

# Rod Hitting Ball Lab

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## 1 Objective

To determine the distance the racquetball will land from the point of launch as well as the angle the launcher will rise.

## 2 Data

Quantity	Value	Unit
$L$ (rod length)	38.1	cm
$l_{cm}$ (distance from axis to rod-mass COM)	29.9	cm
$l_{top}$ (distance from axis to top of rod)	2.5	cm
$l_{weight}$ (distance from bottom of rod to top of weight)	2	cm
$H$ (final track height above ground)	98	cm
$h_i$ (initial track height)	9	cm
$h_f$ (final track height)	12.4	cm
$R$ (ball radius)	2.85	cm
$M$ (ball mass)	81.55	g
$m$ (total rod & weight mass)	101.7	g
$m_{rod}$ (rod mass)	26.54	g
$m_{weight}$ (weight mass)	75.16	g
$\theta_i$ (initial rod angle)	60	°
$\phi$ (track angle wrt horizontal)	1	°

### 3 Calculations

#### 3.1 MOI of rod-mass

Let  $I_{rm}$  be the MOI of the rod-mass about its hinge. The distance  $d$  from the axis to the weight's COM  $= L - l_{top} - \frac{l_{weight}}{2}$ .

$$I_{rm} = \frac{1}{12}m_{rod}L^2 + m_{rod}\left(\frac{L}{2} - l_{top}\right)^2 + m_{weight}d^2.$$

Thus,  $I_{rm} \approx 0.01 \text{ kgm}^2$ .

#### 3.2 Angular speed of rod on collision

From energy conservation:

$$mgl_{cm}(1 - \cos \theta_i) = \frac{1}{2}I_{rm}\omega_i^2.$$

Thus,  $\omega_i \approx 5.46 \text{ rad/s}$ .

#### 3.3 Angular momentum

Let counterclockwise be positive by convention. We have:

$$L_{rm} = I_{rm}\omega_i - Ndt = I_{rm}\omega_f,$$

$$L_b = -NRt = -MRv - I_bv/R,$$

where  $N$  is the normal force between the ball and rod-mass,  $t$  is the collision time,  $I_b = \frac{2}{5}MR^2$  is the MOI of the ball about its COM,  $v$  is the linear velocity of the ball's COM, and  $d$  is the same as above.

Here, the angular momentum of the rod-mass  $L_{rm}$  is taken wrt the hinge; the angular momentum of the ball  $L_b$  is taken wrt its contact point on the track. This eliminates any friction terms that would otherwise be present in our expressions.

Combining these equations, it follows that

$$I_{rm}\omega_i = I_{rm}\omega_f + Mvd + I_bvd/R^2.$$

#### 3.4 Coefficient of Restitution

We require another equation to actually solve for  $\omega_f$ . From a table of CORs, we will estimate that the collision has a COR of  $e = 0.7$ . This means that:

$$e = \frac{v_{tf} - v}{0 - v_{ti}} = 0.7,$$

where  $v_{ti}$  and  $v_{tf}$  are the initial and final linear velocities of the rod-mass contact point with the ball, respectively, and  $v$  is the ball's translational velocity.

Since the rod-mass contact point is a distance  $d$  from the hinge,  $v_{ti} = \omega_i d$  and  $v_{tf} = \omega_f d$ . Combining, we get that

$$v = d(0.7\omega_i + \omega_f).$$

### 3.5 Ball velocity (right after collision)

Substituting the COR expression into angular momentum conservation, we get that  $\omega_f \approx 0.1 \text{ rad/s}$  and  $v \approx 1.36 \text{ m/s}$ .

### 3.6 Final rod angle

We reuse the energy conservation expression and find that  $\omega_f \approx 0.1 \text{ rad/s}$  corresponds to  $\theta_f \approx 1^\circ$ .

### 3.7 Ball velocity (before bump)

By Newton's Second Law:

$$M \frac{dv}{dt} = -F_D - Mg \sin \phi,$$

where  $F_D$  is the drag force and  $Mg \sin \phi$  is component of gravity parallel to the track.

The drag force  $F_D = \frac{1}{2} \rho v^2 C_D A$ . The density of air at room temperature  $\rho$  is  $\approx 1.2 \text{ kg/m}^3$ , the drag coefficient  $C_D$  of the ball is  $\approx 0.5$ , and the cross-sectional area  $A$  of the ball is  $\pi R^2$ . Thus,  $F_D \approx 0.0008 v^2$ .

Solving the differential equation with the condition  $v(0) = 1.36$  and  $x(0) = 0$ :

$$v(t) = 4.18 \tan(.315 - .04t),$$

$$x(t) = 105 \ln(\cos(.315 - .04t)) + 5.3.$$

The distance from the collision point to the point is  $\approx 1 \text{ m}$ ; setting  $x(t) = 1$  indicates that it takes  $\approx 0.77 \text{ s}$  for the ball to travel this distance. Therefore, its translational velocity right before the bump  $v_{bi} \approx 1.22 \text{ m/s}$ .

### 3.8 Ball velocity (after bump)

We will neglect drag here because the bump was relatively short. However, a significant fraction of kinetic energy is transformed into gravitational potential

energy. To simplify calculations, the total kinetic energy  $K$  of the ball is  $K = K_{linear} + K_{rotation} = \frac{1}{2}Mv^2 + \frac{1}{2}I_b(\frac{v}{R})^2 = \frac{7}{10}Mv^2$  for an arbitrary translational velocity  $v$ .

By energy conservation,

$$K_i = K_f + Mg(h_f - h_i)$$

since the ball goes up a height of  $h_f - h_i$  during the bump. Solving for the translational velocity right after the bump, we get that  $v_{bf} \approx 1.0 \text{ m/s}$ .

### 3.9 Ball velocity (right before projectile motion)

Now, we will account for drag and the incline once again. Solving the differential equation again with the new conditions  $v(0) = 1.0$  and  $x(0) = 0$ :

$$v(t) = 4.18 \tan(.235 - .04t),$$

$$x(t) = 105 \ln(\cos(.235 - .04t)) + 2.9.$$

We will estimate that the second portion of the track is also  $\approx 1 \text{ m}$ . Finally, we get that the translational velocity right before projectile motion  $u \approx 0.8 \text{ m/s}$ .

### 3.10 Ball Travel Distance

The travel time of the ball  $t$  is given by

$$-H = -\frac{1}{2}gt^2 \implies t \approx 0.45 \text{ s}.$$

Thus, the ball will travel a distance  $ut \approx 36 \text{ cm}$  off the table.