

Using GC, n > 11.605

At least 12 brackets.

13 (i)
$$p^* + 10i = qi + 5$$
 ----- (1)

(a)
$$|p|^2 - q - 5 + 2i = 0 \implies q = |p|^2 - 5 + 2i$$

Substitute into (1): $p^* + 10i = (|p|^2 - 5 + 2i)i + 5$

Let p = x + yi

$$x - yi + 10i = (x^2 + y^2 - 5 + 2i)i + 5$$

Equating real parts: x = -2 + 5 = 3

Equating imaginary parts: $-y+10 = x^2 + y^2 - 5$

$$\Rightarrow -y+10=9+y^2-5$$

$$\Rightarrow$$
 $y^2 + y - 6 = 0$

$$\Rightarrow$$
 y = -3 or 2 (rejected as Im(p) < 0)

Therefore p = 3 - 3i.

$$|p| = \sqrt{3^2 + 3^2} = \sqrt{18}$$
 and $\arg(p) = -\frac{\pi}{4}$

$$p^{2n} = \left(\sqrt{18}e^{-i\frac{\pi}{4}}\right)^{2n}$$
$$= \left(\sqrt{18}\right)^{2n} \left(\cos\frac{2n\pi}{4} - i\sin\frac{2n\pi}{4}\right)$$

 p^{2n} is purely imaginary $\Rightarrow \cos \frac{n\pi}{2} = 0$

$$\Rightarrow$$
 $n = 2k + 1$, where $k \in \square$

(ii)
$$\arg\left(\frac{w}{p} - p^*\right) = -\frac{\pi}{2} \Rightarrow \arg\left(\frac{w - pp^*}{p}\right) = -\frac{\pi}{2}$$

$$\Rightarrow \arg\left(w - pp^*\right) - \arg\left(p\right) = -\frac{\pi}{2}$$

$$\Rightarrow \arg\left(w - 18\right) - \left(-\frac{\pi}{4}\right) = -\frac{\pi}{2}$$

$$\Rightarrow \arg\left(w - 18\right) = -\frac{3\pi}{4}$$

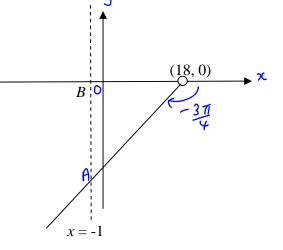


$$\Rightarrow x = -1$$

 \Rightarrow w is represented by point A

$$\tan\frac{\pi}{4} = \frac{BA}{19} \implies BA = 19$$

$$\Rightarrow w = -1 - 19i$$



$$\begin{array}{c|c}
13 \\
\text{(b)} & \left(z - \sqrt{2}\right)^6 = 8
\end{array}$$

$$\Rightarrow \left(z - \sqrt{2}\right)^6 = 8e^{i2k\pi}$$
$$\Rightarrow z - \sqrt{2} = \sqrt{2}e^{\frac{2k\pi}{6}i}$$

$$\Rightarrow z - \sqrt{2} = \sqrt{2}e^{\frac{2k\pi}{6}i}$$

$$\Rightarrow z = \sqrt{2} \left(1 + e^{\frac{2k\pi}{6}i} \right)$$

$$\Rightarrow z = \sqrt{2}e^{\frac{k\pi}{6}i} \left(e^{-\frac{k\pi}{6}i} + e^{\frac{k\pi}{6}i} \right)$$

$$\Rightarrow z = \sqrt{2}e^{\frac{k\pi}{6}i} \left(2\cos\frac{k\pi}{6} \right) = 2\sqrt{2} \left(\cos\frac{k\pi}{6} \right) e^{\frac{k\pi}{6}i} \text{ where } k = 0, \pm 1, \pm 2, 3$$

$$\left(z - \sqrt{2}\right)^6 = 8 \implies \left|z - \sqrt{2}\right| = \sqrt{2}$$

 \therefore the roots lie on a circle centre at $(\sqrt{2},0)$ and radius = $\sqrt{2}$