

Affine homogeneous geodesics and the invariants of $SL(2, \mathbb{R})$

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Homogeneous geodesics in homogeneous affine manifolds

Definition

Let (M, ∇) be a homogeneous affine manifold.

A geodesic is homogeneous if it is an orbit of an one-parameter group of affine diffeomorphisms. (Here the canonical parameter of the group need not be the affine parameter of the geodesic.)

An affine g.o. manifold is a homogeneous affine manifold (M, ∇) such that each geodesic is homogeneous.

Lemma

Let $M = G/H$ be a homogeneous space with a left-invariant affine connection ∇ . Then each regular curve which is an orbit of a 1-parameter subgroup $g_t \subset G$ on M is an integral curve of an affine Killing vector field on M .

Definition

Let (M, ∇) be a manifold with an affine connection.
A vector field X on M is called a Killing vector field if

$$[X, \nabla_Y Z] - \nabla_Y [X, Z] - \nabla_{[X, Y]} Z = 0$$

is satisfied for arbitrary vector fields Y, Z .

Lemma

*(M, ∇) is homogeneous if it admits at least $n = \dim M$ complete affine Killing vector fields which are independent at each point.
If (M, ∇) admits an n -dimensional vector space of complete geodesic Killing vector fields, then it is an affine g.o. space.*

Definition

A nonvanishing smooth vector field Z on M is geodesic along its regular integral curve γ if $\gamma(t)$ is geodesic up to a possible reparametrization. If all regular integral curves of Z are geodesics up to a reparametrization, then the vector field Z is called a geodesic vector field.

For example, a round two-sphere with the corresponding Levi-Civita connection does *not* admit any geodesic affine Killing vector field. Still, all geodesics are homogeneous.

Lemma

Let Z be a nonvanishing Killing vector field on $M = (G/H, \nabla)$.

1) Z is geodesic along its integral curve γ if and only if

$$\nabla_{Z_{\gamma(t)}} Z = k_{\gamma} \cdot Z_{\gamma(t)}$$

holds along γ . Here $k_{\gamma} \in \mathbb{R}$ is a constant.

2) Z is a geodesic vector field if and only if

$$\nabla_Z Z = k \cdot Z$$

holds on M . Here k is a smooth function on M which is constant along integral curves of Z .

$$\dim(M) = 2$$

Theorem (Opozda; Arias-Marco, Kowalski)

Let ∇ be a locally homogeneous affine connection with arbitrary torsion on a 2-dimensional manifold \mathcal{M} . Then, either ∇ is locally a Levi-Civita connection of the unit sphere or, in a neighbourhood \mathcal{U} of each point $m \in \mathcal{M}$, there is a system (u, v) of local coordinates and constants A, B, C, D, E, F, G, H such that ∇ is expressed in \mathcal{U} by one of the following formulas:

$$\begin{array}{ll} \text{Type A :} & \begin{array}{ll} \nabla_{\partial_u} \partial_u = A \partial_u + B \partial_v, & \nabla_{\partial_u} \partial_v = C \partial_u + D \partial_v, \\ \nabla_{\partial_v} \partial_u = E \partial_u + F \partial_v, & \nabla_{\partial_v} \partial_v = G \partial_u + H \partial_v, \end{array} \\ \text{Type B :} & \begin{array}{ll} \nabla_{\partial_u} \partial_u = \frac{A}{u} \partial_u + \frac{B}{u} \partial_v, & \nabla_{\partial_u} \partial_v = \frac{C}{u} \partial_u + \frac{D}{u} \partial_v, \\ \nabla_{\partial_v} \partial_u = \frac{E}{u} \partial_u + \frac{F}{u} \partial_v, & \nabla_{\partial_v} \partial_v = \frac{G}{u} \partial_u + \frac{H}{u} \partial_v, \end{array} \end{array}$$

where not all A, B, C, D, E, F, G, H are zero.

Connections of type A

- ▶ Let us have a connection ∇ with constant Christoffel symbols. The operators ∂_u, ∂_v are affine Killing vector fields.
- ▶ A general vector field $X = x \partial_u + y \partial_v$ satisfies the condition $\nabla_X X = kX$ if it holds

$$\begin{aligned} Ax^2 + (C + E)xy + Gy^2 &= kx, \\ Bx^2 + (D + F)xy + Hy^2 &= ky. \end{aligned} \quad (1)$$

- ▶ By the elimination of the factor k we obtain

$$Bx^3 - (A - D - F)x^2y - (C + E - H)xy^2 - Gy^3 = 0.$$

- ▶ A sufficient condition for a vector field $X = x \partial_u + y \partial_v$ to be geodesic is that the pair (x, y) satisfies this condition.
- ▶ For any connection of type A, a geodesic Killing field (and at least one homogeneous geodesic) exist.

Affine g.o. manifold

Theorem

For (\mathbb{R}^2, ∇) to be an affine g.o. manifold, it is sufficient that

$$B = 0, \quad A = D + F, \quad G = 0, \quad H = C + E. \quad (2)$$

If (\mathbb{R}^2, ∇) admits only two affine Killing vector fields, then these formulas are also necessary conditions for the g.o. property.

- In this case, the equations (1) give

$$Ax + Hy = k,$$

k is nonzero in general and geodesics must be reparametrized.

Connections of type B

We consider the globally homogeneous manifold

$$\mathcal{U} = \{\mathbb{R}(u, v) \mid u > 0\}.$$

- ▶ The general Killing vector field is $X = x\partial_v + y(u\partial_u + v\partial_v)$.
- ▶ The equality $\nabla_X X = kX$ gives

$$\begin{aligned} Gx^2 + [(C + E)u + 2Gv]xy \\ + [(A + 1)u^2 + (C + E)uv + Gv^2]y^2 &= ku^2y, \\ Hx^2 + [(D + F + 1)u + 2Hv]xy \\ + [Bu^2 + (D + F + 1)uv + Hv^2]y^2 &= ku(x + vy). \end{aligned}$$

- ▶ The coordinate components $u(t), v(t)$ of its integral curve $\gamma(t)$ are

$$u(t) = c_1 e^{yt}, \quad v(t) = c_2 e^{yt} - x/y, \quad c_1 > 0, \quad (3)$$

where c_1, c_2 are integration constants.

If we substitute for $u(t), v(t)$ from (3), we get

$$\begin{aligned} ((A+1)c_1^2 + (C+E)c_1c_2 + Gc_2^2)y &= k_\gamma c_1^2, \\ (Bc_1^2 + (D+F+1)c_1c_2 + Hc_2^2)y &= k_\gamma c_1c_2. \end{aligned} \quad (4)$$

By the elimination of k_γ we obtain

$$B c_1^3 - (A - D - F) c_1^2 c_2 - (C + E - H) c_1 c_2^2 - G c_2^3 = 0.$$

- ▶ (\mathcal{U}, ∇) admits at least one homogeneous geodesic through each point.
- ▶ Homogeneous geodesics are the integral curves of Killing vector fields which are not geodesic.
- ▶ In general, connections of type B do not admit any geodesic Killing vector fields.

Affine g.o. manifold

- If it holds

$$B = 0, \quad A = D + F, \quad G = 0, \quad H = C + E, \quad (5)$$

then the equations (4) give us

$$((A + 1)c_1 + Hc_2)y = k_\gamma c_1.$$

Theorem

If the conditions (5) hold, then for any $(x, y) \neq (0, 0)$ the corresponding Killing vector field is geodesic. The manifold (\mathcal{U}, ∇) is an affine g.o. manifold and any homogeneous geodesic is the integral curve of a geodesic Killing vector field.

- For a given geodesic Killing field, different geodesics must be reparametrized by different k_γ .

Invariants of $SL(2, \mathbb{R})$ in \mathbb{R}^6

\mathcal{H} ... set of torsion-free connections with constant CS on \mathbb{R}^2

$$\begin{aligned}\Gamma_{11}^1 &= A_1, & \Gamma_{12}^1 &= \Gamma_{21}^1 = E_1, & \Gamma_{22}^1 &= B_1, \\ \Gamma_{11}^2 &= A_2, & \Gamma_{12}^2 &= \Gamma_{21}^2 = E_2, & \Gamma_{22}^2 &= B_2.\end{aligned}\tag{6}$$

Vector field $X = x \partial_u + y \partial_v$ satisfies
the condition $\nabla_X X = 0$ if it holds

$$\begin{aligned}x^2 A_1 + y^2 B_1 + 2xy E_1 &= 0, \\ x^2 A_2 + y^2 B_2 + 2xy E_2 &= 0.\end{aligned}$$

We calculate the resultant

$$R_1 = 4 (A_1 E_2 - E_1 A_2) (B_1 E_2 - E_1 B_2) + (A_1 B_2 - A_2 B_1)^2.$$

► R_1 is an invariant with respect to $SL(2, \mathbb{R})$ acting on \mathcal{H} .

Hilbert basis of invariants

- Consider the action of $SL(2, \mathbb{R})$ on \mathcal{H} .
- There are 3 independent invariants:

$$\begin{aligned}R_1 &= 4 (A_1 E_2 - E_1 A_2) (B_1 E_2 - E_1 B_2) + (A_1 B_2 - A_2 B_1)^2, \\R_2 &= (A_1 E_2 + A_2 B_2 - A_2 E_1 - E_2^2)(A_1 B_1 - B_1 E_2 + B_2 E_1 - E_1^2) \\&\quad - (A_2 B_1 - E_1 E_2)^2, \\R_3 &= (A_1^2 + A_1 E_2 + A_2 B_2 + A_2 E_1)(A_1 B_1 + B_1 E_2 + B_2^2 + B_2 E_1) \\&\quad - (A_1 E_1 + B_2 E_2 + 2 E_1 E_2)^2.\end{aligned}$$

Invariant of $SL(2, \mathbb{R})$ in \mathbb{R}^9

\mathcal{H}' ... set of torsion-free connections with constant CS on \mathbb{R}^3
 \mathbb{R}^3 , vector field $X = x \partial_u + y \partial_v + z \partial_w$ satisfies
the condition $\nabla_X X = kX$ if it holds

$$\begin{aligned}x^2 A_1 + y^2 B_1 + z^2 C_1 + 2xy E_1 + 2xz F_1 + 2yz G_1 &= kx, \\x^2 A_2 + y^2 B_2 + z^2 C_2 + 2xy E_2 + 2xz F_2 + 2yz G_2 &= ky, \\x^2 A_3 + y^2 B_3 + z^2 C_3 + 2xy E_3 + 2xz F_3 + 2yz G_3 &= kz.\end{aligned}$$

$z = 0, y \neq 0 (y = 1)$:

$$\begin{aligned}A_2 x^3 + (2E_2 - A_1)x^2 + (B_2 - 2E_1)x - B_1 &= 0, \\A_3 x^2 + 2E_3 x + B_3 &= 0.\end{aligned}$$

The resultant of this system is an invariant with respect to
 $SL(2, \mathbb{R})$ acting on \mathcal{H}' .

Invariant of $SL(2, \mathbb{R})$ in \mathbb{R}^9

$$\begin{aligned} R' = & A_1^2 A_3 B_3^2 + A_2^2 B_3^3 + A_3^3 B_1^2 \\ & + (B_2^2 B_3 - 4 B_2 B_3 E_1 + 4 B_3 E_1^2 \\ & + (2 B_2 E_3 + 4 B_3 E_2 - 4 E_1 E_3) B_1) A_3^2 \\ & + (2 A_2 B_3^2 E_3 - 2 A_3^2 B_1 B_3 \\ & + (4 B_1 E_3^2 + 2 B_2 B_3 E_3 - 4 B_3^2 E_2 - 4 B_3 E_1 E_3) A_3) A_1 \\ & + (8 B_1 E_3^3 + 4 B_2 B_3 E_3^2 - 4 B_3^2 E_2 E_3 - 8 B_3 E_1 E_3^2 \\ & + (-6 B_1 B_3 E_3 - 2 B_2 B_3^2 + 4 B_3^2 E_1) A_3) A_2 \\ & + (-8 B_1 E_2 E_3^2 - 4 B_2 B_3 E_2 E_3 + 4 B_3^2 E_2^2 + 8 B_3 E_1 E_2 E_3) A_3. \end{aligned}$$