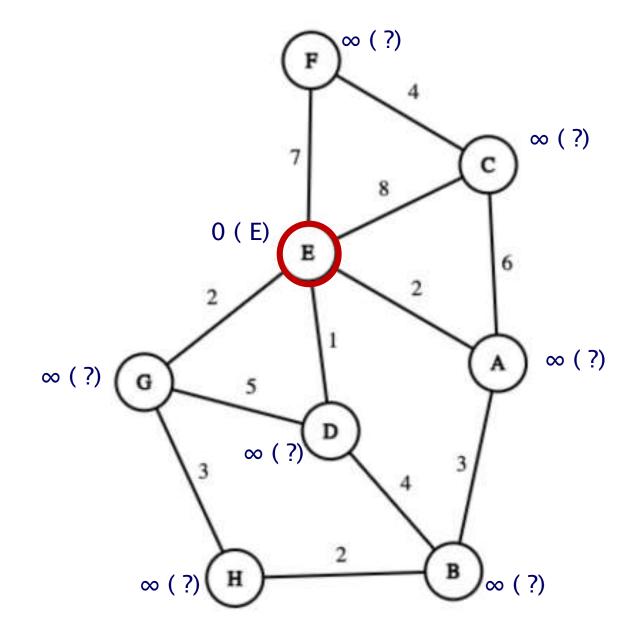
Initial condition is given below. We will start from vertex E.

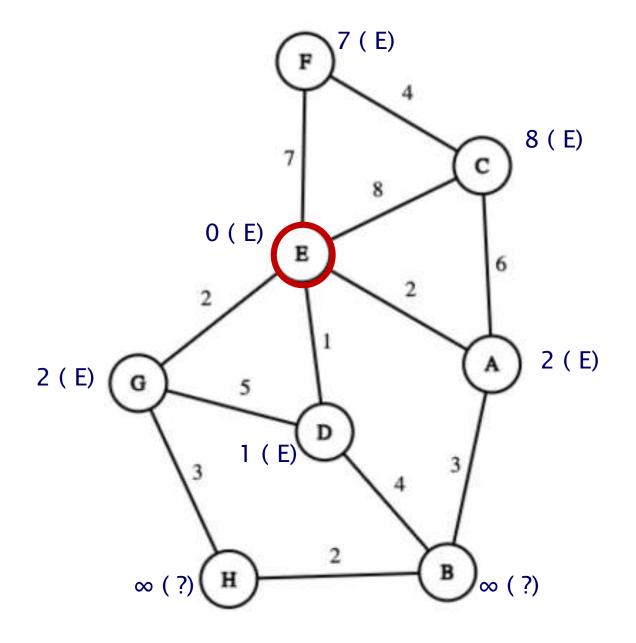
For vertex E;

- Shortest path is 0
- Last visited vertex is E (itself, since it is the starting vertex)
- E is marked as known.



Check the neighbouring vertexes of E. Update their shortest path accordingly.

Next smallest distance value belongs to vertex D among all unknown vertices. So, we move to D.



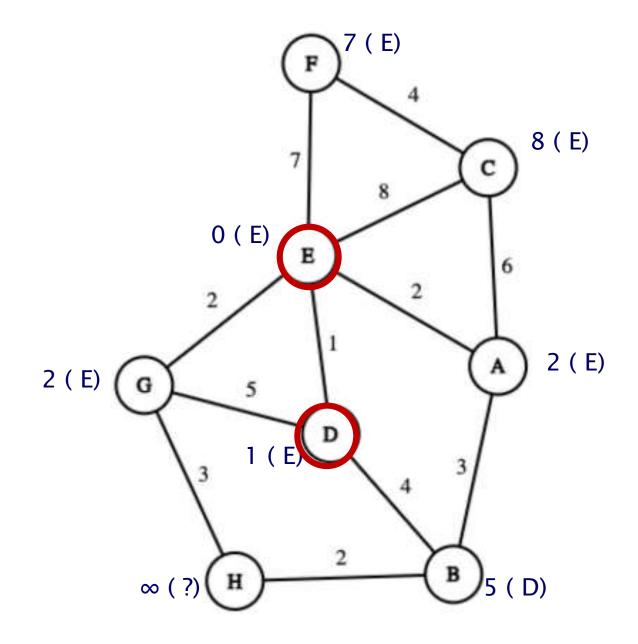
We are at D. D is marked as known. Check its neighbours, and update the shortest paths accordingly.

Shortest path to G is not changed since 2 < (1+5).

Shortest path to E is not changed since it is the initial vertex (dist=0).

B is updated since 5 < infinity. Last visited vertex through B has become D.

Next smallest distance value belongs to vertices G and A among all unknown vertices. Choose one. So, we move to A.

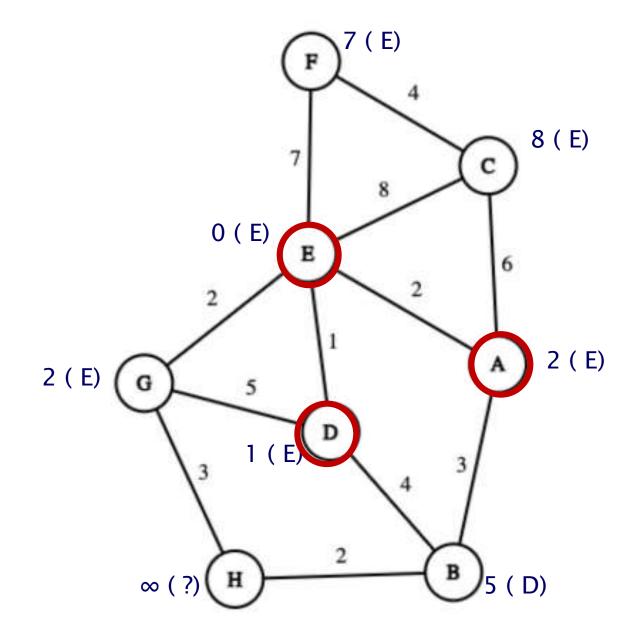


We are at A. A is marked as known. Check its neighbours, and update the shortest paths accordingly.

$$(2+6) = 8$$
 for C, so C is not updated.

$$(2+3) = 5$$
 for B, so B is not updated.

Next smallest distance value belongs to vertex G among all unknown vertices. So, we move to G.



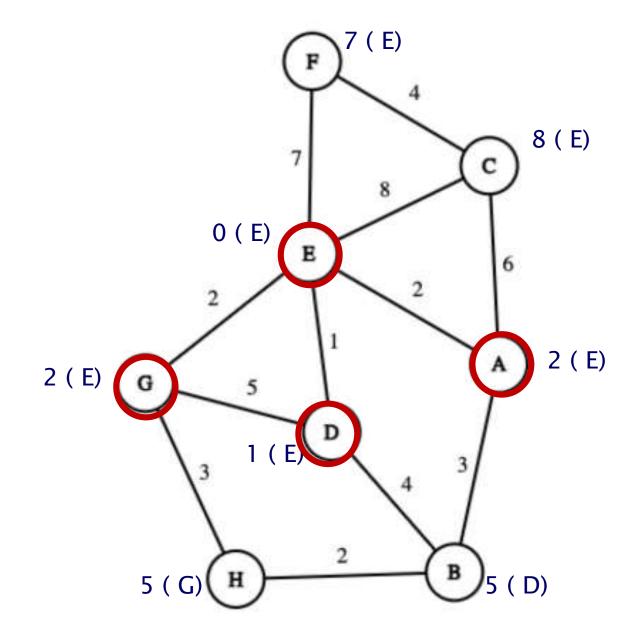
We are at G. G is marked as known. Check its neighbours, and update the shortest paths accordingly.

(2+3) < infinity, so we update H. Last visited vertex through H has become G.

Vertex D is known, skip.

Vertex E is known, skip.

Next smallest distance value belongs to vertices H and B among all unknown vertices. Choose one. So, we move to H.

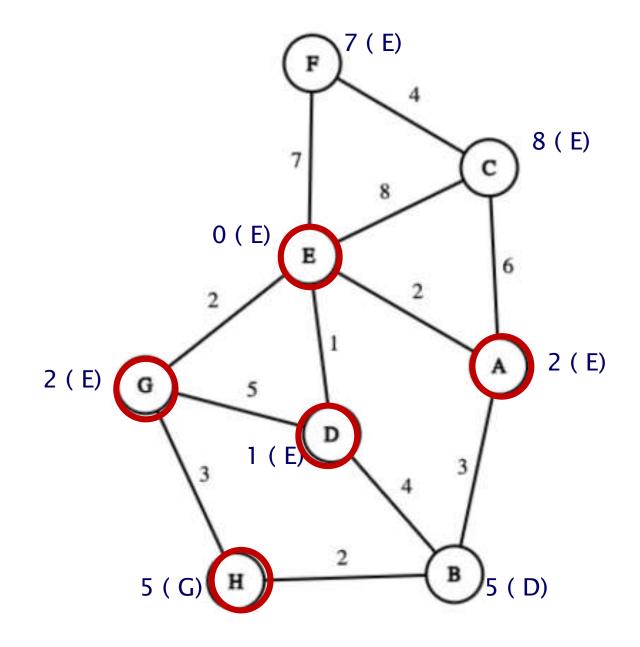


We are at H. H is marked as known. Check its neighbours, and update the shortest paths accordingly.

5 < (5+2), so we do not update B.

Vertex G is known, skip.

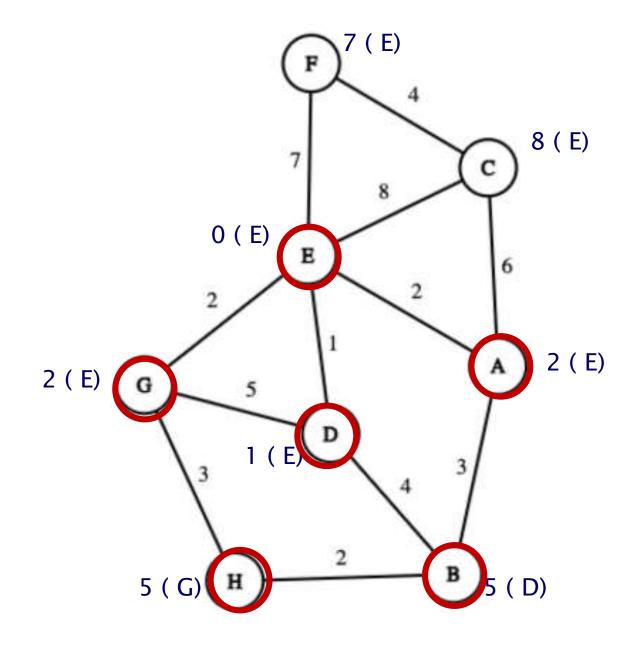
Next smallest distance value belongs to vertex B among all unknown vertices. So, we move to B.



We are at B. B is marked as known. Check its neighbours, and update the shortest paths accordingly.

All neighbours are known, skip.

Next smallest distance value belongs to vertex F among all unknown vertices. So, we move to F.

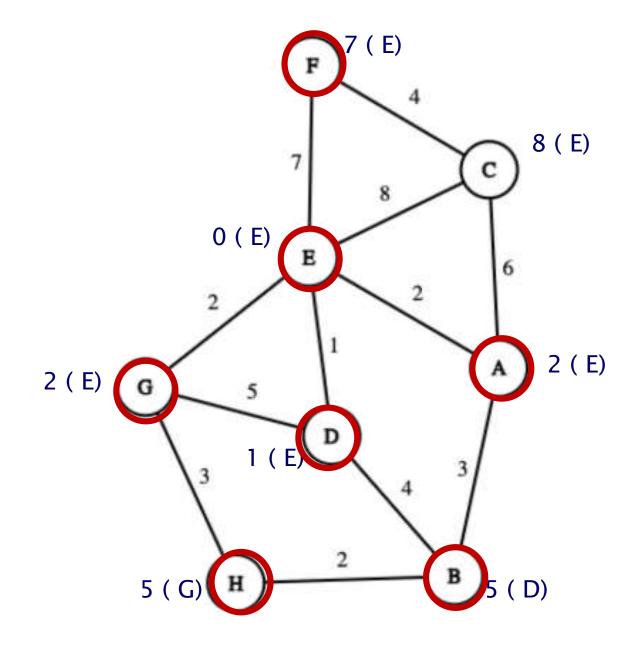


We are at F. F is marked as known. Check its neighbours, and update the shortest paths accordingly.

E is known, skip.

8 < (7+4), so we do not update C.

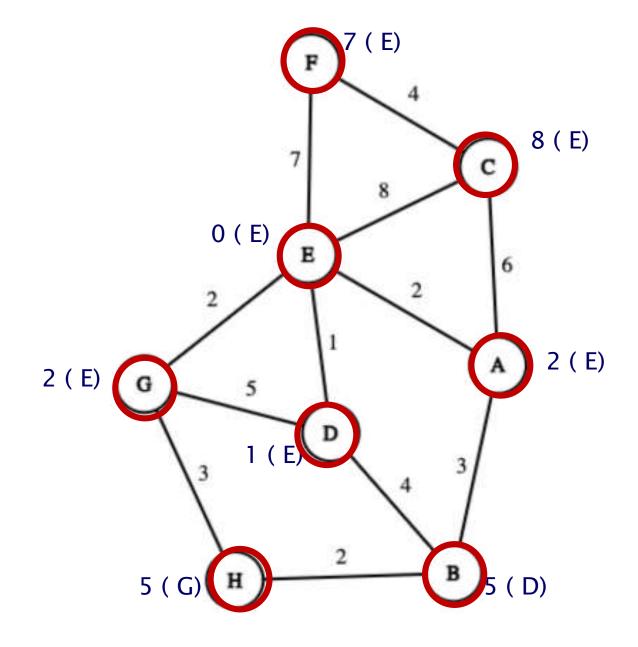
Next smallest distance value belongs to vertex C among all unknown vertices. So, we move to C.



We are at C. C is marked as known. Check its neighbours, and update the shortest paths accordingly.

All neighbours are known, skip.

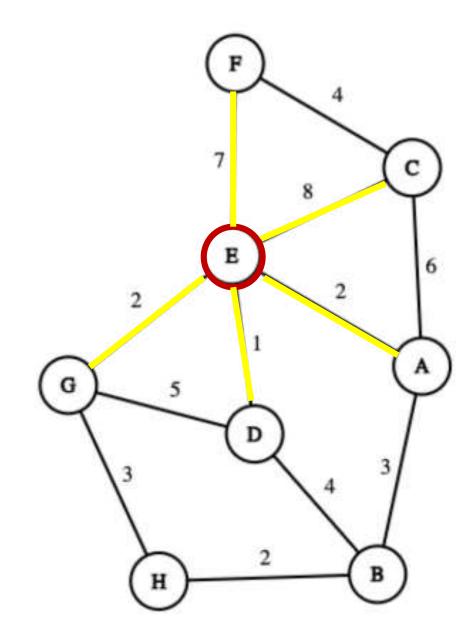
No unknown vertex left. Terminate.



We start with vertex E. E is added to the tree. So, we mark E as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

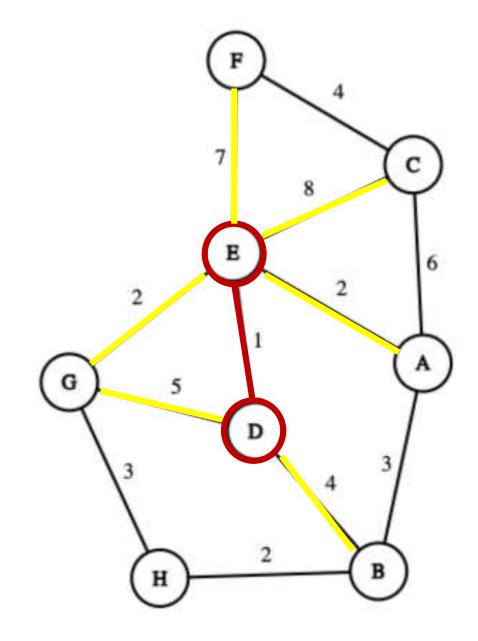
Smallest cost is the edge (E,D), so we move to D.



D is added to the tree. So, we mark D as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

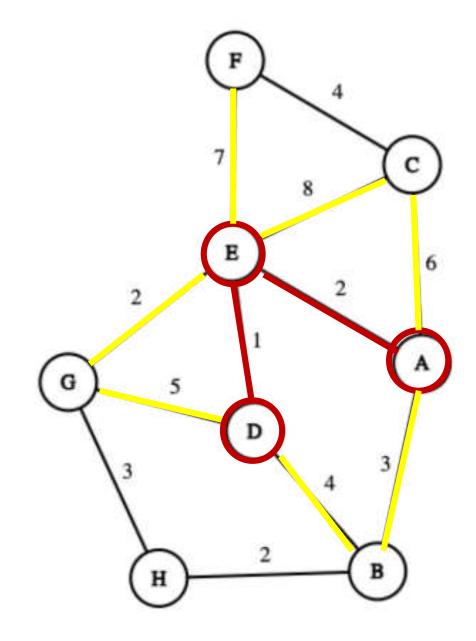
Smallest cost is the edges (E,G) and (E,A). Pick one. So we move to A.



A is added to the tree. So, we mark A as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

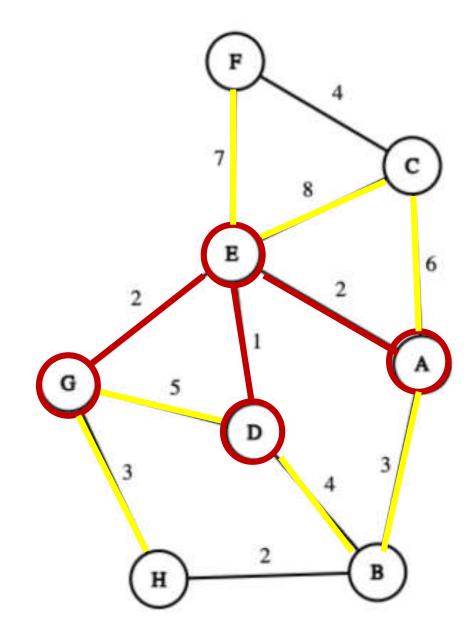
Smallest cost is the edge (E,G). So we move to G.



G is added to the tree. So, we mark G as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

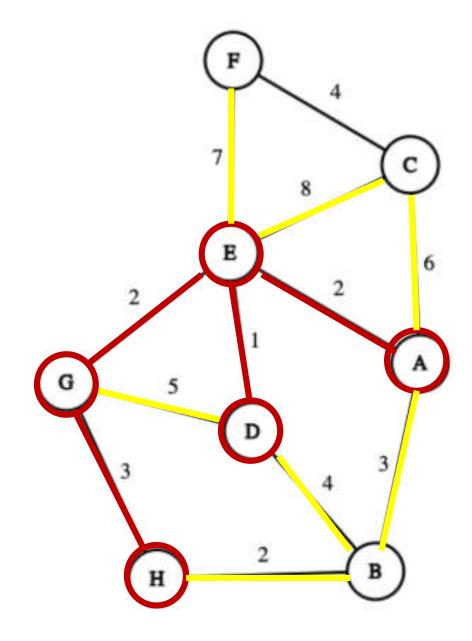
Smallest cost is the edges (A,B) and (G,H). Pick one. So we move to H.



H is added to the tree. So, we mark H as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

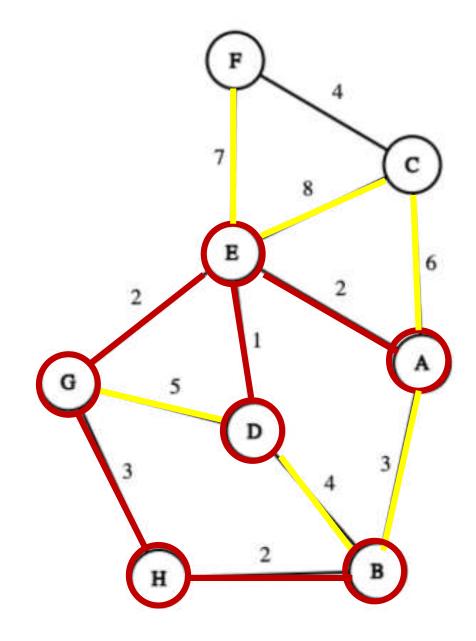
Smallest cost is the edge (H,B). So we move to B.



B is added to the tree. So, we mark B as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

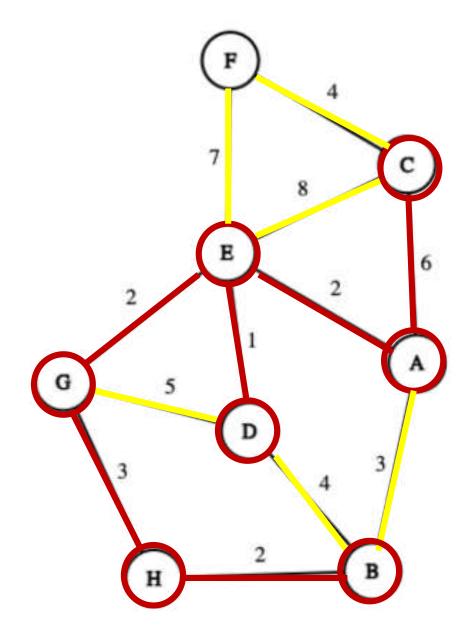
Smallest cost is the edge (A,C). So we move to C.



C is added to the tree. So, we mark C as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

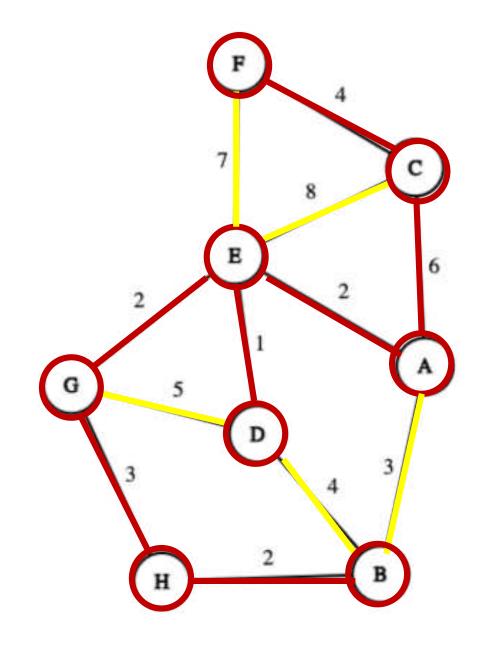
Smallest cost is the edge (C,F). So we move to F.



F is added to the tree. So, we mark F as known.

Check the edges (u,v) such that u is in the tree and v is not, and find which unknown vertex is the closest to the tree.

No more unknown vertices. The minimum spanning tree is shown with the red pathway. Terminate.



First, we sort the edges in ascending order with respect to their weights.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

A to B = 3

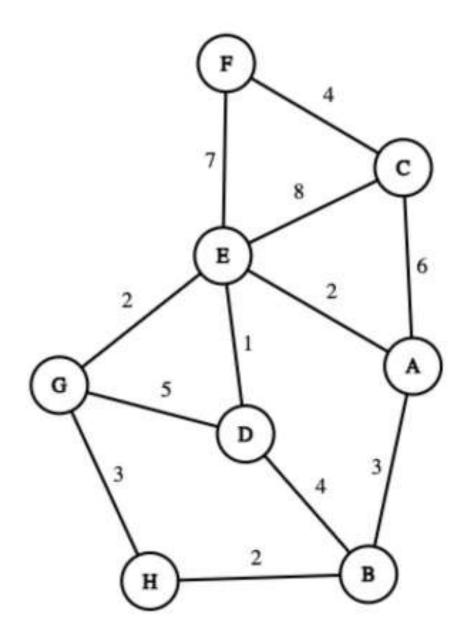
F to C = 4

G to D = 5

C to A = 6

E to F = 7

E to C = 8



Note that U to V = V to U since graph is undirected.

Start with the shortest edge. Union its vertices IF they are NOT already in the same tree.

E and D are connected.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

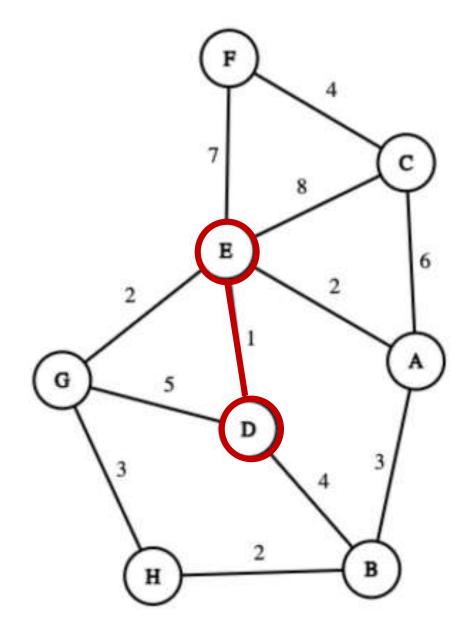
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

E and G are connected.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

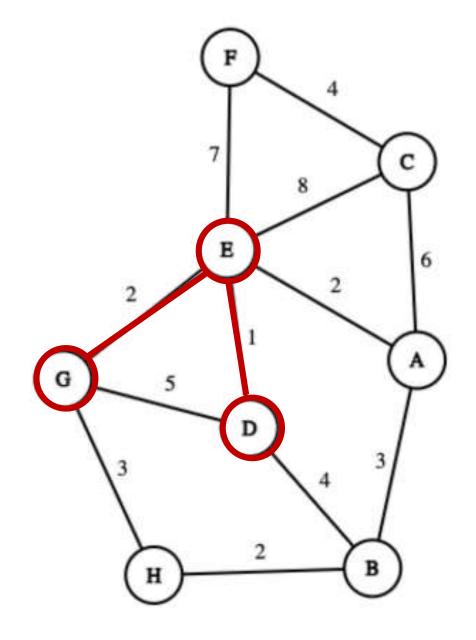
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

E and A are connected.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

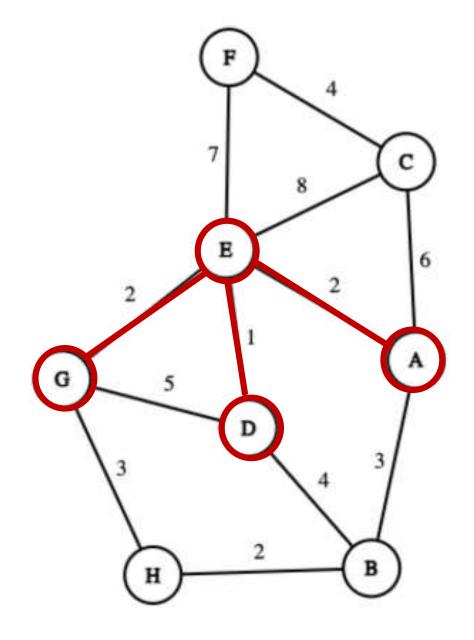
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

H and B are connected.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

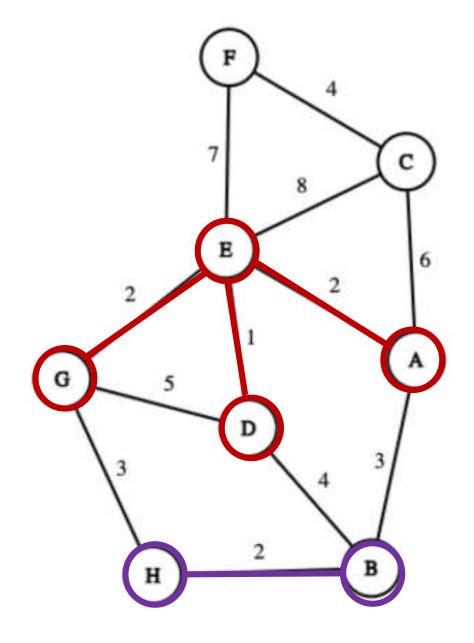
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

G and H belong to different trees although they are connected to somewhere. We union them by merging two trees.

G and H are connected. Two trees merge into one.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

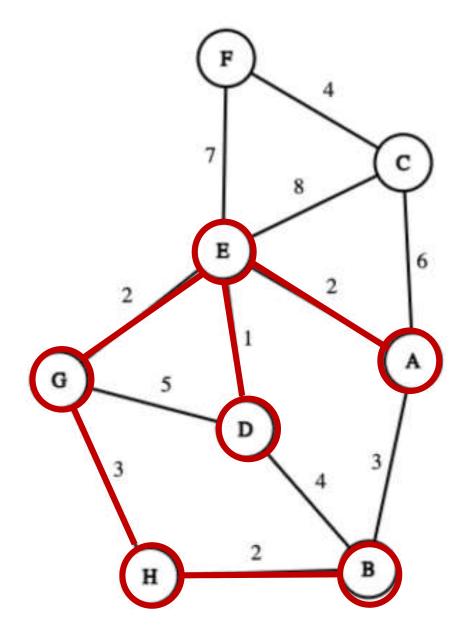
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

A and B are already in the same tree. Skip.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

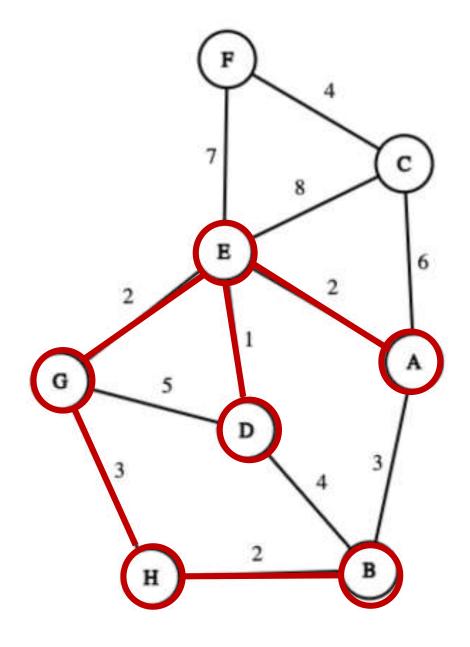
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

F and C are connected.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

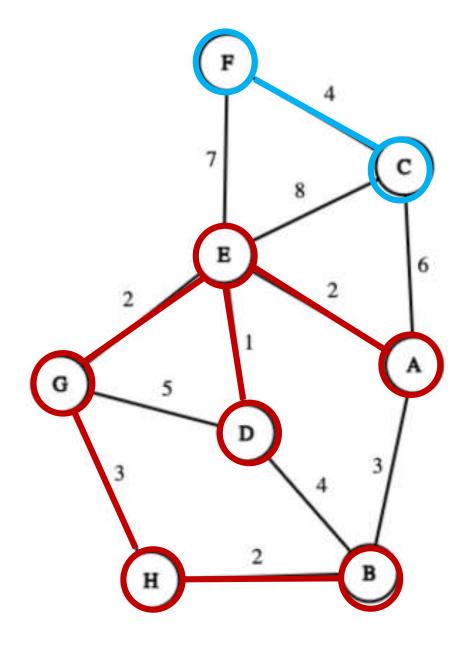
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

F and C are connected.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

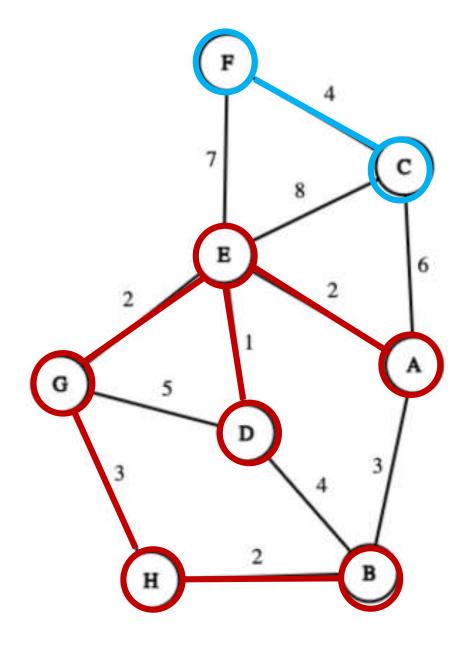
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

A and C belong to different trees although they are connected to somewhere. We union them by merging two trees.

A and C are connected. Two trees merge into one.

E to D = 1

E to G = 2

E to A = 2

H to B = 2

G to H = 3

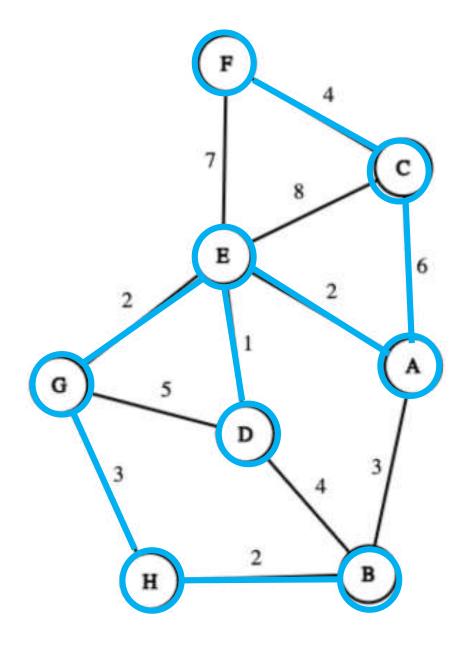
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

E and F are already in the same tree. Skip.

```
E to D = 1
```

E to G = 2

E to A = 2

H to B = 2

G to H = 3

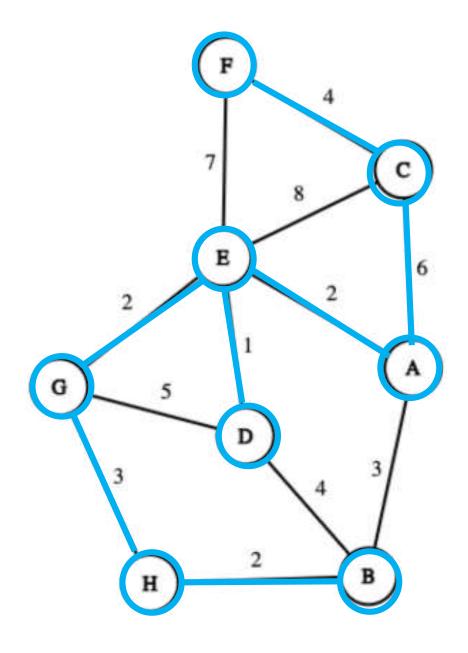
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7



Follow the next shortest edge. Union its vertices IF they are NOT already in the same tree.

E and C are already in the same tree. No unvisited edges left. Resulting minimum spaning tree is shown with blue. Terminate.

```
E to D = 1
```

E to G = 2

E to A = 2

H to B = 2

G to H = 3

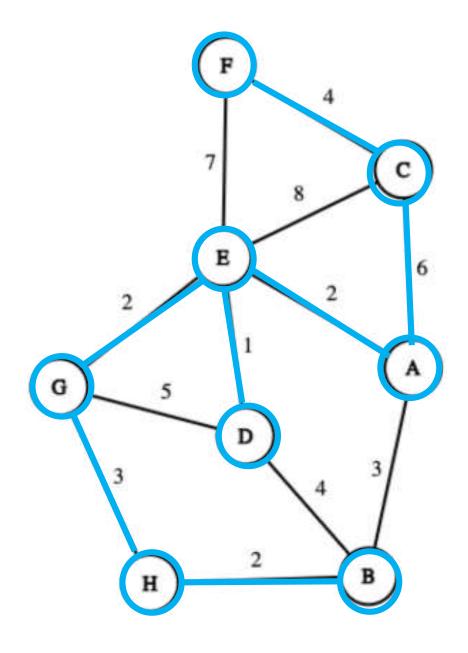
A to B = 3

F to C = 4

G to D = 5

C to A = 6

E to F = 7

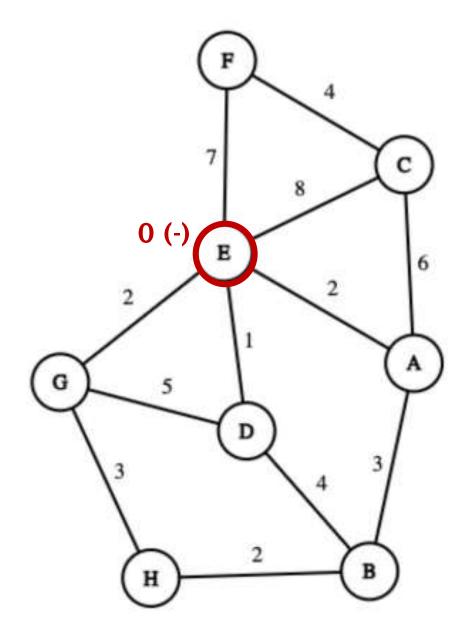


To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

We start with vertex E. Automatically, distance from E to E is 0. E is marked "known"

QUEUE:

empty



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

We enqueue the unknown vertices 1 away from E. So F, C, A, D, G are enqueued.

QUEUE:

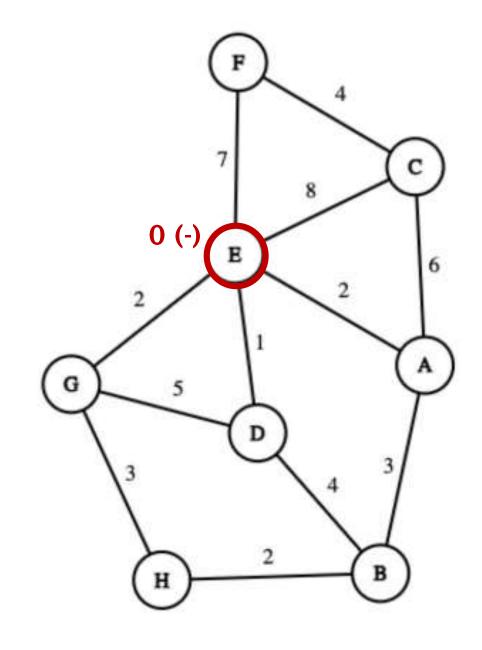
E to F, cost=7

E to C, cost=8

E to A, cost=2

E to D, cost=1

E to G, cost=2



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Go to F. F is known. Its cost and path are updated. Enqueue the unknown vertices 1 away from F. So, C is enqueued.

QUEUE:

E to F, cost=7

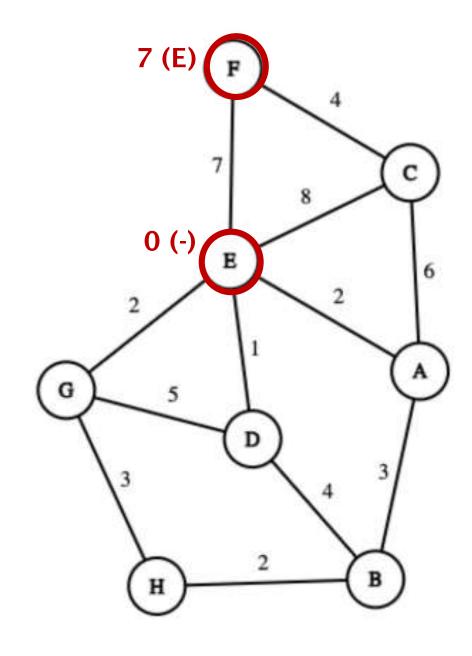
E to C, cost=8

E to A, cost=2

E to D, cost=1

E to G, cost=2

F to C, cost=7+4=11



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Go to C. C is known. Its cost and path are updated. Enqueue the unknown vertices 1 away from C. So, A is enqueued.

QUEUE:

E to C, cost=8

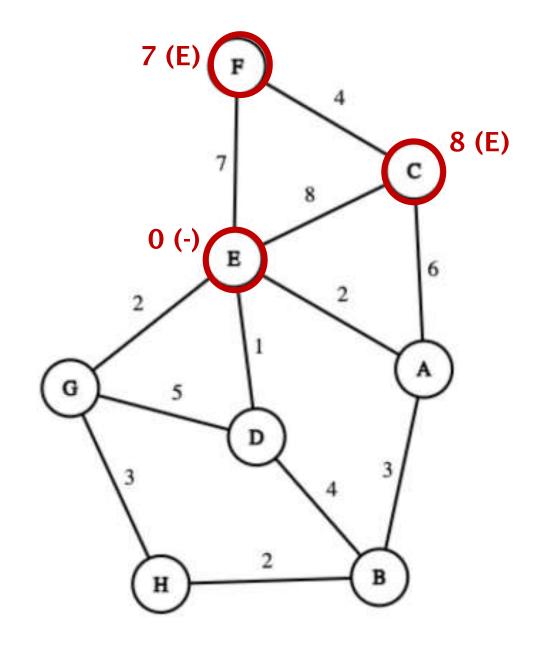
E to A, cost=2

E to D, cost=1

E to G, cost=2

F to C, cost=7+4=11

C to A, cost=8+6=14



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Go to A. A is known. Its cost and path are updated. Enqueue the unknown vertices 1 away from A. So, B is enqueued.

QUEUE:

E to A, cost=2

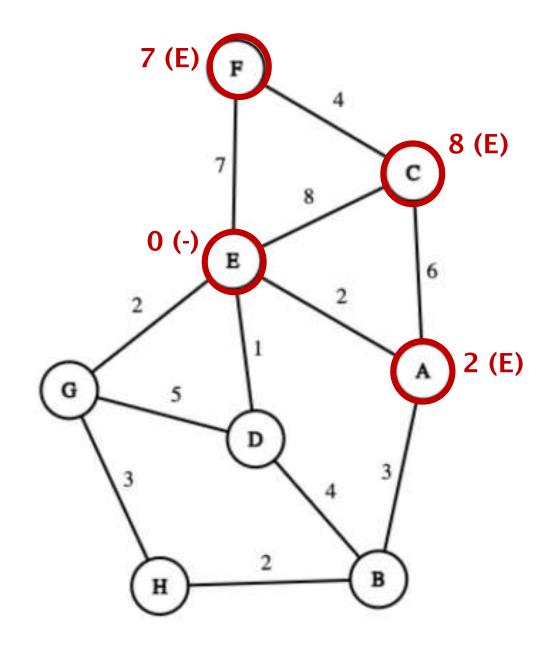
E to D, cost=1

E to G, cost=2

F to C, cost=7+4=11

C to A, cost=8+6=14

A to B, cost=2+3=5



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Go to D. D is known. Its cost and path are updated. Enqueue the unknown vertices 1 away from D. So, B and G are enqueued.

QUEUE:

E to D, cost=1

E to G, cost=2

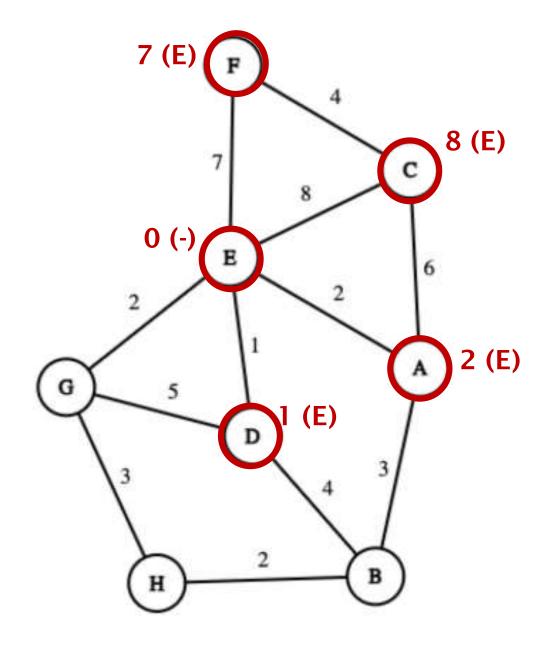
F to C, cost=7+4=11

C to A, cost=8+6=14

A to B, cost=2+3=5

D to G, cost=5+1=6

D to B, cost=1+4=5



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Go to G. G is known. Its cost and path are updated. Enqueue the unknown vertices 1 away from G. So, H is enqueued.

QUEUE:

E to G, cost=2

F to C, cost=7+4=11

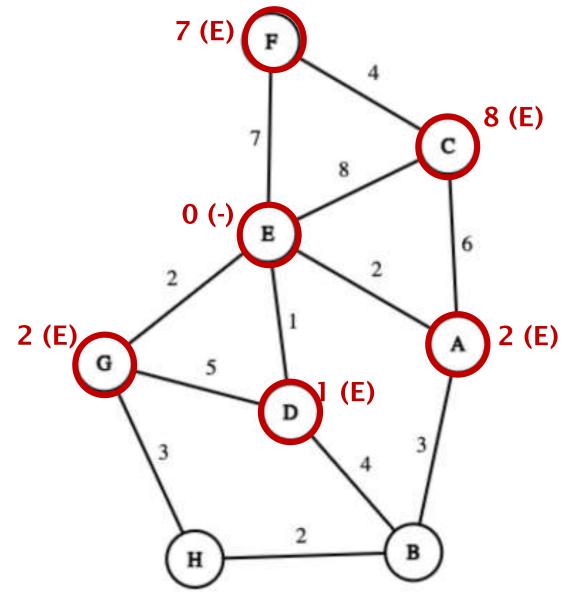
C to A, cost=8+6=14

A to B, cost=2+3=5

D to G, cost=5+1=6

D to B, cost=1+4=5

G to H, cost=2+3=5



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Both F and C are known. Cost: 11 > 8; therefore, path to C is NOT updated. Skip.

QUEUE:

F to C, cost=7+4=11

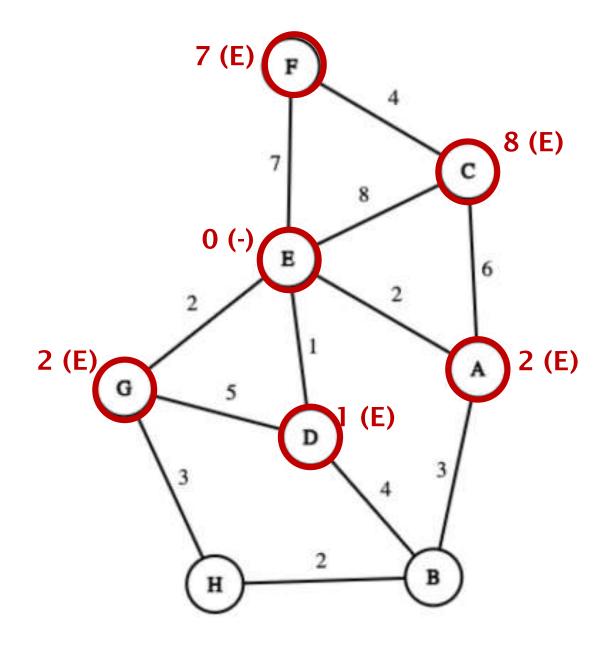
C to A, cost=8+6=14

A to B, cost=2+3=5

D to G, cost=5+1=6

D to B, cost=1+4=5

G to H, cost=2+3=5



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Both C and A are known. Cost: 14 > 2; therefore, path to A is NOT updated. Skip.

QUEUE:

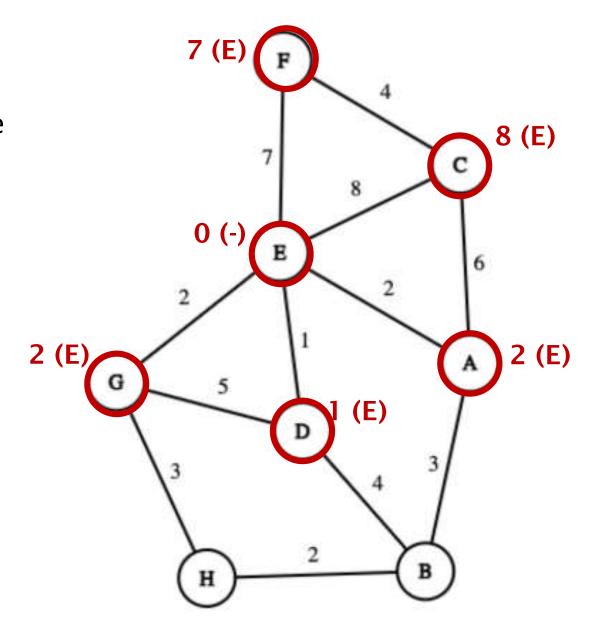
C to A, cost=8+6=14

A to B, cost=2+3=5

D to G, cost=5+1=6

D to B, cost=1+4=5

G to H, cost=2+3=5



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Go to B. B is known. Its cost and path are updated. Enqueue the unknown vertices 1 away from B. So, H is enqueued.

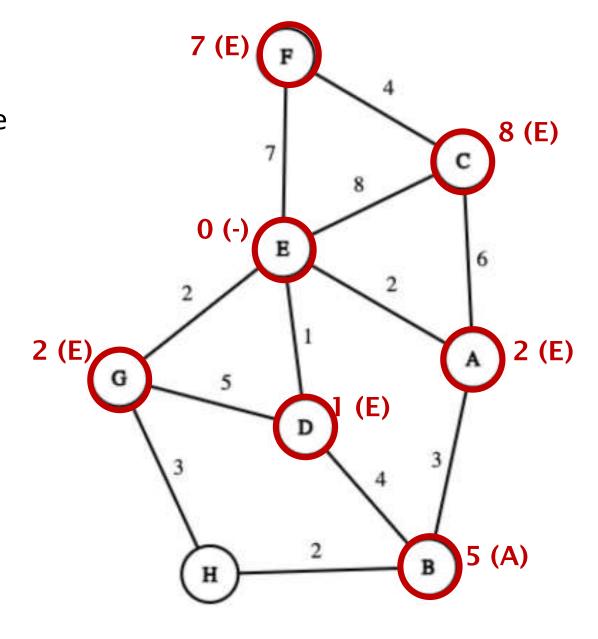
QUEUE:

A to B, cost=2+3=5

D to G, cost=5+1=6

D to B, cost=1+4=5

G to H, cost=2+3=5



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

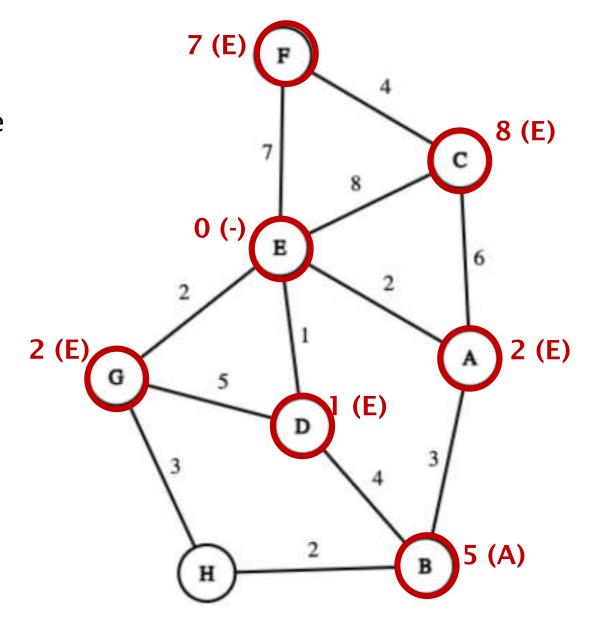
Both D and G are known. Cost: 6 > 2; therefore, path to G is NOT updated. Skip.

QUEUE:

D to G, cost=5+1=6

D to B, cost=1+4=5

G to H, cost=2+3=5



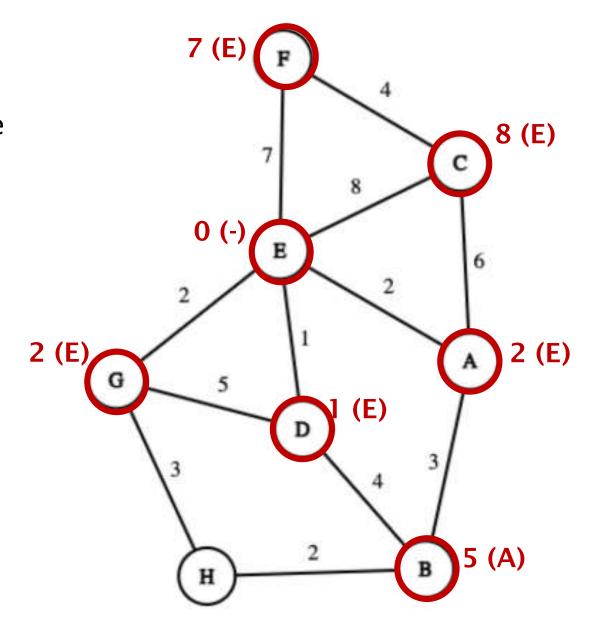
To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Both D and B are known. Cost: 5 = 5; therefore, path to B is NOT updated. Skip.

QUEUE:

D to B, cost=1+4=5

G to H, cost=2+3=5

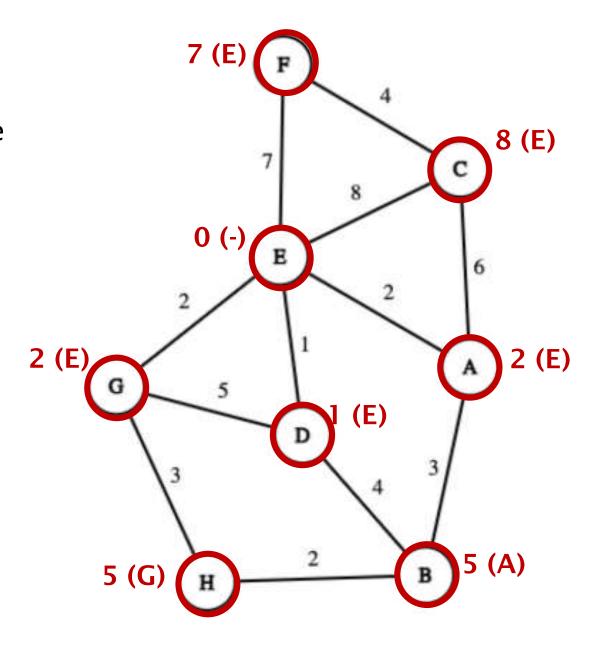


To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Go to H. H is known. Its cost and path are updated. No unknown vertices from H. Skip.

QUEUE:

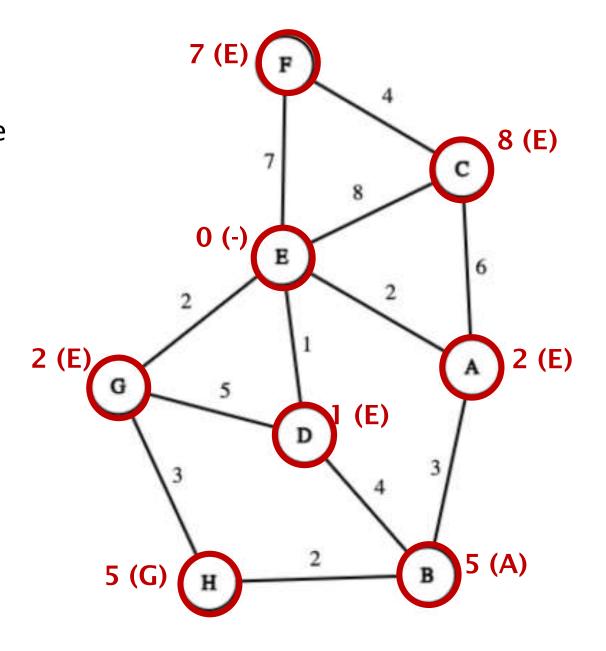
G to H, cost=2+3=5



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

Both B and H are known. Cost: 7 > 5; therefore, path to G is NOT updated. Skip.

QUEUE:



To keep track of BFS, we have a queue. On the graph, next to the vertices, the path and the distance through that vertex is shown in red.

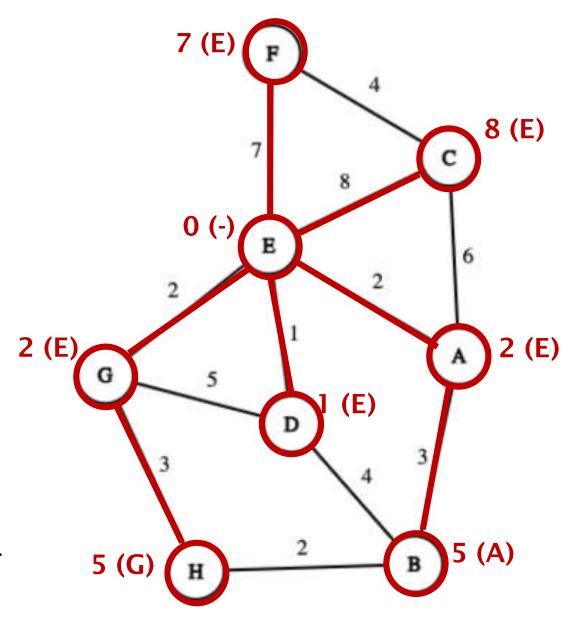
Both B and H are known. Cost: 7 > 5; therefore, path to G is NOT updated. Skip.

QUEUE:

empty

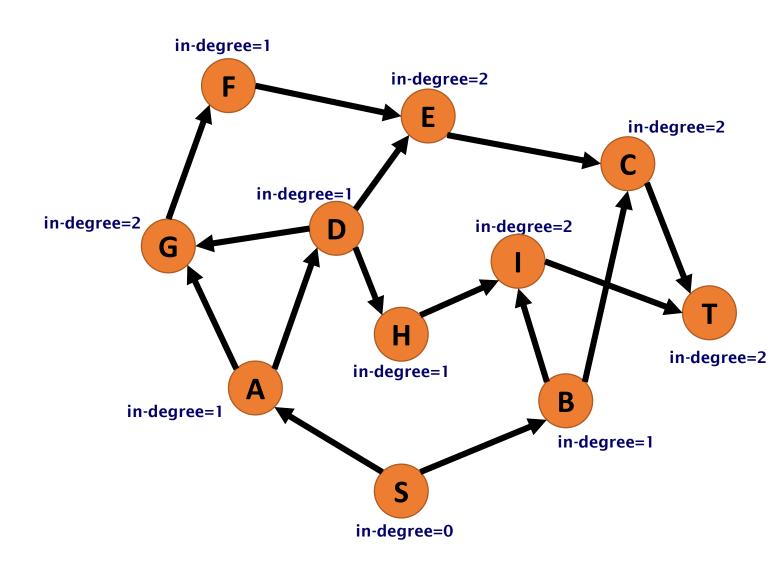
Queue is again empty, which means no further search left. BFS tree is shown on the graph.

Terminate.



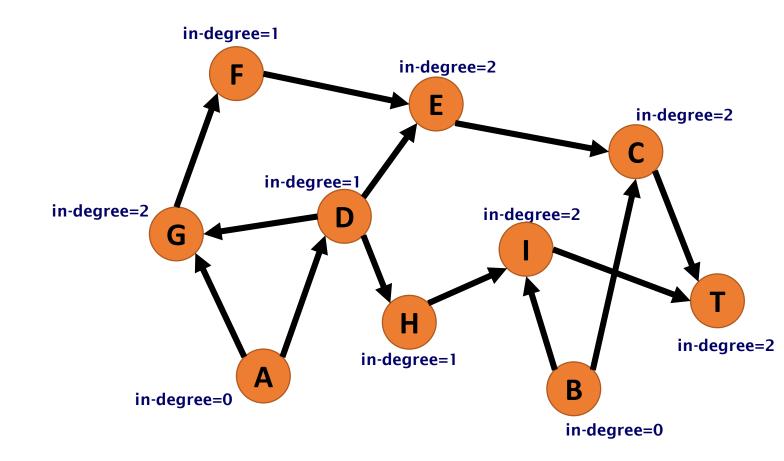
First of all, determine in-degree values for all vertices.

Values are shown on the graph. Start with a vertex having in-degree = 0.



The only vertex having in-degree=0 is vertes S. So, start with S.

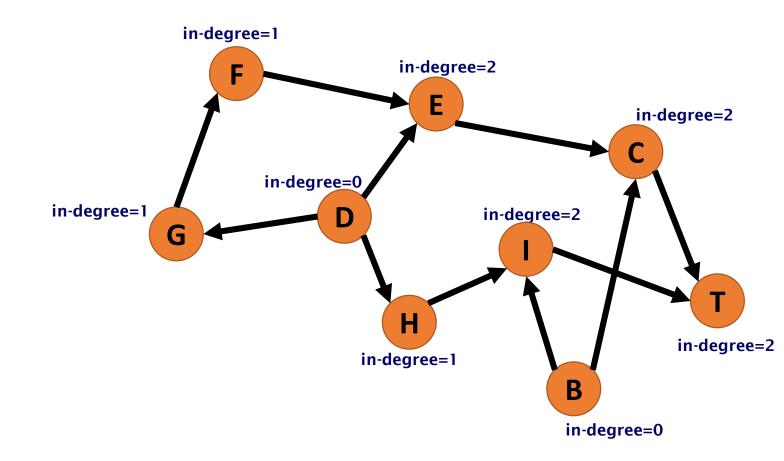
- Select S.
- Print S.
- Remove S.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

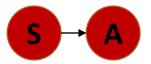




Vertices A and B have in-degree=0. Pick one randomly.

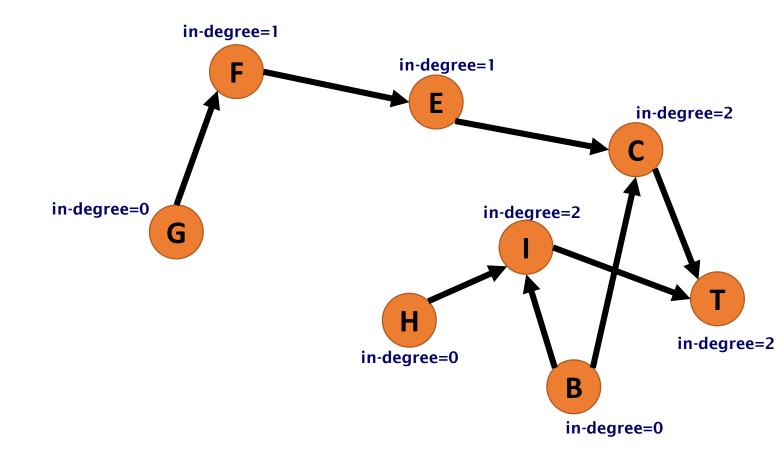
- Select A.
- Print A.
- Remove A.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

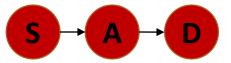




Vertices D and B have in-degree=0. Pick one randomly.

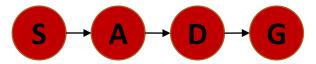
- Select D.
- Print D.
- Remove D.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

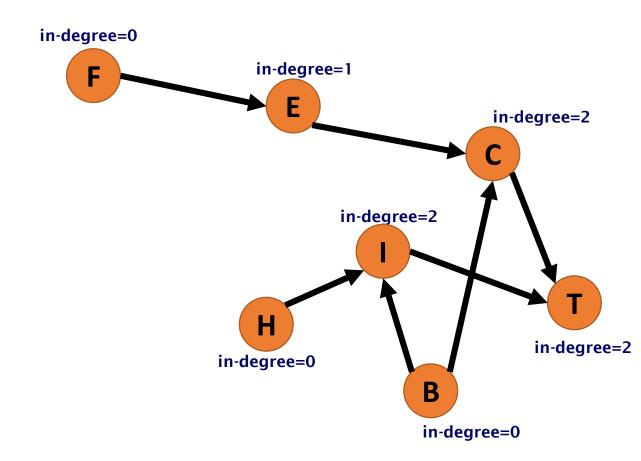




Vertices G, H and B have in-degree=0. Pick one randomly.

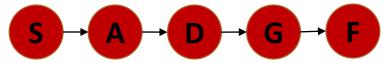
- Select G.
- Print G.
- Remove G.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

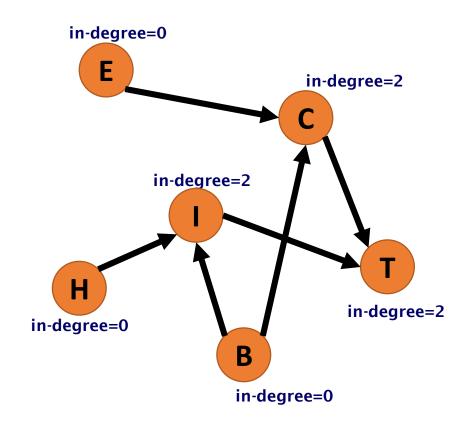




Vertices F, H and B have in-degree=0. Pick one randomly.

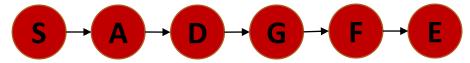
- Select F.
- Print F.
- Remove F.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

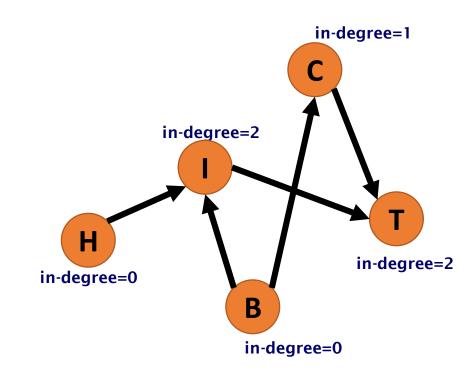




Vertices E, H and B have in-degree=0. Pick one randomly.

- Select E.
- Print E.
- Remove E.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

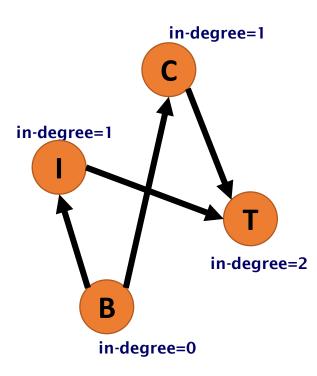




Vertices H and B have in-degree=0. Pick one randomly.

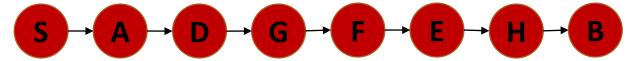
- Select H.
- Print H.
- Remove H.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

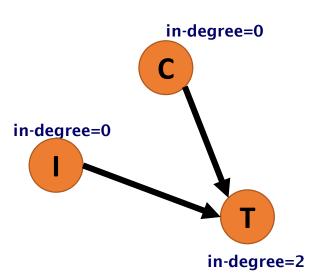




Vertex B have in-degree=0. Pick one randomly.

- Select B.
- Print B.
- Remove B.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

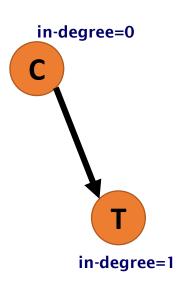




Vertices I and C have in-degree=0. Pick one randomly.

- Select I.
- Print I.
- Remove I.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0

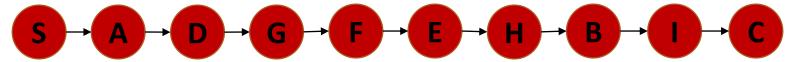




Vertex C have in-degree=0. Pick one randomly.

- Select C.
- Print C.
- Remove C.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0







Vertex T have in-degree=0. Pick one randomly.

- Select T.
- Print T.
- Remove T.
- Update in-degree numbers of neighbouring vertices.
- Move into next vertex with indegree=0



No vertices left.

Output of this topological sorting is as follows:

Output:



Note that this order is NOT unique. Random choices for vertices with in-degree=0 might change the order.