# Dijkstra's Algorithm

09114319: Data Structures and Algorithms

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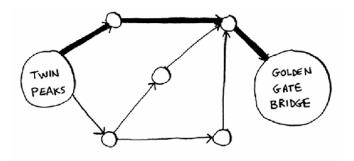
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#### Outline

- Weighted graphs
- Dijkstra's algorithm:
  - Find the shortest path in a weighted graph.
- Cycles in graphs:
  - Dijkstra's algorithm doesn't work with negative weight cycles

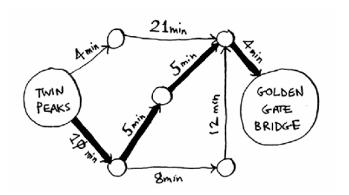
#### Shortest Path

Breadth-first search will find you the path with the fewest segments.

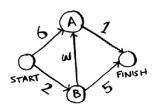


#### Fastest Path

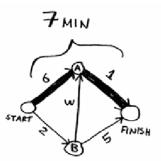
- What if each segment has a travel time in minutes?
- You may need another algorithm to go from start to finish in the shortest possible time.



Find the way to go from start to finish in the shortest possible time.



BFS gives us this shortest path:



#### Dijkstra's Algorithm

There are four steps to this algorithm:

- 1. Find the 'cheapest' node. This is the node you can get to in the least amount of time.
- 2. Update the costs of the neighbors of this node.
- 3. Repeat until you have done this for every node in the graph.
- 4. Calculate the final path.

**Step 1:** Find the cheapest node.

You are standing at the start, wondering if you should go to node A or node B.

#### **Step 1:** Find the cheapest node.

- You are standing at the start, wondering if you should go to node A or node B.
- Mow long does it take to get to each node?

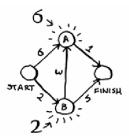
NODE	TIME TO NODE
Α	6
В	2
FINISH	000
1.101314	



#### **Step 1:** Find the cheapest node.

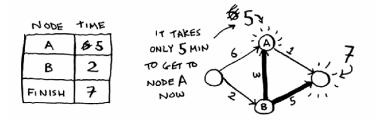
- You are standing at the start, wondering if you should go to node A or node B.
- Mow long does it take to get to each node?

NODE	TIME TO NODE
Α	6
В	2
FINISH	00

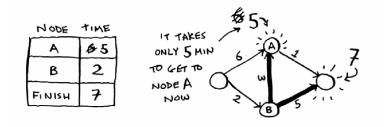


Node B is cheapest.

**Step 2:** Update the costs of the neighbors of node **B**.

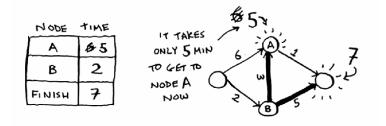


**Step 2:** Update the costs of the neighbors of node **B**.



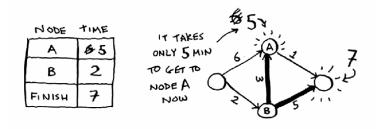
 $\$  You just found the shortest path to node A!

**Step 2:** Update the costs of the neighbors of node **B**.



- You just found the shortest path to node A!
- riangle A shorter path to node A (down from 6 mins o 5 mins)

**Step 2:** Update the costs of the neighbors of node **B**.



- You just found the shortest path to node A!
- A shorter path to node A (down from 6 mins 5 mins)
- riangle A shorter path to the finish (down from  $\infty o 7$  mins)

**Step 3:** Repeat!

**Step 1 again:** Find the cheapest node.

Step 3: Repeat!

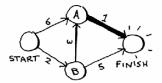
**Step 1 again:** Find the cheapest node.

You are done with node B, so the node A has the smallest time estimate.

N ODE	TIME	
A	5	-
В	2	
FINISH	7	

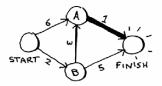
**Step 2 again:** Update the costs of the neighbors of node **B**.

NODE	TIME
A	5
В	2
FINISH	6



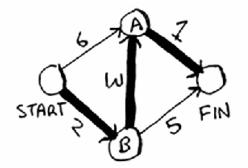
**Step 2 again:** Update the costs of the neighbors of node **B**.

NODE	TIME
A	5
В	2
FINISH	6

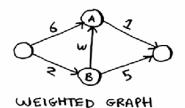


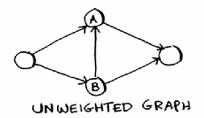
Woo, it takes 6 minutes to get to the finish now!

**Step 4:** Calculate the final path.

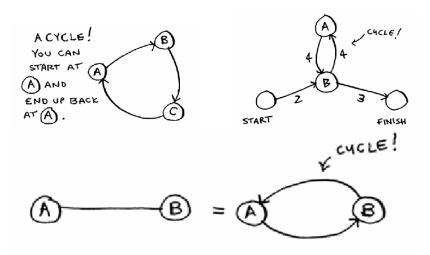


## Weighted graphs

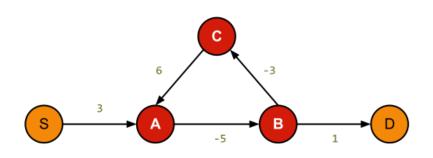




## Cycles



#### Negative weight cycles



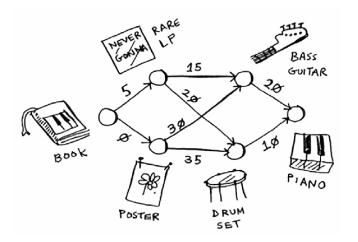
The cycle

$$A \xrightarrow{-5} B \xrightarrow{-3} C \xrightarrow{6} A$$

makes the path from S to D shorter and shorter!



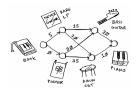
Try to trade a book for a piano!



- Before you start, you may need some setup.
- To calculate the final path, you also need to memorize parents of the chosen nodes.

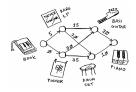
 $\mathsf{Node} = \{\mathsf{LP},\,\mathsf{Poster},\,\mathsf{Guitar},\,\mathsf{Drum}\,\,\}$ 

Parent	Node	Cost
Book	LP	5
Book	Poster	0
_	Guitar	$\infty$
_	Drum	$\infty$
_	Piano	$\infty$



 $\mathsf{Node} = \{\mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum}\}$ 

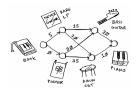
Parent	Node	Cost
Book	LP	5
Book	Poster	0
_	Guitar	$\infty$
_	Drum	$\infty$
_	Piano	$\infty$



 $\mathsf{Node} = \{\mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum}\}$ 

Choose node Poster.

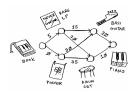
Parent	Node	Cost
Book	LP	5
Book	Poster	0
_	Guitar	$\infty$
_	Drum	$\infty$
_	Piano	$\infty$



Parent	Node	Cost
Book	LP	5
Book	Poster	0
_	Guitar	$\infty$
_	Drum	$\infty$
_	Piano	$\infty$

 $Node = \{LP, Poster, Guitar, Drum\}$ 

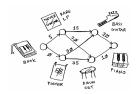
- Choose node Poster.
- $\bigcirc$  Update cost of nbd(Poster) =  $\{Guitar, Drum\}$



Parent	Node	Cost
Book	LP	5
Book	Poster	0
Poster	Guitar	∞ 30
_	Drum	$\infty$
_	Piano	$\infty$

 $Node = \{LP, Poster, Guitar, Drum\}$ 

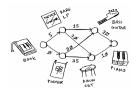
- Choose node Poster.
- Update cost of nbd(Poster) = {Guitar, Drum}
  - Solution S



Parent	Node	Cost
Book	LP	5
Book	Poster	0
Poster	Guitar	∞ 30
Poster	Drum	∞ 35
_	Piano	$\infty$

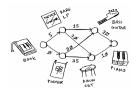
 $Node = \{LP, Poster, Guitar, Drum\}$ 

- Choose node Poster.
- Update cost of nbd(Poster) = {Guitar, Drum}
  - Suitar:  $0 + 30 = 30 < \infty$ , so assign the parent of Guitar to Poster.
  - $\bigcirc$  Drum:  $0+35=35<\infty$ , so assign the parent of Drum to Poster.



 $\mathsf{Node} = \{\mathsf{LP}, \textcolor{red}{\mathsf{Poster}}, \mathsf{Guitar}, \mathsf{Drum}\}$ 

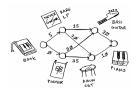
Parent	Node	Cost
Book	LP	5
Book	Poster	0
Poster	Guitar	30
Poster	Drum	35
_	Piano	$\infty$



 $\mathsf{Node} = \{\mathsf{LP}, \textcolor{red}{\mathsf{Poster}}, \mathsf{Guitar}, \mathsf{Drum}\}$ 

Choose node LP.

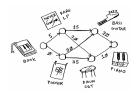
Parent	Node	Cost
Book	LP	5
Book	Poster	0
Poster	Guitar	30
Poster	Drum	35
_	Piano	$\infty$



Node	Cost
LP	5
Poster	0
Guitar	30
Drum	35
Piano	$\infty$
	LP Poster Guitar Drum

 $Node = \{LP, \frac{Poster}{Poster}, Guitar, Drum\}$ 

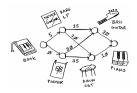
- Choose node LP.
- $\bigcirc$  Update cost of nbd(LP) = {Guitar, Drum}



Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	<del>30</del> 20
Poster	Drum	35
_	Piano	$\infty$

 $Node = \{LP, \frac{Poster}{Poster}, Guitar, Drum\}$ 

- Choose node LP.
- $\bigcirc$  Update cost of nbd(LP) = {Guitar, Drum}
  - $\bigcirc$  Guitar: 5+15=20<30, so assign the parent of Guitar to LP.

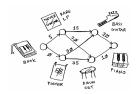


Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	<del>30</del> 20
LP	Drum	<del>35</del> 25
_	Piano	$\infty$

 $Node = \{LP, \frac{Poster}{Poster}, Guitar, Drum\}$ 

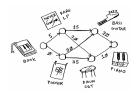
- Choose node LP.
- $\bigcirc$  Update cost of nbd(LP) = {Guitar, Drum}
  - So Guitar: 5 + 15 = 20 < 30, so assign the parent of Guitar to LP.
  - $\bigcirc$  Drum: 5+20=25<35, so assign the parent of Drum to LP.





 $\mathsf{Node} = \{ \mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum} \}$ 

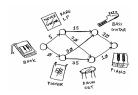
Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
_	Piano	$\infty$



 $\mathsf{Node} = \{ \textcolor{red}{\mathsf{LP}}, \textcolor{red}{\mathsf{Poster}}, \textcolor{blue}{\mathsf{Guitar}}, \textcolor{blue}{\mathsf{Drum}} \}$ 

ParentNodeCostBookLP5BookPoster0LPGuitar20LPDrum25-Piano $\infty$ 

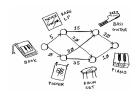
Choose node Guitar.



 $\mathsf{Node} = \{ \mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum} \}$ 

Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
_	Piano	$\infty$

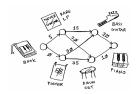
- Choose node Guitar.
- Update cost of nbd(Guitar) =
  {Piano}



$Node = \{LP, Poster$	$\{$ , Guitar, Drum $\}$
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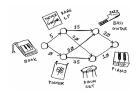
Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
Guitar	Piano	∞ 40

- Choose node Guitar.
- Update cost of nbd(Guitar) =
  {Piano}
  - ightharpoonup Piano:  $20+20=40<\infty$ , so assign the parent of Piano to Guitar.



 $\mathsf{Node} = \{\mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum}\}$ 

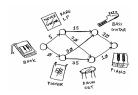
Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
Guitar	Piano	40



 $\mathsf{Node} = \{\mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum}\}$ 

Choose node Drum.

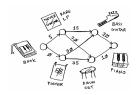
Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
Guitar	Piano	40



 $\mathsf{Node} = \{ \mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum} \}$ 

Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
Guitar	Piano	40

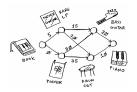
- Choose node Drum.
- Update cost of nbd(Guitar) =
  {Piano}



Node =	$\{LP, Poster,$	${\color{red}Guitar},$	Drum}
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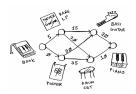
Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
Drum	Piano	40 35

- Choose node Drum.
- Update cost of nbd(Guitar) =
  {Piano}
  - ightharpoonup Piano: 25+10=35<40, so assign the parent of Piano to Drum.



 $\mathsf{Node} = \{ \mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum} \}$ 

Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
Drum	Piano	35

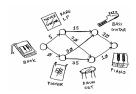


 $\mathsf{Node} = \{ \mathsf{LP}, \mathsf{Poster}, \mathsf{Guitar}, \mathsf{Drum} \}$ 

Read the final path:

$$\mathsf{Book} \xrightarrow{5} \mathsf{LP} \xrightarrow{20} \mathsf{Drum} \xrightarrow{10} \mathsf{Piano}$$

Parent	Node	Cost
Book	LP	5
Book	Poster	0
LP	Guitar	20
LP	Drum	25
Drum	Piano	35



 $Node = \{ LP, Poster, Guitar, Drum \}$ 

ParentNodeCostBookLP5BookPoster0

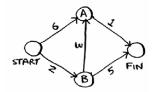
LP Guitar 20 LP Drum 25 Drum Piano 35 Read the final path:

$$\mathsf{Book} \xrightarrow{5} \mathsf{LP} \xrightarrow{20} \mathsf{Drum} \xrightarrow{10} \mathsf{Piano}$$

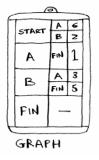
Calculate the cost of the final path:

$$5 + 20 + 10 = 35$$
.

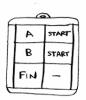
Let's see how to implement Dijkstra'a algorithm for this example:

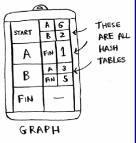


To code this example, you will need 3 hash tables.

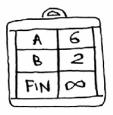




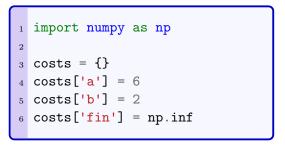




```
graph = {}
graph['start'] = {}
4 graph['start']['a'] = 6
5 graph['start']['b'] = 2
6
  graph['a'] = \{\}
8 graph['a']['fin'] = 1
10 graph['b'] = {}
graph['b']['a'] = 3
12 graph['b']['fin'] = 5
13
14 graph['fin'] = {}
```



COSTS



```
A START
B START
FIN -
```

```
parents = {}
parents['a'] = 'start'
parents['b'] = 'start'
parents['fin'] = None
```

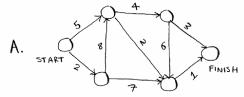
PARENTS

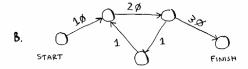
```
processed = [ ]
  node = find_lowest_cost_node(costs, processed)
  while node is not None:
      cost = costs[node]
      neighbors = graph(node)
      for n in neighbors.keys():
          new_cost = cost + neighbors[n]
          if costs[n] > new_cost:
               costs[n] = new_cost
               parents[n] = node
10
      processed.append(node)
11
      node = find_lowest_cost_node(costs)
12
```

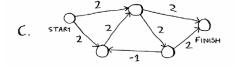
```
import numpy as np
  def find_lowest_cost_node(costs, processed):
      lowest_cost = np.inf
      lowest_cost_node = None
      for node in costs:
          cost = costs[node]
          if cost < lowest_cost and node not in
           → processed:
              lowest_cost = cost
              lowest_cost_node = node
10
      return lowest_cost_node
11
```

#### Exercise

What is the weight of the shortest path from start to finish?







### Recap

- Breadth-first search is used to calculate the shortest path for an unweighted graph.
- Dijkstra's algorithm is used to calculate the shortest path for a weighted graph.
- Dijkstra's algorithm works when all the weights are positive.