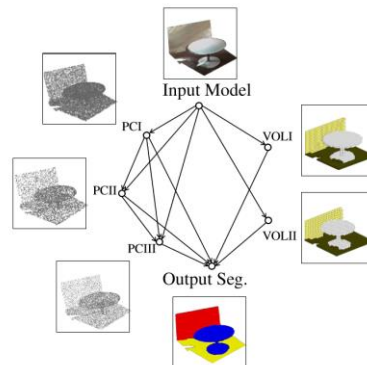
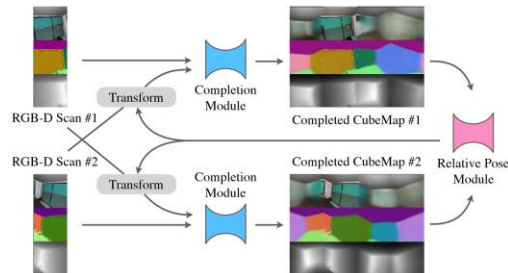
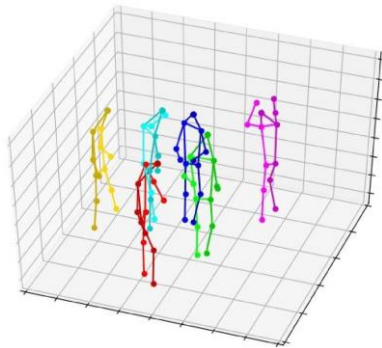
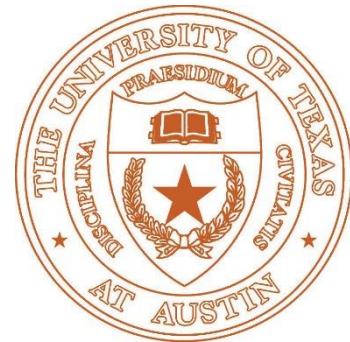


CS376 Computer Vision

Lecture 7: Hough Transform



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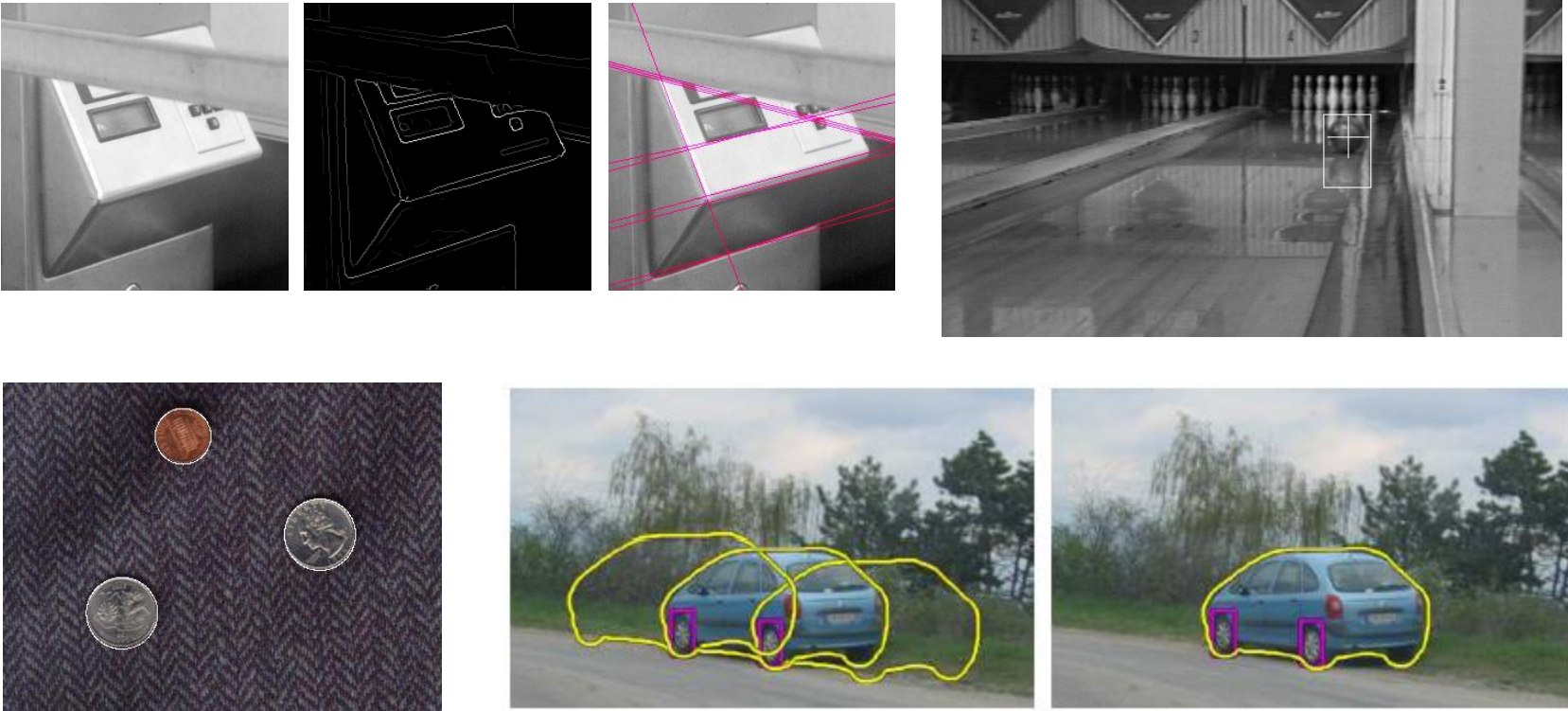
Review

- Image filters
- Edge detection
- Binary image analysis
- Texture
- Optical Flow

Local analysis

Now: Fitting

- Want to associate a model with observed features



[Fig from Marszalek & Schmid, 2007]

For example, the model could be a line, a circle, or an arbitrary shape.

Many Applications

- Vanishing point detection
- Segmentation/Detection
- 3D Vision
 - Calibration
 - Structure-from-motion

Fitting: Main Idea

- Choose a parametric model to represent a set of features
- Correlated problems
 - What are the models
 - Association between models and features
 - How to optimize the models

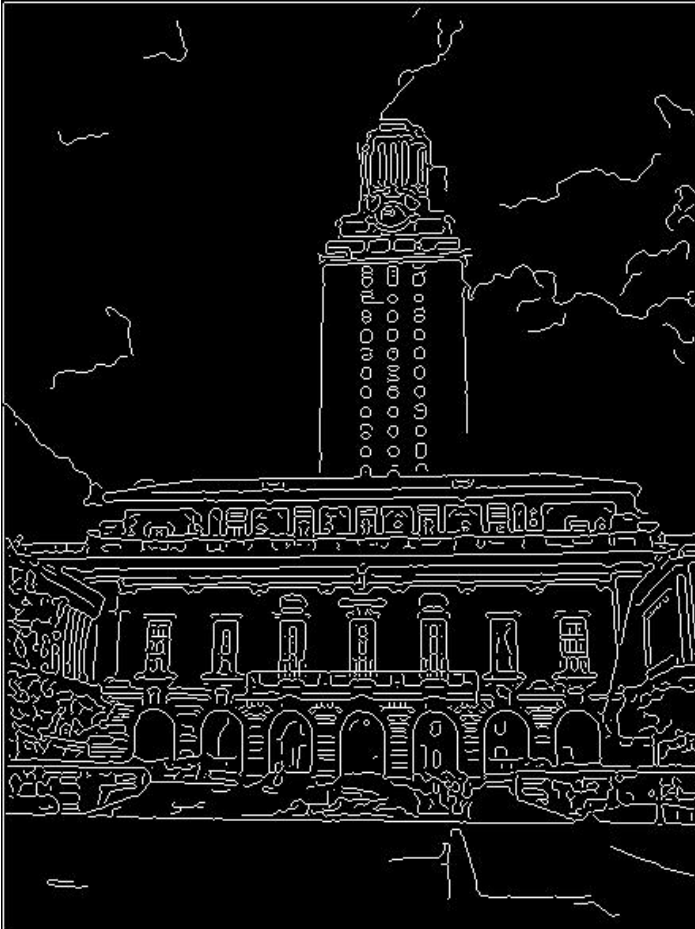
Case study: Line fitting

- Why fit lines?

Line features are quite popular in natural images



Difficulty of line fitting



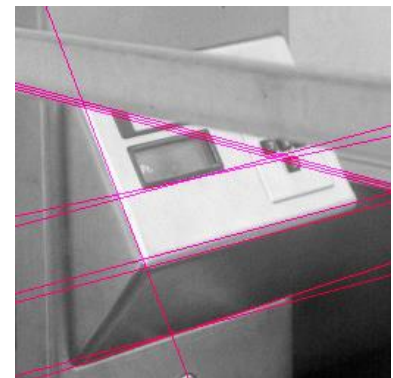
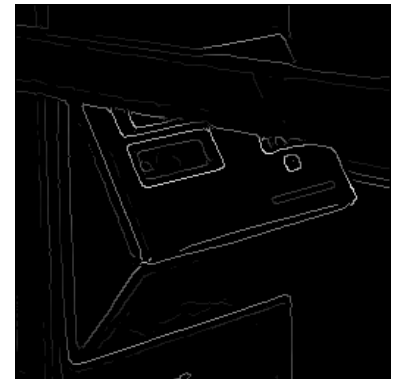
- Incomplete edge detections
- How many lines
- Not all edges are lines
- Noise in detected edges

Voting

- Impossible to test all combinations of features to extract the models
- Let features vote for the models
 - Cycle through features, cast votes for model parameters
 - Usually each model should be low-dimensional
- Noise contribute less to the models

Fitting lines: Hough transform

- Given points that belong to a line, what is the line?
- How many lines are there?
- Which points belong to which lines?
- **Hough Transform** is a voting technique that can be used to answer all of these questions:
 - Record vote for each possible line on which each edge point lies
 - Look for lines that get many votes



Basic Facts

- Not all the votes are correct, but the correct ones form 'clusters'
- Depend on the representations of the models
- Depend on how we fit the models