UD.

2.13 indicate which of the following discrete -time signals are eigenfunctions of stable , LTI ascrete time systems.

2.131e) = (114) An LTI system generates an output signal obtained by subjecting on input signal to a linear and time - independent mathematical processing.

Eigenfunctions at LTI systems are at the form. an so 2.13(e) (1(4)n is elgentunction

232 FOR X(eJW)=11(1-0.e-JW), with -1(0(0, determine and sketch the following as a function of w:

(2.32 c) | X (e JW) | In option C, we are asked

for magnitude for (-1<0<0)

 $|\chi(e^{\jmath \omega})| = [\chi(e^{\jmath \omega})\chi^*(e^{\jmath \omega})]^{\frac{1}{2}}$

2.36 An LTI discrete-time system was frequency response gluen by

$$H(61m) = \frac{1 - 0.86 - 1}{(1 - 16 - 1m)(1 + 16 - 1m)} = \frac{1 - 0.86 - 1}{1 + 6} + \frac{1 - 0.86 - 1}{7} + \frac{1 - 0.86 - 1}{6 - 15m}$$

(c) If the input to this system is

x[n]=4+2 cos(mon) for -ox/1/00

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4 SNJ = A = constant

for - oo < n < oo) what is the constant A)

Denau!

(1)

$$=(0.8)^{n}$$
. $U(8.0) + (0.8)^{n-2}$. $U(8.0) =$

$$A[U] = H(s_{20}) \cdot A + 5 |H(s_{2m0})| \approx (mu) + \nabla H(s_{2m0})$$

$$A[U] = 0.8 h(v - T) = x(v - T)$$

$$A[U] = 0.8 h(v - T) = x(v - T)$$

$$A[U] = 0.8 h(v - T) + x(v - T)$$

$$A[U] = x(s_{2m}) + s_{2m} + x(v - T)$$

$$A[U] = x(s_{2m}) + s_{2m} + x(v - T)$$

$$A[U] = x(s_{2m}) + s_{2m} + x(v - T)$$

$$A[U] = x(s_{2m}) + s_{2m} + s$$

To find the constant cause
$$|H(e^{TWO})| = 0$$

$$1+e^{-T2WO} = 0 \iff WO = \frac{\pi}{2}$$

$$4\cdot \frac{2}{1-0.8} = 4\cdot \frac{2}{0.2} = 40$$