

### ISTANBUL AYDIN UNIVERSITY

IMAGE PROCESS
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SOFTWARE DEVELOPMENT

```
In [ ]: import cv2
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
```

Problem 1. tf2\_engineer.jpg Read the image in color.

Find the BGR value of the center pixel.

Cover the center by drawing a patch (rectangle) with code 329ea8. Compare the new BGR value of the center pixel after the patch is applied.

```
In [ ]:
         img = cv2.imread('tf2_engineer.jpg', cv2.IMREAD_COLOR)
         if img is None:
            raise FileNotFoundError('tf2_engineer.jpg not found. Place it in this directory
         img rgb = cv2.cvtColor(img, cv2.COLOR BGR2RGB)
         plt.imshow(img rgb)
         plt.title('Original Image')
         plt.axis('off')
         h, w = img.shape[:2]
         yc, xc = h//2, w//2
         intensity_center = img[yc, xc]
         print(f'Centre coordinates: (y={yc}, x={xc})')
         print(f'Intensity at centre (BGR): {intensity_center}')
         patch_h, patch_w = 30, 40
         patch_color_hex = '#329ea8'
         patch_color_rgb = tuple(int(patch_color_hex.lstrip('#')[i:i+2], 16) for i in (0, 2
         patch_color = (patch_color_rgb[2], patch_color_rgb[1], patch_color_rgb[0]) # BGR
         top_left = (xc - patch_w//2, yc - patch_h//2)
         bottom_right = (xc + patch_w//2, yc + patch_h//2)
         img_patch = img.copy()
         cv2.rectangle(img_patch, top_left, bottom_right, patch_color, thickness=-1)
         intensity_patch_center = img_patch[yc, xc]
         print(f'Intensity at patch centre (BGR): {intensity_patch_center}')
         img_patch_rgb = cv2.cvtColor(img_patch, cv2.COLOR_BGR2RGB)
         plt.figure()
         plt.imshow(img_patch_rgb)
         plt.title('Image with Colour Patch')
         plt.axis('off')
```



Image with Colour Patch



Problem 2: Negative Image (einstein.tiff) Description:

Read the image in grayscale

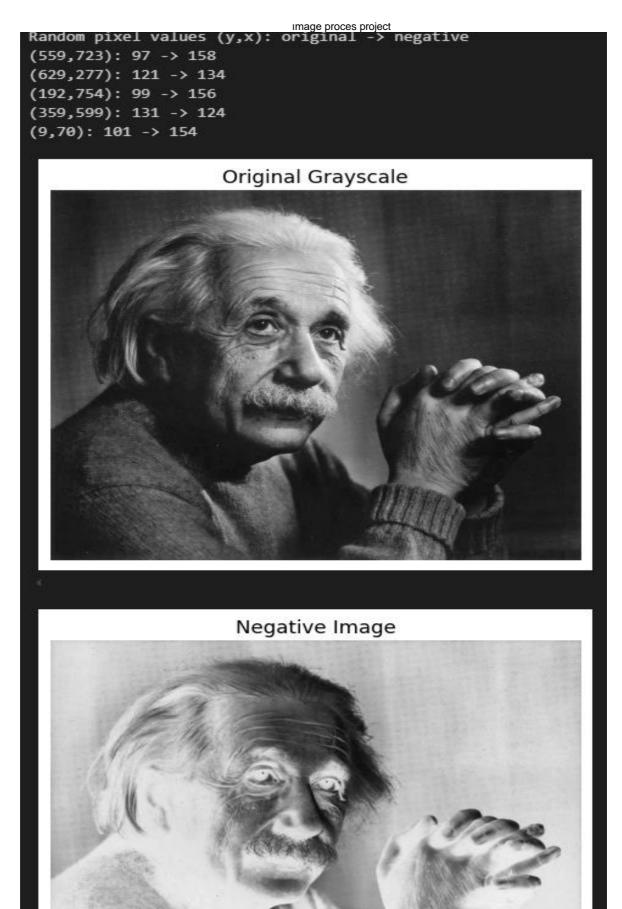
Compute the negative image (255 - r)

Display both original and negative

Print values of five sample pixels in both

```
In [ ]: img_gray = cv2.imread('einstein.tif', cv2.IMREAD_GRAYSCALE)
```

```
if img_gray is None:
    raise FileNotFoundError('einstein.tif not found.')
plt.imshow(img_gray, cmap='gray')
plt.title('Original Grayscale')
plt.axis('off')
neg = 255 - img_gray
plt.figure()
plt.imshow(neg, cmap='gray')
plt.title('Negative Image')
plt.axis('off')
np.random.seed(0)
coords = np.column_stack((np.random.randint(0, img_gray.shape[0], 5),
                           np.random.randint(0, img_gray.shape[1], 5)))
print('Random pixel values (y,x): original -> negative')
for y, x in coords:
    print(f'({y},{x}): {img_gray[y, x]} \rightarrow {neg[y, x]}')
```



Problem 3: Log and Inverse-Log Transformations (pout.tiff) Description:

Read the image in grayscale

Apply log transform:  $s = c \cdot \log(1 + r)$ 

Apply inverse-log transform:  $s = \exp(r / c) - 1$ 

### Perform log then inverse-log to check data loss

```
img_pout = cv2.imread('pout.tif', cv2.IMREAD_GRAYSCALE)
In [ ]:
         if img_pout is None:
             raise FileNotFoundError('pout.tif not found.')
         plt.imshow(img_pout, cmap='gray')
         plt.title('Original pout')
         plt.axis('off')
         c = 255 / np.log(1 + np.max(img_pout))
         log_img = c * np.log(1 + img_pout.astype(np.float64))
         log_img = np.array(log_img, dtype=np.uint8)
         plt.figure()
         plt.imshow(log_img, cmap='gray')
         plt.title('Log Transform')
         plt.axis('off')
         inv_log = np.exp(img_pout.astype(np.float64) / c) - 1
         inv_log = np.clip(inv_log, 0, 255).astype(np.uint8)
         plt.figure()
         plt.imshow(inv_log, cmap='gray')
         plt.title('Inverse Log Transform')
         plt.axis('off')
         inv_log2 = np.exp(log_img.astype(np.float64) / c) - 1
         inv_log2 = np.clip(inv_log2, 0, 255).astype(np.uint8)
         plt.figure()
         plt.imshow(inv_log2, cmap='gray')
         plt.title('Inverse Log of Log Image')
         plt.axis('off')
```

## Original pout



# Log Transform







Problem 4: Unsharp Masking (moon.tiff) Description:

Spatial domain: subtract blurred image from original, then add weighted mask

### Frequency domain: apply FFT-based high-pass filter for comparison

```
moon = cv2.imread('moon.tif', cv2.IMREAD_GRAYSCALE)
In [ ]:
         if moon is None:
             raise FileNotFoundError('moon.tif not found.')
         plt.figure()
         plt.imshow(moon, cmap='gray')
         plt.title('Original Moon')
         plt.axis('off')
         ks = [0.2, 0.5, 1.0]
         D0 = 30
         rows, cols = moon.shape
         u = np.arange(rows)
         v = np.arange(cols)
         U, V = np.meshgrid(u - rows//2, v - cols//2, indexing='ij')
         D = np.sqrt(U^{**}2 + V^{**}2)
         H = 1 - np.exp(-(D**2) / (2*(D0**2)))
         F = np.fft.fft2(moon)
         F_shift = np.fft.fftshift(F)
         for k in ks:
             # Spatial domain unsharp
             blurred = cv2.GaussianBlur(moon, (0,0), sigmaX=3)
             mask = moon - blurred
             g_spatial = np.clip(moon + k * mask, 0, 255).astype(np.uint8)
             # Frequency domain unsharp
             G_freq = (1 + k * H) * F_shift
             G_ifft = np.fft.ifft2(np.fft.ifftshift(G_freq))
             g_freq = np.clip(np.real(G_ifft), 0, 255).astype(np.uint8)
             plt.figure(figsize=(10,4))
             plt.subplot(1,2,1)
             plt.imshow(g_spatial, cmap='gray')
             plt.title(f'Spatial Unsharp (k={k})')
             plt.axis('off')
             plt.subplot(1,2,2)
             plt.imshow(g_freq, cmap='gray')
             plt.title(f'Frequency Unsharp (k={k})')
             plt.axis('off')
```



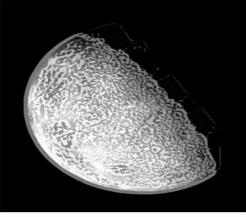
Spatial Unsharp (k=0.2)



Frequency Unsharp (k=0.2)



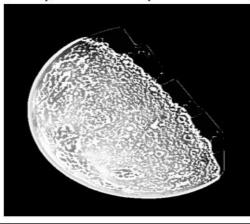
Spatial Unsharp (k=0.5)



Frequency Unsharp (k=0.5)



Spatial Unsharp (k=1.0)



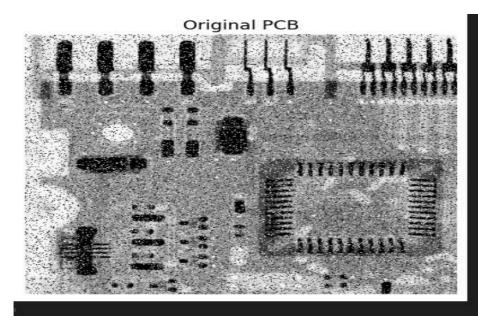
Frequency Unsharp (k=1.0)

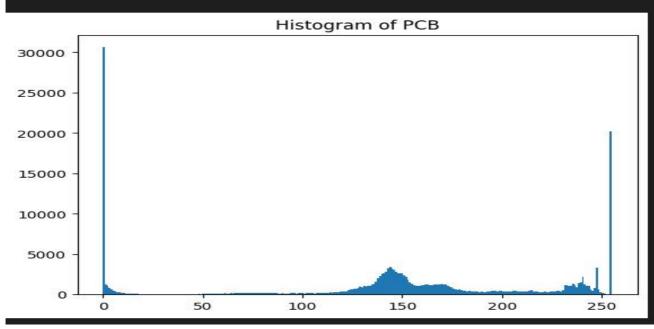


Problem 5: Noise Removal (pcb.tiff) Description:

Read the image in grayscale and view its histogram

Apply median filter for salt-and-pepper noise or Gaussian filter for Gaussian noise





```
plt.title('Histogram of PCB')

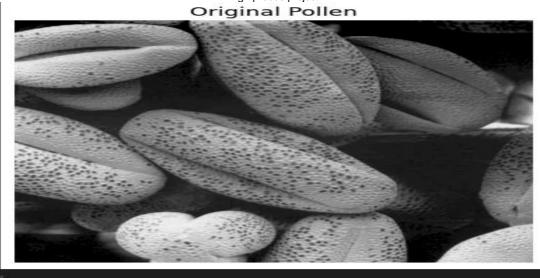
cleaned = cv2.medianBlur(pcb, 3)
cleaned = cv2.GaussianBlur(cleaned, (3,3), 0)
plt.figure()
plt.imshow(cleaned, cmap='gray')
plt.title('Denoised PCB')
plt.axis('off')
```

Problem 6: Pollen Image Enhancement (pollen.tiff) Description:

Read the image and identify issues (blur, contrast, noise)

Apply at least two enhancement methods and compare quantitatively

```
pollen = cv2.imread('pollen.tif', cv2.IMREAD GRAYSCALE)
In [ ]:
         if pollen is None:
             raise FileNotFoundError('pollen.tif not found.')
         plt.figure()
         plt.imshow(pollen, cmap='gray')
         plt.title('Original Pollen')
         plt.axis('off')
         img log = np.log1p(pollen.astype('float'))
         M, N = pollen.shape
         Y, X = np.ogrid[:M, :N]
         center = (M/2, N/2)
         Duv = ((Y-center[0])**2 + (X-center[1])**2)
         gammaL, gammaH, c_{val}, D0 = 0.5, 2.0, 1.0, 30
         H_{\text{hom}} = (gammaH - gammaL)*(1 - np.exp(-c_val*(Duv/(D0**2)))) + gammaL
         fft img = np.fft.fft2(img log)
         fft shift = np.fft.fftshift(fft img)
         filtered = H hom * fft shift
         ifft shift = np.fft.ifftshift(filtered)
         img filtered = np.real(np.fft.ifft2(ifft shift))
         img_homomorphic = np.expm1(img_filtered)
         img_homomorphic = np.clip(img_homomorphic, 0,255).astype(np.uint8)
         plt.figure()
         plt.imshow(img_homomorphic, cmap='gray')
         plt.title('Homomorphic Filtered')
         plt.axis('off')
         clahe = cv2.createCLAHE(clipLimit=2.0, tileGridSize=(8,8))
         img_clahe = clahe.apply(pollen)
         plt.figure()
         plt.imshow(img_clahe, cmap='gray')
         plt.title('CLAHE Equalization')
         plt.axis('off')
```



Homomorphic Filtered

