

"If your brother becomes poor and cannot maintain himself with you, you shall support though he were a stranger and a sojourner, so that he shall live with you." (Leviticus 25)

Reducing Leximin Fairness to Utilitarian Optimization

Accepted to AAAI'25 😊

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**Candidate outcomes
(selections)**



Social Choice



Selection

**Agents'
preferences
over selections**



Candidate outcomes
(selections)

Welfarist
Social Choice

Selection that
optimizes a
welfare objective

Agents'
utility functions
over selections



Welfare objectives

Utilitarian

Maximize the **sum** of agents' utilities.



Egalitarian

Maximize the **minimum** utility.

Leximin

Maximize the **minimum** utility.
subject to this, maximize second-smallest utility;
subject to this, maximize third-smallest utility;
and so on.



Welfare objectives – Computation



Utilitarian

Maximize the **sum** of agents' utilities.

Egalitarian

Maximize the **minimum** utility.

Leximin

Maximize the minimum utility.

subject to this, maximize second-smallest utility;

subject to this, maximize third-smallest utility;

and so on.

Welfare objectives – Complexity



Example: Allocating Indivisible Goods Among Agents With Additive Utilities

Utilitarian

Poly: greedily assign each item to the agent who values it most.

Egalitarian

NP-hard

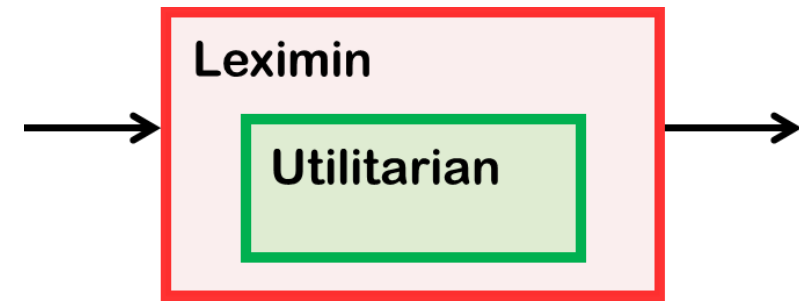
Approximation algorithms exist (e.g. Bansal and Sviridenko, 2006).

Leximin

⇒ NP-hard.

We are not aware of any approximation algorithms.

Our Contribution



For any social choice problem with utilities ≥ 0 :

- If you give us a black-box that computes a **utilitarian-optimal¹** selection in polytime –
- then we give you a polytime algorithm that computes a **leximin-optimal** (in expectation) lottery over selections.

Our reduction is **robust**:

- If your black-box is **α -approximately utilitarian-optimal -**
- then our lottery is **α -approximately leximin-optimal².**

1. for weighted (non-normalized) utilities.

2. for an appropriate definition of ‘approximately leximin-optimal’.

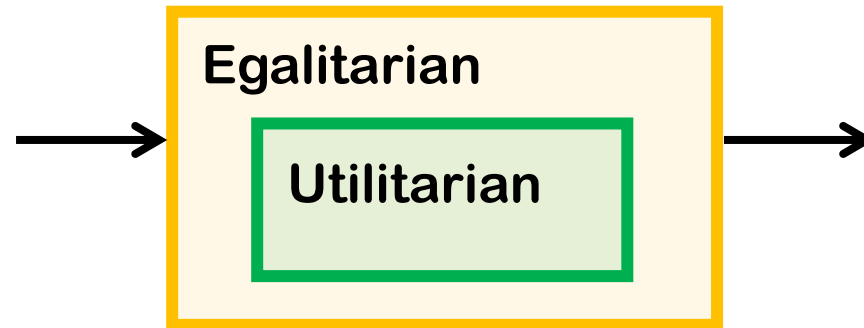
Previous Work (Kawase & Sumita, 2020)

Problem

Stochastic Allocation of Indivisible Goods.

- The output is a lottery over the set of (deterministic) allocations.

Theorem: Given an α -approx. alg. for utilitarian
one can obtain an α -approx. alg. for egalitarian in polynomial time.



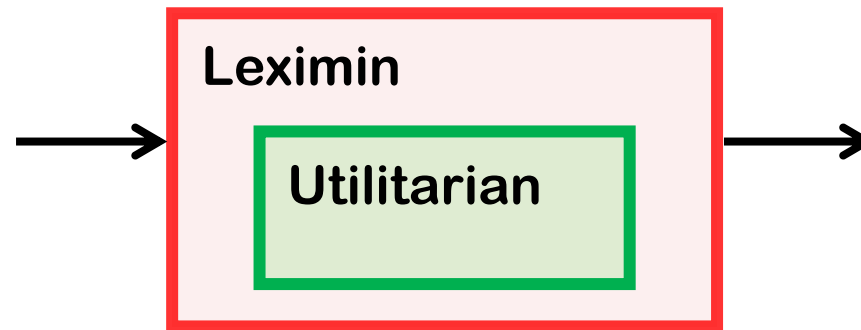
Our Work (2024)

Problem

Any social choice problem with utilities ≥ 0 .

- The output is a lottery over the set of (deterministic) selections.

Theorem: Given an α -approx. alg. for utilitarian
one can obtain an α -approx. alg. for leximin in polynomial time.



Our Work (2024)

Problem

Any social choice problem with utilities ≥ 0 .

- The output is a lottery over the set of (deterministic) selections.

Theorem: Given an α -approx. alg. for **utilitarian** one can obtain an α -approx. alg. for **leximin** in polynomial time.



Applications

Stochastic Indivisible Allocation¹

- Additive utilities \Rightarrow Exact
- Submodular utilities \Rightarrow 0.5-approx (det)
- Submodular utilities $\Rightarrow \left(1 - \frac{1}{e}\right)$ -approx (rand)

Participatory Budgeting Lottery²

- An FPTAS for leximin

Giveaway Lotteries³

- An FPTAS for leximin

1. On the Max-Min Fair Stochastic Allocation of Indivisible Goods. Kawase and Sumita, 2020.
2. Fair Lotteries for Participatory Budgeting. Aziz, Lu, Suzuki, Vollen, and Walsh, 2024.
3. Fair and Truthful Giveaway Lotteries. Arbiv and Aumann, 2022.

The Model

Agents	$N = \{1, \dots, n\}$
Selections	$S = \{s_1, \dots, s_{ S }\}$ (deterministic outcomes)
Solutions	A solution is a <u>distribution</u> over selections. $X = \left\{ \mathbf{x} = (x_1, \dots, x_{ S }) \in \mathbb{R}_{\geq 0}^{ S } \mid \sum_{j=1}^{ S } x_j = 1 \right\}$
Utilities	$u_i : S \rightarrow \mathbb{R}_{\geq 0} \quad \forall i \in N$ (a value oracle)
Expected Utilities	$E_i : X \rightarrow \mathbb{R}_{\geq 0} \quad \forall i \in N$ $E_i(\mathbf{x}) = \sum_{j=1}^{ S } x_j \cdot u_i(s_j)$

The Model

Agents $N = \{1, \dots, n\}$

Selections $S = \{s_1, \dots, s_{|S|}\}$ (deterministic outcomes)

A solution is a distribution over selections.

Solutions
$$X = \left\{ \mathbf{x} = (x_1, \dots, x_{|S|}) \in \mathbb{R}_{\geq 0}^{|S|} \mid \sum_{j=1}^{|S|} x_j = 1 \right\}$$

Utilities $u_i : S \rightarrow \mathbb{R}_{\geq 0} \quad \forall i \in N$ (a value oracle)

$E_i : X \rightarrow \mathbb{R}_{\geq 0} \quad \forall i \in N$

Expected
Utilities

$$E_i(\mathbf{x}) = \sum_{j=1}^{|S|} x_j \cdot u_i(s_j)$$

Utilitarian Opt.

A solution $\mathbf{x}^{uo} \in X$ s.t. $\forall \mathbf{x} \in X$:

$$\sum_{i=1}^{|S|} E_i(\mathbf{x}^{uo}) \geq \sum_{i=1}^{|S|} E_i(\mathbf{x})$$

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$$E_i : X \rightarrow \mathbb{R}_{\geq 0} \quad \forall i \in N$$
$$E_i(\mathbf{x}) = \sum_{j=1}^{|S|} x_j \cdot u_i(s_j)$$

Weighted Utilitarian Opt.

Given n constants $c_1, \dots, c_n \geq 0$.

A solution $\mathbf{x}^{uo} \in X$ s.t. $\forall \mathbf{x} \in X$:

$$\sum_{i=1}^{|S|} \mathbf{c}_i \cdot E_i(\mathbf{x}^{uo}) \geq \sum_{i=1}^{|S|} \mathbf{c}_i \cdot E_i(\mathbf{x})$$

The Model

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Selections $S = \{s_1, \dots, s_{|S|}\}$ (deterministic outcomes)

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Expected Utilities $E_i : X \rightarrow \mathbb{R}_{\geq 0} \quad \forall i \in N$

$$E_i(\mathbf{x}) = \sum_{j=1}^{|S|} x_j \cdot u_i(s_j)$$

Leximin Opt.

A solution $\mathbf{x}^* \in X$ s.t. $\forall \mathbf{x} \in X$:

$$(E_1(\mathbf{x}^*), \dots, E_n(\mathbf{x}^*)) \succcurlyeq (E_1(\mathbf{x}), \dots, E_n(\mathbf{x}))$$

\mathbf{v}^\uparrow

\mathbf{v} sorted in weakly-increasing order

Leximin order
 $\mathbf{v} \succcurlyeq \mathbf{u}$

if (1) $\mathbf{v}^\uparrow = \mathbf{u}^\uparrow$

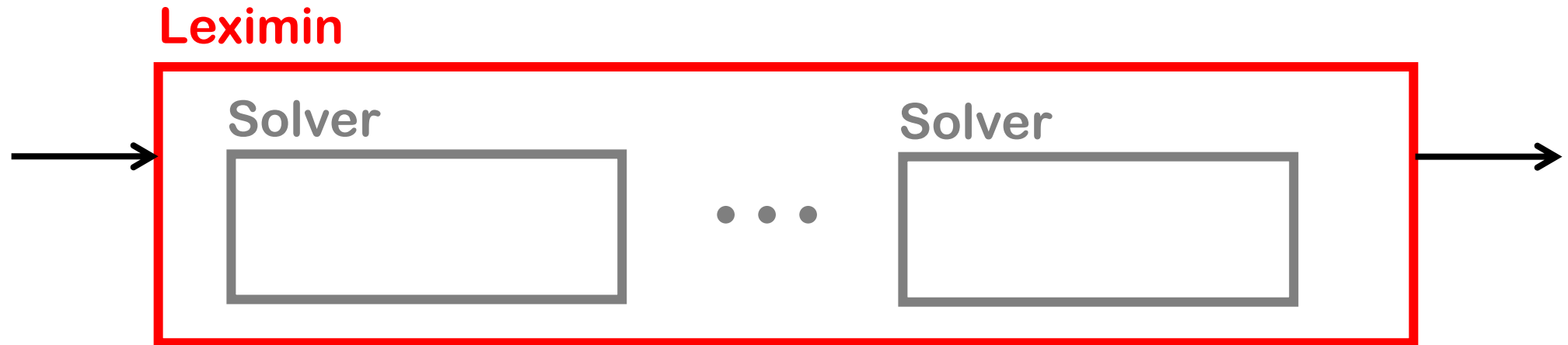
or (2) $\exists 1 \leq k \leq n$ s.t

$$(2.1) \quad v_i^\uparrow = u_i^\uparrow \quad \text{for } i < k$$

$$(2.2) \quad v_k^\uparrow > u_k^\uparrow$$

Leximin Optimization

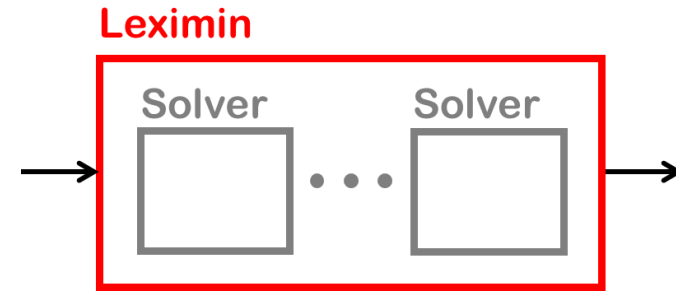
- Leximin is a multi-objective problem.
- Algorithms are usually:
 - Iterative, solve one program in each iteration



- Each iteration uses the opt. values from previous iterations as constants.

Leximin Optimization

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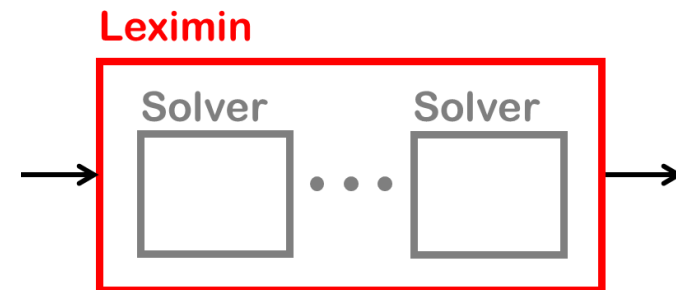
Leximin Optimization

- Leximin is a multi-objective problem.
- Algorithms are usually:
 - Iterative, solve one program in each iteration
 - When $t = 1$, solve egalitarian:

$$\begin{array}{ll} \max & E_1^\uparrow(x) \\ \text{s.t.} & x \in X \end{array}$$

$$E_i^\uparrow(x)$$

The i -th smallest
expected-utility obtained by x

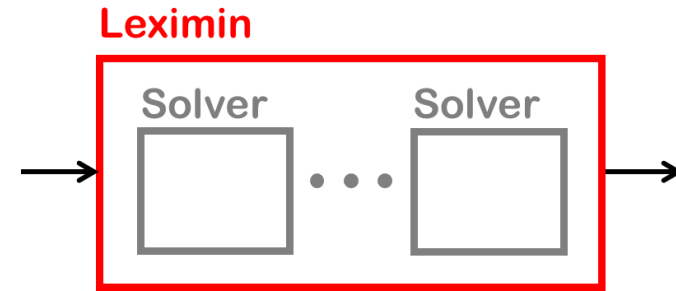


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Leximin Optimization

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- Algorithms are usually:
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 - When $t = 1$, solve egalitarian:

$$\begin{aligned} \max \quad & z \\ \text{s.t.} \quad & (1) \ x \in X \\ & (2) \ E_i(x) \geq z \quad \forall i = 1, \dots, n \end{aligned}$$



- Each iteration uses the opt. values from previous iteration as constants.

The Ordered Outcomes Algorithm

(Ogryczak & Sliwinski, 2006)

- For $t = 1, \dots, n$:

- Solve:

$$\begin{aligned} \max \quad & \sum_{i=1}^t E_i^\uparrow(\mathbf{x}) - \sum_{i=1}^{t-1} z_i & (P1) \\ \text{s.t.} \quad & (P1.1) \sum_{j=1}^{|S|} x_j = 1 \\ & (P1.2) x_j \geq 0 & j = 1, \dots, |S| \\ & (P1.3) \sum_{i=1}^{\ell} E_i^\uparrow(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i & \forall \ell \in [t-1] \end{aligned}$$

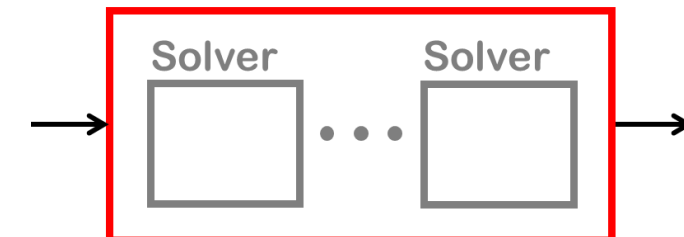
$E_i^\uparrow(\mathbf{x})$

The i -th smallest
expected-utility at solution \mathbf{x}

- Let \mathbf{x}^t be the solution, and z^t be its objective value.

- Return \mathbf{x}^n

Leximin



The Ordered Outcomes Algorithm

- For $t = 1, \dots, n$:

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- Let x^t be the solution, and z^t be its objective value.

- Return x^n

Theorem (Ogryczak & Sliwinski):

Given an exact solver for P1,
the alg. output is leximin-optimal.

In some situations,
solving P1 exactly is NP-hard
(even for $t = 1$)

E.g., stochastic allocation
of indivisible goods among agents
with submodular utilities

Theorem (Kawase & Sumita 2020):
Optimal Egalitarian is NP-hard.

➤ On Direct Methods for Lexicographic Min-Max Optimization. Ogryczak and Sliwinski, 2006.

➤ On the Max-Min Fair Stochastic Allocation of Indivisible Goods. Kawase and Sumita, 2020.

The Ordered Outcomes Algorithm

- For $t = 1, \dots, n$:

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$$\max \quad \sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \quad (\text{P1})$$

$$s.t. \quad (\text{P1.1}) \quad \sum_{j=1}^{|S|} x_j = 1$$

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Approximations?

The Ordered Outcomes Algorithm

- For $t = 1, \dots, n$:

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- Let x^t be the solution, and z^t be its objective value.

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Solving P1 Approximately

For $t = 1$:

The alg. of Kawase & Sumita is an approximate solver for (P1).



For $t > 1$:

Their technique no longer works (due to subtraction in objective)



The Ordered Outcomes Algorithm

- For $t = 1, \dots, n$:

- Solve:

$$\max \quad \sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \quad (\text{P1})$$

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- Let x^t be the solution, and z^t be its objective value.

- Return x^n

What we do:

Define a new type of solver for P1
(even weaker than the approx. one)

- A shallow solver -

Provide a shallow solver for P1
that requires only
a black-box for utilitarian.

Prove:

Given a shallow solver for P1,
the alg. output is leximin-approx.

Leximin Approximation

Leximin Optimal

A solution $\mathbf{x}^* \in X$ s.t $\forall \mathbf{x} \in X :$
 $(E_1(\mathbf{x}^*), \dots, E_n(\mathbf{x}^*)) \succcurlyeq (E_1(\mathbf{x}), \dots, E_n(\mathbf{x}))$

Since leximin has multiple objectives,
defining leximin-approximation is not a trivial task.¹

In this work we use the following definition:

Leximin Approx

$$0 < \alpha \leq 1$$

A solution $\mathbf{x}^A \in X$ s.t $\forall \mathbf{x} \in X :$
 $(E_1(\mathbf{x}^A), \dots, E_n(\mathbf{x}^A)) \succcurlyeq \alpha \cdot (E_1(\mathbf{x}), \dots, E_n(\mathbf{x}))$

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Prove:

Given a shallow solver for P1,

The alg. output is **leximin-approx**

1. Leximin Approximation: From Single-Objective to Multi-Objective. Hartman, Hassidim, Aumann, and Segal-HaLevi, ECAI 2023.

The Ordered Outcomes Algorithm

- For $t = 1, \dots, n$:

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$$\max \quad \sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \quad (\text{P1})$$

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- Let x^t be the solution, and z^t be its objective value.

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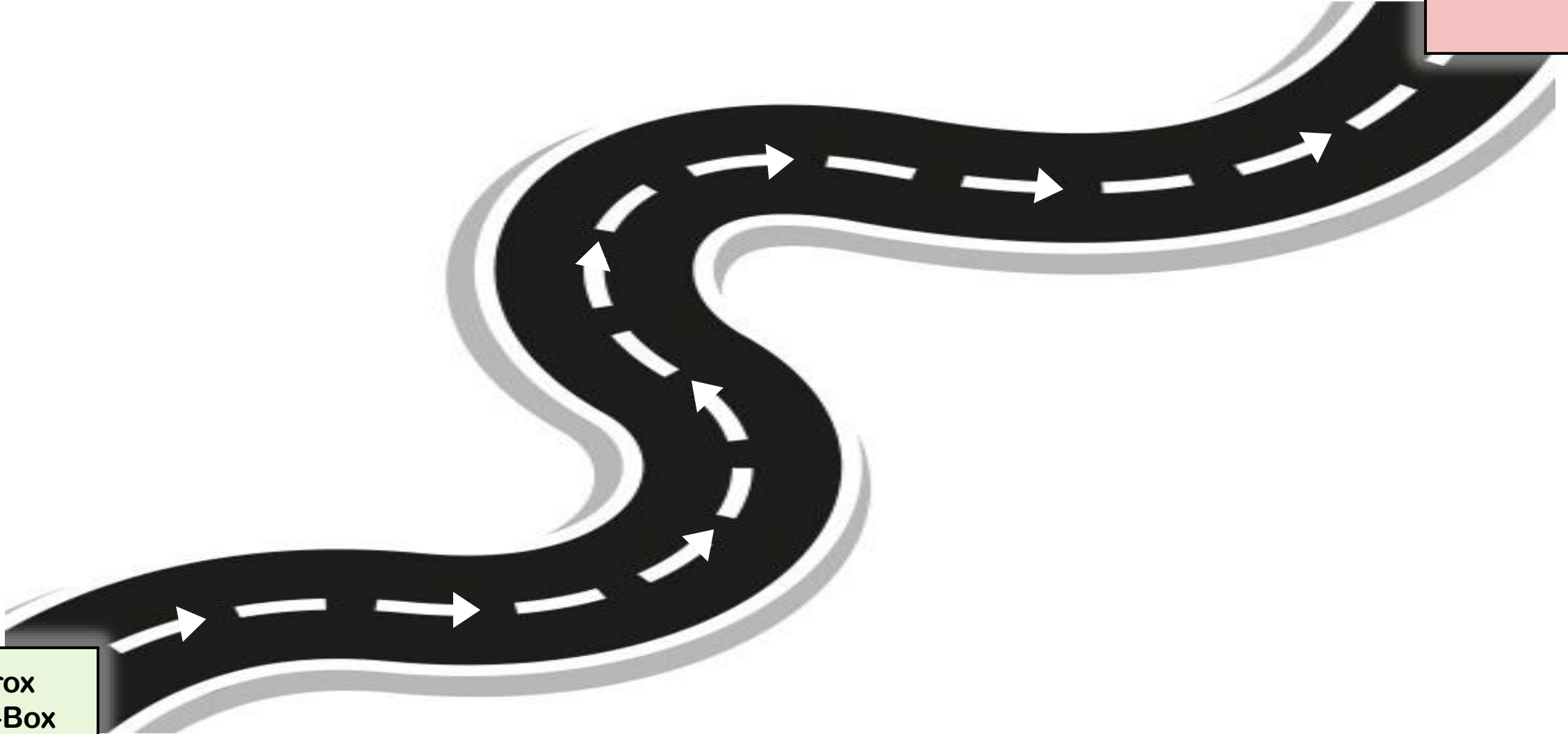
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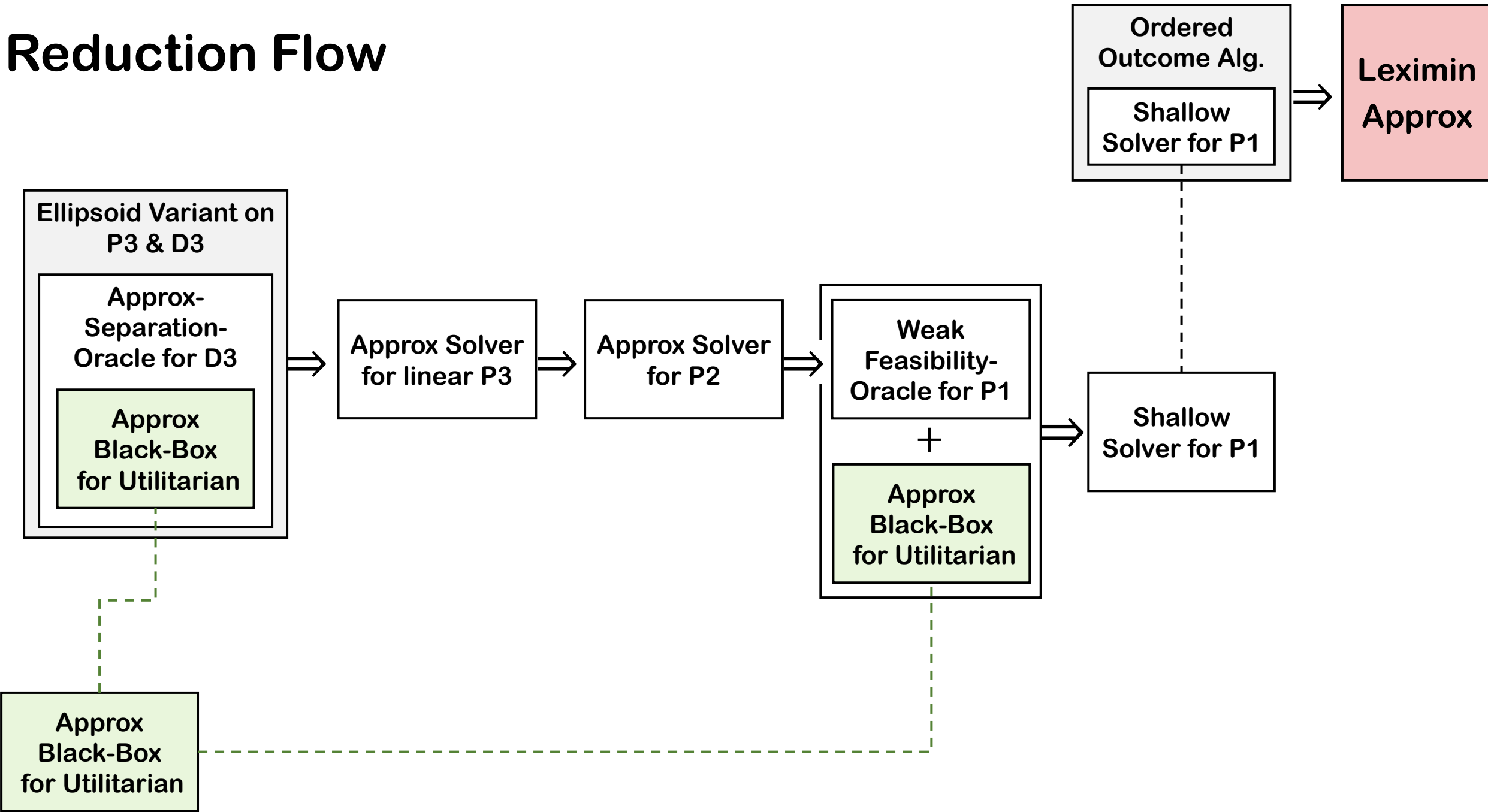
Reduction Flow

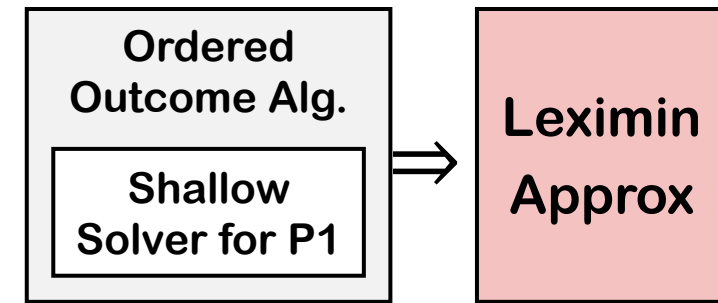
Leximin
Approx

Approx
Black-Box
for Utilitarian



Reduction Flow





Lemma 5.2 in paper

Given an α -shallow-solver for P1,

the output of Ordered Outcomes Alg. is α -leximin-approx.

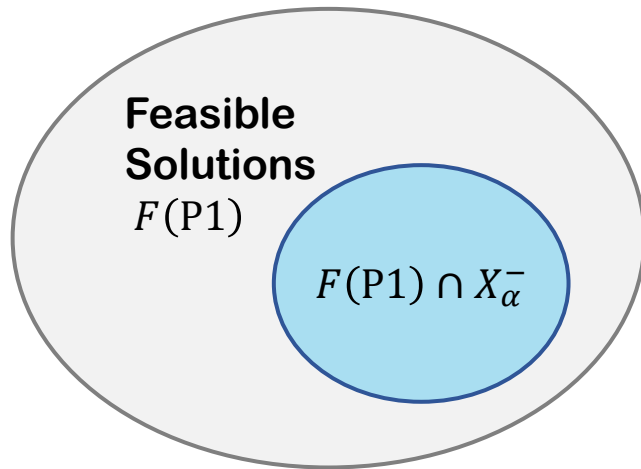
An α -Shallow Solver: Definition

Solver	returns $x^t \in F(P1)$ (<u>feasible</u> for P1)
---------------	---

Exact	$\text{obj}(x^t) \geq \text{obj}(x)$ for any $x \in F(P1)$
--------------	--

α-Shallow	$\text{obj}(x^t) \geq \text{obj}(x)$ for any $x \in F(P1) \cap X_\alpha^-$
------------------------------------	--

↓
solutions using $\leq \alpha$ probability¹



¹ We assume there is a dummy selection that gives all agents utility 0.

An α -Shallow Solver: Definition

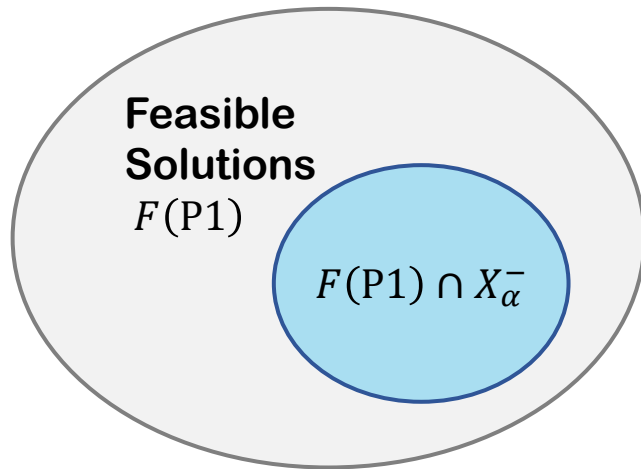
Solver	returns $x^t \in F(P1)$ (<u>feasible</u> for P1)
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Exact	$\text{obj}(x^t) \geq \text{obj}(x)$ for any $x \in F(P1)$
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α -Shallow	$\text{obj}(x^t) \geq \text{obj}(x)$ for any $x \in F(P1) \cap X_\alpha^-$
-------------------	--



$\alpha = 0.9$ solutions using ≤ 0.9 probability¹
(instead of 1)



¹ We assume there is a dummy selection that gives all agents utility 0, $s_d \in S$.

An α -Shallow Solver for P1

Lemma 6.1

(a) Approx. black-box for utilitarian

(b) An arbitrary $x_{init} \in F(P1)$

(c) Weak Feasibility-Oracle for P1

\Rightarrow A shallow-solver for P1



An α -Shallow Solver for P1

Lemma 6.1

(a) Approx. black-box for utilitarian

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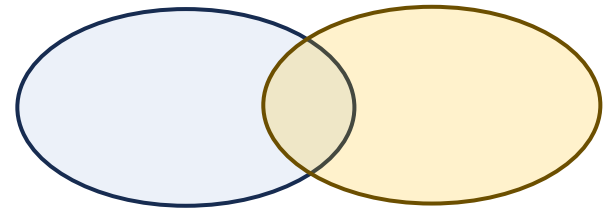
(c) Weak Feasibility-Oracle for P1



Weak Feasibility-Oracle for P1 (Definition)

Given a candidate objective value $z_t \in \mathbb{R}_{\geq 0}$, returns one of the following:

- z_t is a feasible objective-value:
 $\exists x \in F(P1)$ with objective value $\geq z_t$. In this case, returns such x .
- z_t is an infeasible objective-value for solutions using $\leq \alpha$ probability
 $\nexists x \in F(P1) \cap X_{\alpha}^{-}$ with objective value $\geq z_t$.



Weak = not mutually exclusive

An α -Shallow Solver for P1

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Weak Feasibility-Oracle for P1

Given $z_t \in \mathbb{R}_{\geq 0}$ returns one of:

- Feasible objective
- Infeasible objective for sol. using $\leq \alpha$ prob.

An α -Shallow Solver for P1

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Approx
Black-Box
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+

Weak Feasibility-
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\Rightarrow

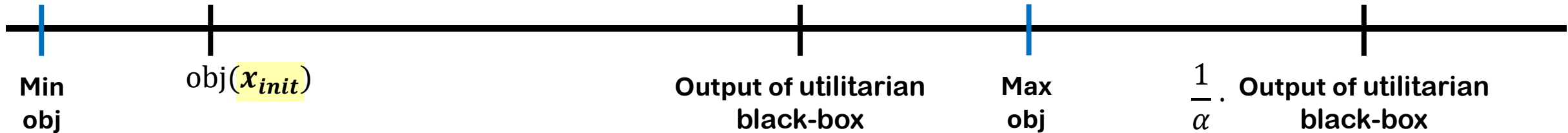
Shallow
Solver
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Weak Feasibility-Oracle for P1

Given $z_t \in \mathbb{R}_{\geq 0}$ returns one of:

- Feasible objective
- Infeasible objective for sol. using $\leq \alpha$ prob.

1. Bound the maximum objective value



An α -Shallow Solver for P1

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Approx
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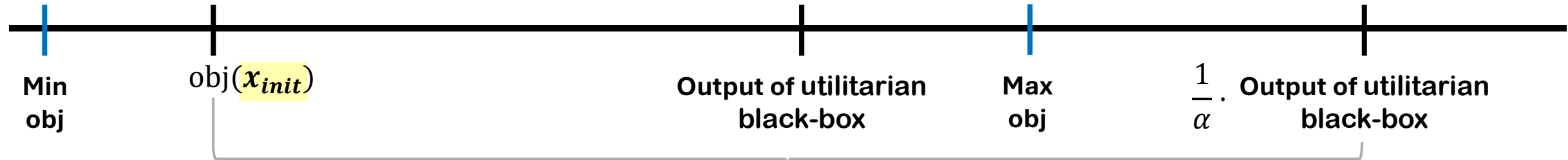
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Weak Feasibility-Oracle for P1

Given $z_t \in \mathbb{R}_{\geq 0}$ returns one of:

- Feasible objective
- Infeasible objective for sol. using $\leq \alpha$ prob.

1. Bound the maximum objective value



2. Perform a binary search

An α -Shallow Solver for P1

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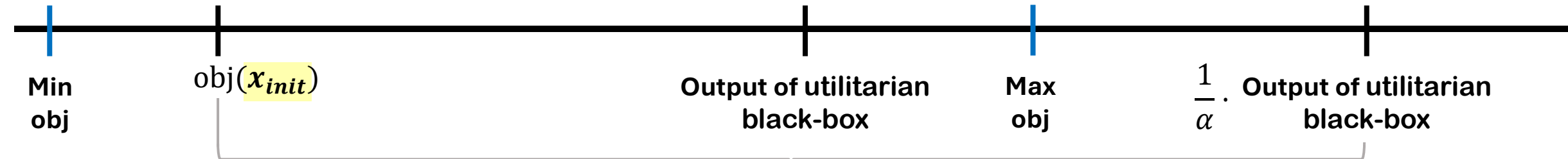
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Given $z_t \in \mathbb{R}_{\geq 0}$ returns one of:

- Feasible objective
- Infeasible objective for sol. using $\leq \alpha$ prob.

1. Bound the maximum objective value



2. Perform a binary search

For each z_t , use the Weak Feasibility-Oracle:

- If 'Feasible' go right (higher values)
- otherwise go left (lower values)

An α -Shallow Solver for P1

Lemma 6.1

(a) Approx. black-box for utilitarian

(b) An arbitrary $x_{init} \in F(P1)$ \Rightarrow A shallow-solver for P1

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Weak Feasibility-
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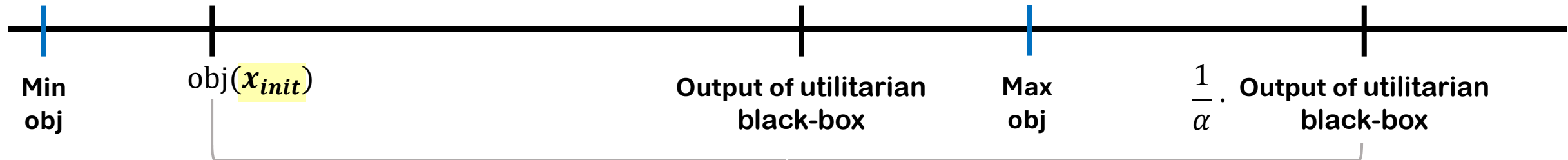
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Weak Feasibility-Oracle for P1

Given $z_t \in \mathbb{R}_{\geq 0}$ returns one of:

- Feasible objective
- Infeasible objective for sol. using $\leq \alpha$ prob.

1. Bound the maximum objective value



2. Perform a binary search

For each z_t , use the Weak Feasibility-Oracle:

- If 'Feasible' go right (higher values)
- otherwise go left (lower values)

3. Return the largest value for which the answer is 'Feasible'.

\rightarrow It is maximum w.r.t. all solutions that use $\leq \alpha$ probability.

An α -Weak Feasibility-Oracle for P1

Approx
Opt-Solver
for P2

Weak Feasibility-
Oracle for P1

Lemma 7.1

$\frac{1}{\alpha}$ -Approx-Optimal Solver for P2

\Rightarrow

α -Weak Feasibility-Oracle for P1

P2 is derived from P1 and a candidate objective-value z_t :

$$\begin{aligned} \max \quad & \sum_{i=1}^t E_i^\uparrow(\mathbf{x}) - \sum_{i=1}^{t-1} z_i & (\text{P1}) \\ \text{s.t.} \quad & (\text{P1.1}) \quad \sum_{j=1}^{|S|} x_j = 1 \\ & (\text{P1.2}) \quad x_j \geq 0 & j = 1, \dots, |S| \\ & (\text{P1.3}) \quad \sum_{i=1}^{\ell} E_i^\uparrow(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i \quad \forall \ell \in [t-1] \end{aligned}$$

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1. Remove the objective function

$$\begin{aligned} \max \quad & \sum_{i=1}^t E_i^\uparrow(\mathbf{x}) - \sum_{i=1}^{t-1} z_i & (P1) \\ s.t. \quad & (P1.1) \quad \sum_{j=1}^{|S|} x_j = 1 \\ & (P1.2) \quad x_j \geq 0 & j = 1, \dots, |S| \\ & (P1.3) \quad \sum_{i=1}^{\ell} E_i^\uparrow(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i \quad \forall \ell \in [t-1] \end{aligned}$$

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α -Weak Feasibility-Oracle for P1

P2 is derived from P1 and a candidate objective-value z_t :

1. Remove the objective function
2. Add a constraint to ensure that the objective $\geq z_t$

$$\max \sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \quad (\text{P1})$$

$$s.t. \quad (\text{P1.1}) \quad \sum_{j=1}^{|S|} x_j = 1$$

$$(\text{P1.2}) \quad x_j \geq 0 \quad j = 1, \dots, |S|$$

$$(\text{P1.3}) \quad \sum_{i=1}^{\ell} E_i^{\uparrow}(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i \quad \forall \ell \in [t-1]$$

$$\sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \geq z_t$$

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\Rightarrow

α -Weak Feasibility-Oracle for P1

P2 is derived from P1 and a candidate objective-value z_t :

1. Remove the objective function
2. Add a constraint to ensure that the objective $\geq z_t$
3. Remove Constraint (P1.1)

$$\max \sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \quad (\text{P1})$$

$$s.t. \quad (\text{P1.1}) \quad \sum_{j=1}^{|S|} x_j = 1$$

$$(\text{P1.2}) \quad x_j \geq 0 \quad j = 1, \dots, |S|$$

$$(\text{P1.3}) \quad \sum_{i=1}^{\ell} E_i^{\uparrow}(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i \quad \forall \ell \in [t-1]$$

$$\sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \geq z_t$$

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Weak Feasibility-
Oracle for P1

Lemma 7.1

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\Rightarrow

α -Weak Feasibility-Oracle for P1

P2 is derived from P1 and a candidate objective-value z_t :

1. Remove the objective function
2. Add a constraint to ensure that the objective $\geq z_t$
3. Remove Constraint (P1.1)
4. Add new obj: minimize the sum of probabilities

$$\min \sum_{j=1}^{|S|} x_j \quad (\text{P1})$$

$$s.t. \quad \text{(P1.1)} \quad \sum_{j=1}^{|S|} x_j = 1$$

$$\text{(P1.2)} \quad x_j \geq 0 \quad j = 1, \dots, |S|$$

$$\text{(P1.3)} \quad \sum_{i=1}^{\ell} E_i^{\uparrow}(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i \quad \forall \ell \in [t-1]$$

$$\sum_{i=1}^t E_i^{\uparrow}(\mathbf{x}) - \sum_{i=1}^{t-1} z_i \geq z_t$$

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\Rightarrow

α -Weak Feasibility-Oracle for P1

P2 is derived from P1 and a candidate objective-value z_t :

1. Remove the objective function
2. Add a constraint to ensure that the objective $\geq z_t$
3. Remove Constraint (P1.1)
4. Add new obj: min the sum over x_j

$$\begin{aligned} \min \quad & \sum_{j=1}^{|S|} x_j \quad s.t. & (P2) \\ (P2.1) \quad & x_j \geq 0 & j = 1, \dots, |S| \\ (P2.2) \quad & \sum_{i=1}^{\ell} E_i^{\uparrow}(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i & \forall \ell \in [t] \end{aligned}$$

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α -Weak Feasibility-Oracle for P1

Given $\frac{1}{\alpha}$ -Approx. solution to P2, x^A :

- If its objective value ≤ 1 :

Assert that z_t is feasible, return x^A .

- Otherwise:

Assert that z_t is infeasible
for solutions using $\leq \alpha$ probability.

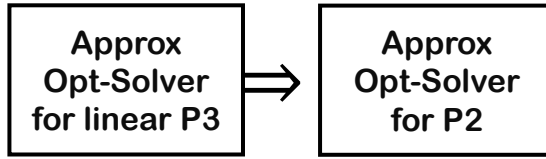
$$\begin{aligned} \min \quad & \sum_{j=1}^{|S|} x_j \quad s.t. \quad (P2) \\ (P2.1) \quad & x_j \geq 0 \quad j = 1, \dots, |S| \\ (P2.2) \quad & \sum_{i=1}^{\ell} E_i^{\uparrow}(\mathbf{x}) \geq \sum_{i=1}^{\ell} z_i \quad \forall \ell \in [t] \end{aligned}$$

Weak Feasibility-Oracle for P1

Given $z_t \in \mathbb{R}_{\geq 0}$ returns one of:

- Feasible objective
- Infeasible objective for sol. using $\leq \alpha$ prob.

An $\frac{1}{\alpha}$ -Approx-Optimal Solver for P2



Lemma 8.1

$\frac{1}{\alpha}$ -Approx-Optimal Solver for linear P3

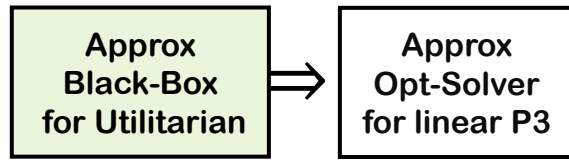
\Rightarrow

$\frac{1}{\alpha}$ -Approx-Optimal Solver for P2

$$\begin{aligned} \min \quad & \sum_{j=1}^{|S|} x_j \quad s.t. \quad (P3) \\ (P3.1) \quad & x_j \geq 0 \quad j = 1, \dots, |S| \\ (P3.2) \quad & \ell y_\ell - \sum_{i=1}^n m_{\ell,i} \geq \sum_{i=1}^{\ell} z_i \quad \forall \ell \in [t] \\ (P3.3) \quad & m_{\ell,i} \geq y_\ell - \sum_{j=1}^{|S|} x_j \cdot u_i(s_j) \quad \forall \ell \in [t], \forall i \in [n] \\ (P3.4) \quad & m_{\ell,i} \geq 0 \quad \forall \ell \in [t], \forall i \in [n] \end{aligned}$$

- A Linear Program which is Equivalent to P2:
 - x^A is a solution for P2 \Leftrightarrow it is part of a solution for P3
 - Auxiliary variables are used to “linearize” the constraints
 - (technique based on Ogryczak and Sliwinski)
- P3 Cannot be solved directly: exp. number of variables.

An $\frac{1}{\alpha}$ -Approx-Optimal Solver for P3



Corollary 9.1 + Lemma 10.1

α -Black-box for Utilitarian

\Rightarrow

$\frac{1}{\alpha}$ -Approx-Optimal Solver for P3

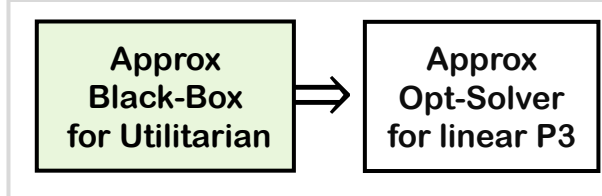
$$\begin{aligned}
 & \min \sum_{j=1}^{|S|} x_j \quad s.t. & (P3) \\
 (P3.1) \quad & x_j \geq 0 & j = 1, \dots, |S| \\
 (P3.2) \quad & \ell y_\ell - \sum_{i=1}^n m_{\ell,i} \geq \sum_{i=1}^{\ell} z_i & \forall \ell \in [t] \\
 (P3.3) \quad & m_{\ell,i} \geq y_\ell - \sum_{j=1}^{|S|} x_j \cdot u_i(s_j) & \forall \ell \in [t], \forall i \in [n] \\
 (P3.4) \quad & m_{\ell,i} \geq 0 & \forall \ell \in [t], \forall i \in [n]
 \end{aligned}$$

Dual

$$\begin{aligned}
 & \max \sum_{\ell=1}^t q_\ell \sum_{i=1}^{\ell} z_i \quad s.t. & (D3) \\
 (D3.1) \quad & \sum_{i=1}^n u_i(s_j) \sum_{\ell=1}^t v_{\ell,i} \leq 1 & \forall j = 1, \dots, |S| \\
 (D3.2) \quad & \ell q_\ell - \sum_{i=1}^n v_{\ell,i} \leq 0 & \forall \ell \in [t] \\
 (D3.3) \quad & -q_\ell + v_{\ell,i} \leq 0 & \forall \ell \in [t], \forall i \in [n] \\
 (D3.4) \quad & q_\ell \geq 0 & \forall \ell \in [t] \\
 (D3.5) \quad & v_{\ell,i} \geq 0 & \forall \ell \in [t], \forall i \in [n]
 \end{aligned}$$

- We approximate P3 with its Dual Program and a variant of the ellipsoid method (for approx)
- The utilitarian solver is used inside the (approx) separation oracle for the Dual.

An $\frac{1}{\alpha}$ -Approx-Optimal Solver for P3



Corollary 9.1 + Lemma 10.1

α -Black-box for Utilitarian

\Rightarrow

$\frac{1}{\alpha}$ -Approx-Optimal Solver for P3

$$\begin{aligned}
 & \min \sum_{j=1}^{|S|} x_j \quad s.t. & (P3) \\
 & (P3.1) \quad x_j \geq 0 & j = 1, \dots, |S| \\
 & (P3.2) \quad \ell y_\ell - \sum_{i=1}^n m_{\ell,i} \geq \sum_{i=1}^{\ell} z_i & \forall \ell \in [t] \\
 & (P3.3) \quad m_{\ell,i} \geq y_\ell - \sum_{j=1}^{|S|} x_j \cdot u_i(s_j) & \forall \ell \in [t], \forall i \in [n] \\
 & (P3.4) \quad m_{\ell,i} \geq 0 & \forall \ell \in [t], \forall i \in [n]
 \end{aligned}$$

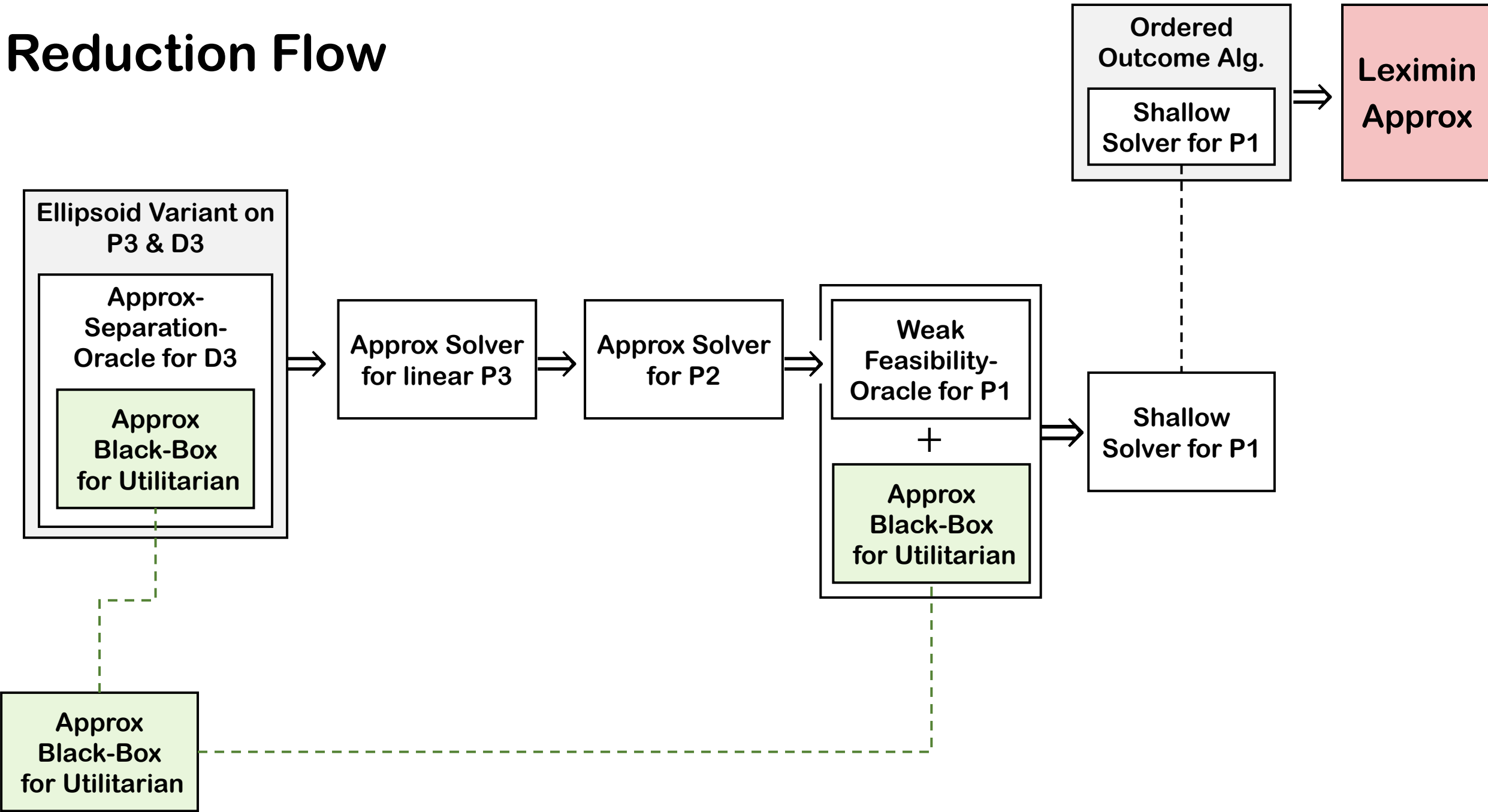
Dual

$$\begin{aligned}
 & \max \sum_{\ell=1}^t q_\ell \sum_{i=1}^{\ell} z_i \quad s.t. & (D3) \\
 & (D3.1) \quad \sum_{i=1}^n u_i(s_j) \sum_{\ell=1}^t v_{\ell,i} \leq 1 & \forall j = 1, \dots, |S| \\
 & (D3.2) \quad \ell q_\ell - \sum_{i=1}^n v_{\ell,i} \leq 0 & \forall \ell \in [t] \\
 & (D3.3) \quad -q_\ell + v_{\ell,i} \leq 0 & \forall \ell \in [t], \forall i \in [n] \\
 & (D3.4) \quad q_\ell \geq 0 & \forall \ell \in [t] \\
 & (D3.5) \quad v_{\ell,i} \geq 0 & \forall \ell \in [t], \forall i \in [n]
 \end{aligned}$$

c_i

- We approximate P3 with its Dual Program and a variant of the ellipsoid method (for approx)
- The utilitarian solver is used inside the (approx) separation oracle for the Dual.

Reduction Flow



Reduction Flow

Leximin
Approx

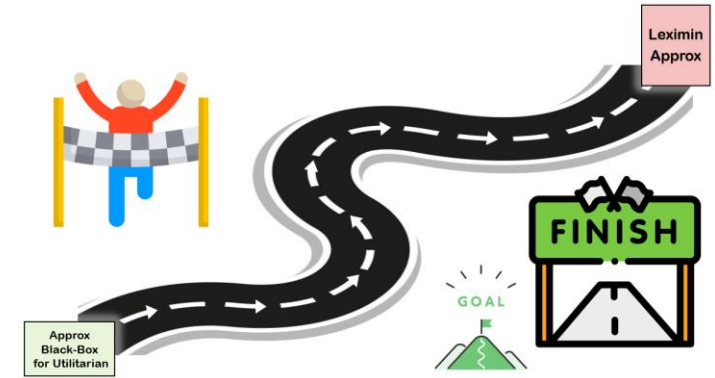


Approx
Black-Box
for Utilitarian



Open Questions

1. **Social choice problems with utilities ≤ 0**
(e.g. fair allocation of chores, facility location)
2. **Nash welfare objective** = Maximize the product of utilities.
 - Sweet-spot between utilitarian and egalitarian.
 - Often as hard as egalitarian.
 - Is there an analogous reduction for Nash welfare?
3. **Best of both worlds:** Can we guarantee any ex-post fairness?



Please contact us for any question and any answer!

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