Deep Learning Homework 3

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Explanations and Discussions

My base model has a single-layer LSTM as Encoder and 2 transpose convolutional layers as Decoder. There are 2 fully connected layers at the end of the encoder to get mean and variance vectors. I have added Batch Norm layers after both of the 2 transpose convolutional layers. A sampler unit takes these vectors to sample a latent representation which fits to input data distribution. In this sampling stage, I have benefited from reparameterization trick. This trick aims to change sampling method in a way to make it differentiable and prevent backpropagation algorithm to get stuck in the sampler unit.

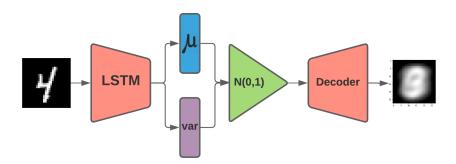
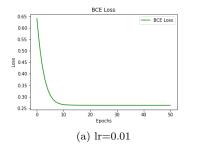


Figure 1: General Model

2 conv-layered base model didn't give satisfying results as a start. KL divergence dropped to zero so fast that model couldn't learn at all. Latent representation dimension was 128 and LSTM hidden layer dimension was 64.



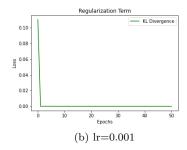
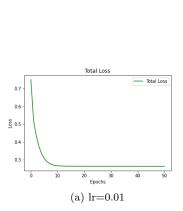


Figure 2: BCE Loss and Regularization Term



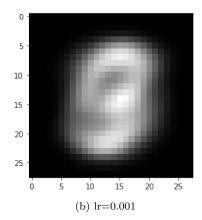
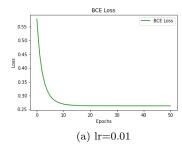


Figure 3: Total Loss and a Sample(Generated)

I have realized that I made a mistake in decoder's output part. I added two activation functions sequentially, so I removed one of them but this didn't effect the performance at all. Then I made LSTM hidden layer's dimension 128, to be sure that model was not missing any information due to small hidden layer size.



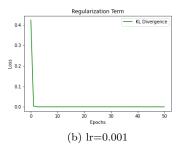


Figure 4: BCE Loss and Regularization Term

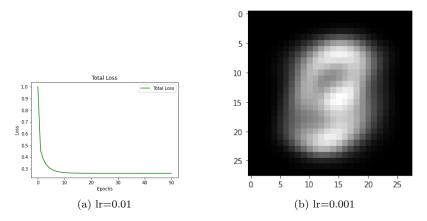


Figure 5: Total Loss and a Sample(Generated)

When I try to sample different images with different (randomly sampled) vectors, the results was always the same. This made me think that my model was not able to learn well so I deleted the Batch Norm layers. My mistake here was adding Batch Norm to the base model. I should have start with basic layers. Yet, this didn't improved performance much.

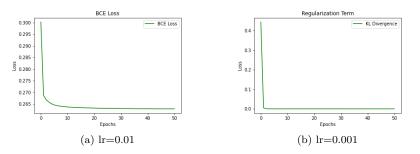


Figure 6: BCE Loss and Regularization Term

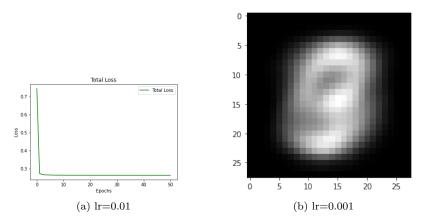


Figure 7: Total Loss and a Sample(Generated)

Then I have changed the dimensions of the linear layer which is at the beginning of the decoder. And deleted the Batch Norm layer which was following this linear layer, too.

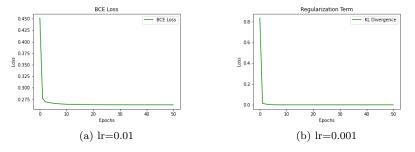


Figure 8: BCE Loss and Regularization Term

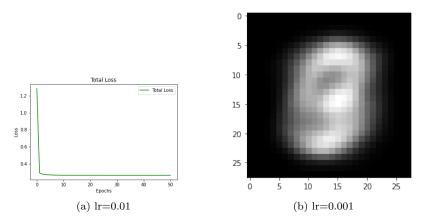


Figure 9: Total Loss and a Sample(Generated)

Finally, I was convinced that the big problem was not about these changes and decided to change my decoder architecture. I got inspired from VAE examples in internet (please see the References section). I added two more transpose convolution layers to my decoder and got rid of the padding in all of these layers since my inputs were already small and clear.

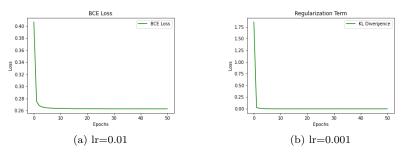
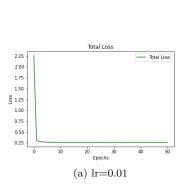


Figure 10: BCE Loss and Regularization Term



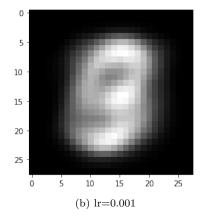


Figure 11: Total Loss and a Sample(Generated)

I have finally added dropout layers after 3 of 4 transpose convolutional layers but this didn't help too. With a better encoder, results may be different.

Additional Notes

Lecture slides, Pytorch Documentations [1], Pytorch Tutorial [2] and "Deep Learning" book [3] have been used during this study. Also I have inspired from different examples in internet [4], [5], [6], [7].

References

- [1] "Pytorch Documentation", https://pytorch.org/docs/master/nn.html.
- [2] "Pytorch Tutorial", https://github.com/pytorch/tutorials/blob/master/beginner_source/blitz/cifar10_tutorial.py.
- [3] Goodfellow, I., Y. Bengio and A. Courville, *Deep Learning*, MIT Press, 2016, http://www.deeplearningbook.org.
- [4] "Teaching a Variational Autoencoder", https://towardsdatascience. com/teaching-a-variational-autoencoder-vae-to-draw-mnist-characters-978675c95776.
- [5] "The Reparameterization Trick", https://sassafras13.github.io/ReparamTrick/.
- [6] "VAE Pytorch Tutorial", https://github.com/Jackson-Kang/ Pytorch-VAE-tutorial/blob/master/01_Variational_AutoEncoder. ipynb.
- [7] "Generative Models Variational Autoencoders", https://atcold.github.io/pytorch-Deep-Learning/en/week08/08-3/.