# Measures of Precision





#### Overview

- How to quantify uncertainty
- Why variance is important
- Components of variation in distance sampling
- Controlling variance
- Estimating variance
- Analytic
- Bootstrap
- Confidence Intervals





#### Consider an artificial population

 $D = 500 \text{ per unit}^2 \text{ (no density gradient)}$ 

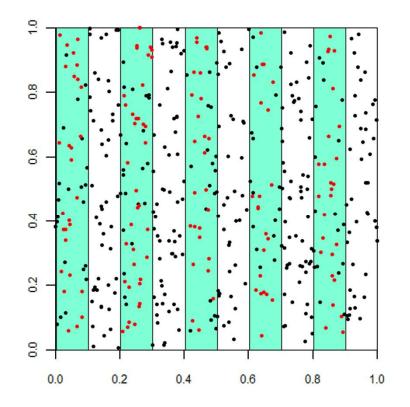
Design: 5 transects equally-spaced (w=0.05)

#### Results:

$$n = 140$$

$$\hat{f}(0) = 34.6$$

$$\hat{D} = 484.4$$







#### Consider a duplicate survey

Same population model

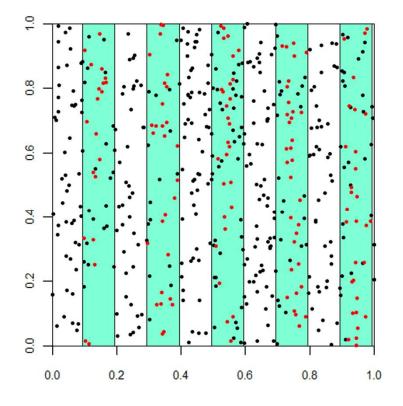
Same survey design (with a new random start point)

#### Results:

$$n = 139$$

$$\hat{f}(0) = 37.6$$

$$\hat{D} = 522.1$$







Imagine repeating this process over and over, using the same survey design and a population drawn from the same density model

Each survey will yield:

A different value for n

A different value for  $\hat{f}(0)$ 

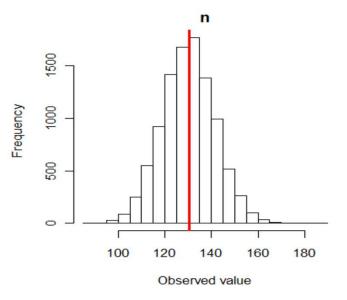
A different value for  $\hat{D}$ 

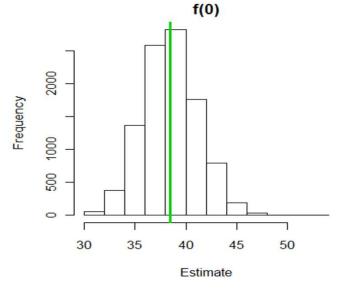


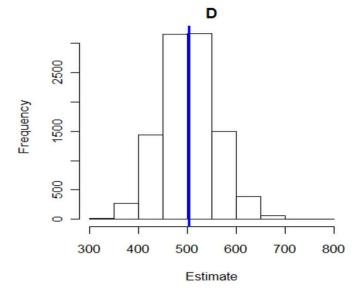


What happens if we repeat this simulated survey 10,000 times?

We end up with  $\operatorname{distributions}$  for n ,  $\widehat{f}(0)$  and  $\widehat{D}$ 









Note, 
$$\hat{f}(0) = \frac{1}{w\hat{P}_a}$$



We are interested in the hypothetical long-run behaviour of our estimator

$$\widehat{D} = \frac{n}{2wL\hat{a}}$$

How variable are the estimates?

E.g. what is the variance of the distribution for  $\widehat{D}$ ?

What is the average value of the estimates?

E.g. is the distribution for  $\widehat{D}$  centred on the truth?





# Quantifying uncertainty

#### Different ways of measuring uncertainty:

Variance = the average squared difference from the mean (the inverse of precision)
 If the estimator for D is unbiased, then

$$Var[\hat{D}] = E[(\hat{D} - D)^2]$$

2. Standard error = the standard deviation of an estimator (i.e. the square root of estimator variance)

$$Se[\hat{D}] = \sqrt{Var[\hat{D}]}$$





# Quantifying uncertainty

3. Coefficient of Variation (CV) = the standard error divided by the mean (i.e. a standardised version of the standard error)  $C = \hat{C}$ 

$$CV[\hat{D}] = \frac{Se[\hat{D}]}{E[\hat{D}]}$$

Useful for comparing variances when the scale and/or the units of measurement differ

E.g. consider two variables: X has mean = 100 and variance = 400, Y has mean = 1 and variance = 0.04

$$CV[X] = \frac{\sqrt{400}}{100} = \frac{20}{100} = 0.2 = 20\%$$
  $CV[Y] = \frac{\sqrt{0.04}}{1} = \frac{0.2}{1} = 0.2 = 20\%$ 





# Quantifying uncertainty

4. Confidence Interval (CI) = a range of plausible values for the truth

Calculations are based on variance

Different ways to calculate CIs, depending on the data, e.g.

Normal

Lognormal (available in Distance)

Bootstrap (available in Distance)

More about CIs later...





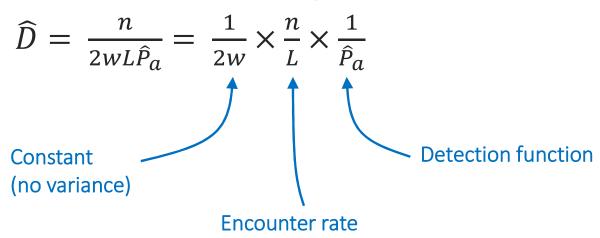
# Why is variance important?

- •In a real survey, we use an estimator and the survey data to produce a single estimate for *D*
- •If the estimator variance is low, then individual estimates are more likely to be close to the truth (assuming low bias)
- •If estimator variance is high, then individual estimates are more likely to be far from the truth
- •For reliable results, we want estimators with LOW variance (and low bias!)





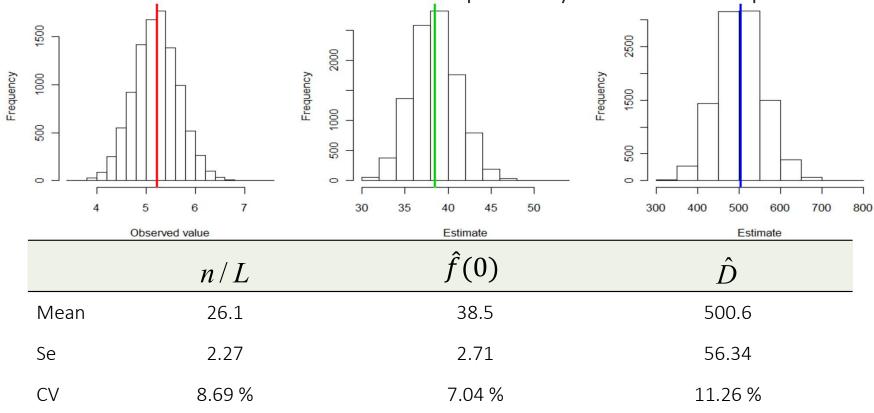
We can break down the familiar distance sampling density estimator (for line transects with no clusters) into three components:







We can calculate variance measures separately for each component







- •The variance of  $\widehat{D}$  is affected by the variance of its components
- If the variance of n is high,
- then the variance of  $\frac{n}{L}$  will be high and
- the variance of  $\widehat{D}$  will be high
- If the variance of  $\widehat{P}_a$  is high
- ullet then the variance of  $\widehat{D}$  will be high
- •For reliable estimates,
- we want  $Var\left[\frac{n}{L}\right]$  and  $Var\left[\hat{P}_a\right]$  to be low





Distance provides several variance measures for each component

```
Estimate
                                        SE
                                                  CV
                     0.3491863 0.02160949 0.06188528
Average p
N in covered region 300.6991117 30.11200030 0.10013997
Summary statistics:
  Region Area CoveredArea Effort n k ER
                                                  se.ER
                                                            CV.ER
1 Default
                   3436.8
                              48 105 12 2.1875 0.3169604 0.1448962
            1
Abundance:
  Label Estimate
                                             lcl
                                                       ucl
                                                                 df
                          se
                                    CV
1 Total 8.749392
                    1.378541 0.1575585
                                        6.270328 12.20859 15.32522
Density:
  Label
         Estimate
                                             lcl
                                                       ucl
                          se
                                                                 df
                                    CV
1 Total 0.08749392 0.01378541 0.1575585 0.06270328 0.1220859 15.32522
```





# Controlling variance

- We can use this knowledge of encounter rate variance to help design good surveys
- Three main ways we can reduce encounter rate variance:
  - Use systematic survey designs
  - Run transects parallel to density gradients
  - Use designs with multiple transects





We can describe the relationship between the variance of  $\hat{D}$  and the variance of its components more formally using a useful approximation known as the <code>Delta method</code>

$$\left\{cv(\widehat{D})\right\}^{2} = \left\{cv\left(\frac{n}{L}\right)\right\}^{2} + \left\{cv(\widehat{P}_{a})\right\}^{2}$$

Rule: when two or more components are multiplied together, squared CVs add





	$\frac{n}{L}$	$\hat{f}(0)$	$\widehat{m{D}}$
Mean	26.1	38.5	500.6
Se	2.27	2.71	56.34
CV	8.69 %	7.04 %	11.26 %

We can check this approximation works using the results of our simulation,

$$\left\{cv(\widehat{D})\right\}^2 = 0.1126^2 = 0.01266$$

$$\left\{cv\left(\frac{n}{L}\right)\right\}^2 + \left\{cv(\hat{P}_a)\right\}^2 = 0.0869^2 + 0.0704^2 = 0.01251$$

We can rearrange the squared CV to get an estimate of the variance

$$var(\widehat{D}) \approx \widehat{D}^2 \times \{cv(\widehat{D})\}^2$$





- To estimate  $var(^n/_L)$  we need to use data from the individual lines (or points)
- A minimum of 20 replicate lines (or points) is recommended for obtaining a reliable estimate of encounter rate variance
- The formula used in Distance:

$$\left\{cv\left(\frac{n}{L}\right)\right\}^{2} = \frac{k}{n^{2}(k-1)} \sum_{i=1}^{k} l_{i}^{2} \left(\frac{n_{i}}{l_{i}} - \frac{n}{L}\right)^{2}$$

$$k = \text{number of lines}$$

$$l_{i} = \text{effort for line i}$$





```
Estimate
Average p
                   0.3491863 0.02160949 0.06188528
N in covered region 300.6991117 30.11200030 0.10013997
Summary statistics:
  Region Area CoveredArea Effort n k ER
                                             se.ER
                                                      CV.ER
1 Default
                 3436.8
                           48 105 12 2.1875 0.3169604 0.1448962
Abundance:
 Label Estimate
                       se
                                CV
                                         lcl ucl
                                                          df
1 Total 8.749392 1.378541 0.1575585 6.270328 12.20859 15.32522
Density:
 Label
        Estimate se
                                cv lcl
                                                 นตไ
1 Total 0.08749392 0.01378541 0.1575585 0.06270328 0.1220859 15.32522
```

Component percentages of variance:

.Label Detection ER

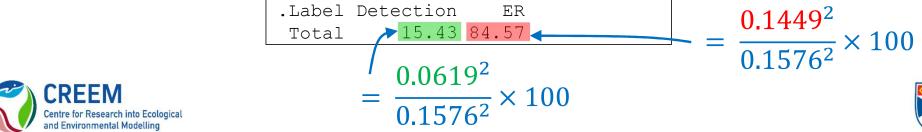
Total 15.43 84.57

Abundance and Density always have the same CV





```
Estimate
                  0.3491863 0.02160949 0.06188528
Average p
N in covered region 300.6991117 30.11200030 0.10013997
Summary statistics:
  Region Area CoveredArea Effort n k ER
                                            se.ER
                                                     CV.ER
1 Default
                 3436.8 48 105 12 2.1875 0.3169604 0.1448962
Abundance:
 Label Estimate
                       se
                               CV
                                        lcl ucl
                                                         df
1 Total 8.749392 1.378541 0.1575585
                                    6.270328 12.20859 15.32522
Density:
                               cv lcl ucl df
 Label
        Estimate
1 Total 0.08749392 0.01378541 0.1575585 0.06270328 0.1220859 15.32522
```



Component percentages of variance:





To find the relative contributions of each component we take the ratio of squared CVs

E.g. 
$$100\% \times \frac{\{cv(\widehat{P}_a)\}^2}{\{cv(\widehat{D})\}^2} = \frac{\text{The percentage relative}}{\text{contribution made by } \widehat{P}_a}$$

	Typical values		
Component	Line	Point	
Encounter rate	70-80%	40-50%	
Detection function	<30%	>50%	





### Estimating variance – Bootstrap

- Works well if the original sample is large and representative
- The distribution of density estimates approximates the true distribution that we would (theoretically) get from duplicate surveys
- The variance of the bootstrap estimates can be used as an estimate of the true variance
- In Distance we resample the individual transects





## Estimating variance – Bootstrap

- For example, consider a survey with 12 replicate lines
  - Bootstrap sample 1:
    - Transects: 5, 12, 1, 7, 6, 11, 7, 6, 9, 7, 11, 2
    - Density estimate =  $D_1$
  - Bootstrap sample 2:
    - Transects: 3, 4, 9, 1, 12, 7, 8, 11, 1, 3, 2, 12
    - Density estimate =  $D_2$
- Do this B times and use the variance of the B density estimates as an estimate of  $var(\widehat{D})$





### Estimating variance – Bootstrap

Basic function to generate a bootstrap:

bootdht(model, flatfile, nboot, summary\_fun)

model - detection function model

flatfile - data object used to fit model

summary\_fun - function to harvest required statistic from each bootstrap sample

nboot – the number of bootstrap samples to use





#### Confidence Intervals

- Confidence intervals (CIs) give us a range of plausible values for the truth
- Constructed using data from a single sample
- If we were to carry out multiple surveys and construct 95% CIs from each survey, we would expect 95% of those CIs to contain the true value
- To calculate CIs, it would be beneficial to know the shape of the distribution of estimates





# Confidence Intervals - Analytic

mean = 
$$1$$
, se =  $0.5$ 

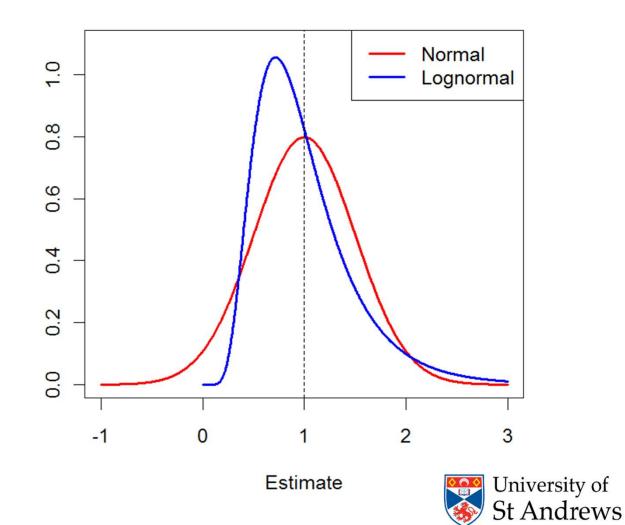
#### Two choices:

#### Normal

- symmetrical
- easy to use
- allows negative values

#### Lognormal

- asymmetric (skewed)
- trickier to use
- typically higher interval limits
- does not allows negative values





# Confidence Intervals - Analytic

#### Distance uses 95% lognormal CIs

#### Abundance:

Label Estimate se cv (lcl ucl) df 1 Total 8.749392 1.378541 0.1575585 6.270328 12.20859 15.32522

#### Density:

Label Estimate se cv 1cl ucl df 1 Total 0.08749392 0.01378541 0.1575585 0.06270328 0.1220859 15.32522

$$\left(\frac{\widehat{D}}{C}, \widehat{D} \times C\right) \qquad C = exp\left[1.96\sqrt{ln\left\{1 + \left(cv(\widehat{D})\right)^2\right\}}\right]$$





## Confidence Intervals – Bootstrap

The nonparametric option is provided in Distance

Bootstrap results

Boostraps : 999

Successes : 999

Failures : (

```
Estimate se ucl lcl cv

N 8.58 1.44 11.67 5.94 0.17 Sta

D 0.09 0.01 0.12 0.06 0.17 by
```

Standard error divided by the mean





# Further reading about precision

- Section 3.6 of Buckland et al. (2001) Introduction to Distance Sampling
- Fewster et al. (2009) Estimating the encounter rate variance in distance sampling. Biometrics 65: 225-236.
- Sections 6.3.1.2 and 6.3.2.2 of Buckland et al. (2015) Distance Sampling: Methods and Applications.





# Producing a better estimate of variance when systematic samplers are used

• Fewster, RM, Buckland, ST, Burnham, KP, Borchers, DL, Jupp, PE, Laake, JL, and Thomas, L. 2009. Estimating the encounter rate in distance sampling. Biometrics 65: 225-236.

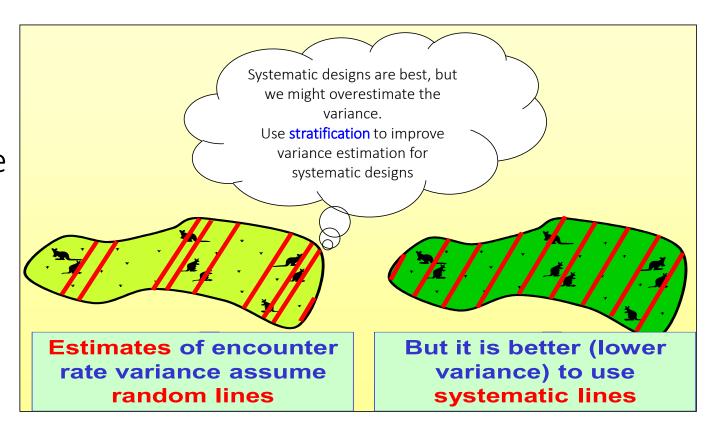




# Systematic samples

#### Problem:

Systematic designs give the best variance, but the worst variance estimation!



No unbiased estimator exists for estimating variance from a single systematic sample

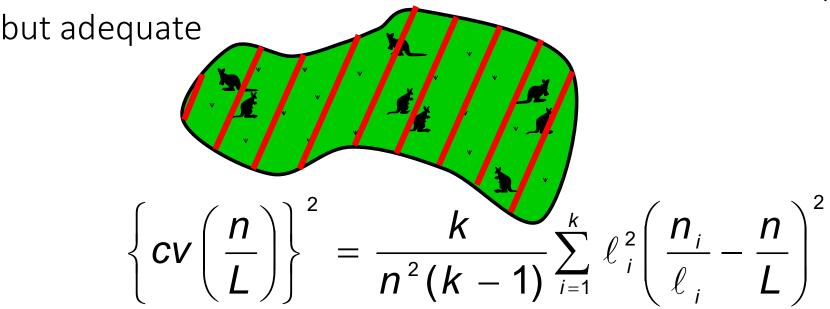




# Systematic samples advice

#### Usually, do nothing!

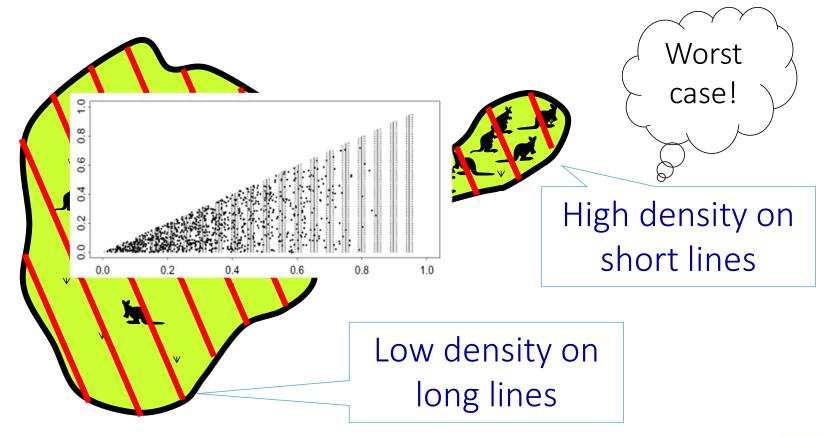
Variance estimation based on random lines will not be perfect,







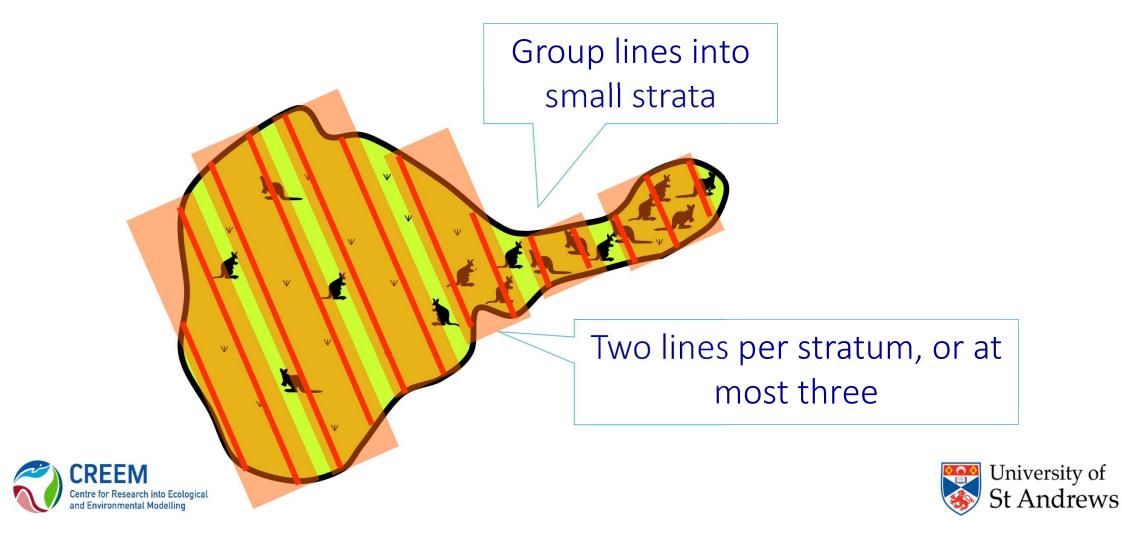
#### If there are strong trends, variance might be significantly overestimated







#### Post-stratification can give much better variance estimates



#### In Distance:

The encounter rate variance can be specified in the dht2 function with the er est argument

```
dht2(model, flatfile, er_est)
```

- The options follow the notation used in Fewster et al. (2009)
- The default is er est="R2" random line placement with unequal line length
- For systematic estimators, successive pairs of lines will be grouped together, according to the Sample.Label and so labels should be numeric (e.g. lines 1 and 2 grouped)
- If there are an odd number of lines, the last 3 will be grouped





### Post-stratification can give much better <u>estimates</u> of variance

Pool by-stratum
variance estimates
together, weighted by
Total Effort in Stratum

Trends within strata are minor; Estimate encounter rate variance separately for each stratum

$$var\left(\frac{n}{L}\right) = \frac{1}{L^2} \sum_{h=1}^{H} L_h^2 var_h \left(\frac{n_h}{L_h}\right)$$



Option is er est="S2"



Overlapping strata are even better, as you get a larger sample size of post-strata



# Point transect surveys

Default (and only) option is er\_est="P2"

