

EE 150L
Signals and Systems Lab

Lab2 System Analysis in Time Domain

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1. About system response

- a) Describe the characteristics of zero-input responses and zero-state response briefly. What is the difference between the initial conditions of the two responses?
- b) Consider a linear system whose zero-input response $y_{zi}(t) = (4e^{-t} - 3e^{-2t})u(t)$ and the system full response $y(t) = (3e^{-t} - 2e^{-2t} + te^{-t})u(t)$, what is the zero-state response of the system?

a) For zero-input responses there's no input to the system, and only the initial state of the system acts on the system. For zero-state responses, the initial state is zero, and only the input acts on the system.

b) since $y(t) = y_{zi}(t) + y_{zs}(t)$

we have known $y_{zi}(t)$ and $y(t)$

then $y_{zs}(t) = y(t) - y_{zi}(t)$

$$= (3e^{-t} - 2e^{-2t} + te^{-t})u(t) - (4e^{-t} - 3e^{-2t})u(t)$$

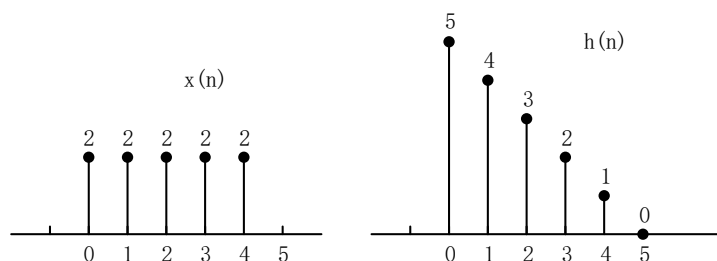
$$= (e^{-2t} - e^{-t} + te^{-t})u(t)$$

so the zero-state response of the system

is $y_{zs}(t) = (e^{-2t} - e^{-t} + te^{-t})u(t)$

2. Convolve the following two signals and record the result as $y(n)$.

- Please describe the convolution process in detail (both formulas and schematic are accepted).
- What is the relationship between the length of $y(n)$ and the length of $x(n)$ and $h(n)$?



$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$= x[0] h[n] + x[1] h[n-1] + x[2] h[n-2] + x[3] h[n-3] + x[4] h[n-4]$$

$$= 2 h[n] + 2 h[n-1] + 2 h[n-2] + 2 h[n-3] + 2 h[n-4]$$

$$= 2 \left\{ 5 u[n] - u[n-1] - u[n-2] - u[n-3] - u[n-4] - u[n-5] \right\}$$

$$+ 2 \left\{ 5 u[n-1] - u[n-2] - u[n-3] - u[n-4] - u[n-5] - u[n-6] \right\}$$

$$+ 2 \left\{ 5 u[n-2] - u[n-3] - u[n-4] - u[n-5] - u[n-6] - u[n-7] \right\}$$

$$+ 2 \left\{ 5 u[n-3] - u[n-4] - u[n-5] - u[n-6] - u[n-7] - u[n-8] \right\}$$

$$+ 2 \left\{ 5 u[n-4] - u[n-5] - u[n-6] - u[n-7] - u[n-8] - u[n-9] \right\}$$

$$= 10 u[n] + 8 u[n-1] + 6 u[n-2] + 4 u[n-3] + 2 u[n-4] - 10 u[n-5]$$

$$- 8 u[n-6] - 6 u[n-7] - 4 u[n-8] - 2 u[n-9]$$

a) Substitution: t becomes $\tau \rightarrow f_1(\tau), f_2(\tau)$;

Inversion translation: from $f_2(\tau)$ inversion $\rightarrow f_2(-\tau)$ right shift $t \rightarrow f_2(t-\tau)$;

Product: $f_1(\tau) f_2(t-\tau)$;

Integration : τ is the integral from $-\infty$ to ∞ of the product term

b) The length of $y[n] = \text{the length of } x[n] + \text{the length of } h[n] - 1$