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Algorithms and Data Structures
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Quiz 6
given: 2017-05-04

You have 20 minutes.

Problem 1

Points: 2+3+5

Consider the following recursive function:

```
fun additiveFold(x : IndList[ℤ]) : ℤ =  
  match x  
    Nil ↦ 0  
    Cons(hd, tl) ↦ hd + additiveFold(tl)
```

1. Give the result of *additiveFold*([1, 2, 3, 4]).
2. Explain why this function is not tail-recursive.
3. Convert it to a tail-recursive function by completing the dotted parts below.

```
fun additiveFoldAux(x : IndList[ℤ], result : ℤ) : ℤ =  
  match x  
    Nil ↦ .....  
    Cons(hd, tl) ↦ .....  
fun additiveFold(x : IndList[ℤ]) : ℤ = {additiveFoldAux(....., .....)}
```

Solution:

1. 10
2. It does something else after receiving the result of the recursive call (in this case: the addition)
- 3.

```
fun additiveFoldAux(x : IndList[ℤ], result : ℤ) : ℤ =  
  match x  
    Nil ↦ result  
    Cons(hd, tl) ↦ additiveFold(tl, hd + result)  
fun additiveFold(x : IndList[ℤ]) : ℤ = {additiveFoldAux(x, 0)}
```

Problem 2

Points: 5+3+2

Assume an unlabeled directed graph *G* with distinguished nodes *start* and *end*.

```
fun search(state : List[Node]) : Option[List[Node]] =  
  
  if (abort(state)) {return None}  
  if (solution(state)) {return Some(state)}  
  foreach(choices(state), c ↦  
    x := search(state + [c])  
    if (x ≠ None) {return x}  
  )  
  return None  
  
fun choices(state : List[Node]) : List[Node] =  
  outgoing(G, last(state))  
  
fun solution(state : List[Node]) : bool =  
  last(state) == end
```

Name: _____

the last element of x

Consider the backtracking algorithm on the left.

1. What does $search([start])$ return?
2. What is the purpose of the function *abort* in general?
3. What is the purpose of the function *abort* in this particular case?

Solution:

1. a path from *start* to *end*
2. speed up the search by avoiding the search of subtrees where no solution can be found
3. abort if a cycle is found (in this case, the algorithm would keep running along the circle, i.e., search an infinite subtree; thus, aborting is not only necessary for efficiency but also to find a path at all)

Note that this algorithm is the basic algorithm for finding the exit of a maze (if intersections are represented as nodes of a graph).
