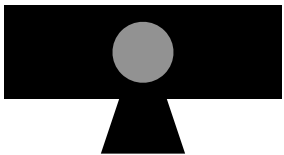
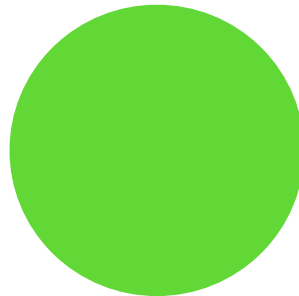


Depth Sensor



Observation
 $p(\mathbf{y} | \mathbf{x})$

Prior
 $p(\mathbf{x})$



Target



Estimate

$p(\mathbf{x} | \mathbf{y})$
Posterior

