# Euler's Method and its Applications Numerical Methods for Dynamical Systems

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# Taylor Series

#### **Definition**

The Taylor series of a real-value function f(x), that is infinitely differentiable at x=a, is a power series

$$f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \frac{f'''(a)}{3!}(x-a)^3 + \cdots$$

or in summation form,

$$\sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n.$$

## Theorem (Taylor Series Convergence Theorem)

Let f(x) be an infinitely differentiable function on an open interval I containing a. The Taylor series of f(x) centered at a, converges to f(x) for all x in I if and only if the remainder term

$$R_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-a)^{n+1}, \text{ for some } \xi \in (a,x),$$

satisfies

$$\lim_{n\to\infty} R_n(x) = 0.$$

- $\$  If  $R_n(x) \to 0$ , the Taylor series converges to f(x).
- $\blacksquare$  If  $R_n(x)$  does not vanish, the Taylor series may diverge or approximate another function.

## **Example (Exponential Function)**

Find the Taylor series of  $f(x) = e^x$  around x = 0.

Solution: The Taylor series is given by

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n.$$

Compute derivatives:

$$f(x) = e^x$$
,  $f'(x) = e^x$ ,  $f''(x) = e^x$ ,  $f'''(x) = e^x$ ,...

Since  $f^{(n)}(0) = e^0 = 1$ , we substitute:

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \cdots$$

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# **Example (Sine Function)**

Find the Taylor series of  $f(x) = \sin x$  around x = 0.

Solution: The Taylor series is given by

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n.$$

Compute derivatives:

$$f(x) = \sin x$$
,  $f'(x) = \cos x$ ,  $f''(x) = -\sin x$ ,  $f'''(x) = -\cos x$ .

Evaluating at x = 0:

$$f(0) = 0$$
,  $f'(0) = 1$ ,  $f''(0) = 0$ ,  $f'''(0) = -1$ ,  $f''''(0) = 0$ ,...

Only odd powers of x remain, leading to:

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots$$

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#### **Example (Cosine Function)**

Find the Taylor series of  $f(x) = \cos x$  around x = 0.

Solution: The Taylor series is given by

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n.$$

Compute derivatives:

$$f(x) = \cos x$$
,  $f'(x) = -\sin x$ ,  $f''(x) = -\cos x$ ,  $f'''(x) = \sin x$ .

Evaluating at x = 0:

$$f(0) = 1$$
,  $f'(0) = 0$ ,  $f''(0) = -1$ ,  $f'''(0) = 0$ ,  $f''''(0) = 1$ ,...

Only even powers of x remain, leading to:

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots$$

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#### **Example (Natural Logarithm Function)**

Find the Taylor series of  $f(x) = \ln(1+x)$  around x = 0.

Solution: The Taylor series is given by

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n.$$

Compute derivatives:

$$f(x) = \ln(1+x), \quad f'(x) = \frac{1}{1+x}, \quad f''(x) = -\frac{1}{(1+x)^2}, \quad f'''(x) = \frac{2}{(1+x)^3}.$$

Evaluating at x = 0:

$$f(0) = 0$$
,  $f'(0) = 1$ ,  $f''(0) = -1$ ,  $f'''(0) = 2$ ,  $f''''(0) = -6$ ,...

The resulting series is:

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{2} - \frac{x^4}{4} + \cdots, \quad |x| < 1.$$

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Derive the Taylor series expansion of a real-valued, infinitely differentiable function f around x for a small increment h>0.

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$$f(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \frac{f'''(a)}{3!}(x - a)^3 + \cdots$$

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Next, substitute x - a = h (or x = a + h) into the above equation to get:

$$f(a+h) = f(a) + f'(a) \cdot h + \frac{f''(a)}{2!} \cdot h^2 + \frac{f'''(a)}{3!} \cdot h^3 + \cdots$$

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Next, substitute x - a = h (or x = a + h) into the above equation to get:

$$f(a+h) = f(a) + f'(a) \cdot h + \frac{f''(a)}{2!} \cdot h^2 + \frac{f'''(a)}{3!} \cdot h^3 + \cdots$$

Since  $\boldsymbol{a}$  is an arbitrary, substitute it with  $\boldsymbol{x}$  into the above equation to get:

$$f(x+h) = f(x) + hf'(x) + h^2 \frac{f''(x)}{2!} + h^3 \frac{f'''(a)}{3!} + \cdots$$

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#### Initial Value Problem (IVP)

$$\dot{x}(t) = f(t, x(t)), \quad x(t_0) = x_0.$$

**Goal:** Construct a discrete approximation  $\{x_n\}$  to x(t) at times  $t_n = t_0 + nh$ .

Time	$t_0$	$t_0 + h$	$t_0 + 2h$	 $t_0 + nh$
Solution	$x(t_0)$	$x(t_0+h)$	$x(t_0+2h)$	 $x(t_0 + nh)$
Approximation	$x_0$	$x_1$	$x_2$	 $x_n$

**Key Idea:** Use a *first-order Taylor expansion* to approximate x(t+h) in terms of x(t).

#### Step 1: Taylor Expansion Around t

$$x(t+h) = x(t) + h x'(t) + \frac{h^2}{2!} x''(\xi), \text{ for some } \xi \in (t, t+h).$$

Since x'(t) = f(t, x(t)), we truncate after the first derivative term:

$$x(t+h) \approx x(t) + h f(t, x(t)).$$

#### Remark:

- Higher-order terms are grouped into  $\mathcal{O}(h^2)$ .
- This yields a *local* truncation error of order  $h^2$ .

#### Step 2: Discretize the Time Domain

- $\bigcirc$  Define  $t_n = t_0 + nh$ , where h is the step size.
- $\triangle$  Let  $x_n \approx x(t_n)$ .

#### Step 3: Derive the Update Formula

Applying the approximation:

$$x_{n+1} = x_n + h f(t_n, x_n).$$

#### Euler Algorithmic Implementation

- 1. Initialize:  $x_0, t_0, h$ .
- 2. **Loop:**  $x_{n+1} = x_n + h f(t_n, x_n), \quad t_{n+1} = t_n + h.$
- 3. **Stop:** when  $t_n$  reaches (or exceeds) final time T.

#### Local Truncation Error (LTE):

$$x(t+h) - (x(t) + h f(t, x(t))) = \mathcal{O}(h^2).$$

#### **Global Error:**

- $\bigcirc$  Over n steps, the total (global) error is  $\mathcal{O}(h)$ .
- This is why Euler's method is called a first-order method.

#### **Summary:**

- Euler's method is simple and easy to implement.
- Accuracy can be improved by decreasing h, but too small h increases computational cost.
- More advanced methods (e.g., Modified Euler, Runge–Kutta) use higher-order terms of the Taylor expansion for better accuracy.

#### **Example (Exponential Growth)**

Solve numerically using Euler's method:

$$\dot{x} = x$$
,  $x(0) = 1$ ,  $h = 0.1$ .

**Solution:** Using Euler's method:

$$x_{n+1} = x_n + hx_n.$$

Starting at  $x_0 = 1$ :

$$x_1 = 1 + 0.1(1) = 1.1.$$
  
 $x_2 = 1.1 + 0.1(1.1) = 1.21.$   
 $x_3 = 1.21 + 0.1(1.21) = 1.331.$ 

Compare with exact solution:  $x(t) = e^t$ .

Observation: Euler's method slightly underestimates the true solution.

## **Example (Logistic Growth)**

Solve numerically using Euler's method:

$$\dot{x} = 2x(1-x), \quad x(0) = 0.1, \quad h = 0.1.$$

Solution: Using Euler's method:

$$x_{n+1} = x_n + h \cdot 2x_n(1 - x_n).$$

Starting at  $x_0 = 0.1$ :

$$x_1 = 0.1 + 0.1 \cdot 2(0.1)(1 - 0.1) = 0.118.$$
  
 $x_2 = 0.118 + 0.1 \cdot 2(0.118)(1 - 0.118) = 0.138.$ 

Compare with exact solution:  $x(t) = (1 + 9e^{-2t})^{-1}$ . Observation: Euler's method provides reasonable accuracy for small t but deviates for larger t.

#### Consider the second-order ODE:

$$\ddot{x} + x = 0$$
,  $x(0) = 1$ ,  $\dot{x}(0) = 0$ .

# Step 1: Convert to a First-Order System in Vector Form Let

$$\mathbf{s} = \begin{bmatrix} x \\ y \end{bmatrix} \quad \text{where } y = \dot{x}.$$

Then,

$$\dot{\mathbf{s}}(t) = \begin{bmatrix} \dot{x}(t) \\ \dot{y}(t) \end{bmatrix} = \begin{bmatrix} y(t) \\ -x(t) \end{bmatrix} =: \mathbf{f}(\mathbf{y}(t)).$$

Consider the second-order ODE:

$$\ddot{x} + x = 0$$
,  $x(0) = 1$ ,  $\dot{x}(0) = 0$ .

#### Step 2: Apply Euler's Method

$$\mathbf{s}_{n+1} = \mathbf{s}_n + h\,\mathbf{f}(\mathbf{s}_n).$$

In coordinates, this becomes:

$$\begin{bmatrix} x_{n+1} \\ y_{n+1} \end{bmatrix} = \begin{bmatrix} x_n \\ y_n \end{bmatrix} + h \begin{bmatrix} y_n \\ -x_n \end{bmatrix} = \begin{bmatrix} x_n + h y_n \\ y_n - h x_n \end{bmatrix}.$$

#### Consider the second-order ODE:

$$\ddot{x} + x = 0$$
,  $x(0) = 1$ ,  $\dot{x}(0) = 0$ .

#### Step 3: Implementation Example

Initial conditions: 
$$\mathbf{s}_0 = \mathbf{s}(0) = \begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad h = 0.1.$$

$$\mathbf{s}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 0.1 \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -0.1 \end{bmatrix}.$$

$$\mathbf{s}_2 = \begin{bmatrix} 1 \\ -0.1 \end{bmatrix} + 0.1 \begin{bmatrix} -0.1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 - 0.01 \\ -0.1 - 0.1 \end{bmatrix} = \begin{bmatrix} 0.99 \\ -0.2 \end{bmatrix}.$$

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Consider the second-order ODE:

$$\ddot{x} + x = 0$$
,  $x(0) = 1$ ,  $\dot{x}(0) = 0$ .

Compare with exact solution:  $x(t) = \cos(t)$ .

**Observation:** Euler's method introduces numerical damping or growth (energy drift) for oscillatory systems. Over many steps, this leads to inaccurate long-term behavior.