

COMPUTER COMMUNICATION PROJECT 01 REPORT

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1 Stop-and-Wait Protocol Data Structers

```
class my_frame{
         int frame_id; //used for storing frame's id
         bool has_transmission_error; //used for controlling is there a error in frame
         bool has_ack_error; //used for controlling is there a error in acknowledge
         my_frame(); // constructor for this class and equalize both
         has transmission error and has ack error to "false"
         void set_transmission_error(bool t); // used for setting a value to
         has transmission error
         void set_ack_error(bool t); // used for setting a value to has_ack_error
 }
 class my event{
         char station; // used to store station type 'A' or 'B'
         my_frame t_frame; // used to store which frame is used in this event
         int event_time; // used to store time when this event is happening
         int is_transmitted; // is frame transmitted succesfully
         int is received; // is frame received succesfully
         my_event(); // used for equalize is_transmitted and is_received to zero
         void set is transmitted(int t); // used for setting a value to is transmitted
         void set_is_received(int t); // used for setting a value to is_received;
         void set_event_time(int t); // used for setting a value to event_time
         void set_station(char t); // used for setting a value to station
 }
 class stop_and_wait{
         vector<my frame> frame array; //used to store frames
         vector<my_event> my_event_list; // used to store every event both transmitting
         and receiving
         int starting_time; //starting time of our transmission
         int ending time; //time that shows when our transmission is ended
         int number_of_frame; //used for storing number of frame
         stop_and_wait(int t_size,int t_starting_time); //this function is a constructor
         and used for setting starting_time and number_of_frame
         my event last event(); // used for returning last event in our event list
         void station_A(); // used for transmitting
         void station B(); //used for receiving
         bool is finished(); //used for controlling our transmission is ended or not
         void print_event_list(); //used for printing event list
         void rand_function(int error_rate); //used for setting random errors to our frame
         array
 }
```

2 Stop-and-Wait Protocol Implementation

Psuedo Code of station_A

```
my_event t_event;
if my_event_list is empty{
       Set time to t_event
       Set transmitted frame to t_event
       if frame has an error{
               Set is_transmitted of t_event to '1'
       }
       else{
               Set is_transmitted of t_event to '0'
        }
}
else{
       if last frame transmitted successfully{
               take next frame;
               set time to event
               if frame has an error{
                       Set is_transmitted of t_event to '1'
               }
               else{
                       Set is_transmitted of t_event to '0'
               }
        }
       else{
               take last frame
               set a timeout to event
               Set is_transmitted of t_event to '1'
        }
push t_event to my_event_list vector
```

Psuedo Code of station_B

3 Selective Repeat Implementation

Psuedo Code of Station_A

• Psuedo Code of Station_B

```
frame n in [rcvbase, rcvbase+N-1]
send ACK(n)
out-of-order: buffer
in-order: deliver, advance window to next not-yet received frame
frame n in [rcvbase-N,rcvbase-1]
ACK(n)
otherwise
ignore
```

4 Explanation of Frame Series in Test Set

4.1 Test 1 - Stop and Wait

- Station A sends Frame 1
- Station B receives Frame 1 and send ack for Frame 2
- Station A receives ack for Frame 2 and sends Frame 2
- Station B receives Frame 2 and send ack for Frame 3
- Station A receives ack for Frame 3 but can not send Frame 3 because of error
- Timeout expires Station A sends Frame 3 again
- Station B receives Frame 3 and send ack for Frame 4
- Station A receives ack for Frame 4 and sends Frame 4
- Station B receives Frame 4 and send ack for Frame 5
- Station A receives ack for Frame 5 and sends Frame 5
- Station B receives Frame 5 and send ack for Frame 6

- Station A receives ack for Frame 6 and sends Frame 6
- Station B receives Frame 6 and send ack for Frame 7
- Station A receives ack for Frame 7 and sends Frame 7
- Station B receives Frame 7 and send ack for Frame 8
- Station A receives ack for Frame 8 and sends Frame 8
- Station B receives Frame 8 and send ack for Frame 9
- Station A receives ack for Frame 9 and sends Frame 9
- Station B receives Frame 9 and send ack for Frame 10
- Station A receives ack for Frame 10 and sends Frame 10
- Station B receives Frame 10 and send ack
- Transmission ends.

4.2 Test 2 – Selective Repeat

- Station A sends Frame 1
- Station B receives Frame 1 and send ack for Frame 2
- Station A receives ack for Frame 2 and sends Frame 2
- Station B receives Frame 2 and send ack for Frame 3
- Station A receives ack for Frame 3 but can not send Frame 3
- Frame 3 lost and can not be received by station B.
- Whenever an out-of-sequence frame is observed at the station B, an NAK frame is sent by station B with number of expected frame, frame 3 (NAK3)
- When station A receives NAK frame, it transmits Frame 3 again.
- When waiting for Frame 3, station B receives Frames 4,5,6,7 and buffers them
- After station A transmits Frame 3, station transmits Frame 8,9,10
- Station B receives Frame 8.9.10 and sends ack to Station A.
- Transmission ends.

4.3 Test 3 - Selective Repeat

- Station A sends Frame 1
- Station B receives Frame 1 and send ack for Frame 2
- Station A receives ack for Frame 2 and sends Frame 2
- Station B receives Frame 2 and send ack for Frame 3
- Station A receives ack for Frame 3 but can not send Frame 3
- Frame 3 lost and can not be received by station B.
- Whenever an out-of-sequence frame is observed at the station B, an NAK frame is sent by station B with number of expected frame, frame 3 (NAK3)
- Station A receives ack error before so it retransmits all Frames that are transmitted after Frame 3..
- Station B receives Frames 3,4,5,6,7,8,9,10
- Station B sends ack for Frames 3,4,5,6,7,8,9,10 to station A.
- Transmission ends.

5 Size of the sliding window in Technique 2

In the test 2 set, the sender was sending 4 frames after error occured when sending frame Therefore the windows size is 4 for that table. Source; http://www.cse.iitk.ac.in/users/dheeraj/cs425/lec09.html

6 Size of buffer in Technique 2

Size of buffer have to be same with size of sliding window int Technique 2.

7 Maximum window size for Technique 2

Sequence number is 3 bit so the max window size=2^(n-1)=2^2=4

8 Graph for presenting relationship between error rate and simulation time

