Eric Dinh

April 21, 2017

ECE465-001

Socket-based Remote Controller for Drones

Hardware and Software Settings

Development PC

CPU Intel i5-3570K

RAM 16 GB

OS Windows 8.1 Professional

Software VMWare Workstation Pro 12.0.0

Programming Language C

Server/Client Virtual Machines

CPU 1 Processor/2 Cores

RAM 4 GB

OS Ubuntu 16.04.02 LTS

Required Packages git, build-essential, autoconf, libtool, libavahi-

client-dev, mplayer, libavcodec-dev, libavformat-dev,

libswscale-dev, libncurses5-dev, unzip

Transport Protocol Between Client and Server

UDP was used as the transport protocol between the server and client. This protocol was chosen since using a controller does not require 100% packet transmission. When using a controller, inputs are sent often enough that a lost packet would not make much of a difference. The smaller amount of overhead also makes UDP faster. An example of where UDP may be a better choice than TCP is in the event of an emergency power off. If a TCP connection does not receive the emergency power off command, there is a wait between until it can be sent again and no commands would be able to be sent. With UDP if this packet is lost, it can be immediately be sent again until it is received by the drone.

Console Screenshots

Server console

```
onot@ubuntu:/home/server/Documents
root@ubuntu:/home/server/Documents# ./server
Emergency power off
Take off
Land
Wrong command
Adjust roll left
Adjust roll right
Adjust pitch down
Adjust pitch up
Gaz decreased
Gaz increased
Yaw decreased
Yaw increased
Yaw decreased
Yaw increased
```

Client console

```
© ● ① root@ubuntu:/home/client/Documents

INSTRUCTIONS

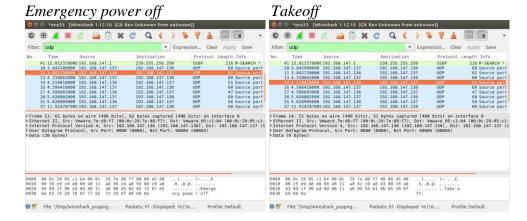
1: Emergency power off

2: Takeoff

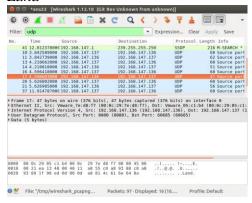
3: Land
a/d: Roll left/right
w/s: Pitch down/up
k/i: Gaz decrease/increase
j/i: Yaw decrease/increase
x: Exit controller

Emergency power off
Take off
Land
Wrong command
Adjust roll left
Adjust roll right
Adjust roll right
Adjust pitch down
Adjust pitch down
Adjust pitch up
Gaz decreased
Gaz increased
Yaw decreased
Yaw decreased
Yaw cereased
Exiting controller
root@ubuntu:/home/client/Documents#
```

Wireshark Screenshots



Land



Transport Protocol Between Server and Drone

UDP was also used as the transport protocol between the server and drone for the same reasons it was used between the client and server.

Code Installation Instructions

- Install dependencies listed above in "Required Packages" on server machine
- Move server folder to server machine, client folder to client machine
- Navigate to server folder and run: unzip out.zip -d /path/to/server/folder then make
- Navigate to client folder and run: make
- Start server by running: ./server
- Start client by running: ./client

^{*}Tested on Ubuntu 16.04.02