

# Higher-Order Taylor Method and its Applications

## Numerical Methods for Dynamical Systems

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# Higher-Order Taylor Method

Higher-order Taylor methods are numerical methods used to approximate solutions to an Initial Value Problem (IVP) by extending the idea of Euler's method to higher-order derivatives.

## Initial Value Problem (IVP)

$$\dot{x}(t) = f(t, x(t)), \quad x(t_0) = x_0.$$

**Key Idea:** Since Euler's method was derived by using Taylor's Theorem with  $n = 1$  to approximate the solution of a differential equation, we can improve the accuracy of the approximation by considering higher-order terms of the Taylor series expansion.

# Higher-Order Taylor Method

Consider the  $n^{\text{th}}$  Taylor polynomial about  $t$ . Evaluating it at  $t + h$ , we obtain

$$x(t + h) = x(t) + hx'(t) + \frac{h^2}{2}x''(t) + \cdots + \frac{h^n}{n!}x^{(n)}(t) + \frac{h^{n+1}}{(n+1)!}x^{(n+1)}(\xi),$$

for some  $\xi$  in  $(t, t + h)$ .

Since  $x'(t) = f(t, x(t))$ ,  $x''(t) = f'(t, x(t))$ , and, generally,

$$x^{(k)}(t) = f^{(k-1)}(t, x(t)).$$

# Higher-Order Taylor Method

Substituting these results into the Taylor series expansion, we obtain

$$\begin{aligned} x(t+h) = & x(t) + hf(t, x(t)) + \frac{h^2}{2} f'(t, x(t)) + \dots \\ & + \frac{h^n}{n!} f^{(n-1)}(t, x(t)) + \frac{h^{n+1}}{(n+1)!} f^{(n)}(\xi), \end{aligned}$$

for some  $\xi \in (t, t+h)$ .

**The difference-equation method** corresponding to this equation is obtained by deleting the remainder term involving  $\xi$ .

# Higher-Order Taylor Method

**Taylor method of order  $p$ :**

$$x(t_0) = x_0,$$

$$x(t+h) = x(t) + hT^{(p)}(t, x(t)),$$

for each  $t = t_0, t_1, \dots, t_{n-1}$ , where

$$T^{(p)}(t, x(t)) = f(t, x(t)) + \frac{h}{2}f'(t, x(t)) + \dots + \frac{h^{p-1}}{p!}f^{(p-1)}(t, x(t)).$$

**Remark:** Euler's method is Taylor's method of order one.

# Higher-Order Taylor Method



## Step 1: Truncate to Order $p$

$$x(t+h) = x(t) + hf(t, x(t)) + \frac{h^2}{2}f'(t, x(t)) + \frac{h^2}{3!}f''(t, x(t)) \dots$$

We can choose to truncate the Taylor series at a specific order  $p$ .  
For example, if we truncate at  $p = 2$ :


$$x(t+h) \approx x(t) + hf(t, x(t)) + \frac{h^2}{2}f'(t, x(t))$$


## Remark:

-  The truncation error depends on the order  $p$  of the Taylor series used.
-  Higher  $p$  results in a lower truncation error.

# Higher-Order Taylor Method

## Step 2: Discretize the Time Domain

 Define  $t_n = t_0 + nh$ , where  $h$  is the step size.

 Let  $x_n \approx x(t_n)$ .

## Step 3: Derive the Update Formula

Applying the approximation:

$$\text{(Second-Order): } x_{n+1} = x_n + h f(t_n, x_n) + \frac{h^2}{2} f'(t_n, x_n).$$

## Second-Order Taylor Algorithmic Implementation



1. **Initialize:**  $x_0, t_0, h$ .
2. **Loop:**  $x_{n+1} = x_n + h f(t_n, x_n) + \frac{h^2}{2} f'(t_n, x_n), \quad t_{n+1} = t_n + h$ .
3. **Stop:** when  $t_n$  reaches (or exceeds) final time  $T$ .

# Higher-Order Taylor Method




## Local Truncation Error (LTE):

$$x(t+h) - \left( x(t) + h f(t, x) + \frac{h^2}{2} (f_t + f_x f) + \cdots + \frac{h^p}{p!} x^{(p)}(t) \right) = \mathcal{O}(h^{p+1}).$$

## Global Error:

-  Over  $n$  steps, the total (global) error is  $\mathcal{O}(h^p)$ .
-  This is why the **Taylor method of order  $p$**  is called a  *$p$ -th order method*.

## Summary:

-  The **Higher-Order Taylor Method** improves accuracy by including more terms from the Taylor series.
-  Increasing the order  $p$  significantly reduces global error.
-  However, higher-order methods require computing higher derivatives of  $f(t, x)$ , which increases complexity.



## Example

Solve numerically using Higher-Order Taylor's method:

$$\dot{x} = x - t^2 + 1, \quad x(0) = 0.5, \quad h = 0.2.$$

**Solution:** Using Apply Taylor's method of orders two ( $p = 2$ ):

$$x_{n+1} = x_n + hf(t_n, x_n) + \frac{h^2}{2} f'(t_n, x_n).$$

we need the first derivative of  $f(t, x) = x - t^2 + 1$  with respect to the variable  $t$ .

$$\begin{aligned} f'(t, x) &= \frac{d}{dt}(x - t^2 + 1) = x' - 2t \\ &= x - t^2 + 1 - 2t \\ &= x - t^2 - 2t + 1 \end{aligned}$$

## Example

Solve numerically using Higher-Order Taylor's method:

$$\dot{x} = x - t^2 + 1, \quad x(0) = 0.5, \quad h = 0.2.$$

So,

$$\begin{aligned} x_{n+1} &= x_n + h f(t_n, x_n) + \frac{h^2}{2} f'(t_n, x_n) \\ &= x_n + h(x_n - t_n^2 + 1) + \frac{h^2}{2}(x_n - t_n^2 - 2t_n + 1) \end{aligned}$$

Starting at  $x_0 = 0.5$  and  $t_0 = 0$ :

$$\begin{aligned} x_1 &= 0.5 + (0.2)(0.5 - (0)^2 + 1) \\ &\quad + \frac{(0.2)^2}{2}((0.5) - (0)^2 - 2(0) + 1) \\ &= 0.83. \end{aligned}$$

## Example

Solve numerically using Higher-Order Taylor's method:

$$\dot{x} = x - t^2 + 1, \quad x(0) = 0.5, \quad h = 0.2.$$

$$\begin{aligned} x_2 &= 0.83 + (0.2)(0.83 - (0.2)^2 + 1) \\ &\quad + \frac{(0.2)^2}{2} ((0.83) - (0.2)^2 - 2(0.2) + 1) \\ &= 1.2158. \end{aligned}$$

**Compare with exact solution:**  $y = 2.5e^t - (t^2 + 2t + 2)$

## Example

Solve numerically using Higher-Order Taylor's method:

$$\dot{x} = x - t^2 + 1, \quad x(0) = 0.5, \quad h = 0.2.$$

**Solution:** Using Apply Taylor's method of orders two ( $p = 4$ ):

$$x_{n+1} = x_n + hf(t_n, x_n) + \frac{h^2}{2} f'(t_n, x_n) + \frac{h^3}{6} f''(t_n, x_n) + \frac{h^4}{24} f'''(t_n, x_n).$$

we need the first three derivatives of  $f(t, x) = x - t^2 + 1$  with respect to the variable  $t$ .

$$\begin{aligned} f'(t, x) &= x - t^2 - 2t \\ f''(t, x) &= \frac{d}{dt}(x - t^2 - 2t + 1) \\ &= x' - 2t - 2 \\ &= x - t^2 + 1 - 2t - 2 \\ &= x - t^2 - 2t - 1. \end{aligned}$$

## Example

Solve numerically using Higher-Order Taylor's method:

$$\dot{x} = x - t^2 + 1, \quad x(0) = 0.5, \quad h = 0.2.$$

$$\begin{aligned} f'''(t, x) &= \frac{d}{dt}(x - t^2 - 2t - 1) \\ &= x' - 2t - 2 \\ &= x - t^2 - 2t - 1 \end{aligned}$$

So,

$$\begin{aligned} x_{n+1} &= x_n + h f(t_n, x_n) + \frac{h^2}{2} f'(t_n, x_n) + \frac{h^3}{6} f''(t_n, x_n) + \frac{h^4}{24} f'''(t_n, x_n) \\ &= x_n + h(x_n - t_n^2 + 1) + \frac{h^2}{2}(x_n - t_n^2 - 2t_n + 1) \\ &\quad + \frac{h^3}{6}(x_n - t_n^2 - 2t_n - 1) + \frac{h^4}{24}(x_n - t_n^2 - 2t_n - 1). \end{aligned}$$

## Example

Solve numerically using Higher-Order Taylor's method:

$$\dot{x} = x - t^2 + 1, \quad x(0) = 0.5, \quad h = 0.2.$$

Starting at  $x_0 = 0.5$  and  $t_0 = 0$ :

$$\begin{aligned} x_1 &= 0.5 + (0.2)(0.5 - (0)^2 + 1) \\ &\quad + \frac{(0.2)^2}{2} ((0.5) - (0)^2 - 2(0) + 1) \\ &\quad + \frac{(0.2)^3}{6} ((0.5) - (0)^2 - 2(0) - 1) \\ &\quad + \frac{(0.2)^4}{24} ((0.5) - (0)^2 - 2(0) - 1) \\ &= 0.8293. \end{aligned}$$

## Example

Solve numerically using Higher-Order Taylor's method:

$$\dot{x} = x - t^2 + 1, \quad x(0) = 0.5, \quad h = 0.2.$$

Starting at  $x_0 = 0.5$ :

$$\begin{aligned} x_2 &= 0.8293 + (0.2)(0.8293 - (0.2)^2 + 1) \\ &\quad + \frac{(0.2)^2}{2} ((0.8293) - (0.2)^2 - 2(0.2) + 1) \\ &\quad + \frac{(0.2)^3}{6} ((0.8293) - (0.2)^2 - 2(0.2) - 1) \\ &\quad + \frac{(0.2)^4}{24} ((0.8293) - (0.2)^2 - 2(0.2) - 1) \\ &= 1.214091. \end{aligned}$$

**Compare with exact solution:**  $y = 2.5e^t - (t^2 + 2t + 2)$ .