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1. (a) for $x_1(t) = 1$, $y_1(t) = 10$

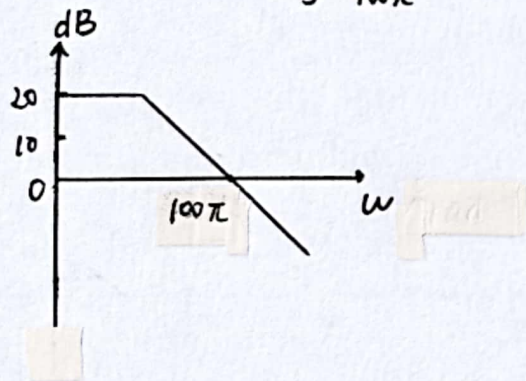
$$A \times 10 = 1000\pi \quad A = 100\pi$$

$$\text{So } \frac{dy(t)}{dt} + 100\pi y(t) = 1000\pi x(t)$$

$$j\omega Y(j\omega) + 100\pi Y(j\omega) = 1000\pi X(j\omega)$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{1000\pi}{100\pi + j\omega}$$

$$(b) H(j\omega) = 10 \frac{1}{1 + j\omega \frac{1}{100\pi}}$$



$$(c). y_2(t) = 50 e^{j10\pi t} + 10 e^{j1000\pi t} e^{j\frac{\pi}{4}}$$



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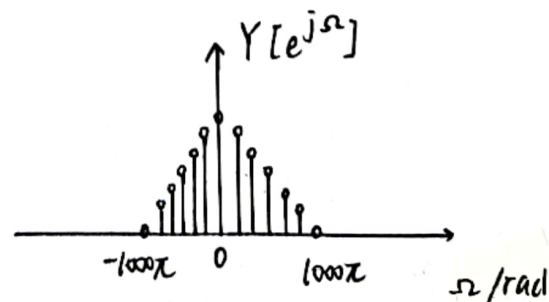
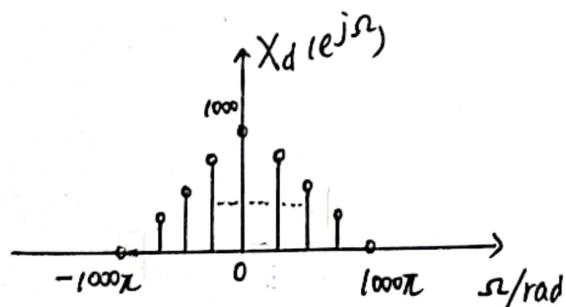
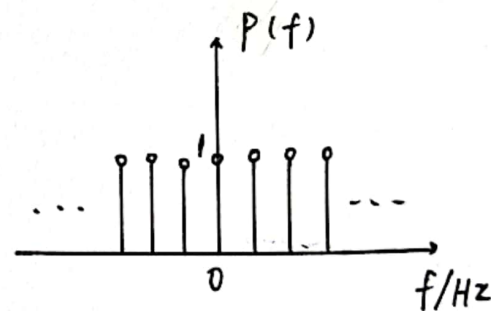
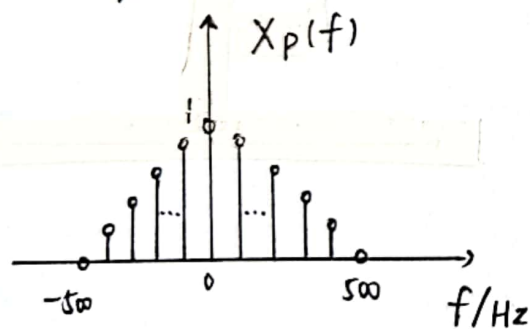
$$2. (a) X_p(t) = \sum X_a(nT_1) \frac{\sin[\frac{\pi}{T_1}(t-nT_1)]}{\frac{\pi}{T_1}(t-nT_1)}$$

$$X_d[n] = \sum X_a(nT_1)$$

$$Y[n] = \sum X_a(\frac{nT_1}{2})$$

$$(b) 0 < T_1 \leq \frac{1}{1000}$$

$$(c) T_1 = \frac{1}{1000} \text{ s}$$



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3. (a) from $x(t)=15, y(t)=-29$

$$-15 \times 29 = A \times 15$$

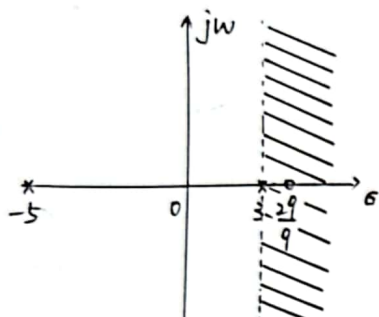
$$\text{so } A = -29$$

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} - 15 y(t) = 9 \frac{dx(t)}{dt} - 29 x(t)$$

$$s^2 Y(s) + 2s Y(s) - 15 Y(s) = 9s X(s) - 29 X(s)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{9s - 29}{s^2 + 2s - 15} = \frac{9s - 29}{(s+5)(s-3)} = \frac{\frac{37}{4}}{s+5} - \frac{\frac{1}{4}}{s-3}$$

(b)

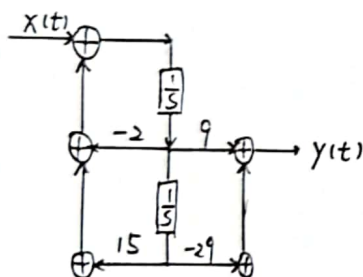


$$\text{ROC: } \text{Re}\{s\} > 3 \text{ and } \text{Re}\{s\} \neq \frac{3}{9}$$

(c) $H(s)$ is not stable (b) doesn't include $j\omega$ axis)

$H(s)$ is causal

(d)



$$(e) H(s) = \frac{\frac{37}{4}}{s+5} - \frac{\frac{1}{4}}{s-3}$$

$$\text{so } h(t) = \frac{37}{4} e^{-5t} u(t) - \frac{1}{4} e^{3t} u(t)$$



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4. (a) for $y[n] = [-\frac{7}{4}(-7)^n - \frac{1}{4}]u[n]$ $Y(z) = -\frac{7}{4} \cdot \frac{1}{1+7z^{-1}} - \frac{1}{4} \cdot \frac{1}{1-z^{-1}}$

for $x[n] = \alpha u[n]$ $X(z) = \frac{\alpha}{1-z^{-1}}$

for $y[n] + 7y[n-1] = x[n] - 2x[n-1]$

$$Y(z) + 7z^{-1}Y(z) + 7y[-1] = X(z) - 2z^{-1}X(z) - 2x[-1]$$

$$(1+7z^{-1})Y(z) + 7y[-1] = (1-2z^{-1})X(z)$$

$$-\frac{7}{4} - \frac{1}{4} \cdot \frac{1+7z^{-1}}{1-z^{-1}} + 7\beta = \frac{\alpha(1-2z^{-1})}{1-z^{-1}}$$

we can get $\beta = \frac{4}{7}$ $\alpha = 2$

(b). for zero-state. $y[-1] = 0$

then $(1+7z^{-1})Y(z) = (1-2z^{-1})X(z)$

since $X(z) = \frac{\alpha}{1-z^{-1}} = \frac{2}{1-z^{-1}}$

$$Y(z) = \frac{1-2z^{-1}}{1+7z^{-1}} \cdot \frac{2}{1-z^{-1}} = \frac{\frac{9}{4}}{1+7z^{-1}} - \frac{\frac{1}{4}}{1-z^{-1}}$$

so $y_{zs}[n] = \frac{9}{4} \cdot (-7)^n u[n] - \frac{1}{4} u[n]$

for zero-input $x[n] = 0$

so $(1+7z^{-1})Y(z) + 7y[-1] = 0$

$$Y(z) = \frac{-7y[-1]}{1+7z^{-1}} = \frac{-4}{1+7z^{-1}}$$

so $y_{zi}[n] = -4 \cdot (-7)^n u[n]$

(it's true that $y_{zs}[n] + y_{zi}[n] = y[n]$).



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