

CamScanner ile tarandı

2) 
$$S_{1}(t) = \frac{At}{T}$$
,  $0 \le t \le T$ 
 $S_{2}(t) = A(1 - \frac{t}{T}) = A - \frac{At}{T}$ ,  $0 \le t \le T$ 
 $2(t) = \int_{0}^{T} (S_{2}(t) - S_{1}(t)) \cdot \Gamma(t)$ 
 $E_{S_{1}} \rightarrow \int_{0}^{T} \frac{A^{2}t^{2}}{T^{2}} dt = \frac{A^{2}t^{3}}{3T^{2}} \Big|_{0}^{T} = \frac{A^{2}T}{3}$ 
 $E_{S_{2}} \rightarrow \int_{0}^{T} A^{2} - \frac{2A^{2}t}{T^{2}} + \frac{A^{2}t^{2}}{T^{2}} dt = A^{2}t - \frac{A^{2}t^{2}}{T} + \frac{A^{2}t^{2}}{3T^{2}} = \frac{A^{2}T}{3}$ 
 $E_{S_{1}} = E_{S_{2}} \rightarrow Thay have some energy and some probability. Thus,  $2(T) - \int_{0}^{T} \frac{E_{S_{1}}E_{S_{1}}}{2} = O$ 

Decision Rule: (expected for receiver)

From Lecture notes use 2 correlator receiver;

$$F_{C}(t) \rightarrow \int_{0}^{T} \frac{2(T)}{2N_{0}} \rightarrow \int_{0}^{T} \frac{2(T)}{2(T)} \rightarrow \int_$$$ 

3) For antipodal binary PAM;
$$P_b = Q\left(\sqrt{\frac{2E_b}{N_o}}\right), \quad E_b = A^2 T_b, \quad T_b = \frac{1}{R_b} = 10^5 \text{sec}$$
in verse Q function where it equals to  $10^{-6}$ .

$$\sqrt{\frac{2\epsilon_b}{N_0}} = 4.75$$

$$A^{2}T_{b} = \frac{(4.75)^{2} \cdot N_{b}}{2} = A = \sqrt{\frac{(4.75)^{2} \times 10^{2} \times 10^{5}}{2}}$$

4): 
$$S_1(t) = A$$
 for OLECT for transmitting 1  
 $S_0(t) = 0$  for OLECT for transmitting 0  
 $S_0(t) = 0$  for OLECT for transmitting 0  
We know that this is on "ON-OFF Keying" from lecture notes.

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t)} h_2(t) \xrightarrow{f} 2(\tau) \xrightarrow{f} Computator$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

$$(t) \xrightarrow{h_2(t) = s_1(\tau - t) = s_1(t)} t = T$$

where, 
$$E_{s_0} = 0$$
,  $E_{s_1} = A^2T = E_d$ 

$$E_b = \frac{1}{2}E_{so} + \frac{1}{2}E_{s_1} = \frac{A^2T}{2}$$

$$8 = \frac{E_{s_1} - E_{s_2}}{2} = \frac{A^2 T}{2}$$

$$P_{L} = Q(\sqrt{\frac{Ed}{2N_{0}}})$$

$$8_{0} = \frac{1}{2}E_{0} + \frac{1}{2}E_{0} + \frac{1}{2}E_{0}$$

$$8_{0} = \frac{E_{0} - E_{0}}{2} = \frac{A^{2}T}{2}$$

$$8_{0} = \frac{E_{0} - E_{0}}{2} = \frac{A^{2}T}{2}$$

$$9_{0} = \frac{E_{0} - E_{0}}{2} = \frac{A^{2}T}{2}$$

$$1 = \frac{E_{0}}{2} = \frac{E_{0} - E_{0}}{2} = \frac{A^{2}T}{2}$$

$$1 = \frac{E_{0} - E_{0}}{2} = \frac{E_{0} - E_{0}$$

5) 
$$S_{0}(t) = -1$$
,  $0 \le t \le T$  for "0"

 $S_{1}(t) = 1$ ,  $0 \le t \le T$  for "4"

 $P(0) = \frac{1}{3}$ ,  $P(1) = \frac{2}{3}$ 
 $V_{0} = \frac{1}{4 \times 100} = \frac{1}{2}$ 
 $V_{0} = \frac{1}{4 \times 100} = \frac{1}{4 \times 100} = \frac{1}{2}$ 
 $V_{0} = \frac{1}{4 \times 100} = \frac{1}{4 \times 100} = \frac{1}{2}$ 
 $V_{0} = \frac{1}{4 \times 100} = \frac{1}{4 \times 100} = \frac{1}{4 \times 100} = \frac{1}{2}$ 
 $V_{0} = \frac{1}{4 \times 100} =$ 

d) We know from part b,

$$P_{b} = P Q\left(\frac{\sqrt{t_{b}}' - \delta_{0}}{\sqrt{N_{0}}}\right) + (4 - P) Q\left(\frac{\sqrt{t_{b}} + \delta_{0}}{\sqrt{N_{0}}}\right)$$
We know for maximum likelihood we have equally likely antipodal signals. Thus,
$$V_{0} = \frac{\alpha_{1} + \alpha_{2}}{2} + \frac{\sqrt{t_{0}}^{2}}{\alpha_{1} - \alpha_{2}} \ln\left(\frac{P(S_{1})}{P(S_{0})}\right) = 0$$
Thus,
$$P_{b} = \frac{1}{2} Q\left(\frac{2E_{b}}{N_{0}}\right) + \frac{1}{2} Q\left(\frac{2t_{b}}{N_{0}}\right)$$

$$P_{b} = Q\left(\frac{2E_{b}}{N_{0}}\right)$$

## CamScanner ile tarandı