

MAX487- RO

Receiver Output Enable (RO):
RO is enabled when ~RE is low;
RO is high impedance when ~RE is high

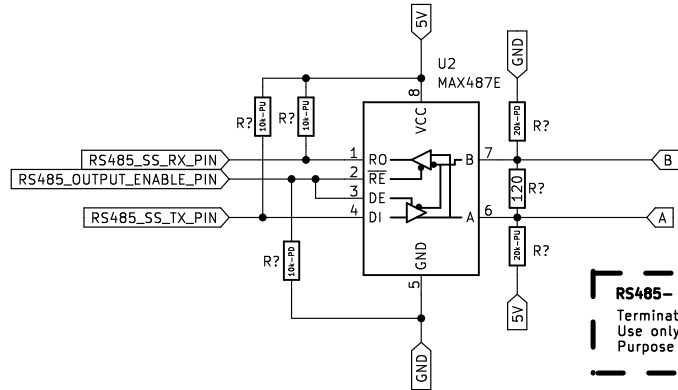
If $V_a > V_b$, RO is high
If $V_b > V_a$, RO is low

At Idle, UART RX line should be kept at positive voltage
Thus 10K Pull-Up resistor is added to keep line
voltage positive when high impedance mode is active

MAX487- DI

Driver Input(DI):
If DE is high. The output terminals A & B are
controlled according to DI.
If $DI > 0$, $V_a > V_b$
If $DI < 0$, $V_b > V_a$

A pull up resistor is connected to DI. When
DI is floating, This pull-up resistor keeps DI positive
so that $V_a > V_b$ is achieved (as if device is of speaking)



RS485- LINE TERMINATION

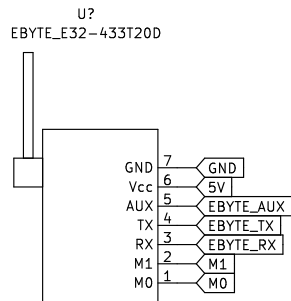
Termination resistor (120 Ohm)
Use only at the master and at the eol.
Purpose is to eliminate reflected EMWs

MAX487- OUTPUT PULL-UP & PULL DOWN

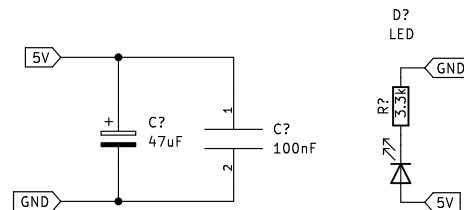
If A and B are floating terminals and
~RE pin is LOW, state of RO is not well defined.
Thus 20k pull-up & pull-down resistors are added
to A and B terminals respectively. When A & B are floating
The RO pin is HIGH

This resistors also keeps $V_a > V_b$ when no device
is transmitting

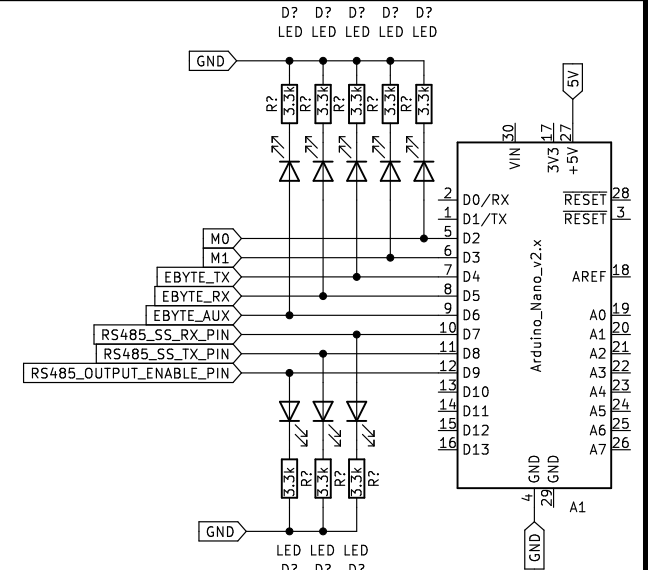
RS485 (MAX487)



LoRa (EBYTE E32 433TD20D)



Power Input



MCU (Arduino Nano)