



# **Cuvature homogeneous Lorentzian three-manifolds**

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- Einstein-like examples.
- Explicit examples for all admissible forms of  $Q$ .



# Curvature homogeneity

A p.R. manifold  $(M, g)$  is said to be **curvature homogeneous up to order  $k$**  if, for any points  $p, q \in M$ , there exists a linear isometry  $\phi : T_p M \rightarrow T_q M$  such that

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When  $\dim M \geq 3$ , a curvature homogeneous space **needs not to be locally homogeneous**.

# 3D Lorentzian manifolds

$(M, g)$  connected 3D Lorentzian manifold. Its curvature tensor is completely determined by the Ricci tensor

$$\varrho(X, Y)_p = \sum_{i=1}^3 \varepsilon_i g(R(X, e_i)Y, e_i),$$

where  $\{e_1, e_2, e_3\}$  is a pseudo-orthonormal basis of  $T_p M$  and  $\varepsilon_i = g(e_i, e_i) = \pm 1$  for all  $i$ .

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$\varrho$  is symmetric  $\Rightarrow$  the *Ricci operator*  $g(QX, Y) = \varrho(X, Y)$  is self-adjoint.

In the Riemannian case, there always exists an orthonormal basis diagonalizing  $Q$ , in the Lorentzian case four different cases can occur, called *Segre types*.



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In particular, at each point of a 3D Lorentzian manifold there exists a pseudo-orthonormal basis  $\{e_1, e_2, e_3\}$ , with  $e_3$  timelike, such that  $Q$  takes one of the following forms:

$$\text{S. type } \{11, 1\} : \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{pmatrix}, \quad \text{S. type } \{1z\bar{z}\} : \begin{pmatrix} a & 0 & 0 \\ 0 & b & c \\ 0 & -c & b \end{pmatrix},$$

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The first examples of 3D Lorentzian manifolds, **curvature homogeneous up to order one but not locally homogeneous**, were given by Bueken and Vanhecke [Class. Quantum Grav., 1997].

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(**Riemannian examples:** only space forms and direct products  $\mathbb{R} \times S^2$ ,  $\mathbb{R} \times \mathbb{H}^2$ .)

# Homog. Lorentzian 3-spaces

**Theorem** [GC, J.G.P., 2007] *A 3D connected, simply connected, complete homogeneous Lorentzian manifold  $(M, g)$  is either *symmetric*, or isometric to a *Lorentzian Lie group*, equipped with a left-invariant Lorentzian metric.*



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**Riemannian counterpart:** just one form for the unimodular Lie algebra and one form for the non-unimodular one [Milnor, Adv. Math., 1976].

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- (2) *the Ricci form has signature  $(+, +, 0)$  and, up to a re-numeration,*

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They also proved that a 3D Lorentzian manifold, curvature homogeneous up to order two, is locally homogeneous.

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*"we do not know, however, if there exist non-homogeneous curvature homogeneous three-dimensional Lorentzian manifolds whose Ricci operator is of this type or curvature homogeneity is sufficient to guarantee local homogeneity of the manifolds of this type."* [Bueken-Djorić, 2000]





# Einstein-like metrics



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This is equivalent to requiring that  $\varrho$  is a *Killing tensor*, that is,  $(\nabla_X \varrho)(X, X) = 0$  for all  $X$ .

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$$\mathcal{A} \cup \mathcal{B} \subset \mathcal{C} \text{ (constant scalar curvature),}$$

$$\mathcal{E} \subset \mathcal{A} \cap \mathcal{B} = \mathcal{P} \text{ (Einstein and Ricci-parallel manifolds).}$$



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■ *belongs to class  $\mathcal{A}$  if and only if it is naturally reductive.*



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3D manifolds are natural candidates for a deep investigation about Einstein-like metrics, because in dimension three the curvature is completely determined by the Ricci tensor.

A 3D p.-R. manifold  $(M, g)$  has constant sectional curvature if and only if it is Einstein, and is locally symmetric if and only if it is Ricci-parallel.

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What about Einstein-like Lorentzian metrics?

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Locally homogeneous conformally flat Riemannian manifolds are locally symmetric. Thus, conformal flatness is a weaker assumption in Lorentzian geometry than in the Riemannian framework.

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- *A curvature homogeneous Lorentzian three-manifold with Ricci operator of degenerate Segre type  $\{21\}$ , belonging to class  $\mathcal{A}$ , is curvature homogeneous up to order one. (Remark: ANY 3D Riemannian manifold in class  $\mathcal{A}$  is locally homogeneous! [Pedersen and Tod, D.G.A., 1999])*
- There is a large class of proper curvature homogeneous Lorentzian three-manifolds with Ricci operator of degenerate Segre type  $\{21\}$ , belonging to class  $\mathcal{B}$ .

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De Turk [Bull. A.M.S., 1980 and Invent. Math., 1981] obtained local existence theorems under very general hypotheses. In particular, if  $\mathcal{R}$  is analytic in a neighborhood of  $x_0 \in \mathbb{R}^n$  and  $\mathcal{R}^{-1}(x_0)$  exists, then there exists an analytic metric  $g$  (of any desired signature) such that  $\varrho = \mathcal{R}$  in a neighborhood of  $x_0$ .

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The second problem remains **open**, even for 3D manifolds and for particularly simple symmetric  $(0, 2)$ -tensors  $\mathcal{R}$ .

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**Main Theorem:** *Three-dimensional proper curvature homogeneous Lorentzian metrics exist for all different Segre types of  $Q$  (except in the degenerate diagonal case with three equal Ricci eigenvalues, when the manifold has necessarily constant sectional curvature).*

# Previous contributions

Bueken [J.M.P., 1997] studied curvature homogeneous examples in the case of **degenerate Segre type  $\{11, 1\}$**  with two distinct Ricci eigenvalues.

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For all forms of the *shear operator*, local homogeneity is proven to be very rare among the classified curvature homogeneous Lorentzian three-manifolds with this curvature properties.

Again Bueken [J.G.P., 1997] described and classified curvature homogeneous examples with  $Q$  of *degenerate Segre type*  $\{21\}$ .

# manifolds with a parallel degenerate line field

A **parallel degenerate** line field  $\mathcal{D}$  on a Lorentzian manifold  $(M, g)$  is one spanned by a locally defined null vector  $U$  satisfying  $\nabla U = \omega \otimes u$ .

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A 3D Lorentzian manifold  $(M, g_f)$  admitting a parallel degenerate line field admits local coordinates  $(t, x, y)$  such that w.r. to  $\{\partial_t, \partial_x, \partial_y\}$ ,

$$g_f = \begin{pmatrix} 0 & 0 & 1 \\ 0 & \varepsilon & 0 \\ 1 & 0 & f(t, x, y) \end{pmatrix}$$

for some function  $f(t, x, y)$ , where  $\varepsilon = \pm 1$ . Here we fix  $\varepsilon = 1$ , so that the Lorentzian metric tensor will have signature  $(+, +, -)$ . When  $U = \partial_t$  is a parallel null vector field, then  $f = f(x, y)$ . These manifolds were studied by Chaichi, García-Río and Vázquez-Abal [J. Phys. A, 2005].

# manifolds with a parallel degenerate line field

With respect to  $\{\partial_t, \partial_x, \partial_y\}$ , the Ricci operator  $Q$  of  $(M, g_f)$  is given by:

$$Q = \begin{pmatrix} \frac{1}{2}f''_{tt} & \frac{1}{2}f''_{tx} & -\frac{1}{2}f''_{xx} \\ 0 & 0 & \frac{1}{2}f''_{tx} \\ 0 & 0 & \frac{1}{2}f''_{tt} \end{pmatrix}.$$



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We now find conditions so that  $(M, g_f)$  is curvature homogeneous with  $Q$  either of Segre type  $\{3\}$  or of nondegenerate Segre type  $\{21\}$ .

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$$f''_{tt} = 0, \quad f''_{tx} = a_1, \quad f''_{xx} = a_2,$$

where  $a_1 \neq 0$  and  $a_2$  are two real constants, then  $(M, g)$  is curvature homogeneous and  $Q$  is of Segre type  $\{3\}$ .

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*where  $p, q, s$  are three arbitrary one-variable functions,  $(M, g_f)$  is curvature homogeneous and has Ricci operator of Segre type  $\{3\}$ .*



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We also studied isometries between curvature homogeneous Lorentzian three-manifolds  $(M, g)$  and  $(M', g')$ , having the Ricci operators of Segre type  $\{3\}$ .

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As a consequence, there are infinitely many curvature homogeneous Lorentzian metrics on  $\mathbb{R}^3[w, x, y]$ , with the same Ricci operator of Segre type  $\{3\}$ , not locally isometric to one another.

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A similar argument applies to Lorentzian metrics with the same Ricci operator of nondegenerate Segre type  $\{21\}$ .



# A general description

$(M, g)$  a 3D curvature homogeneous Lorentzian manifold,  $\{e_i\}$  a local pseudo-orthonormal frame field on  $(M, g)$ , with respect to which the Ricci components are constant.

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The Levi Civita connection  $\nabla$  of  $(M, g)$  is completely determined by

$$\begin{aligned}\nabla_{e_1} e_1 &= \alpha e_2 + \beta e_3, & \nabla_{e_2} e_1 &= \kappa e_2 + \mu e_3, & \nabla_{e_3} e_1 &= \sigma e_2 + \tau e_3, \\ \nabla_{e_1} e_2 &= -\alpha e_1 + \gamma e_3, & \nabla_{e_2} e_2 &= -\kappa e_1 + \nu e_3, & \nabla_{e_3} e_2 &= -\sigma e_1 + \psi e_3, \\ \nabla_{e_1} e_3 &= \beta e_1 + \gamma e_2, & \nabla_{e_2} e_3 &= \mu e_1 + \nu e_2, & \nabla_{e_3} e_3 &= \tau e_1 + \psi e_2,\end{aligned}$$

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for nine smooth functions  $\alpha, \dots, \psi$ . These functions are not all independent. In fact, since the scalar curvature  $r$  is constant, the [divergence formula](#)  $dr = 2\text{div}\varrho$  implies

$$\sum_j \varepsilon_j \nabla_j \varrho_{ij} = 0 \quad \text{for all } i,$$

which gives some restrictions for the connection functions.

# A general description

In function of  $\alpha, \dots, \psi$ , the Ricci components are given by

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$$\varrho_{22} = e_2(\alpha) - e_1(\kappa) + e_3(\nu) - e_2(\psi) - \alpha^2 - \kappa^2 + \nu^2 - \psi^2 \\ + \beta\nu - \kappa\tau + 2\gamma\sigma,$$

$$\varrho_{33} = e_1(\tau) - e_3(\beta) - e_3(\nu) + e_2(\psi) - \beta^2 + \tau^2 - \nu^2 + \psi^2 \\ - \alpha\psi + \kappa\tau - 2\gamma\mu,$$

$$\varrho_{12} = e_3(\gamma) - e_1(\psi) + \gamma(\beta + \nu) + \sigma(\beta - \nu) - \tau(\alpha + \psi),$$

$$\varrho_{13} = e_2(\sigma) - e_3(\kappa) - \alpha(\mu + \sigma) - \nu(\kappa - \tau) - \psi(\mu - \sigma),$$

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We require  $\varrho_{ij}$  to be constant when we look for curvature homogeneous examples.

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Choose a surface  $S$  through  $p$  transversal to the lines generated by  $e_3$ , a local coordinates system  $(w, x)$  on  $S$  and a neighborhood  $U_p$  of  $p$ , sufficiently small that each  $q \in U_p$  is situated on exactly one line generated by  $e_3$  and passing through one point  $\bar{q} \in S$ . We then choose an orientation of  $S$  and put

$$y(q) = \text{dist}(q, \pi(q)), \quad w(q) = w(\pi(q)), \quad x(q) = x(\pi(q)),$$

where  $\pi : U_p \rightarrow S$  is the corresponding projection. In this way, a local coordinate system  $(w, x, y)$  is introduced in  $U_p$ .

# Explicit metrics

Fix  $p \in M$  and consider a p.o. frame field  $\{e_1, e_2, e_3\}$  as before in a neighborhood of  $p$ .

Choose a surface  $S$  through  $p$  transversal to the lines generated by  $e_3$ , a local coordinates system  $(w, x)$  on  $S$  and a neighborhood  $U_p$  of  $p$ , sufficiently small that each  $q \in U_p$  is situated on exactly one line generated by  $e_3$  and passing through one point  $\bar{q} \in S$ . We then choose an orientation of  $S$  and put

$$y(q) = \text{dist}(q, \pi(q)), \quad w(q) = w(\pi(q)), \quad x(q) = x(\pi(q)),$$

where  $\pi : U_p \rightarrow S$  is the corresponding projection. In this way, a local coordinate system  $(w, x, y)$  is introduced in  $U_p$ .

The coframe  $\{\omega_1, \omega_2, \omega_3\}$  of  $\{e_1, e_2, e_3\}$  takes the form

$$\omega^1 = A dw + B dx, \quad \omega^2 = C dw + D dx, \quad \omega^3 = G dw + H dx + dy,$$

for some functions  $A, B, C, D, G, H$ .



# Basic system of PDE

The connection forms  $\omega_j^i$  are given by  $d\omega^i + \sum_j \omega_j^i \wedge \omega^j = 0, \quad \forall i$ .  
Connection equations above are equivalent to

$$A'_y = \beta A + (\mu + \sigma)C,$$

$$B'_y = \beta B + (\mu + \sigma)D,$$

$$C'_y = (\gamma - \sigma)A + \nu C,$$

$$D'_y = (\gamma - \sigma)B + \nu D,$$

$$G'_y = -\tau A - \psi C,$$

$$H'_y = -\tau B - \psi D,$$

$$B'_w - A'_x = \alpha \mathcal{D} - \beta \mathcal{E} - (\mu + \sigma)\mathcal{F},$$

$$D'_w - C'_x = \kappa \mathcal{D} - (\gamma - \sigma)\mathcal{E} - \nu \mathcal{F},$$

$$H'_w - G'_x = -(\gamma - \mu)\mathcal{D} + \tau \mathcal{E} + \psi \mathcal{F},$$

where  $\mathcal{D} = AD - BC, \mathcal{E} = AH - BG, \mathcal{F} = CH - DG$ .  $\mathcal{D} \neq 0$  is a necessary and sufficient condition for linear independence of  $\omega^i$ .

# Basic system of PDE

The curvature forms  $\Omega_j^i$ , depending on the Ricci curvature  $(\varrho_{ij})$ , are determined by

$$-d\Omega_j^i = d\omega_j^i + \sum_k \omega_k^i \wedge \omega_j^k,$$

and may be written down explicitly, like the previous equations for the Levi Civita connection.

# Basic system of PDE

The curvature forms  $\Omega_j^i$ , depending on the Ricci curvature  $(\varrho_{ij})$ , are determined by

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and may be written down explicitly, like the previous equations for the Levi Civita connection.

**Theorem** *Let  $A, B, C, D, G, H$  be smooth functions on the three variables  $w, x, y$ , satisfying partial differential equations above. Then, the coframe  $\{\omega^1, \omega^2, \omega^3\}$  describes a curvature homogeneous Lorentzian metric  $g$  on  $\mathbb{R}^3$ , whose Ricci tensor has constant (local) components  $(\varrho_{ij})$ .*

(REF: [Kowalski and Prüfer, Math. Ann., 1994], [GC, J.M.P., 2007, D.G.A., 2008 and A.G.A.G.] )

# The remaining Segre types

**Theorem** For any choice of distinct real numbers  $q_1, q_2, q_3$ , there exists a family of curvature homogeneous p.R. metrics on  $\mathbb{R}^3$ , with diagonalizable Ricci tensor and Ricci eigenvalues  $q_i$ , depending on two functions of two variables and two more functions of one variable.

**Theorem** For any real constant  $c \neq 0$ , let  $Q$  be the linear operator of Segre type  $\{1z\bar{z}\}$  described by

$$Q = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & c \\ 0 & -c & 0 \end{pmatrix}.$$

Then, there exists a family of curvature homogeneous Lorentzian metrics on  $\mathbb{R}^3$ , having this Ricci operator, depending on two arbitrary functions of two variables and two arbitrary functions of one variable.