

# Optimality conditions for unconstrained optimization

$$\min_{x \in \mathbb{R}^n} f(x)$$

**Def** Descent direction  
 $f: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $d \in \mathbb{R}^n$  is a descent direction for  $f$  at point  $x \in \mathbb{R}^n$  if  $\nabla f(x) \cdot d > 0$   
 $f(x + \alpha d) < f(x)$  for all  $\alpha: 0 \leq \alpha \leq \bar{\alpha}$

**Lemma** For a continuously differentiable function  $f$ , if a direction  $d$  such that  $\langle \nabla f(x), d \rangle < 0$  then  $d$  is a descent direction at  $x$ .

$$\nabla g(\alpha) := f(x + \alpha d) \quad g: \mathbb{R} \rightarrow \mathbb{R} \text{ as a function of } \alpha$$

$$g'(\alpha) = d^T \nabla f(x + \alpha d) \quad (\text{chain rule in multivariate case})$$

$$g(\alpha) = g(0) + g'(0)\alpha + \bar{o}(\alpha)$$

$$f(x + \alpha d) = f(x) + \alpha \nabla f(x) \cdot d + \bar{o}(\alpha)$$

$$\frac{f(x + \alpha d) - f(x)}{\alpha} = \nabla f(x) \cdot d + \frac{\bar{o}(\alpha)}{\alpha} \xrightarrow{\alpha \rightarrow 0} \nabla f(x) \cdot d$$

So, the sign of derivative is the same as  $\nabla f(x) \cdot d$

Note:

Some descent directions might not satisfy

$$\nabla f(x) \cdot d < 0:$$

$$d = (0, 1)$$

$$f(x) = x_1^2 - x_2^2$$

$$\nabla f(x) = (2x_1, -2x_2)$$

$$\nabla f(1, 0) = (2, 0)$$

$$\langle \nabla f, d \rangle = 0, \text{ but}$$

$$f(x + \alpha d)|_{x=(1,0)} = 1 - \alpha^2 < f(x) = 1$$

## FONC (first order necessary condition)

**Thm** If  $\bar{x}$  is an unconstrained local min of  $f$   
 If  $f$  is differentiable  $f: \mathbb{R}^n \rightarrow \mathbb{R}$   
 Then  $\nabla f(\bar{x}) = 0$ .

$\nabla f(\bar{x})$  would be a descent direction

Note (\*):

Some points with no descent directions might not be local minima:

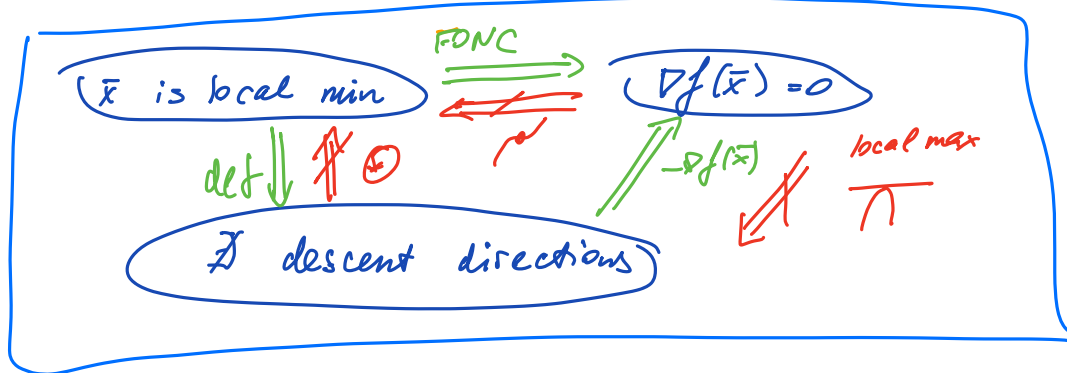
$$f(x_1, x_2) = (x_1^2 - 2x_2)(2x_1^2 - x_2)$$

Proof of Note (\*): Not a local min:  $f(0,0) = 0$ ,  $f(t, t^2) = (t^2 - 2t^2)(2t^2 - t^2) = -t^4 < 0$  for  $t > 0$

$$\text{Take a direction } (d_1, d_2), \quad g(\alpha) = f(x + \alpha d)|_{x=0}, \quad g(0) = 0$$

$$g(\alpha) = (\alpha^2 d_1^2 - 2\alpha d_2)(2\alpha^2 d_1^2 - \alpha d_2) = 2\alpha^4 d_1^4 - \alpha^3 5d_1^2 d_2 + 2\alpha^2 d_2^2 = 2\alpha^2 (d_1^4 \frac{5}{2} \alpha d_1^2 d_2 + d_2^2) > 0$$

$$D = \frac{25}{4} d_1^4 d_2^2 - 4d_1^4 d_2^2 = \frac{9}{4} d_1^4 d_2^2 \text{ for small } \alpha$$



## SONC (Second order necessary condition)

(Thm) If  $f$  is twice CTS differentiable  
 If  $\bar{x}$  is a strict local minimizer  
 Then  $\nabla f(\bar{x}) = 0$  and  $\nabla^2 f(\bar{x}) \succeq 0$ .

$$\nabla f(\bar{x} + \alpha d) = f(\bar{x}) + \alpha d^T \underbrace{\nabla f(\bar{x})}_{=0} + \frac{\alpha^2}{2} d^T \nabla^2 f(\bar{x}) d + o(\alpha^2)$$

$$\frac{f(\bar{x} + \alpha d) - f(\bar{x})}{\alpha^2} = \frac{1}{2} d^T \nabla^2 f(\bar{x}) d + \frac{o(\alpha^2)}{\alpha^2} \underset{\alpha \rightarrow 0}{\rightarrow} 0$$

$$\text{So, } d^T \nabla^2 f(\bar{x}) d \geq 0$$

for any direction  $d$ , so  $\nabla^2 f(\bar{x}) \succeq 0$

Note: even if  $\nabla f(x^*) = 0$   
 and  $\nabla^2 f(x) \succeq 0$  the point  
 might be not a strict  
 minimizer ( $= 0$ ).

## SOSC (Second order sufficient condition)

(Thm) If  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is twice CTS differentiable

$$\exists \bar{x} : \nabla f(\bar{x}) = 0, \nabla^2 f(\bar{x}) \succ 0$$

Then  $\bar{x}$  is a strict local minimizer

Let  $\lambda$  be the min eigenvalue of  $\nabla^2 f(\bar{x})$

$$\Rightarrow y^T \nabla^2 f(\bar{x}) y \geq \lambda \|y\|^2 \quad \forall y \in \mathbb{R}^n \quad (\text{let } y = \alpha d, \|d\|=1)$$

$$f(\bar{x} + y) - f(\bar{x}) = \frac{1}{2} y^T \nabla^2 f(\bar{x}) y + o(\|y\|^2) \geq \frac{1}{2} \|y\|^2 \lambda + o(\|y\|^2)$$

$$\frac{f(\bar{x} + y) - f(\bar{x})}{\|y\|^2} \geq \frac{1}{2} \lambda + \frac{o(\|y\|^2)}{\|y\|^2} \xrightarrow{\alpha \rightarrow 0} \frac{1}{2} \lambda > 0$$

So,  $f(\bar{x} + y) > f(\bar{x})$  for  $\|y\|$  small enough.

Note: Strict local  
 minimizers might not  
 have  $\nabla^2 f(x) \succ 0$

Two problems: ① We got no info about global minima

② FONC + SONC + SOSC can be together inconclusive.

Example  $f(x) = 4x_1^2 - x_2^3$  at  $(0,0)$

$$\nabla f(0,0) = (8x_1, -3x_2^2) = (0,0) \quad \text{FONC} \checkmark$$

$$\nabla^2 f(0,0) = \begin{pmatrix} 8 & 0 \\ 0 & -6x_2 \end{pmatrix} = \begin{pmatrix} 8 & 0 \\ 0 & 0 \end{pmatrix} \quad \text{SONC} \checkmark$$

SOSC  $\times$  since 0 eigenvalue

② Not a local min  $d = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  is problematic  $f(\alpha d) = \begin{pmatrix} 0 \\ -\alpha^3 \end{pmatrix}$

### Application 1 Least squares problem

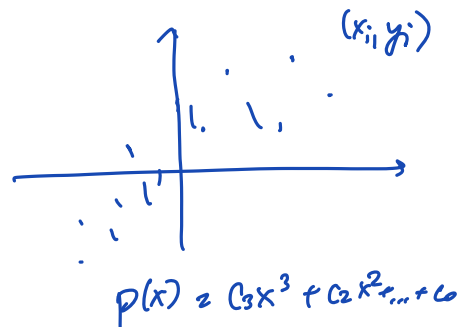
$$\min_x \|Ax - b\|_2^2$$

$\begin{matrix} n \\ A \\ m \end{matrix}$

$m \gg n$   
 (cannot solve system directly)

That is, we have more data than dimensions

Note: Curve fitting is also a least squares problem!



Suppose  $A$  has linearly independent columns

$$f(x) = \|Ax - b\|_2^2 = x^T A^T A x - 2x^T A^T b + b^T b$$

$$\nabla f(x) = 2A^T A x - 2A^T b \quad \text{candidates for solutions}$$

$$\nabla f(x) = 0 \quad x = (A^T A)^{-1} A^T b$$

Note: nullspace of  $A^T A$ :

$$x^T A^T A x = 0$$

$$\|Ax\|_2^2 = 0 \Rightarrow Ax = 0$$

$\Rightarrow x = 0 \Rightarrow A^T A$  is invertible

Hence,  $\nabla^2 f(x) > 0 \Rightarrow x$  is a strict local min

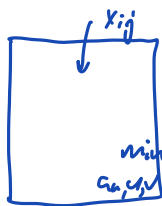
Uniqueness: objective is radially unbounded

### Application 2 Fermat - Weber facility location problem

$$\min_{x \in \mathbb{R}^n} \sum_{i=1}^m \|x - z_i\|$$

place new grocery store to minimize travel to the houses

### Application 3 More general function fitting



$$\min_{a_i, u_i, v_j} \sum_{i,j} (x_{ij} - \sum_{k=1}^r a_k u_i v_j)^2$$

$$\min_{a_i, u_i, v_j} \sum_{i,j} (x_{ij} - \sum_k a_k \exp(-|u_i - v_j|^2))$$