MTH362 Spring 2016

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CHAPTER 1

Review

1.1. Preliminaries and Definitions

DEFINITION 1.1.1 (binary operation). A binary operation on a set S is a function from $S \times S$ into S.

Examples of binary operations:

- \bullet + : $\mathbb{N} \times \mathbb{N} \to \mathbb{N}$ Addition of natural numbers
- \bullet \cdot : $\mathbb{N} \times \mathbb{N} \to \mathbb{N}$ Multiplication of natural numbers

Definition 1.1.2 (group). A group consists of:

- \bullet A set G
- A binary operation $+: G \times G \to G$ with the following properties:

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\begin{array}{ll} x+(y+z)=(x+y)+z \ \forall x,y,z \in G & (associativity) \\ \exists 0 \in G \ such \ that \ a+0=0+a=a \ \forall a \in G & (identity) \\ \forall a \in G \ \exists \ a^{-1} \ such \ that \ a+a^{-1}=a^{-1}+a=0 & (inverse) \end{array}
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DEFINITION 1.1.3 (field). A field consists of:

- A set F
- A binary operation $+: F \times F \to F$ with the following properties:

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\begin{array}{ll} x+y=y+x \ \forall x,y\in F & (additive \ commutativity) \\ x+(y+z)=(x+y)+z \ \forall x,y,z\in F & (additive \ associativity) \\ \exists 0\in F \ such \ that \ a+0=0+a=a \ \forall a\in F & (additive \ identity) \\ \forall a\in F \ \exists \ a^{-1} \ such \ that \ a+a^{-1}=a^{-1}+a=0 & (additive \ inverse) \end{array}
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• A binary operation : $F \times F \to F$ with the following properties:

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 \begin{array}{lll} xy = yx \ \forall x,y \in F & (multiplicative \ commutativity) \\ x(yz) = (xy)z \ \forall x,y,z \in F & (multiplicative \ associativity) \\ \exists 1 \in F \ such \ that \ a1 = 1a = a \ \forall a \in F & (multiplicative \ identity) \\ \forall a \in F \setminus 0 \ \exists \ a^{-1} \ such \ that \ aa^{-1} = a^{-1}a = 1 & (multiplicative \ inverse) \\ x(y+z) = xy + xz \ \ \forall x,y,z \in F & (distributive \ property) \\ \end{array}
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2 1. REVIEW

Definition 1.1.4 (vector space). A vector space or linear space consists of:

- A field F of elements called **scalars**
- A commutative group V of elements called **vectors** with respect to a binary operation +
- A binary operation: $F \times V \to V$ called **scalar multiplication** that associates with each scalar $\alpha \in F$ and vector $v \in V$ a vector αv in such a way that:

$$1v = v \quad \forall v \in V$$

$$(\alpha\beta)v = \alpha(\beta v) \quad \forall \alpha, \beta \in F, \ v \in V$$

$$\alpha(v + w) = \alpha v + \alpha w \quad \forall \alpha \in F, \ v, w \in V$$

$$(\alpha + \beta)v = \alpha v + \beta v \quad \forall \alpha, \beta \in F, \ v \in V$$

DEFINITION 1.1.5 (norm). A nonnegative real-valued function $\| \| : V \to \mathbb{R}$ is called a **norm** if:

- $||v|| \ge 0$ and $||v|| = 0 \Leftrightarrow v = \vec{0}$
- $||v + w|| \le ||v|| + ||w||$ (triangle inequality)
- $\|\alpha v\| = |\alpha| \|x\| \quad \forall \alpha \in F, \ v \in V$

DEFINITION 1.1.6 (normed linear space). A linear space V together with a norm $\|\cdot\|$, denoted by the pair $(V,\|\cdot\|)$, is called a **normed** linear space

DEFINITION 1.1.7 (inner product). Let the field F be either \mathbb{R} or \mathbb{C} and a set V of vectors which together with F form a vector space. An inner product on V is a map

$$\cdot: V \times V \to \mathbb{F}$$

with the following properties:

$$\begin{array}{ll} (u+v)\cdot w = u\cdot w \ + \ v\cdot w & \forall u,v,w\in V \\ (\alpha u)\cdot v = \alpha(u\cdot v) & \forall \alpha\in F,\ u,v\in V \\ u\cdot v = (\overline{v\cdot u}) & \forall u,v\in V \\ u\cdot u\geq 0 & \forall u\in V \ \textit{with equality when } u=\vec{0} \end{array}$$

If the underlying field is \mathbb{R} , the fourth condition can be replaced by

$$u \cdot v = v \cdot u \quad \forall u, v \in V$$

since a real number is its own conjugate. In this case, the condition just says the inner product is commutative.

Definition 1.1.8 (metric). A metric on a set S is a function

$$\rho: S \times S \to \mathbb{R}$$

where ρ has the following three properties for any $x, y, z \in S$:

$$\rho(x,y) \ge 0 \text{ and } \rho(x,y) = 0 \Leftrightarrow x = y$$

$$\rho(x,y) = \rho(y,x)$$

$$\rho(x,y) \le \rho(x,z) + \rho(z,y)$$

DEFINITION 1.1.9 (metric space). A **metric space** is a pair $\{S, \rho\}$ where S is a set and ρ is a metric defined on S.

DEFINITION 1.1.10 (topology). A **topology** is a set X and a collection \mathcal{J} of subsets of X having the following properties:

- \emptyset and X are in \mathcal{J}
- ullet The union of any subcollection of elements of ${\mathcal J}$ belongs to ${\mathbb J}$
- ullet The intersection of any finite subcollection of ${\mathcal J}$ belongs to ${\mathcal J}$

Convergence

DEFINITION 1.1.11 (sequence). A sequence is a function whose domain is \mathbb{N} .

DEFINITION 1.1.12 (convergent sequence). A sequence x_n in \mathbb{R} converges to x if, for every $\epsilon > 0$, there is an $N \in \mathbb{N}$ such that

$$|x_n - x|, \epsilon \quad whenever \quad n \ge N$$

DEFINITION 1.1.13 (Cauchy sequence). A sequence x_n in \mathbb{R} is said to be a Cauchy sequence if, for every $\epsilon > 0$, there is an $N \in \mathbb{N}$ such that

$$|x_n - x_m|, \epsilon \quad whenever \quad n, m \ge N$$

1. REVIEW

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Topology Review

Definition 1.1.14 (ϵ -neighborhood). If $x \in \mathbb{R}$ and $\epsilon > 0$, the ϵ -neighborhood $V_{\epsilon}(x)$ is defined by

$$V_{\epsilon} = \{ y \in \mathbb{R} : |x - y| < \epsilon \}$$

DEFINITION 1.1.15 (limit point). A real number $x \in A$ is a limit point of A if for every $\epsilon > 0$, $V_{\epsilon}(x)$ contains elements of A other than x.

DEFINITION 1.1.16 (isolated point). A element $x \in A$ is an isolated point of A if $x \in A$ and x is not a limit point of A.

DEFINITION 1.1.17 (open set). A set $A \subseteq \mathbb{R}$ is open if, for every $a \in A$, there is an $\epsilon > 0$ such that

$$V_{\epsilon}(a) \subseteq A$$

That is, there is an ϵ -neighborhood of every element of A that is contained entirely in A.

Definition 1.1.18 (closed set). A set $A \subseteq \mathbb{R}$ is closed if it contains all of its limit points.

DEFINITION 1.1.19 (closure). The closure of a set $A \subseteq \mathbb{R}$ denoted by \overline{A} is the union of A and its limit points.

DEFINITION 1.1.20 (compact set). A set $A \subseteq \mathbb{R}$ is compact if every sequence in A has a convergent subsequence whose limit is in A.

DEFINITION 1.1.21 (perfect set). A set $A \subseteq \mathbb{R}$ is perfect if it is closed and has no isolated points.

Definition 1.1.22 (bounded set). A set $A \subseteq \mathbb{R}$ is bounded if there exists an M > 0 such that

$$|a| \le M$$
 for all $a \in A$

DEFINITION 1.1.23 (separated sets). Two nonempty sets $A, B \subseteq \mathbb{R}$ are separated if

$$A \cap \overline{B} = \emptyset = \overline{A} \cap B$$

Definition 1.1.24 (disconnected set). A set $E \subseteq \mathbb{R}$ is disconnected if it can be written as

$$E = A \cup B$$

where A and B are nonempty separated sets.

DEFINITION 1.1.25 (connected set). A set $A \subseteq \mathbb{R}$ is connected if it is not disconnected.

THEOREM 1.1.1. A set $A \subseteq \mathbb{R}$ is open if and only if its compliment A^c is closed.

PROOF. (\Rightarrow) Let $A \subseteq \mathbb{R}$ be open. Suppose for the sake of contradiction that $a \in A$ is a limit point of A^c . By definition, for every $\epsilon > 0$, $V_{\epsilon}(a)$ contains points of A^c . This means that no ϵ -neighborhood of a is entirely contained in A, contradicting the assumption that A is open.

(\Leftarrow) Now suppose $A \subseteq \mathbb{R}$ with A^c closed. Let a be an element of $(A^c)^c = A$. By hypothesis, A^c is closed, so a cannot be a limit point of A^c because $a \notin A$. By definition, this means there must be an $\epsilon > 0$ such that $V_{\epsilon}(a)$ contains no points of A^c . Therefore, $V_{\epsilon}(a) \subseteq A$. Since a was arbitrarily chosen, we can find an ϵ -neighborhood of every element of A that is entirely contained in A, so by definition A is open. \square

CHAPTER 2

Homework Problems

2.1. Week 1 Homework (assignment 1)

Team 1 (Ali, Emily, Frank).

PROBLEM 2.1.1. Let S be the set of ordered n-tuples in \mathbb{R} :

$$S = \{ (x_1, x_2, \dots, x_n) : x_i \in \mathbb{R}, \quad 1 \le i \le n \}$$

- a) Define a binary operation on $S \times S$, an identity element, and an inverse that makes S into an Abelian group.
- b) Define a multiplication operation on $\mathbb{R} \times S$ that makes S into a vector space over \mathbb{R} .

PROBLEM 2.1.2. Let S be set of real-valued functions on [-1, 1]:

$$S = \{ f : [-1, 1] \rightarrow \mathbb{R} \}$$

- a) Define a binary operation on $S \times S$, an identity element, and an inverse that makes S into an Abelian group.
- b) Define a multiplication operation on $\mathbb{R} \times S$ that makes S into a vector space over \mathbb{R} .

PROBLEM 2.1.3. Let V be \mathbb{R}^3 , the set of ordered triples of real numbers, with addition defined in the usual way:

$$u + v = (u_1 + v_1, u_2 + v_2, u_3 + v_3) \quad \forall u, v \in V$$

Define the **sum norm** on this vector space as:

$$||v||_1 = |v_1| + |v_2| + |v_3|$$

Show that the sum norm satisfies the triangle inequality.

Presenters:

• 2.1.1 Ali

- 2.1.2 Frank
- 2.1.3 Emily

Team 2 (Blaine, Katie, Siobhan, Rachel).

PROBLEM 2.1.4. Let $S^{m \times n}$ be the set of all $m \times n$ matrices over \mathbb{R} .

$$S = \{ x_{i,j} : 1 \le i \le m, \ 1 \le j \le n, x_{i,j} \in \mathbb{R} \}$$

- a) Define a binary operation on $S \times S$, an identity element, and an inverse that makes S into an Abelian group.
- b) Define a multiplication operation on $\mathbb{R} \times S$ that makes S into a vector space over \mathbb{R} .

PROBLEM 2.1.5. Let P be set of polynomial functions on \mathbb{R} : $P = \{ p : \mathbb{R} \to \mathbb{R} \text{ such that for } x \in \mathbb{R}, \ p(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n \}$ where $a_1, a_1, \dots, a_n \in \mathbb{R}$ and $n \in \mathbb{N}$.

- a) Define a binary operation on $P \times P$, an identity element, and an inverse that makes P into an Abelian group.
- b) Define a multiplication operation on $\mathbb{R} \times P$ that makes P into a vector space over \mathbb{R} .

PROBLEM 2.1.6. Let V be \mathbb{R}^3 , the set of ordered triples of real numbers, with addition defined in the usual way:

$$u + v = (u_1 + v_1, u_2 + v_2, u_3 + v_3) \quad \forall u, v \in V$$

Define the max norm on this vector space as:

$$||v||_{\infty} = \max(|v_1|, |v_2|, |v_3|)$$

Show that the max norm satisfies the triangle inequality.

PROBLEM 2.1.7. Let V be \mathbb{R}^3 , the set of ordered triples of real numbers, with zero element:

$$\vec{0} = (0, 0, 0)$$

Define the **sum norm** on this vector space as:

$$||v||_1 = |v_1| + |v_2| + |v_3|$$

Show that the sum norm satisfies the required condition

$$||v|| = 0$$
 if and only if $v = \vec{0}$

Presenters:

- 2.1.4 Blaine
- 2.1.5 Katie
- 2.1.6 Rachel
- 2.1.7 Siobhan

2.2. Week 1 Homework (assignment 2)

Team 1 (Ali, Emily, Frank).

Problem 2.2.1. Prove that arbitrary unions of open sets are open.

Problem 2.2.2. Prove that a finite union of closed sets is closed.

PROBLEM 2.2.3. Prove that a point x is a limit point of A if and only if $x = \lim a_n$ for some sequence (a_n) in A satisfying $a_n \neq x$ for all $n \in \mathbb{N}$.

Presenters:

- 2.2.1 Ali
- 2.2.2 Frank
- 2.2.3 Emily

Team 2 (Blaine, Katie, Siobhan, Rachel).

Problem 2.2.4. Prove that finite intersections of open sets are open.

PROBLEM 2.2.5. Prove that a set O is open if and only if its compliment, O^c , is closed.

Problem 2.2.6. Prove that a set F is closed if and only if its compliment F^c is open.

Problem 2.2.7. Prove that arbitrary intersections of closed sets are closed.

Presenters:

- 2.2.4 Blaine
- 2.2.5 Katie
- 2.2.6 Rachel
- 2.2.7 Siobhan