

A red Ferrari Formula 1 car is shown from a side-rear perspective, driving on a racetrack. The car features prominent sponsor logos including Shell, Santander, and Snap. The driver's helmet is visible in the cockpit. The background shows the track's edge with green and red curbs and a grassy area. The title text is overlaid in a large, white, serif font.

# RL for F1 Race Strategy Optimization

Elliot Porter Winter 2025

# F1 is more than Speed - Strategy Wins

## Track Position

- Knowing where you are relative to ALL other cars
- Predicting Pit Windows

## Pitstop Timing

- Overcuts → Staying out longer to gain advantage
- Undercuts → Pitting earlier to gain track position

## Tyre Management

- Balancing degradation vs. pace
- Adjusting strategy based on compound and wear

## Monitoring your Rival

- Defensive driving → Responding to rival attacks
- Adapting strategy based on rival's tire wear

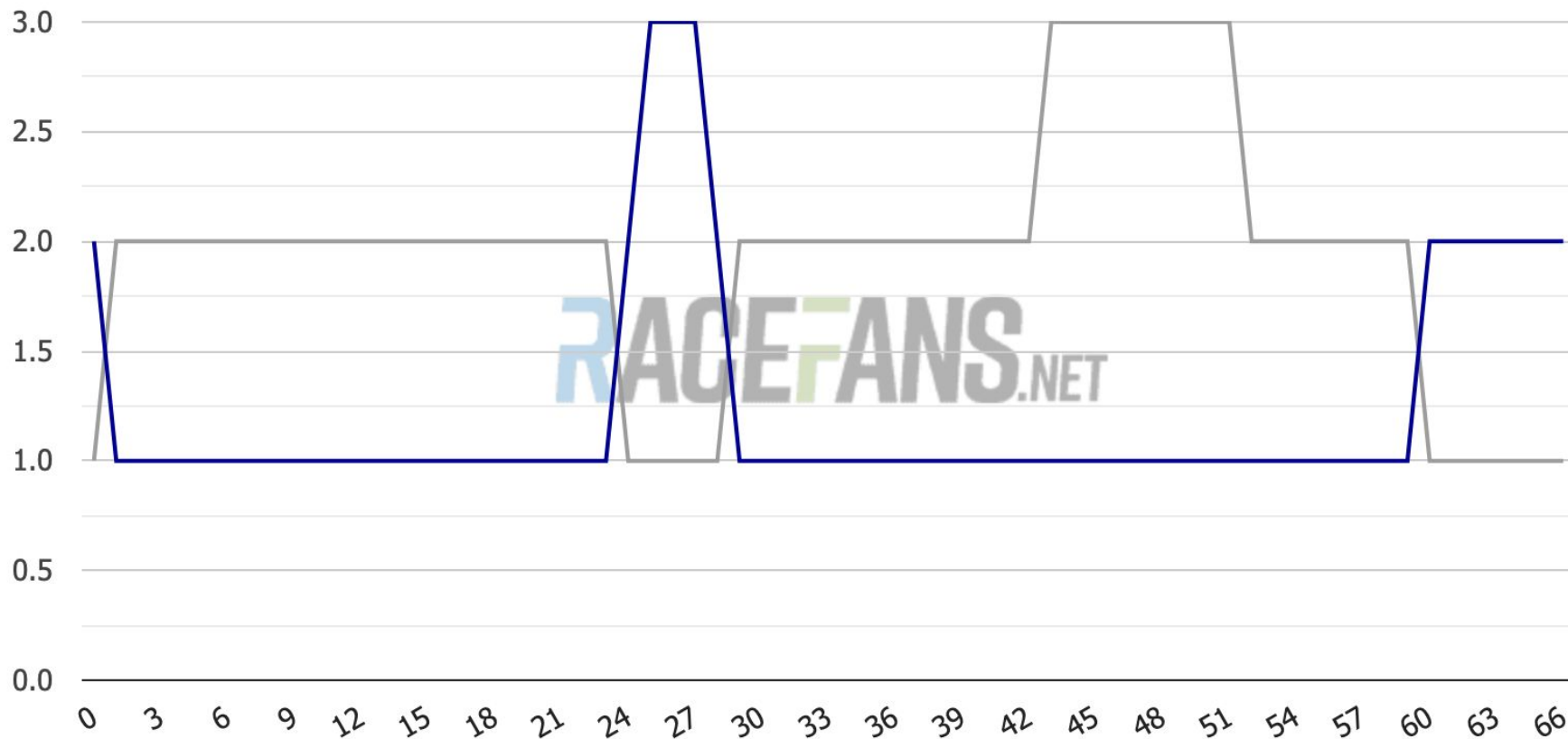
# Complexity of a race engineer's job

- Raw pace does not guarantee wins
- Race strategists and engineers are just as responsible as drivers
- They balance:
  - Tyre degradation vs. pace
  - Timing pit stops to avoid traffic
  - Predicting rival behavior

**Goal: Create a model to optimize strategy**

## 2021 Spanish Grand Prix lap chart

— Lewis Hamilton — Max Verstappen





# Model Goal

**Goal:** Create a model to optimize strategy

**Objective**

- Predicts best lap to pit
- Adapts to rival behavior
- Considers traffic and race conditions (i.e. rain)



# Model Outline

## **Inputs:**

- Current Lap
- All Laptimes of every driver up to that point
- Driver/Car whose race you want to optimize
- Their rival that you want to beat

## **Outputs**

- Which lap(s) to pit

# Modeling Strategy as an MDP

Race Strategy can be modeled as an MDP

- State space: (Track Position, Lap Times, Gap to Rival, Traffic)
- Action space: Pit or stay out, Tyre selection, Push/manage
- Rewards: Gain/Lose position, successful over/undercut, avoiding traffic
- Dynamic Transition Probabilities based on
  - Track (average lap speed, track length, # corners)
  - Pace difference between rival
  - Time gap between rival
  - Tyre wear delta

RL Algorithms

- Policy optimization
- Multi Agent Dynamics



# Inputs and State Space

## **Input:**

- Current Lap number
- All previous lap times of all drivers
- Tyre state: compound, age (number of laps)
- Gap to Rival
- Projected Traffic if pitted on current lap

# Action Space

## **Actions**

- Pitstop timing (which lap is best)
- Tyre compound choice (soft, medium, hard)
  - Soft: Fastest but does not last many laps
  - Hard: Slowest, lasts many laps
  - Medium: Balance of both speed and longevity
- Driving Strategy
  - Push: Higher pace, more degradation
  - Defend: Slower pace, conserve position
  - Manage: Maximize longevity of tyres

# Overtaking Probability Model

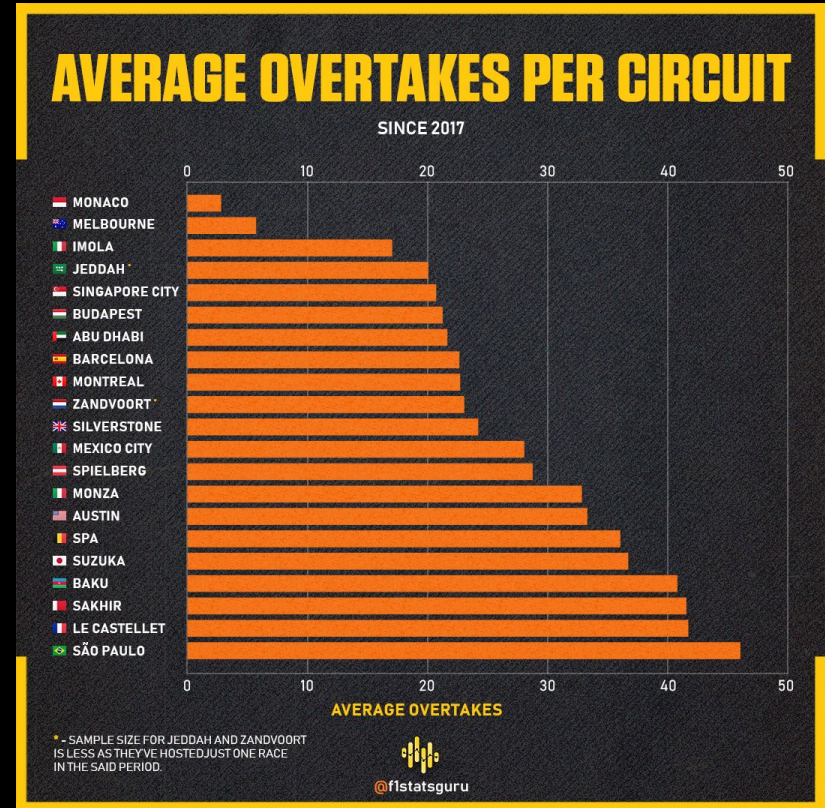
Probability of an overtake depends on:

- Pace difference between two cars
- Pace is correlated to tyre wear
- Gap between two cars

But you have to take into account which track you are at:

- Monaco is Near impossible to pass
- Sao Paulo is much easier to pass

This is where we introduce a scaling factor for each track applied to calculated probability



# Overtaking Probability Model

Sigmoid based Probabilistic Model

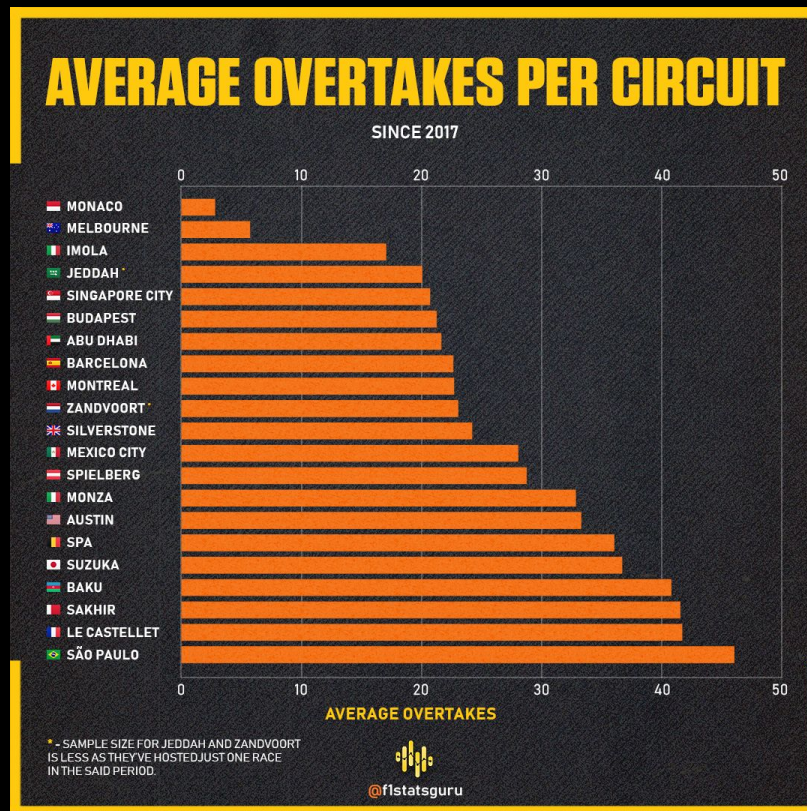
$$P_{\text{overtake}} = \frac{1}{1 + e^{-(\Delta\text{pace} - \text{threshold} - \text{gap})/\text{scaling}}}$$

Threshold = minimum pace advantage for a certain overtake

Pace delta = difference in lap times on previous lap

Gap = difference between two drivers

Scaling factor = variable for each track



# Modeling opponent strategy

Start Heuristically

- Fixed strategy and tyre management
- Learns from simplified model

Then introduce Multi Agent modeling

- The other agent updates its policy based on your actions and vice versa

Adaptive behavior

- Learns to prioritize and optimize final position
- Penalize for pitting in bad windows (release into traffic)

# Data and Training

## **Dataset** - Kaggle Full F1 Dataset

- Includes lap times of every driver from every race
- Has pitstop information
- Car status (i.e. crash/accident/retire)

**Evaluate** performance by simulating **Full** races

## Success Criteria

- Finish ahead of rival
- Optimal tyre management
- Successful over/undercuts





# Simplifications and Assumptions

- **Weight with fuel loss**
- **Use Data after 2014**
- No track evolution
- Safety cars are present
- Variable condition races
- Pit stops times can be modeled as gaussian distributions
- ERS ignored
- DRS provides overtake probability bonus
- Agent starts in a fixed position, grid slot



# Summary

- **Take Past F1 Race data**
- Model lap times and races as MDPs
- Train an RL model to automate race strategy
- Validate by trying to replicate wins like Lewis Hamilton's in 2021





# Q & A

