Graphical models for high-dimensional data

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- Some basics
- 2 Estimation of Gaussian graphical models
- Graphical models in exponential form
- 4 Graphs with corrupted or hidden variables

- Some basics

Undirected graphical models

- An undirected graph G = (V, E) consists of a set of vertices $V=1,2,\ldots,d$ joined together by a collection of edges E. An edge (j, k) is an unordered pair of distinct vertices $j, k \in V$.
- We associate to each vertex $j \in V$ a random variable X_i , taking values in some space X_i . We then consider the distribution \mathbb{P} of the *d*-dimensional random vector $X = (X_1, \dots, X_d)$.
- A clique C means that $(j, k) \in E$ for all distinct vertices $i, k \in C$. A maximal clique is a clique that is not a subset of any other clique. We use & to denote the set of all cliques in G, and for each clique $C \in \mathfrak{C}$, we use ψ_C to denote a function of the subvector $x_C := (x_i, j \in C)$. This clique compatibility function takes inputs from the Cartesian product space $X^{C} := \bigotimes_{i \in C} X_{i}$, and returns non-negative real numbers.

Factorization

Definition (11.1)

The random vector (X_1, \ldots, X_d) factorizes according to the graph G if its density function p can be represented as

$$p(x_1,\ldots,x_d) \propto \prod_{C\in\mathfrak{C}} \psi_C(x_C)$$
 (11.1)

for some collection of clique compatibility functions $\psi_C: \mathcal{X}^C \to [0, \infty).$

Example 11.3

Any non-degenerate Gaussian distribution with zero mean can be parameterized in terms of its inverse covariance matrix $\mathbf{\Theta}^* = \mathbf{\Sigma}^{-1}$. also known as the precision matrix. In particular, its density can be written as

$$p(x_1,...,x_d; \mathbf{\Theta}^*) = \frac{\sqrt{\det(\mathbf{\Theta}^*)}}{(2\pi)^{d/2}} e^{-\frac{1}{2}x^T\mathbf{\Theta}^*x}$$
(11.2)

By expanding the quadratic form, we see that

$$e^{-\frac{1}{2}x^{\mathrm{T}}\Theta^{*}x} = \exp\left(-\frac{1}{2}\sum_{(j,k)\in E}\Theta_{jk}^{*}x_{j}x_{k}\right) = \prod_{(j,k)\in E}\underbrace{-\frac{1}{2}\Theta_{jk}^{*}x_{j}x_{k}}_{\psi_{jk}(x_{j},x_{k})},$$

showing that any zero-mean Gaussian distribution can be factorized in terms of functions on edges, or cliques of size two.

Conditional independence

- A vertex cutset S is a subset of vertices whose removal from the graph breaks it into two or more disjoint pieces.
- Removing S from the vertex set V leads to the vertex-induced subgraph $G(V \backslash S)$, consisting of the vertex set $V \backslash S$, and the residual edge set

$$E(V \backslash S) := \{ (j, k) \in E \mid j, k \in V \backslash S \}. \tag{11.4}$$

The set S is a vertex cutset if the residual graph G(V\S)
consists of two or more disconnected non-empty components.

For any subset $A \subseteq V$, let $X_A := (X_i, j \in A)$ represent the subvector of random variables indexed by vertices in A. For any three disjoint subsets, say A, B and S, of the vertex set V, we use $X_A \perp \!\!\!\perp X_B \mid X_S$ to mean that the subvector X_A is conditionally independent of X_B given X_S .

Definition (11.5)

A random vector $X = (X_1, \dots, X_d)$ is Markov with respect to a graph G if, for all vertex cutsets S breaking the graph into disjoint pieces A and B, the conditional independence statement $X_A \perp \!\!\!\perp X_B \mid X_S$ holds.

Example 11.6

The Markov chain graph on vertex set $V = \{1, 2, ..., d\}$ contains the edges (j, j + 1) for j = 1, 2, ..., d - 1. For such a chain graph, each vertex $j \in \{2, 3, ..., d - 1\}$ is a non-trivial cutset, breaking the graph into the "past" $P = \{1, 2, ..., j - 1\}$ and "future" $F = \{j + 1, ..., d\}$. These singleton cutsets define the essential Markov property of a Markov time-series model-namely, that the past X_P and future X_F are conditionally independent given the present X_i .

Theorem (11.8 Hammersley-Clifford)

For a given undirected graph and any random vector

- $X = (X_1, \dots, X_d)$ with strictly positive density p, the following two properties are equivalent:
- (a) The random vector X factorizes according to the structure of the graph G, as in Definition 11.1.
- (b) The random vector X is Markov with respect to the graph G, as in Definition 11.5

Proof

- (a) \Rightarrow (b): Let S be an arbitrary vertex cutset of the graph such that subsets A and B are separated by S. We may assume without loss of generality that both A and B are non-empty, and we need to show that $X_A \perp \!\!\!\perp X_B \mid X_S$.
 - $\mathfrak{C}_A := \{C \in \mathfrak{C} \mid C \cap A \neq \emptyset\}, \mathfrak{C}_B := \{C \in \mathfrak{C} \mid C \cap B \neq \emptyset\}$ and $\mathfrak{C}_{S} := \{ C \in \mathfrak{C} \mid C \subseteq S \}$.
 - $\mathfrak{C} = \mathfrak{C}_{\mathsf{A}} \cup \mathfrak{C}_{\mathsf{S}} \cup \mathfrak{C}_{\mathsf{B}}$.

$$p(x_A, x_S, x_B) = \frac{1}{Z} \underbrace{\left[\prod_{C \in \mathfrak{C}_A} \psi_C(x_C) \right]}_{\Psi_A(x_A, x_S)} \underbrace{\left[\prod_{C \in \mathfrak{C}_S} \psi_C(x_C) \right]}_{\Psi_S(x_S)} \underbrace{\left[\prod_{C \in \mathfrak{C}_B} \psi_C(x_C) \right]}_{\Psi_B(x_B, x_S)}.$$

Defining the quantities

$$Z_{A}\left(x_{S}\right):=\sum_{x_{A}}\Psi_{A}\left(x_{A},x_{S}\right)\text{ and }Z_{B}\left(x_{S}\right):=\sum_{x_{B}}\Psi_{B}\left(x_{B},x_{S}\right),$$

we then obtain the following expressions for the marginal distributions of interest:

$$\begin{split} \rho\left(x_{S}\right) &= \frac{Z_{A}\left(x_{S}\right)Z_{B}\left(x_{S}\right)}{Z} \Psi_{S}\left(x_{S}\right), \\ \rho\left(x_{A}, x_{S}\right) &= \frac{Z_{B}\left(x_{S}\right)}{Z} \Psi_{A}\left(x_{A}, x_{S}\right) \Psi_{S}\left(x_{S}\right), \\ \rho\left(x_{B}, x_{S}\right) &= \frac{Z_{A}\left(x_{S}\right)}{Z} \Psi_{B}\left(x_{B}, x_{S}\right) \Psi_{S}\left(x_{S}\right). \end{split}$$

for any x_S for which $p(x_S) > 0$

$$\frac{p(x_A, x_S, x_B)}{p(x_S)} = \frac{\Psi_A(x_A, x_S)\Psi_B(x_B, x_S)}{Z_A(x_S)Z_B(x_S)},
\frac{p(x_A, x_S)}{p(x_S)} = \frac{\Psi_A(x_A, x_S)}{Z_A(x_S)},
\frac{p(x_B, x_S)}{p(x_S)} = \frac{\Psi_B(x_B, x_S)}{Z_B(x_S)}.
\Rightarrow p(x_A, x_B | x_S) = \frac{p(x_A, x_B, x_S)}{p(x_S)} = \frac{p(x_A, x_S)}{p(x_S)} \frac{p(x_B, x_S)}{p(x_S)}
= p(x_A | x_S) p(x_B | x_S).$$

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The graphical Lasso estimator

$$\widehat{\boldsymbol{\Theta}} \in \arg\min_{\boldsymbol{\Theta} \in \mathcal{S}^{d \times d}} \{ \underbrace{\langle \langle \boldsymbol{\Theta}, \widehat{\boldsymbol{\Sigma}} \rangle \rangle - \log \det \boldsymbol{\Theta}}_{\mathcal{L}_n(\boldsymbol{\Theta})} + \lambda_n \|\boldsymbol{\Theta}\|_{1, \mathrm{off}} \},$$

where $\|\mathbf{\Theta}\|_{1, \text{ off}} := \sum_{i \neq k} |\Theta_{ik}|$ corresponds to the ℓ_1 -norm applied to the off-diagonal entries of Θ .

The following result is based on a sample covariance matrix Σ formed from *n* i.i.d. samples $\{x_i\}_{i=1}^n$ of a zero-mean random vector in which each coordinate has σ -sub-Gaussian tails.

Theorem (11.9 Frobenius norm bounds for graphical Lasso)

Suppose that the inverse covariance matrix Θ^* has at most m non-zero entries per row, and we solve the graphical Lasso (11.10) with regularization parameter $\lambda_n = 8\sigma^2 \left(\sqrt{\frac{\log d}{n}} + \delta\right)$ for some $\delta \in (0,1]$. Then as long as $\left(\left\|\mathbf{\Theta}^*\right\|_2 + 1\right)^2 \lambda_n \sqrt{md} < 1$, the graphical Lasso estimate $\widehat{\Theta}$ satisfies

$$\left\|\widehat{\boldsymbol{\Theta}} - \boldsymbol{\Theta}^*\right\|_{\mathrm{F}}^2 \le \frac{9}{\left(\left\|\boldsymbol{\Theta}^*\right\|_2 + 1\right)^4} m d\lambda_n^2 \tag{11.11}$$

with probability at least $1 - 8e^{-\frac{1}{16}n\delta^2}$.

Proof

•
$$\mathbb{B}_F(1) = \left\{ \Delta \in \mathcal{S}^{d \times d} \mid ||\Delta||_F \leq 1 \right\}$$

•
$$\nabla \mathcal{L}_n(\mathbf{\Theta}) = \widehat{\Sigma} - \mathbf{\Theta}^{-1}$$
 and $\nabla^2 \mathcal{L}_n(\mathbf{\Theta}) = \mathbf{\Theta}^{-1} \otimes \mathbf{\Theta}^{-1}$

$$\underbrace{\mathcal{L}_{n}\left(\mathbf{\Theta}^{*}+\Delta\right)-\mathcal{L}_{n}\left(\mathbf{\Theta}^{*}\right)-\left\langle \left\langle \nabla\mathcal{L}_{n}\left(\mathbf{\Theta}^{*}\right),\Delta\right\rangle \right\rangle }_{\mathcal{E}_{n}\left(\Delta\right)}=$$

$$\frac{1}{2} \operatorname{vec}(\Delta)^{\mathrm{T}} \nabla^2 \mathcal{L}_n (\mathbf{\Theta}^* + t\Delta) \operatorname{vec}(\Delta)$$
 for some $t \in [0, 1]$

• $\|\mathbf{A}^{-1} \otimes \mathbf{A}^{-1}\|_2 = \frac{1}{\|\mathbf{A}\|_2^2}$ for any symmetric invertible matrix

Verifying restricted strong convexity

For any $\Delta \in \mathbb{B}_F(1)$,

$$\mathcal{E}_n(\Delta) \geq \frac{1}{2} \gamma_{\min} \left(\nabla^2 \mathcal{L}_n \left(\mathbf{\Theta}^* + t \Delta \right) \right) \| \operatorname{vec}(\Delta) \|_2^2 = \frac{1}{2} \frac{\|\Delta\|_F^2}{\left\| \mathbf{\Theta}^* + t \Delta \right\|_2^2}.$$

 $|t||\Delta||_2 \le t||\Delta||_F \le 1$ implies that $||\Theta^* + t\Delta||_2^2 \le (||\Theta^*||_2 + 1)^2$. Then

$$\mathcal{E}_n(\Delta) \ge \frac{\kappa}{2} \|\Delta\|_F^2 \quad \text{ where } \kappa := \left(\left\|\Theta^*\right\|_2 + 1\right)^{-2}$$

showing that the RSC condition from Definition 9.15 holds over $\mathbb{B}_F(1)$ with tolerance $\tau_n^2 = 0$.

Computing the subspace Lipschitz constant

Letting S denote the support set of Θ^* , we define the subspace $\mathbb{M}(S) = \{ \mathbf{\Theta} \in \mathbb{R}^{d \times d} \mid \Theta_{jk} = 0 \text{ for all } (j,k) \notin S \}.$ Then we have

$$\Psi^{2}(\mathbb{M}(S)) = \sup_{\boldsymbol{\Theta} \in \mathcal{M}(S)} \frac{\left(\sum_{j \neq k} \left| \boldsymbol{\Theta}_{jk} \right| \right)^{2}}{\left\| \boldsymbol{\Theta} \right\|_{F}^{2}} \leq \left| S \right| \stackrel{(i)}{\leq} \textit{md}.$$

where inequality (i) follows since Θ^* has at most m non-zero entries per row.

Verifying event $\mathbb{G}(\lambda_n)$

Using Lemma 6.26, we have

$$\mathbb{P}\left[\|\widehat{\Sigma} - \Sigma\|_{\text{max, off }} \geq \sigma^2 t\right] \leq 8e^{-\frac{\pi}{16}\min\{t,t^2\} + 2\log d} \quad \text{ for all } t > 0.$$

Setting $t = \lambda_n/\sigma^2$ shows that the event $\mathbb{G}(\lambda_n)$ from Corollary 9.20 holds with the claimed probability. Consequently, Proposition 9.13 implies that the error matrix Δ satisfies the bound $\|\widehat{\Delta}_{S^c}\|_1 \le 3 \|\widehat{\Delta}_S\|_1$, and hence $\|\widehat{\Delta}\|_1 \le 4 \|\widehat{\Delta}_S\|_1 \le 4 \sqrt{md} \|\widehat{\Delta}\|_F$, where the final inequality again uses the fact that $|S| \leq md$. In order to apply Corollary 9.20, the only remaining detail to verify is that $\widehat{\Delta}$ belongs to the Frobenius ball $\mathbb{B}_F(1)$.

Localizing the error matrix

The result of Exercise 9.10 then implies that

$$\left\langle \left\langle \nabla \mathcal{L}_{n}\left(\boldsymbol{\Theta}^{*} + \Delta\right) - \nabla \mathcal{L}_{n}\left(\boldsymbol{\Theta}^{*}\right), \Delta \right\rangle \right\rangle \geq \kappa \|\Delta\|_{F} \quad \text{ for all } \Delta \in \mathcal{S}^{d \times d} \backslash \mathbb{B}_{F}(1).$$

By the optimality of $\widehat{\mathbf{\Theta}}$, we have $0 = \langle \langle \nabla \mathcal{L}_n (\mathbf{\Theta}^* + \widehat{\Delta}) + \lambda_n \widehat{\mathbf{Z}}, \widehat{\mathbf{\Delta}} \rangle \rangle$, where $\widehat{\mathbf{Z}} \in \partial \|\widehat{\mathbf{\Theta}}\|_{1, \text{ off}}$. By adding and subtracting terms, we find that

$$\left\langle \left\langle \nabla \mathcal{L}_{n} \left(\mathbf{\Theta}^{*} + \widehat{\Delta} \right) - \nabla \mathcal{L}_{n} \left(\mathbf{\Theta}^{*} \right), \widehat{\Delta} \right\rangle \right\rangle \leq \lambda_{n} |\langle \widehat{\mathbf{Z}}, \widehat{\Delta} \rangle| + \left\langle \left\langle \nabla \mathcal{L}_{n} \left(\mathbf{\Theta}^{*} \right), \widehat{\Delta} \right\rangle \right\rangle \\
\leq \left\{ \lambda_{n} + \left\| \nabla \mathcal{L}_{n} \left(\mathbf{\Theta}^{*} \right) \right\|_{\text{max}} \right\} ||\widehat{\Delta}||_{1}.$$

the right-hand side is at most $\frac{3\lambda_n}{2}\|\widehat{\mathbf{\Delta}}\|_1 \leq 6\lambda_n \sqrt{md}\|\widehat{\mathbf{\Delta}}\|_F$. If $\|\widehat{\Delta}\|_F > 1$, then we obtain $\kappa \|\widehat{\Delta}\|_F \le \frac{3\lambda_n}{2} \|\widehat{\Delta}\|_1 \le 6\lambda_n \sqrt{md} \|\widehat{\Delta}\|_F$ This inequality leads to a contradiction whenever $\frac{6\lambda_n \sqrt{md}}{\pi}$ < 1, which completes the proof.

- $S := E \cup \{(j,j) \mid j \in V\}, S^c = (V \times V) \setminus S$.
- the matrix $\Gamma^* := \nabla^2 \mathcal{L}_n(\mathbf{\Theta}^*)$ is α -incoherent if $\max_{e \in S^c} \left\| \Gamma_{eS}^* \left(\mathbf{\Gamma}_{SS}^* \right)^{-1} \right\|_{1}^{\infty} \le 1 - \alpha \quad \text{ for some } \alpha \in (0, 1].$
- $\widehat{E} := \{(j, k) \in [d] \times [d] \mid j < k \text{ and } \widehat{\Theta}_{jk} \neq 0\}.$
- $||\mathbf{A}||_2 \le m+1$ for any graph of degree at most m.

Theorem (11.10)

Consider a zero-mean d-dimensional Gaussian distribution based on an α -incoherent inverse covariance matrix Θ^* . Given a sample size lower bounded as $n > c_0 (1 + 8\alpha^{-1})^2 m^2 \log d$, suppose that we solve the graphical Lasso (11.10) with a regularization parameter $\lambda_n = \frac{c_1}{\alpha} \, \sqrt{\frac{\log d}{n}} + \delta$ for some $\delta \in (0,1]$. Then with probability at least $1 - c_2 e^{-c_3 n \delta^2}$, we have the following: (a) The graphical Lasso solution leads to no false inclusions-that

- is, $\Theta_{ik} = 0$ for all $(j, k) \notin E$.
- (b) It satisfies the sup-norm bound

$$\left\|\widehat{\boldsymbol{\Theta}} - \boldsymbol{\Theta}^*\right\|_{\max} \le c_4 \{\underbrace{\left(1 + 8\alpha^{-1}\right)\sqrt{\frac{\log d}{n}}}_{\tau(n,d,\alpha)} + \lambda_n\}. \tag{11.16}$$

Corollary (11.11)

Under the conditions of Proposition 11.10, consider the graphical Lasso estimate $\widehat{\Theta}$ with regularization parameter $\lambda_n = \frac{c_1}{\alpha} \sqrt{\frac{\log d}{n}} + \delta$ for some $\delta \in (0,1]$. Then with probability at least $1 - c_2 e^{-c_3 n \delta^2}$. we have

$$\left\|\widehat{\boldsymbol{\Theta}} - \boldsymbol{\Theta}^*\right\|_2 \le c_4 \|\mathbf{A}\|_2 \left\{ \left(1 + 8\alpha^{-1}\right) \sqrt{\frac{\log d}{n}} + \lambda_n \right\}, \qquad (11.17a)$$

where A denotes the adjacency matrix of the graph G (including ones on the diagonal). In particular, if the graph has maximum degree m, then

$$\left\|\widehat{\boldsymbol{\Theta}} - \boldsymbol{\Theta}^*\right\|_2 \le c_4(m+1)\left\{\left(1 + 8\alpha^{-1}\right)\sqrt{\frac{\log d}{n}} + \lambda_n\right\}. \quad (11.17b)$$

Neighborhood-based methods

•
$$\mathcal{N}^+(j) := \{j\} \cup \mathcal{N}(j), X_j \perp X_{V \setminus \mathcal{N}^+(j)} \mid X_{\mathcal{N}(j)}.$$

Lasso-based neighborhood regression:

- 1 For each node $i \in V$:
- (a) Extract the column vector $X_i \in \mathbb{R}^n$ and the submatrix
- $\mathbf{X}_{\backslash \{i\}} \in \mathbb{R}^{n \times (d-1)}$.
- (b) Solve the Lasso problem:

$$\widehat{\theta} = \arg\min_{\theta \in \mathbb{R}^{d-1}} \left\{ \frac{1}{2n} \left\| X_j - \mathbf{X}_{\setminus \{j\}} \theta \right\|_2^2 + \lambda_n \|\theta\|_1 \right\}.$$

- (c) Return the neighborhood estimate $\widehat{\mathcal{N}}(j) = \{k \in V \setminus \{j\} \mid \widehat{\theta}_k \neq 0\}.$
- 2 Combine the neighborhood estimates to form an edge estimate \widehat{E} , using either the OR rule or the AND rule.

Assume diag $(\Sigma^*) \le 1$ and $n \ge m \log d$.

Theorem (11.12)

Consider a zero-mean Gaussian random vector with covariance $\pmb{\Sigma}^*$ such that for each $j \in V$, the submatrix $\pmb{\Sigma}^*_{\backslash \{j\}} := \mathsf{cov}\left(\pmb{X}_{\backslash \{j\}}\right)$ is lpha-incoherent with respect to $\mathcal{N}(j)$, and $\left\|\left(\Sigma_{\mathcal{N}(j),\mathcal{N}(j)}^*\right)^{-1}\right\| \ \leq b$ for some $b \ge 1$. Suppose that the neighborhood Lasso selection method is implemented with $\lambda_n = c_0 \left\{ \frac{1}{lpha} \, \sqrt{\frac{\log d}{n}} + \delta \right\}$ for some $\delta \in (0,1]$. Then with probability greater than $1 - c_2 e^{-c_3 n \min\{\delta^2, \frac{1}{m}\}}$, the estimated edge set E, based on either the AND or OR rules, has the following properties: (a) No false inclusions: it includes no false edges, so that $E \subseteq E$. (b) All significant edges are captured: it includes all edges (j, k) for which $\left|\Theta_{jk}^*\right| \ge 7b\lambda_n$.

•
$$\mathbf{\Gamma}^* = \operatorname{cov}\left(X_{\setminus\{j\}}\right), \widehat{\mathbf{\Gamma}} = \frac{1}{n} \mathbf{X}_{\setminus\{j\}}^{\mathrm{T}} \mathbf{X}_{\setminus\{j\}}, S = \mathcal{N}(j), S^c = V \setminus \mathcal{N}^+(j).$$

• $\widehat{\Gamma}_{SS}$:= the submatrix indexed by the subset S.

Proof of part (a)

We follow the proof of Theorem 7.21 until equation (7.53), namely

$$\widehat{\boldsymbol{z}}_{S^c} = \underbrace{\widehat{\boldsymbol{\Gamma}}_{S^cS} \left(\widehat{\boldsymbol{\Gamma}}_{SS}\right)^{-1} \widehat{\boldsymbol{z}}_{S}}_{\mu \in \mathbb{R}^{d-s}} + \underbrace{\boldsymbol{X}_{S^c}^T \left[\boldsymbol{I}_n - \boldsymbol{X}_S \left(\boldsymbol{X}_S^T \boldsymbol{X}_S\right)^{-1} \boldsymbol{X}_S^T\right] \left(\frac{W_j}{\lambda_n n}\right)}_{V_{S^c} \in \mathbb{R}^{d-s}}$$

As argued in Chapter 7, in order to establish that the Lasso support is included within S, it suffices to establish the strict dual feasibility condition $\|\widehat{z}_{S}\|_{\infty} < 1$. We do so by establishing that

$$\mathbb{P}\left[||\mu||_{\infty} \ge 1 - \frac{3}{4}\alpha\right] \le c_1 e^{-c_2 n\alpha^2 - \log d},\tag{11.25a}$$

$$\mathbb{P}\left[\|V_{S^c}\|_{\infty} \ge \frac{\alpha}{4}\right] \le c_1 e^{-c_2 n \delta^2 \alpha^2 - \log d}. \tag{11.25b}$$

Taken together, these bounds ensure that $\|\bar{z}_{S^c}\|_{\infty} \leq 1 - \frac{\alpha}{2} < 1$, and hence that the Lasso support is contained within S = N(j), with probability at least $1 - c_1 e^{-c_2 n \delta^2 \alpha^2 - \log d}$, where the values of the universal constants may change from line to line. Taking the union bound over all d vertices, we conclude that $\widehat{E} \subseteq E$ with probability at least $1 - c_1 e^{-c_2 n \delta^2 \alpha^2}$.

Proof of (11.25a): $\mathbf{X}_{S^c}^T = \mathbf{\Gamma}_{S^cS}^* (\mathbf{\Gamma}_{SS}^*)^{-1} \mathbf{X}_S^T + \tilde{\mathbf{W}}_{S^c}^T$, where $\tilde{\mathbf{W}}_{S^c} \in \mathbb{R}^{n \times |S^c|}$ is a zero-mean Gaussian random matrix that is independent of X_S . Since

 $\operatorname{cov}\left(\tilde{\mathbf{W}}_{S^c}\right) = \mathbf{\Gamma}^*_{S^cS^c} - \mathbf{\Gamma}^*_{S^cS}\left(\mathbf{\Gamma}^*_{SS}\right)^{-1} \mathbf{\Gamma}^*_{SS^c} \leq \mathbf{\Gamma}^* \text{ and diag } (\mathbf{\Gamma}^*) \leq 1, \text{ we}$ see that the elements of $\tilde{\mathbf{W}}_{S^c}$ have variance at most 1.

$$\|\mu\|_{\infty} = \left\| \mathbf{\Gamma}_{S^{c}S}^{*} \left(\mathbf{\Gamma}_{SS}^{*} \right)^{-1} \widehat{\mathbf{z}}_{S} + \frac{\widetilde{\mathbf{W}}_{S^{c}}^{T}}{\sqrt{n}} \frac{\mathbf{X}_{S}}{\sqrt{n}} \left(\widehat{\mathbf{\Gamma}}_{SS} \right)^{-1} \widehat{\mathbf{z}}_{S} \right\|_{\infty}$$

$$\stackrel{(i)}{\leq} \left(1 - \alpha \right) + \| \underbrace{\frac{\widetilde{\mathbf{W}}_{S^{c}}^{T}}{\sqrt{n}} \frac{\mathbf{X}_{S}}{\sqrt{n}} \left(\widehat{\mathbf{\Gamma}}_{SS} \right)^{-1} \widehat{\mathbf{z}}_{S}}_{V \in \mathbb{P}^{|S^{c}|}} \|_{\infty}$$

$$(11.27)$$

$$\frac{1}{\sqrt{n}} \left\| \frac{\mathbf{X}_{S}}{\sqrt{n}} \left(\widehat{\mathbf{\Gamma}}_{SS} \right)^{-1} \widehat{\mathbf{Z}}_{S} \right\|_{2} \leq \frac{1}{\sqrt{n}} \left\| \frac{\mathbf{X}_{S}}{\sqrt{n}} \left(\widehat{\mathbf{\Gamma}}_{SS} \right)^{-1} \right\|_{2} \left\| \widehat{\mathbf{Z}}_{S} \right\|_{2} \\
\leq \frac{1}{\sqrt{n}} \sqrt{\left\| \left(\widehat{\mathbf{\Gamma}}_{SS} \right)^{-1} \right\|_{2}} \sqrt{m} \\
\leq 2 \sqrt{\frac{bm}{n}},$$

where inequality (i) follows with probability at least $1 - 4e^{-c_1n}$, using standard bounds on Gaussian random matrices (see Theorem 6.1). Using this upper bound to control the conditional variance of V, standard Gaussian tail bounds and the union bound then ensure that

$$\mathbb{P}\left[\|\widetilde{V}\|_{\infty} \geq t\right] \leq 2\left|S^{c}\right| e^{-\frac{nn^{2}}{8bm}} \leq 2e^{-\frac{nn^{2}}{8bm} + \log d}.$$

We now set $t = \left[\frac{64bm\log d}{n} + \frac{1}{64}\alpha^2\right]^{1/2}$, a quantity which is less than $\frac{\alpha}{4}$ as long as $n \ge c \frac{bm \log d}{\alpha}$ for a sufficiently large universal constant. Thus, we have established that $\|\widetilde{V}\|_{\infty} \leq \frac{\alpha}{4}$ with probability at least $1 - c_1 e^{-c_2 n\alpha^2 - \log d}$. Combined with the earlier bound (11.27), the claim (11.25a) follows.

$$V_{S^c} = \tilde{\mathbf{W}}_{S^c}^{\mathrm{T}} \mathbf{\Pi} \left(\frac{W_j}{\lambda_n n} \right),$$

where $\tilde{\mathbf{W}}_{S^c} \in \mathbb{R}^{|S^c|}$ is independent of Π and W_j . Since Π is a projection matrix, we have $\|\Pi W_j\|_2 \leq \|W_j\|_2$. The vector $W_j \in \mathbb{R}^n$ has i.i.d. Gaussian entries with variance at most 1, and hence the event $\mathcal{E} = \left\{ \frac{||W_j||_2}{\sqrt{n}} \leq 2 \right\}$ holds with probability at least $1 - 2e^{-n}$. Conditioning on this event and its complement, we find that

$$\mathbb{P}\left[\|V_{S^c}\|_{\infty} \geq t\right] \leq \mathbb{P}\left[\|V_{S^c}\|_{\infty} \geq t \mid \mathcal{E}\right] + 2e^{-c_3n}.$$

Conditioned on \mathcal{E} , each element of V_{S^c} has variance at most $\frac{4}{\lambda^2 n}$, and hence

$$\mathbb{P} \left[\|V_{S^c}\|_{\infty} \geq \frac{\alpha}{4} \right] \leq 2e^{-\frac{\lambda_n^2 n^2}{256} + \log \left|S^c\right|} + 2e^{-n},$$

where we have combined the union bound with standard Gaussian tail bounds. Since $\lambda_n = c_0 \left\{ rac{1}{lpha} \, \sqrt{rac{\log d}{n}} + \delta
ight\}$ for a universal constant c_0 that may be chosen, we can ensure that $\frac{\lambda_n^2 n \alpha^2}{256} \ge c_2 n \alpha^2 \delta^2 + 2 \log d$ for some constant c_2 , for which it follows that

$$\mathbb{P}\bigg[\|V_{S^c}\|_{\infty} \geq \frac{\alpha}{4}\bigg] \leq c_1 e^{-c_2 n \delta^2 \alpha^2 - \log d} + 2e^{-n}.$$

Proof of part (b)

It suffices to establish ℓ_{∞} -bounds on the error in the Lasso solution. Here we provide a proof in the case $m \leq \log d$. Again returning to the proof of Theorem 7.21, equation (7.54) guarantees that

$$\begin{aligned} \left\| \widehat{\boldsymbol{\theta}}_{S} - \boldsymbol{\theta}_{S}^{*} \right\|_{\infty} &\leq \left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} \boldsymbol{X}_{S}^{T} \frac{\boldsymbol{W}_{j}}{n} \right\|_{\infty} + \lambda_{n} \left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} \right\|_{\infty} \\ &\leq \left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} \boldsymbol{X}_{S}^{T} \frac{\boldsymbol{W}_{j}}{n} \right\|_{\infty} + \lambda_{n} \left\{ \left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} - \left(\boldsymbol{\Gamma}_{SS}^{*} \right)^{-1} \right\|_{\infty} + \left\| \left(\boldsymbol{\Gamma}_{SS}^{*} \right)^{-1} \right\| \end{aligned}$$

$$(11.28)$$

Now for any symmetric $m \times m$ matrix, we have

$$\|\mathbf{A}\|_{\infty} = \max_{i=1,...,m} \sum_{\ell=1}^{m} |A_{i\ell}| \le \sqrt{m} \max_{i=1,...,m} \sqrt{\sum_{\ell=1}^{m} |A_{i\ell}|^2} \le \sqrt{m} \|\mathbf{A}\|_2$$

Applying this bound to the matrix $\mathbf{A} = (\widehat{\mathbf{\Gamma}}_{SS})^{-1} - (\mathbf{\Gamma}_{SS}^*)^{-1}$, we find

$$\left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} - \left(\boldsymbol{\Gamma}_{SS}^* \right)^{-1} \right\|_{\infty} \le \sqrt{m} \left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} - \left(\boldsymbol{\Gamma}_{SS}^* \right)^{-1} \right\|_{2}. \tag{11.29}$$

Since $\|\Gamma_{SS}^*\|_2 \le \|\Gamma_{SS}^*\|_{\infty} \le b$, applying the random matrix bound from Theorem 6.1 allows us to conclude that

$$\left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} - \left(\boldsymbol{\Gamma}_{SS}^* \right)^{-1} \right\|_2 \le 2b \left(\sqrt{\frac{m}{n}} + \frac{1}{\sqrt{m}} + 10 \sqrt{\frac{\log d}{n}} \right),$$

with probability at least $1 - c_1 e^{-c_2 \frac{n}{m} - \log d}$. Combined with the earlier bound (11.29), we find that

$$\left\| \left(\widehat{\boldsymbol{\Gamma}}_{SS} \right)^{-1} - \left(\boldsymbol{\Gamma}_{SS}^* \right)^{-1} \right\|_{\infty} \le 2b \left(\sqrt{\frac{m^2}{n}} + 1 + 10 \sqrt{\frac{m \log d}{n}} \right) \stackrel{(i)}{\le} 6b, \tag{11.30}$$

Estimation of Gaussian graphical models

where inequality (i) uses the assumed lower bound $n \gtrsim m \log d \ge m^2$. Putting together the pieces in the bound (11.28) leads to

$$\left\|\widehat{\theta}_{S} - \theta_{S}^{*}\right\|_{\infty} \leq \left\|\underbrace{\left(\widehat{\Gamma}_{SS}\right)^{-1} \mathbf{X}_{S}^{T} \frac{W_{j}}{n}}_{U_{S}}\right\|_{\infty} + 7b\lambda_{n}.$$
(11.31)

Now the vector $W_i \in \mathbb{R}^n$ has i.i.d. Gaussian entries, each zero-mean with variance at most var $(X_i) \leq 1$, and is independent of X_S . Consequently, conditioned on X_S , the quantity U_S is a zero-mean Gaussian m -vector, with maximal variance

$$\frac{1}{n}\left\|\operatorname{diag}\left(\widehat{\boldsymbol{\Gamma}}_{SS}\right)^{-1}\right\|_{\infty} \leq \frac{1}{n}\left\{\left\|\left(\widehat{\boldsymbol{\Gamma}}_{SS}\right)^{-1} - \left(\boldsymbol{\Gamma}_{SS}^{*}\right)^{-1}\right\|_{\infty} + \left\|\left(\boldsymbol{\Gamma}_{SS}^{*}\right)^{-1}\right\|_{\infty}\right\} \leq \frac{7b}{n},$$

where we have combined the assumed bound $\left\| \left(\mathbf{\Gamma}_{SS}^* \right)^{-1} \right\| \leq b$ with the inequality (11.30).

$$\mathbb{P}\left[\|U_{S}\|_{\infty} \geq b\lambda_{n}\right] \leq 2|S|e^{-\frac{n\lambda_{n}^{2}}{14}} \stackrel{(i)}{\leq} c_{1}e^{-c_{2}nb\delta^{2}-\log d},$$

where, as in our earlier argument, inequality (i) can be guaranteed by a sufficiently large choice of the pre-factor c_0 in the definition of λ_n . Substituting back into the earlier bound (11.31), we find that $\left\|\widehat{\theta}_S - \theta_S^* \right\|_{L^2} \le 7b\lambda_n$ with probability at least $1 - c_1 e^{-c_2 n \{\delta^2 \wedge \frac{1}{m}\} - \log d}$. Finally, taking the union bound over all vertices $j \in V$ causes a loss of at most a factor log d in the exponent.

- Some basics
- 2 Estimation of Gaussian graphical models
- 3 Graphical models in exponential form
- 4 Graphs with corrupted or hidden variables

Let us now move beyond the Gaussian case, and consider the graph estimation problem for a more general class of graphical models that can be written in an exponential form. In particular, for a given graph G = (V, E), consider probability densities that have a pairwise factorization of the form

$$p_{\mathbf{\Theta}^*}(x_1,\ldots,x_d) \propto \exp \left\{ \sum_{j\in V} \phi_j(x_j;\Theta_j^*) + \sum_{(j,k)\in E} \phi_{jk}(x_j,x_k;\mathbf{\Theta}_{jk}^*) \right\},$$

Example 11.4(Ising model)

$$p(x_1,...,x_d;\theta^*) \propto \exp \left\{ \sum_{j \in V} \theta_j^* x_j + \sum_{(j,k) \in E} \theta_{jk}^* x_j x_k \right\}$$

A general form of neighborhood regression

- We can form a matrix $\mathbf{X} \in \mathbb{R}^{n \times d}$ with x_i^T as the *i* th row. For j = 1, ..., d, we let $X_i \in \mathbb{R}^n$ denote the j th column of X. Neighborhood regression is based on predicting the column $X_j \in \mathbb{R}^n$ using the columns of the submatrix $\mathbf{X}_{\setminus \{i\}} \in \mathbb{R}^{n \times (d-1)}$.
- Consider the conditional likelihood of $X_i \in \mathbb{R}^n$ given $\mathbf{X}_{\setminus (i)} \in \mathbb{R}^{n \times (d-1)}$, this conditional likelihood depends only on the vector of parameters

$$\mathbf{\Theta}_{j+} := \left\{ \Theta_j, \mathbf{\Theta}_{jk}, k \in V \setminus \{j\} \right\}$$

Moreover, in the true model Θ^* , we are guaranteed that $\Theta^*_{ik} = 0$ whenever $(i, k) \notin E$, so that it is natural to impose some type of block-based sparsity penalty on Θ_{i+} .

$$\widehat{\boldsymbol{\Theta}}_{j+} = \arg\min_{\boldsymbol{\Theta}_{j+}} \left\{ \underbrace{-\frac{1}{n} \sum_{i=1}^{n} \log p_{\boldsymbol{\Theta}_{j+}} \left(x_{ij} \mid x_{i \setminus \{j\}} \right)}_{\mathcal{L}_{n} \left(\boldsymbol{\Theta}_{j+}; x_{j,}, x_{\setminus \{j\}} \right)} + \lambda_{n} \sum_{k \in V \setminus \{j\}} \left\| \boldsymbol{\Theta}_{jk} \right\}.$$

Especially, or the Ising model, the neighborhood regression estimate:

$$\widehat{\theta}_{j+} = \arg\min_{\theta_{j+} \in \mathbb{R}^d} \left\{ \frac{1}{n} \sum_{i=1}^n f\left(\theta_j x_{ij} + \sum_{k \in V \setminus \{j\}} \theta_{jk} x_{ij} x_{ik}\right) + \lambda_n \sum_{k \in V \setminus \{j\}} \left|\theta_{jk}\right| \right\}$$

where $f(t) = \log(1 + e^t)$ is the logistic function.

Let θ_{i+}^* denote the minimizer of the population objective function $\overline{\mathcal{L}}(\theta_{i+}) = \mathbb{E}\left[\mathcal{L}_n\left(\theta_{i+}; X_i, \mathbf{X}_{\setminus\{i\}}\right)\right]$. We then consider the Hessian of the cost function $\overline{\mathcal{L}}$ evaluated at the "true parameter" θ_{i+}^* -namely, the *d*-dimensional matrix $\mathbf{J} := \nabla^2 \overline{\mathcal{L}} \left(\theta_{i+}^* \right)$.

• For a given $\alpha \in (0,1]$, we say that **J** satisfies an α -incoherence condition at node $i \in V$ if

$$\max_{k \notin S} \left\| J_{kS} \left(\mathbf{J}_{SS} \right)^{-1} \right\|_{1} \leq 1 - \alpha,$$

- We assume the submatrix J_{SS} has its smallest eigenvalue lower bounded by some $c_{\min} > 0$.
- The following result applies to an Ising model defined on a graph G with d vertices and maximum degree at most m.

Theorem 11.15 Given *n* i.i.d. samples with $n > c_0 m^2 \log d$, consider the estimator with $\lambda_n = \frac{32}{\alpha} \sqrt{\frac{\log d}{n}} + \delta$ for some $\delta \in [0, 1]$. Then with probability at least $1 - c_1 e^{-c_2(n\delta^2 + \log d)}$, the estimate $\widehat{\theta}_{i+}$ has the following properties:

- (a) It has a support $\widehat{S} = \operatorname{supp}(\widehat{\theta})$ that is contained within the neighborhood set $\mathcal{N}(i)$.
- (b) It satisfies the ℓ_{∞} -bound $\|\widehat{\theta}_{j+} \theta_{j+}^*\|_{\infty} \leq \frac{c_3}{c_{\min}} \sqrt{m} \lambda_n$.

Part (a) guarantees that the method leads to no false inclusions. On the other hand, the ℓ_{∞} -bound in part (b) ensures that the method picks up all significant variables.

- 4 Graphs with corrupted or hidden variables

Let us begin our exploration with the case of corrupted data. Letting $\mathbf{X} \in \mathbb{R}^{n \times d}$ denote the data matrix corresponding to the original samples, suppose that we instead observe a corrupted version **Z**. In the simplest case, we might observe $\mathbf{Z} = \mathbf{X} + \mathbf{V}$, where the matrix **V** represents some type of measurement error.

$$\widehat{\boldsymbol{\Theta}}_{\mathrm{NAI}} = \arg\min_{\boldsymbol{\Theta} \in \mathcal{S}^{d \times d}} \left\{ \left\langle \boldsymbol{\Theta}, \widehat{\boldsymbol{\Sigma}}_{\mathcal{Z}} \right\rangle \right\} - \log \det \boldsymbol{\Theta} + \lambda_{n} \|\boldsymbol{\Theta}\|_{1, \, \mathsf{off}} \, \right\}$$

where
$$\widehat{\boldsymbol{\Sigma}}_{z} = \frac{1}{n} \mathbf{Z}^{\mathrm{T}} \mathbf{Z} = \frac{1}{n} \sum_{i=1}^{n} z_{i} z_{i}^{\mathrm{T}}$$
.

More generally, any unbiased estimate $\widehat{\Gamma}$ of Σ_{\sim} :

$$\widetilde{\Theta} = \arg\min_{\Theta \in \mathcal{S}_{+}^{d \times d}} \{\langle \Theta, \widehat{\Gamma} \rangle \rangle - \log \det \Theta + \lambda_n \|\Theta\|_{1, \text{ off }} \right\}.$$

Unbiased covariance estimate

In order to obtain a consistent estimator, we need to replace Σ_{7} with an unbiased estimator of cov(x) based on the observed data matrix **Z**. In order to develop intuition, let us explore an example. Suppose that each row v_i of the noise matrix **V** is drawn i.i.d. from a zero-mean distribution, say with covariance Σ_{ν} .

$$\widehat{\boldsymbol{\Gamma}} := \frac{1}{n} \mathbf{Z}^{\mathrm{T}} \mathbf{Z} - \boldsymbol{\Sigma}_{v}.$$

As long as the noise matrix **V** is independent of **X**, then $\widehat{\Gamma}$ is an unbiased estimate of Σ_x .

Missing data

Example 11.17 (Missing data) In other settings, some entries of the data matrix **X** might be missing, with the remaining entries observed. In the simplest model of missing data known as missing completely at random-entry (i, j) of the data matrix is missing with some probability $v \in [0, 1)$.

$$\widetilde{Z}_{ij} = \begin{cases} \frac{Z_{ij}}{1-v} & \text{if entry } (i,j) \text{ is observed,} \\ 0 & \text{otherwise.} \end{cases}$$

With this choice, it can be verified that

$$\widehat{\boldsymbol{\Gamma}} = \frac{1}{n} \widetilde{\mathbf{Z}}^{\mathrm{T}} \widetilde{\mathbf{Z}} - v \operatorname{diag} \left(\frac{\widetilde{\mathbf{Z}}^{\mathrm{T}} \widetilde{\mathbf{Z}}}{n} \right)$$

linear regression

In order to obtain a consistent form of linear regression, consider the following population-level objective function

$$\overline{\mathcal{L}}(\theta) = \frac{1}{2} \theta^T \mathbf{\Gamma} \theta - \langle \theta, \gamma \rangle,$$

where $\Gamma := cov(x)$ and $\gamma := cov(x, y)$. By construction, the true regression vector is the unique global minimizer of $\overline{\mathcal{L}}$. Thus

$$\mathcal{L}_n(\theta) = \frac{1}{2} \theta^T \widehat{\mathbf{\Gamma}} \theta - \langle \theta, \widehat{\gamma} \rangle.$$

As in our analysis of the ordinary Lasso from Chapter 7, we impose a restricted eigenvalue (RE) condition on the covariance estimate $\widehat{\Gamma}$: more precisely, we assume that there exists a constant $\kappa > 0$ such that

$$\langle \Delta, \widehat{\Gamma} \Delta \rangle \ge \kappa ||\Delta||_2^2 - c_0 \frac{\log d}{n} ||\Delta||_1^2 \quad \text{for all } \Delta \in \mathbb{R}^d.$$

Proposition 11.18 Under the RE condition, suppose that the pair $(\widehat{\gamma}, \widehat{\Gamma})$ satisfy the deviation condition

$$\left\|\widehat{\Gamma}\theta^* - \widehat{\gamma}\right\|_{\max} \leq \varphi\left(\mathbb{Q}, \sigma_w\right) \sqrt{\frac{\log d}{n}},$$

for a pre-factor $\varphi\left(\mathbb{Q},\sigma_{w}\right)$ depending on the conditional distribution \mathbb{Q} and noise standard deviation σ_{w} . Then for any regularization parameter $\lambda_{n}\geq 2\left(2c_{0}+\varphi\left(\mathbb{Q},\sigma_{w}\right)\right)\sqrt{\frac{\log d}{n}}$, any local optimum $\widetilde{\theta}$ to the program (11.48) satisfies the bound

$$\left\|\widetilde{\theta} - \theta^*\right\|_2 \le \frac{2}{\kappa} \sqrt{s} \lambda_n.$$

Proof:

 $\left\langle \widehat{\Delta}, \nabla \mathcal{L}_{n}\left(\boldsymbol{\theta}^{*} + \widehat{\Delta}\right) - \nabla \mathcal{L}_{n}\left(\boldsymbol{\theta}^{*}\right) \right\rangle \leq \left|\left\langle \widehat{\Delta}, \nabla \mathcal{L}_{n}\left(\boldsymbol{\theta}^{*}\right) \right\rangle\right| - \lambda_{n}\langle \widehat{\boldsymbol{z}}, \widehat{\Delta} \rangle$ $\leq \|\widehat{\Delta}\|_{1} \|\nabla \mathcal{L}_{n}\left(\theta^{*}\right)\|_{\infty} + \lambda_{n} \{\|\theta^{*}\|_{1} - \|\widetilde{\theta}\|_{1}$

- $\|\theta^*\|_1 \|\widetilde{\theta}\|_1 \le \|\widehat{\Delta}_S\|_1 \|\widehat{\Delta}_S\|_1$. (Theorem 7.8)
- Since θ^* is s-sparse, we have $\|\theta^*\|_1 \le \sqrt{s} \|\theta^*\|_2 \le \sqrt{\frac{n}{\log d}}$, where the final inequality follows from the assumption that $n \ge s \log d$. Consequently, we have

$$\|\widehat{\Delta}\|_1 \le \|\widehat{\theta}\|_1 + \|\theta^*\|_1 \le 2\sqrt{\frac{n}{\log d}}.$$

• $\langle \widehat{\Delta}, \widehat{\Gamma \Delta} \rangle \ge \kappa ||\widehat{\Delta}||_2^2 - c_0 \frac{\log d}{n} ||\widehat{\Delta}||_1^2 \ge \kappa ||\widehat{\Delta}||_2^2 - 2c_0 \sqrt{\frac{\log d}{n}} ||\widehat{\Delta}||_1.$

Gaussian graph selection with hidden variables

Consider a family of d + r random variables-say written as X := $(X_1, \ldots, X_d, X_{d+1}, \ldots, X_{d+r})$ and suppose that this full vector can be modeled by a sparse graphical model with d + r vertices. Now suppose that we observe only the subvector $X_0 := (X_1, \dots, X_d)$, with the other components $X_H := (X_{d+1}, \dots, X_{d+r})$ staying hidden.

$$\mathbf{\Theta}^{\diamond} = \begin{bmatrix} \mathbf{\Theta}_{\mathrm{OO}}^{\diamond} & \mathbf{\Theta}_{\mathrm{OH}}^{\diamond} \\ \mathbf{\Theta}_{\mathrm{HO}}^{\diamond} & \mathbf{\Theta}_{\mathrm{HH}}^{\diamond} \end{bmatrix}.$$

$$\mathbf{E}_{\mathrm{OO}}^{*} = \begin{bmatrix} \mathbf{\Theta}_{\mathrm{OO}}^{\circ} - \mathbf{\Theta}_{\mathrm{OH}}^{\circ} \left(\mathbf{\Theta}_{\mathrm{HH}}^{\circ} \right)^{-1} \mathbf{\Theta}_{\mathrm{HO}}^{\circ} \end{bmatrix}.$$

$$\left(\boldsymbol{\Sigma}_{\mathrm{OO}}^{*}\right)^{\!-1} = \underbrace{\boldsymbol{\Theta}_{\mathrm{OO}}^{\circ}}_{\boldsymbol{\Gamma}^{*}} - \underbrace{\boldsymbol{\Theta}_{\mathrm{OH}}^{\circ}\left(\boldsymbol{\Theta}_{\mathrm{HH}}^{\circ}\right)^{\!-1}\boldsymbol{\Theta}_{\mathrm{HO}}^{\circ}}_{\boldsymbol{\Lambda}^{*}}.$$

The Hammersley-Clifford theorem implies that the inverse covariance matrix Θ^{\diamond} of the full vector $X = (X_0, X_H)$ is sparse. By our modeling assumptions, the matrix $\Gamma^* := \Theta_{00}^{\circ}$ is sparse.

When n > d, then the sample covariance matrix $\widehat{\Sigma} = \frac{1}{n} \sum_{i=1}^{n} x_i x_i^T$ will be invertible with high probability, and hence setting $\mathbf{Y} := (\widehat{\boldsymbol{\Sigma}})^{-1}$, we can consider an observation model of the form

$$\boldsymbol{Y} = \boldsymbol{\Gamma}^* - \boldsymbol{\Lambda}^* + \boldsymbol{W}.$$

For a threshold $v_n > 0$ to be chosen, we define the estimates

$$\widehat{\Gamma}:=T_{\nu_n}ig((\widehat{oldsymbol{\Sigma}})^{-1}ig)$$
 and $\widehat{oldsymbol{\Lambda}}:=\widehat{oldsymbol{\Gamma}}-(\widehat{oldsymbol{\Sigma}})^{-1}.$

Here the hard-thresholding operator is given by $T_{V_n}(v) = vI[|v| > v_n].$

• (A2)
$$\left\| \sqrt{\Theta^*} \right\|_{\infty} = \max_{j=1,\dots,d} \sum_{k=1}^d \left| \sqrt{\Theta^*} \right|_{jk} \leq \sqrt{M}$$

• (A3)
$$v_n := M\left(4\sqrt{\frac{\log d}{n}} + \delta\right) + \frac{\alpha}{d}$$
 for some $\delta \in [0, 1]$

Proposition 11.19 Consider a precision matrix Θ^* that can be decomposed as the difference $\Gamma^* - \Lambda^*$. Given n > d i.i.d. samples from the $\mathcal{N}(0, (\boldsymbol{\Theta}^*)^{-1})$ distribution and any $\delta \in (0, 1]$

$$\left\|\widehat{\mathbf{\Gamma}} - \mathbf{\Gamma}^*\right\|_{\max} \le 2M\left(4\sqrt{\frac{\log d}{n}} + \delta\right) + \frac{2\alpha}{d}$$

and

$$\|\widehat{\mathbf{\Lambda}} - \mathbf{\Lambda}^*\|_2 \le M \left(2\sqrt{\frac{d}{n}} + \delta \right) + s \|\widehat{\mathbf{\Gamma}} - \mathbf{\Gamma}^*\|_{\text{max}}$$

with probability at least $1 - c_1 e^{-c_2 n\delta^2}$.

Proof

$$\begin{split} \bullet & (\widehat{\boldsymbol{\Sigma}})^{-1} - \boldsymbol{\Theta}^* = \sqrt{\boldsymbol{\Theta}^*} \left\{ n^{-1} \mathbf{V}^T \mathbf{V} - \mathbf{I}_d \right\} \sqrt{\boldsymbol{\Theta}^*} \\ & \left\| (\widehat{\boldsymbol{\Sigma}})^{-1} - \boldsymbol{\Theta}^* \right\|_{\max} = \max_{j,k=1,\dots,d} \left\| e_j^T \sqrt{\boldsymbol{\Theta}^*} \widetilde{\boldsymbol{\Sigma}} \sqrt{\boldsymbol{\Theta}^*} e_k \right\| \\ & \leq \max_{j,k=1,\dots,d} \left\| \sqrt{\boldsymbol{\Theta}^*} e_j \right\|_1 \left\| \widetilde{\boldsymbol{\Sigma}} \sqrt{\boldsymbol{\Theta}^*} e_k \right\|_{\infty} \\ & \leq \|\widetilde{\boldsymbol{\Sigma}}\|_{\max} \max_{j=1,\dots,d} \left\| \sqrt{\boldsymbol{\Theta}^*} e_j \right\|_1^2. \\ & \left\| \widehat{\boldsymbol{\Gamma}} - \boldsymbol{\Gamma}^* \right\|_{\max} \leq \left\| \mathbf{Y} - \boldsymbol{\Theta}^* \right\|_{\max} + \left\| \mathbf{Y} - T_{v_n}(\mathbf{Y}) \right\|_{\max} + \left\| \boldsymbol{\Lambda}^* \right\|_{\max} \\ & \leq M \left(4 \sqrt{\frac{\log d}{n}} + \delta \right) + v_n + \frac{\alpha}{d} \\ & \leq 2M \left(4 \sqrt{\frac{\log d}{n}} + \delta \right) + \frac{2\alpha}{d} \end{split}$$