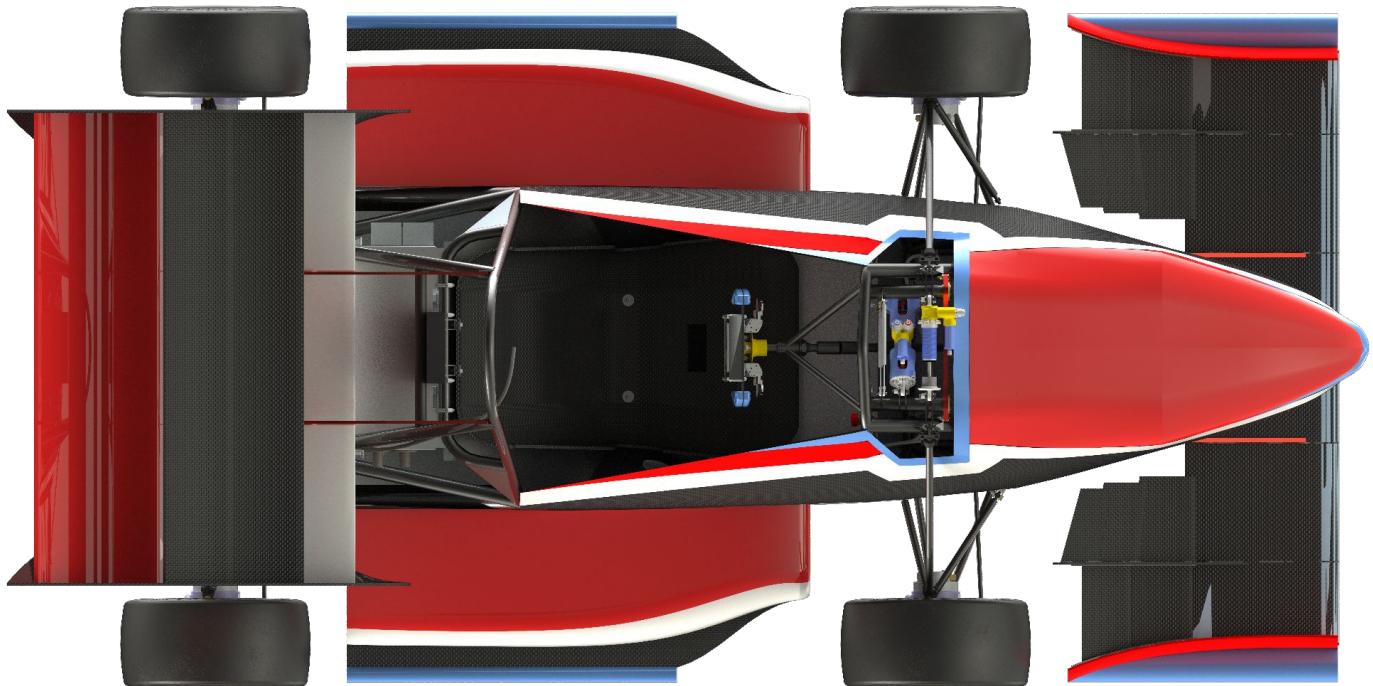


# Vehicle Architecture and Systems Management



## Design Binder

MY25 Exec

04/19

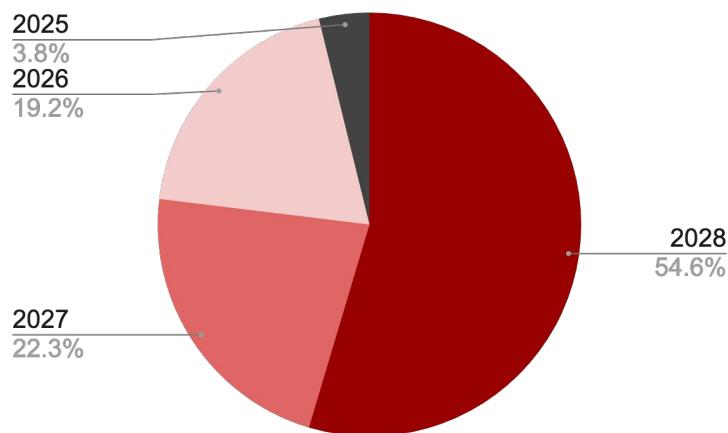
# Table of Contents

- Team Structure
- Team Goals
- Simulations
- Architecture Decisions
- Design Cycle Process
- Timeline
- Risk Management
- Testing and Validation

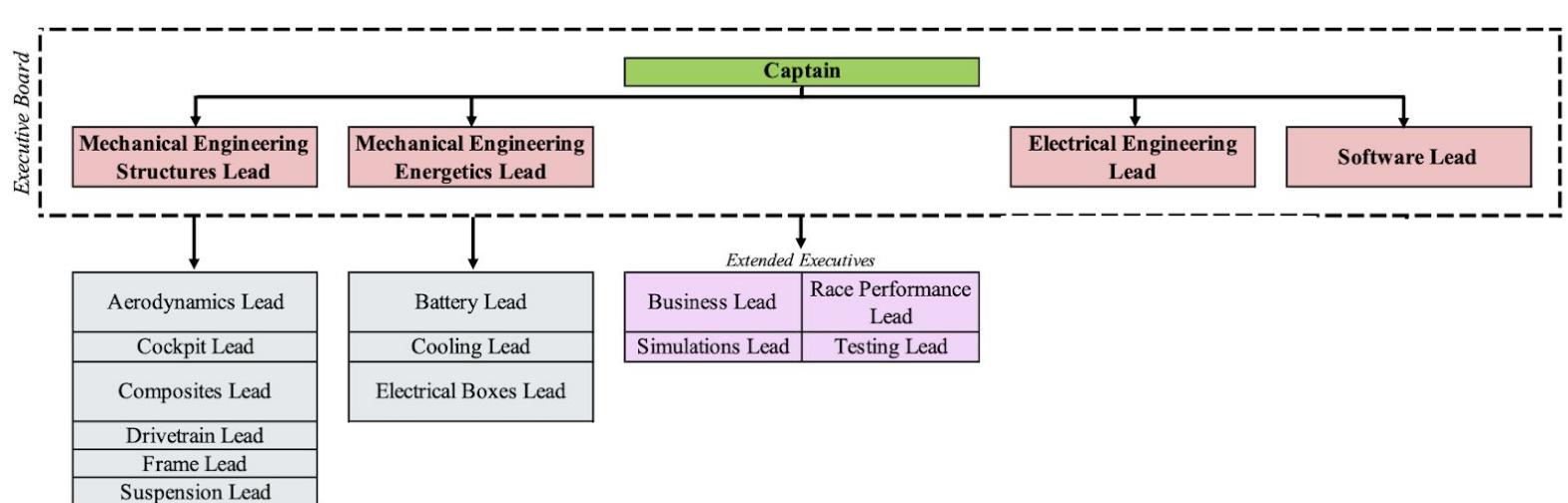
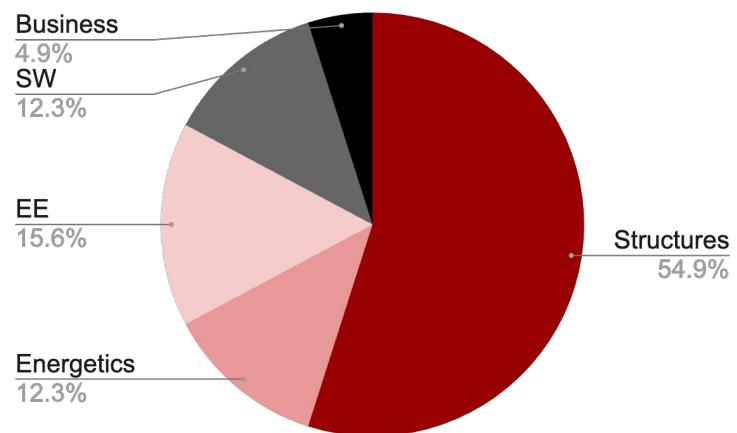
# Team Structure

85 Total Members

## Class Breakdown



## Subteam Breakdown



Key	
Captain	
Subteam Lead	
Extended Executives	
System Lead	

# Team Goals

**Competition Finish: Top 5 Overall at FSAE Michigan**

Dynamic Events:

Lap Sim with Car architecture + 10% margin:

- **Accel:**  $3.555 + 0.355 = 3.91 \text{ s}$
- **Skidpad:**  $4.91 + .491 = 5.4$

Linear regression from historical Top 5 team performance

- **Autocross:** 48.0s
- **Endurance:** 1600s

Static Events:

Winning Design Event at Hybrid

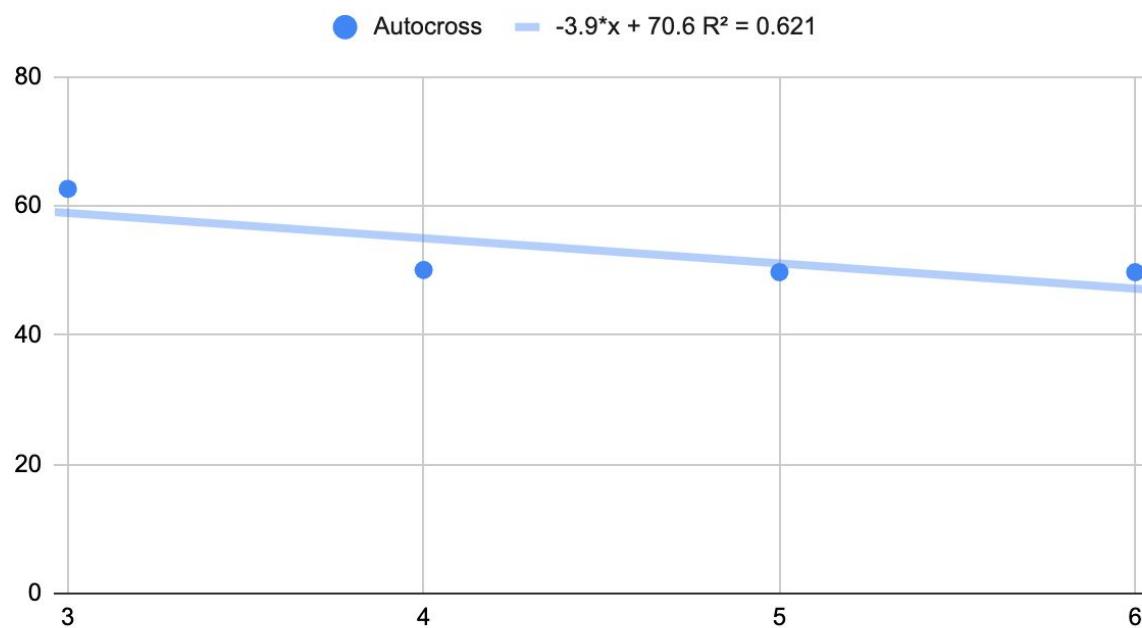
Design Finalist at Michigan (~110/150 points)

Top 10 Cost Event (~77/100 points)

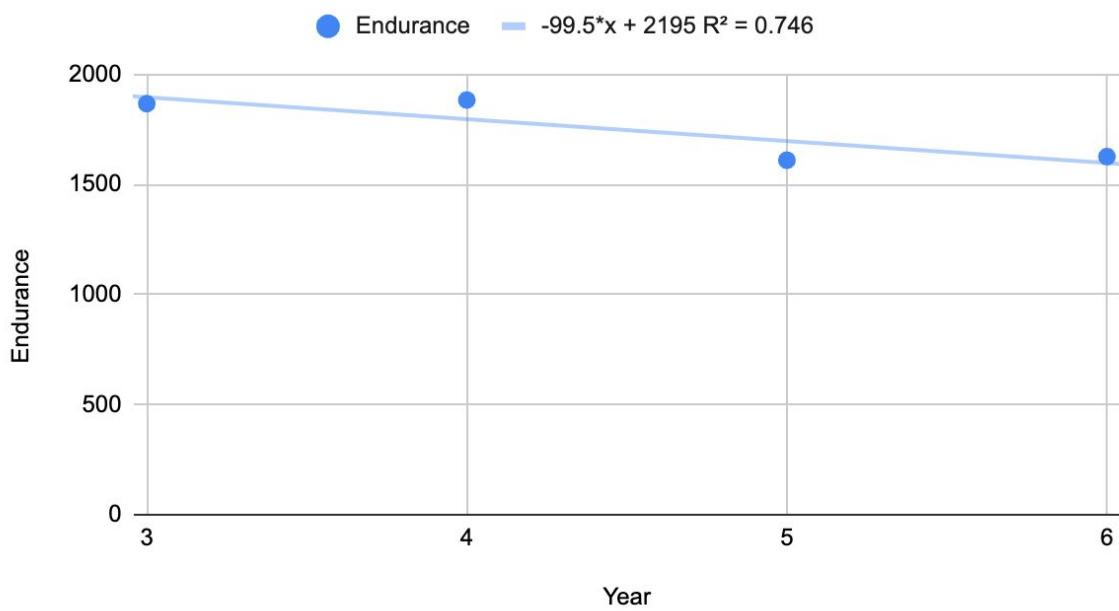
Business Finalist at Michigan (~67/75 points)

# Team Goals

## Autocross Times in Last 3 Years



## Endurance Times in Last 5 Years



## Predicted 2025 FSAE Electric Performance

# Team Goals Cont.

## Reliability:

- Testing Metrics:
  - **5 Representative Endurances** with no faults or failures
  - **10 Representative Accels**, timed
  - **5 Representative Skidpads**, timed
  - **10 Representative Autocrosses**, timed
  - Successful Brakes and Rain tests
- **Over 200 km of intentional testing**
- Rigorous Testing documentation
  - Preflight and Inflight checklists
- Onboard telemetry to track:
  - Battery Power Draw
  - Motor, Inverter, Battery Temperature
  - Motor torque and speed
  - Suspension shock pot data

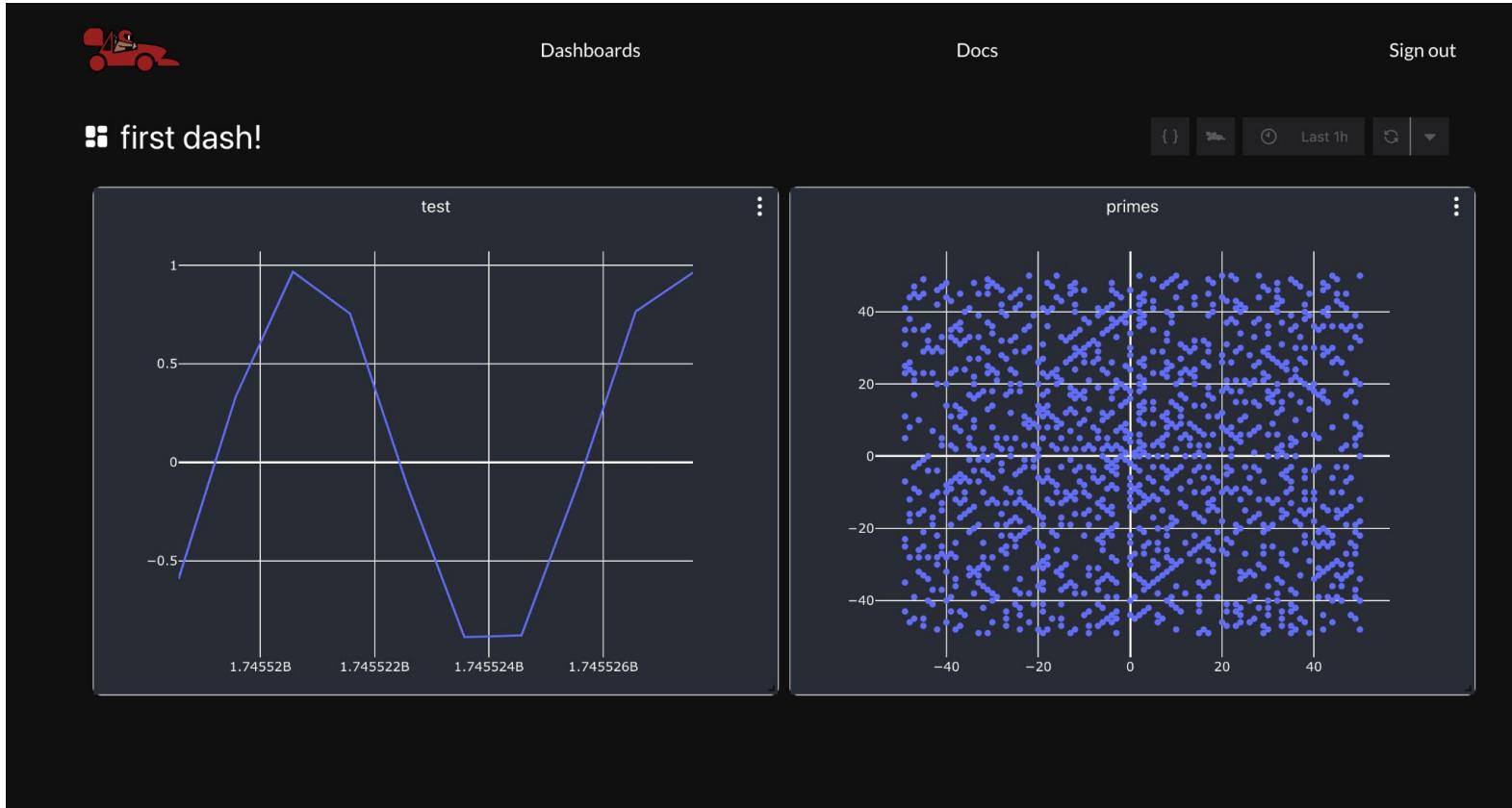
# Preflight Checklist

## Before car leaves jacks

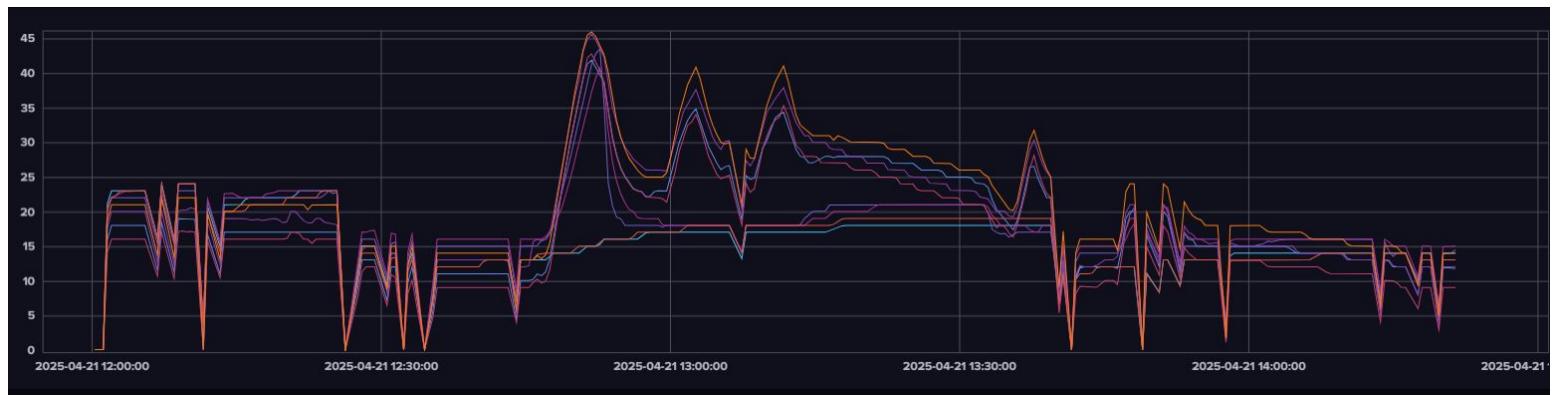
	Item to check	Sign Off
<b>1.1</b>	<b>Vehicle is Ready</b>	
1.1	HV battery is charged	
1.2	BMS cable is plugged back into battery, HVD is plugged in	
1.3	LV battery is charged (record voltage)	
1.4	Back-up LV battery is charged (record voltage)	
1.5	Area around vehicle is clear	
<b>2</b>	<b>Vehicle Safety Checks - Mechanical</b>	
<b>2.1</b>	<b>General Mechanical Checks</b>	
2.1.1	Brake pedal is tight	
2.1.2	Accel pedal is tight	
2.1.3	Check wheels by shaking rims (shouldn't wiggle much)	
2.1.4	Reservoirs are full	
2.1.5	Steering has full range of travel	
2.1.6	Brake overtravel switch is flipped in the correct direction	
<b>2.2</b>	<b>Powertrain</b>	
2.2.1	Lug nuts on + tight on all 4 wheels	
2.2.2	No leaks in brake line	
2.2.3	Brake pads are good, rotors aren't rubbing	
2.2.4	Brake rotors are secure	
2.2.5	Halfshaft rubber boots are tight/not loose	
2.2.6	Chain is tensioned (~0.25" travel when poked)	
2.2.7	Chain is greased	
2.2.8	Motor nut is tight	
2.2.9	Cooling loop is full, bled, and no leaks	
2.2.10	Catch can is empty	
<b>2.3</b>	<b>Chassis</b>	

# Telemetry

## Custom Data Acquisition Website

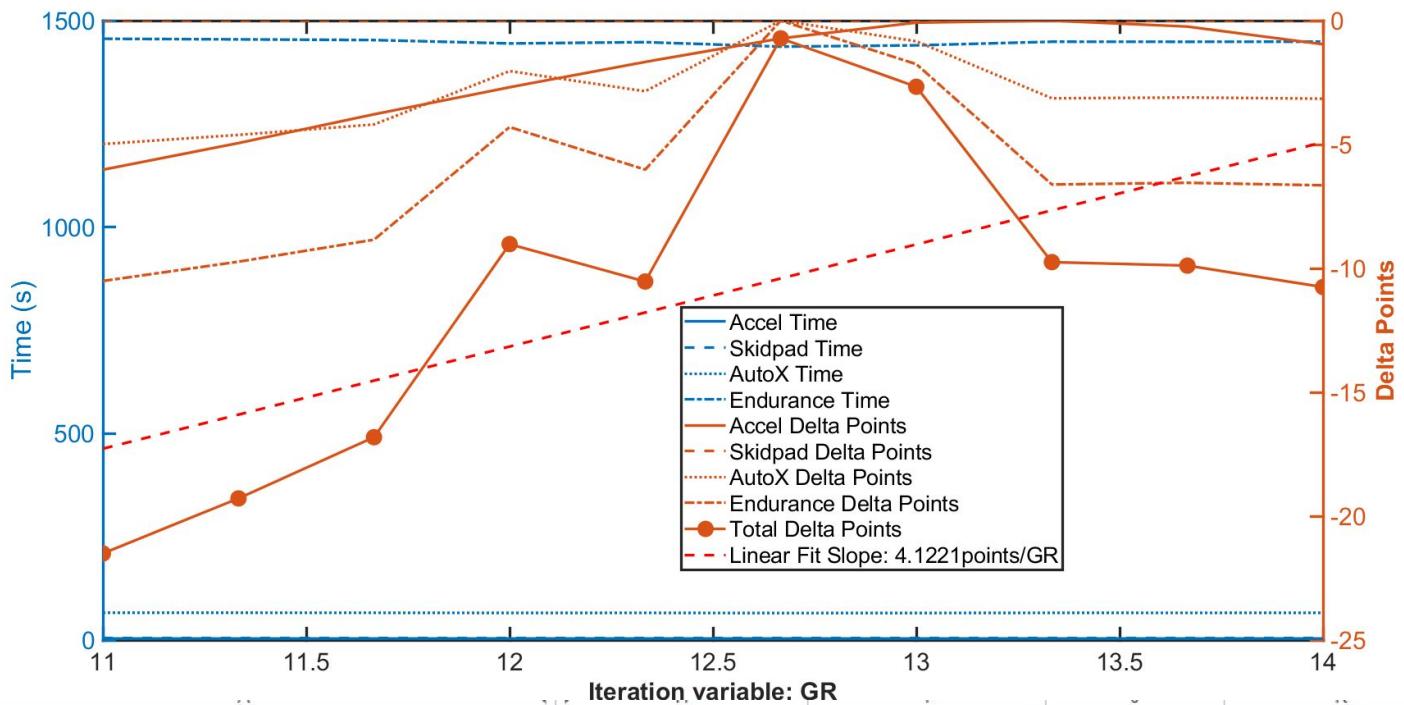


## Live Motor, Battery, Inverter Temperature Dashboard



# Simulations

## 4WD Justification + Motor Selection

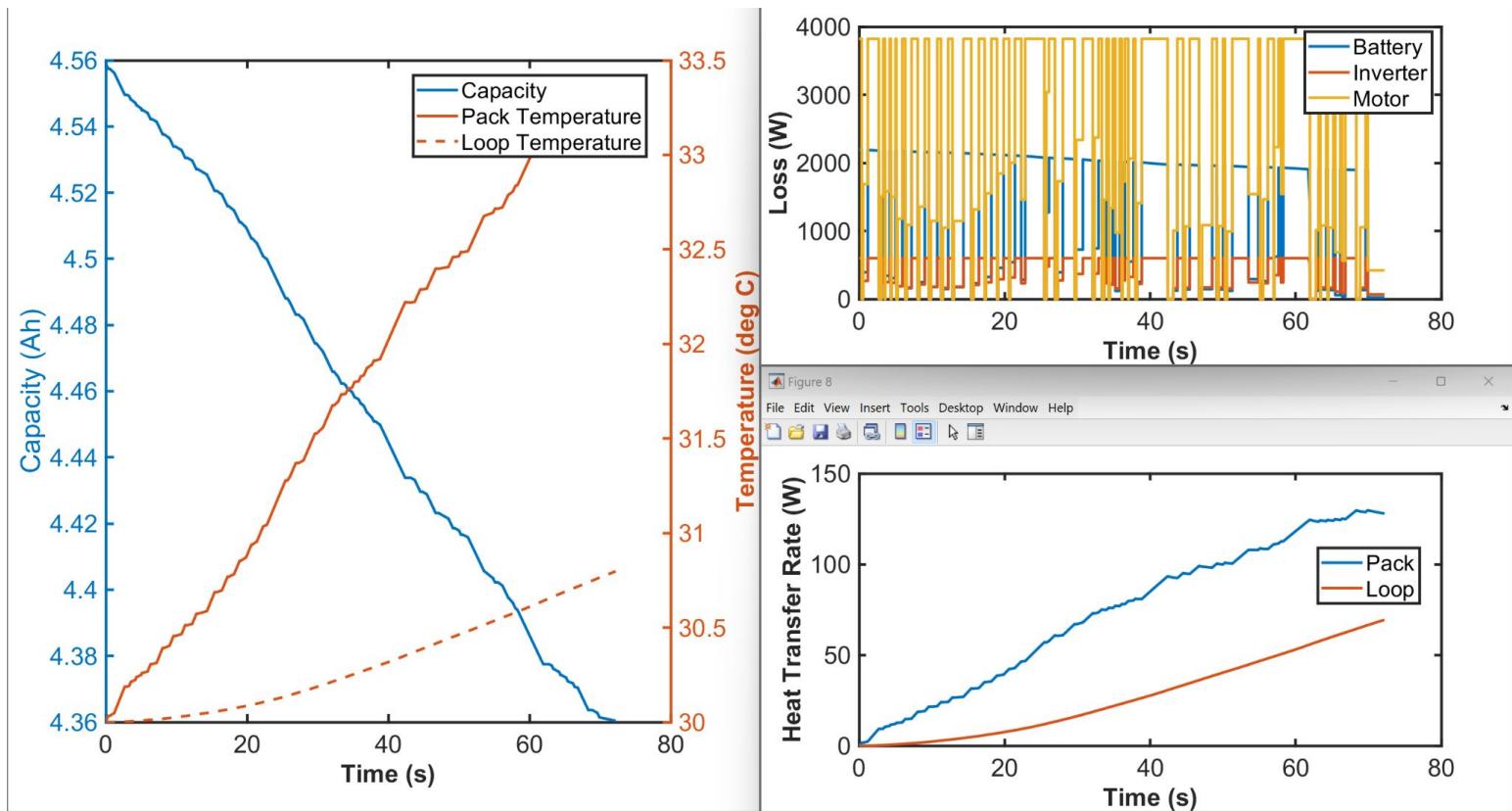


Motor:	Accel (s):	Skidpad (s):	Lap (s):	Endurance (s):
Fischer TI085-052-070-04B7S-07S04BE2	3.508	4.8502	65.1054	1432.3197
DHX Hawk40/K40	3.518	4.8715	65.6044	1443.297
DHX Hawk20/K20	3.87	4.8431	67.2682	1479.9014
Parker GVM142-050G	4.09	4.8767	68.5478	1508.0526
Parker GVM142-050K	3.809	4.8767	67.3389	1481.4554
Moog AFW505E	3.78	4.8562	65.1585	1433.4872
AMK DD5-14-10-POW-18600-B5 (600V)	3.598	4.8125	65.3188	1437.0129
AMK DD5-14-10-POW-18600-B5 (400V)	3.806	4.8125	66.7349	1468.1684

Motor:	Power (W):	Gearbox (Stages):	Voltage (V):	OD (in):	Length (in):	Total Mass (kg):	Cost (\$):	Total Cost(\$):	Feasibility (rank):	Performance (rank):
Fischer TI085-052-070-04B7S-07S04BE2	35,366	2	600	4.72	5.49	10.53	2873	11492	4	1
DHX Hawk40/K40	66,240	1	400	5.25	6.5	13.7	4200	16800	3	4
DHX Hawk20/K20	18,400	1	400	5.25	5.44	9.5	3200	12800	2	5
Parker GVM142-050G	14,000	1	400	5.59	8.72	14.5	1882	7528	7	7
Parker GVM142-050K	29,000	1	400	5.59	8.72	14.5	1882	7528	6	6
Moog AFW505E	54,797	1	600	3.74	10.16	11.4	0	0	5	2
AMK DD5-14-10-POW-18600-B5	36,000	2	600	4.28	5	8.55	See AMK Pricing	See AMK Pricing	1	3

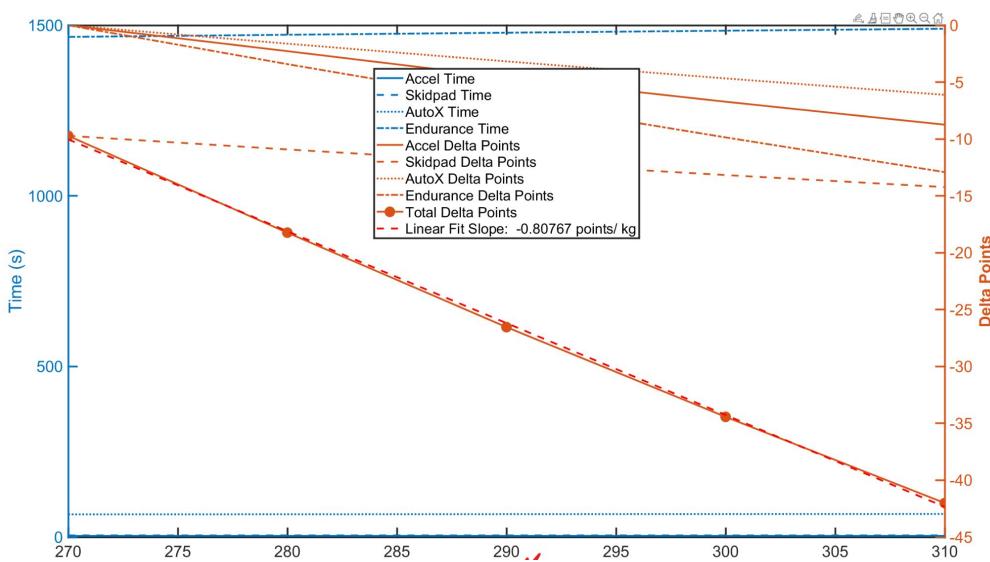
# Simulations

## Battery Sizing



# Simulations Cont.

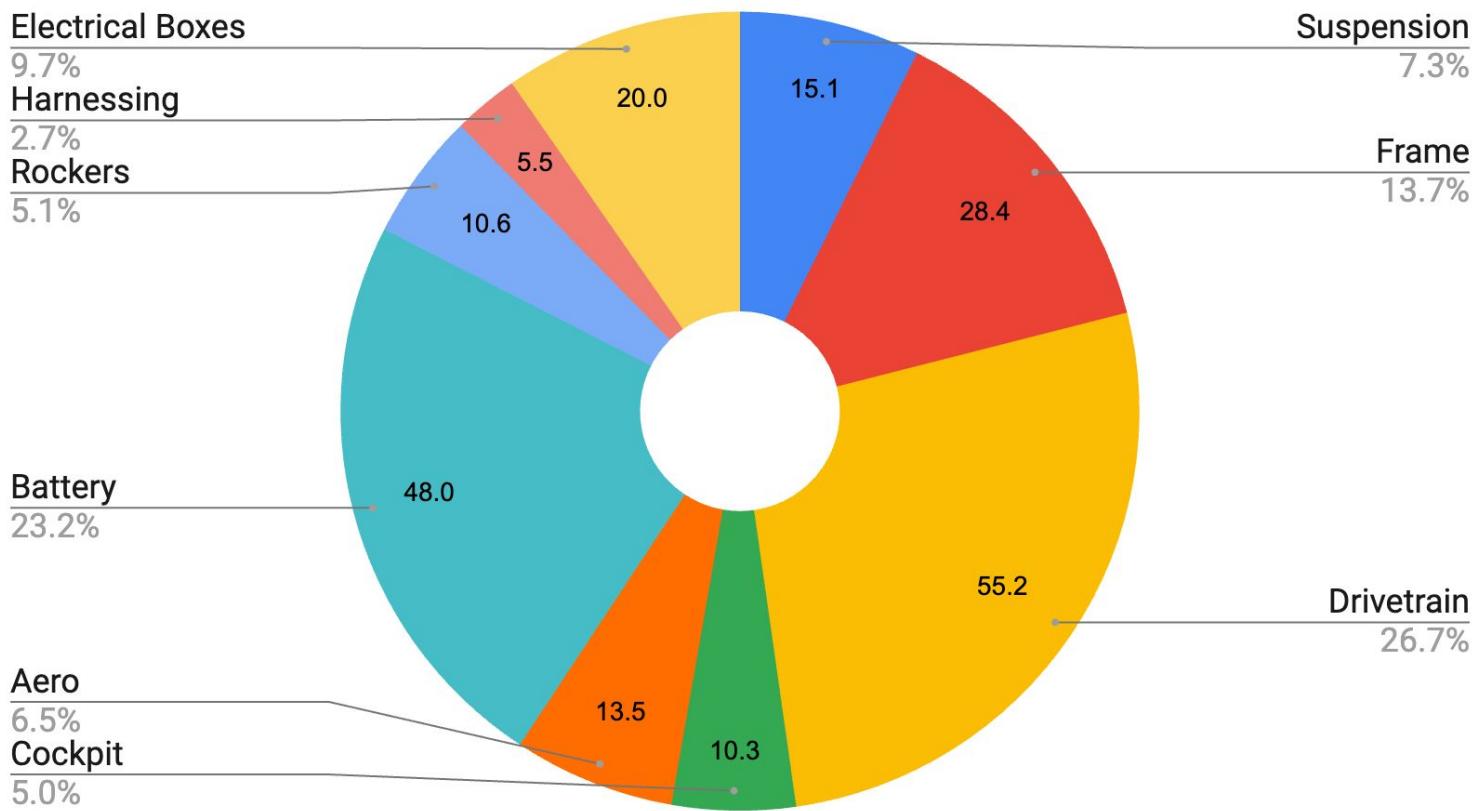
## Car Parameter Sensitivities



Sprung Mass  
Actual: 222 kg

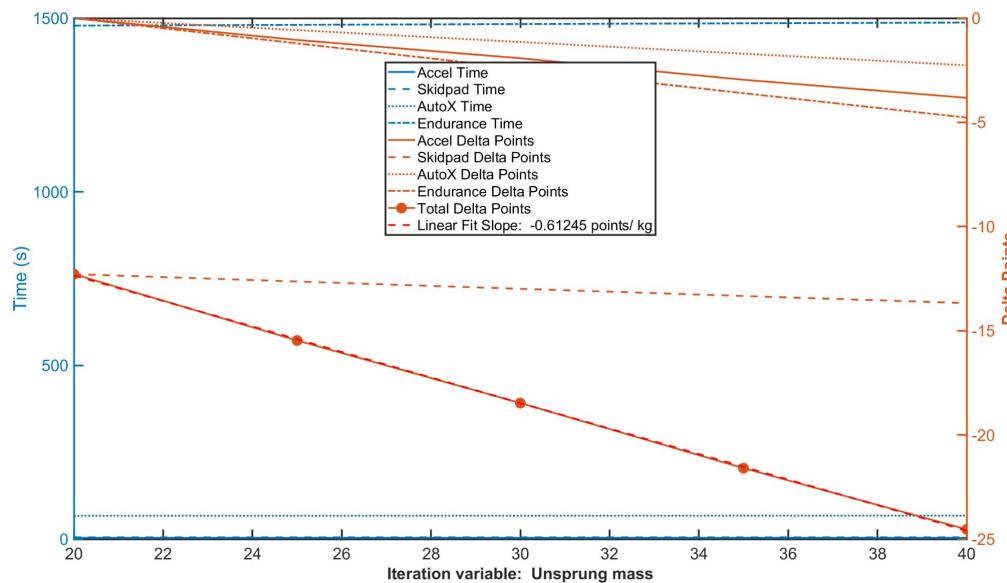
Sprung Mass (kg)

## MY25 Mass Allocations (222 kg)

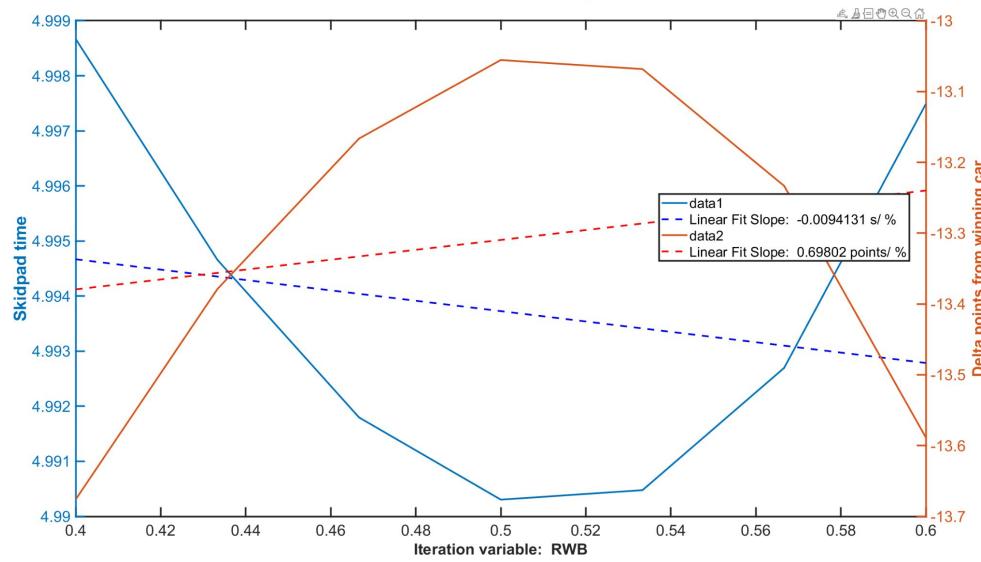


# Simulations Cont.

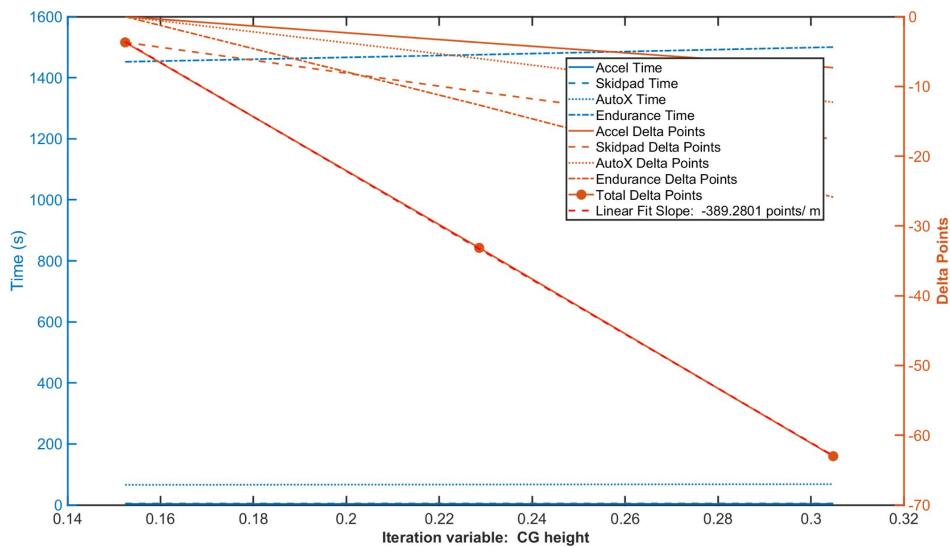
# Car Parameter Sensitivities



Unsprung  
Mass  
Actual: 50 kg



RWB  
Goal: 51%  
Actual: 51%



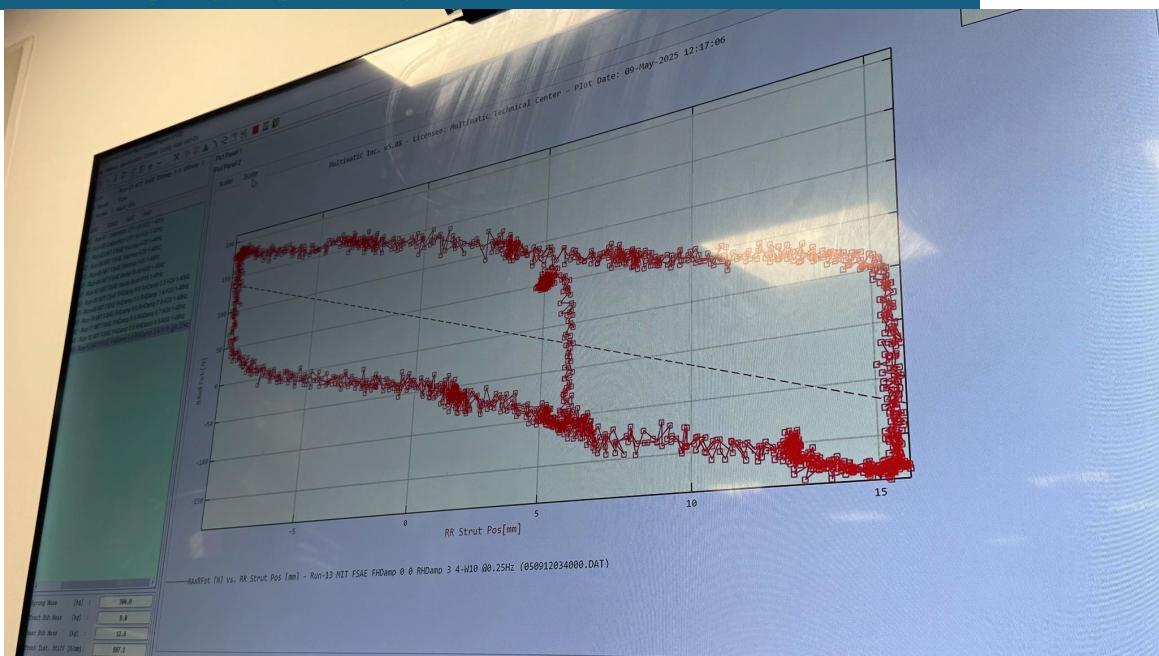
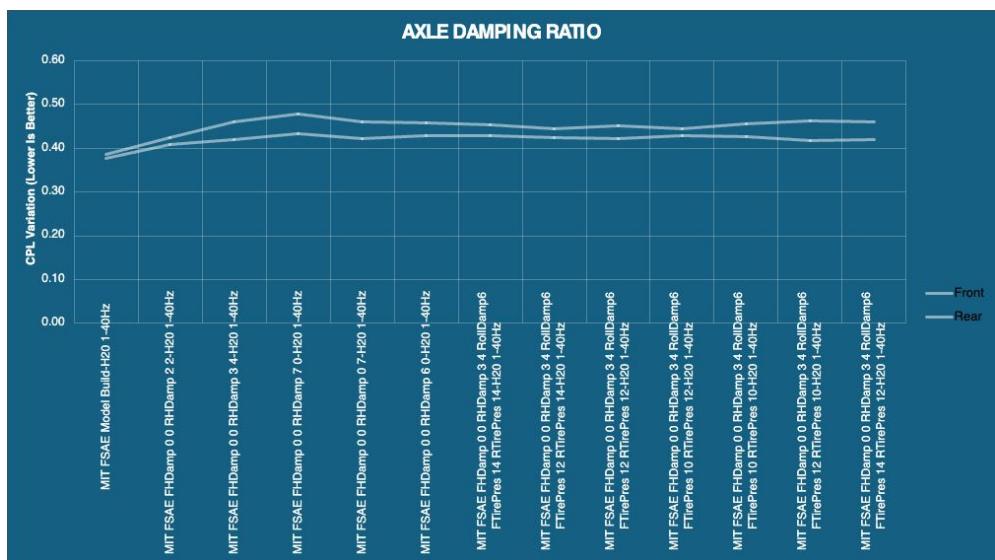
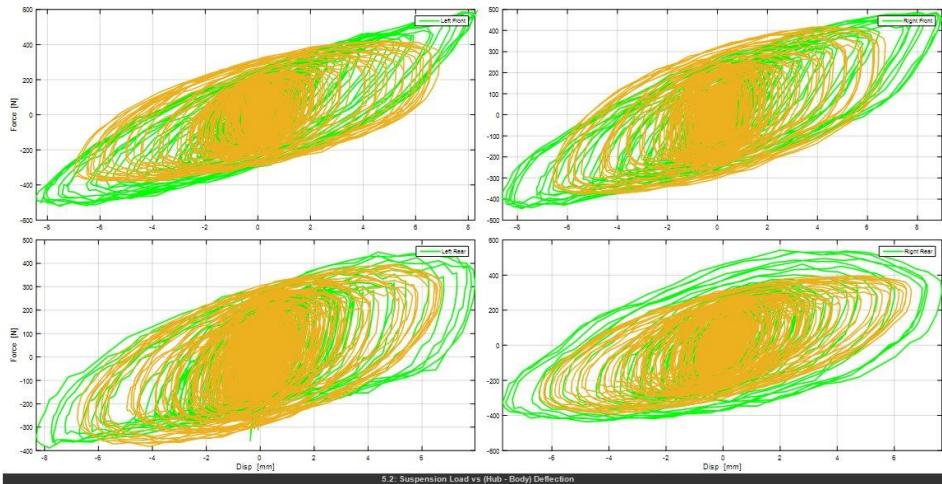
# Architecture

## Structures:

- Custom In-hub compound planetary gearboxes
- Decoupled Roll-Heave Suspension, sponsored by Multimatic
- Mass: 215 kg
  - Composites R&D



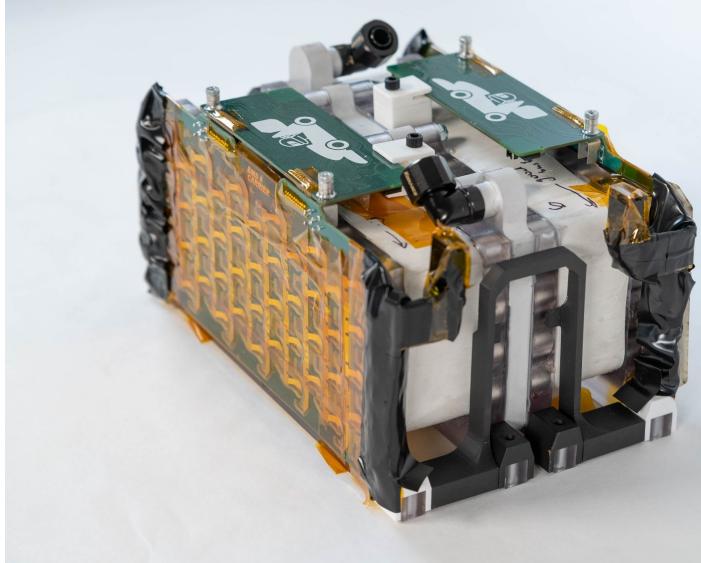
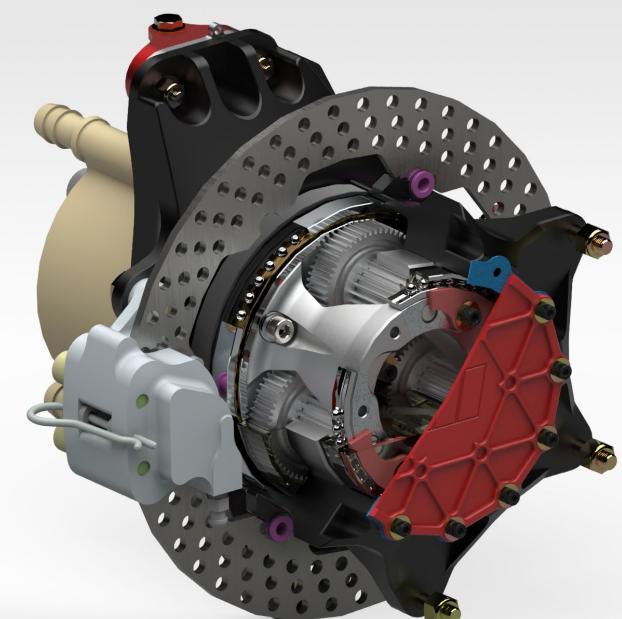
# 4-post Testing



# Architecture

## Tractive System and Firmware:

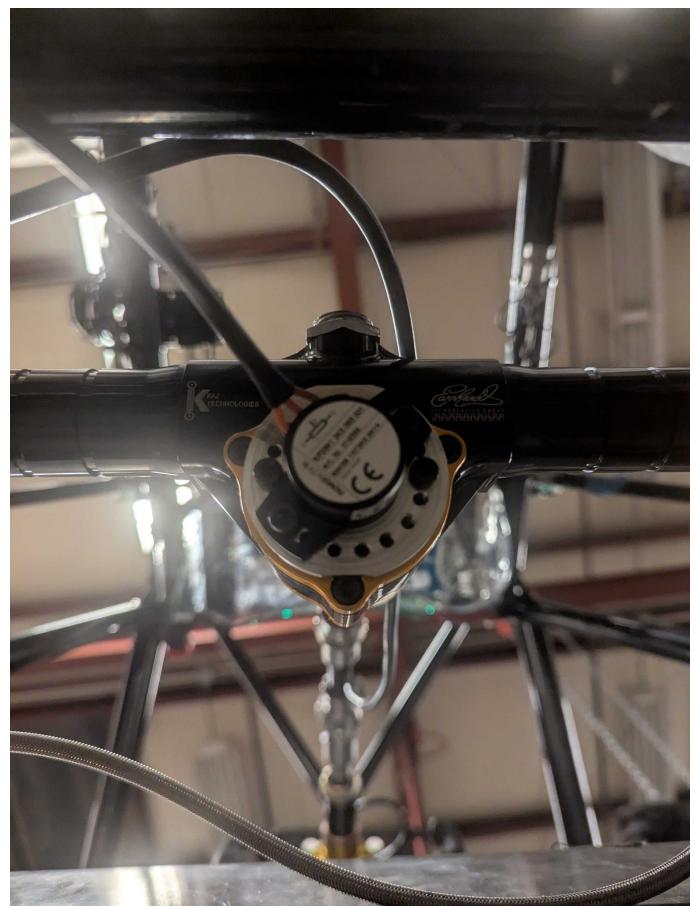
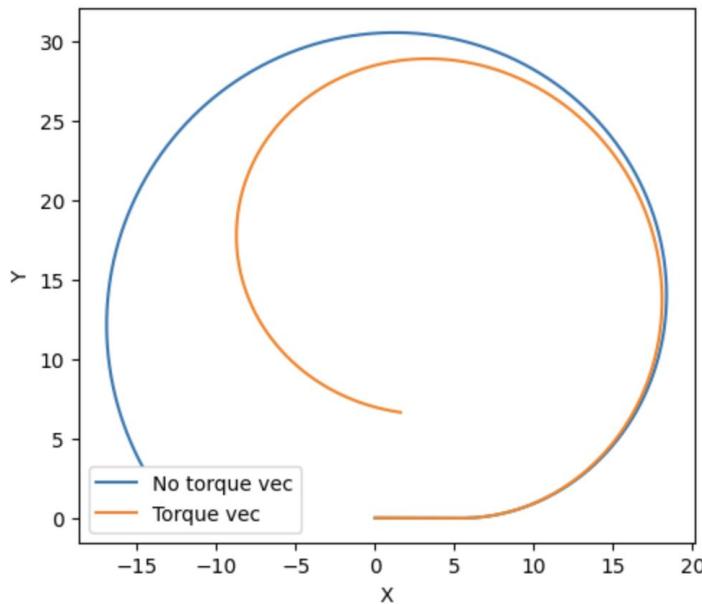
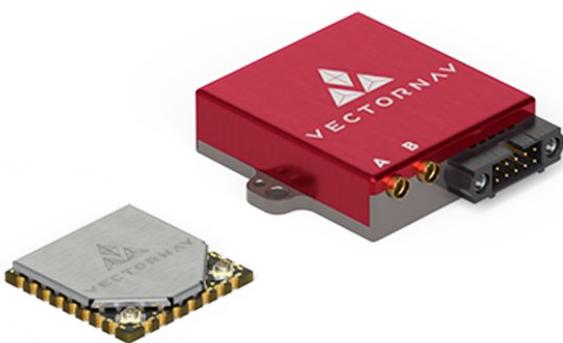
- 4x AMKMotion Formula Student Motor + Inverter kit
- 600V Water-cooled battery + inverter loop
- Water-cooled motor loop
- Fully custom Low Voltage System



# Architecture

## Controls:

- Steering encoder and IMU to capture steering angle and yaw rate data
- 4WD torque vectoring PID loop to optimize yaw rate



# Design Cycle Process

DRDR	CoDR	DR1	DR2	MaDR/Test Plans
<b>Design Requirements Review</b>	<b>Concept Design Review</b>	<b>MVP Design of selected concept</b>	<b>Ready for deployment, manufacturing, assembly</b>	Plans, timelines for manufacturing, testing, assembly
Defining Design requirements from: <ul style="list-style-type: none"><li>- Budget</li><li>- Timeline</li><li>- Rules</li><li>- Load Cases</li><li>- Optimization</li><li>Sims</li><li>- Interfaces</li></ul>	Presenting possible concepts which do/don't satisfy design requirements <ul style="list-style-type: none"><li>Selecting a system</li><li>concept you want to go with</li><li>Building out a timeline for said concept</li></ul>	Full analysis for critical elements	End of design phase - "freeze"	
		Packages/interfaces with smoothly		
		No critical issues		
		Major risks and remaining to do highlighted		

Milestone	Deadline	Actual Date Hlt
LV EE Bench	2/1	3/20
Rolling	2/14	3/21
HV EE Bench w/ PSU	2/14	3/21
HV EE Bench w/ Battery	2/21	3/22
Stands Test	3/08	3/23
Roman	3/08	3/24
Shakedown	3/12	4/21

### **Summer:**

- System level DRDR and CoDRs
- Finalize justifying team goals

### **Fall:**

- System + subsystem DR1 and DR2
- MY24 Fall Testing + Wind Tunnel Testing
- Finalize car design and analysis
- Scrutineering
- Document Submission

### **Winter:**

- IAP Manufacturing Sprint
- Subscale/Unit Tests
- Static Event preparation

### **Spring:**

- Full Car Testing
- Controls and Telemetry Testing
- Mock inspections
- Driver Training

# Timeline

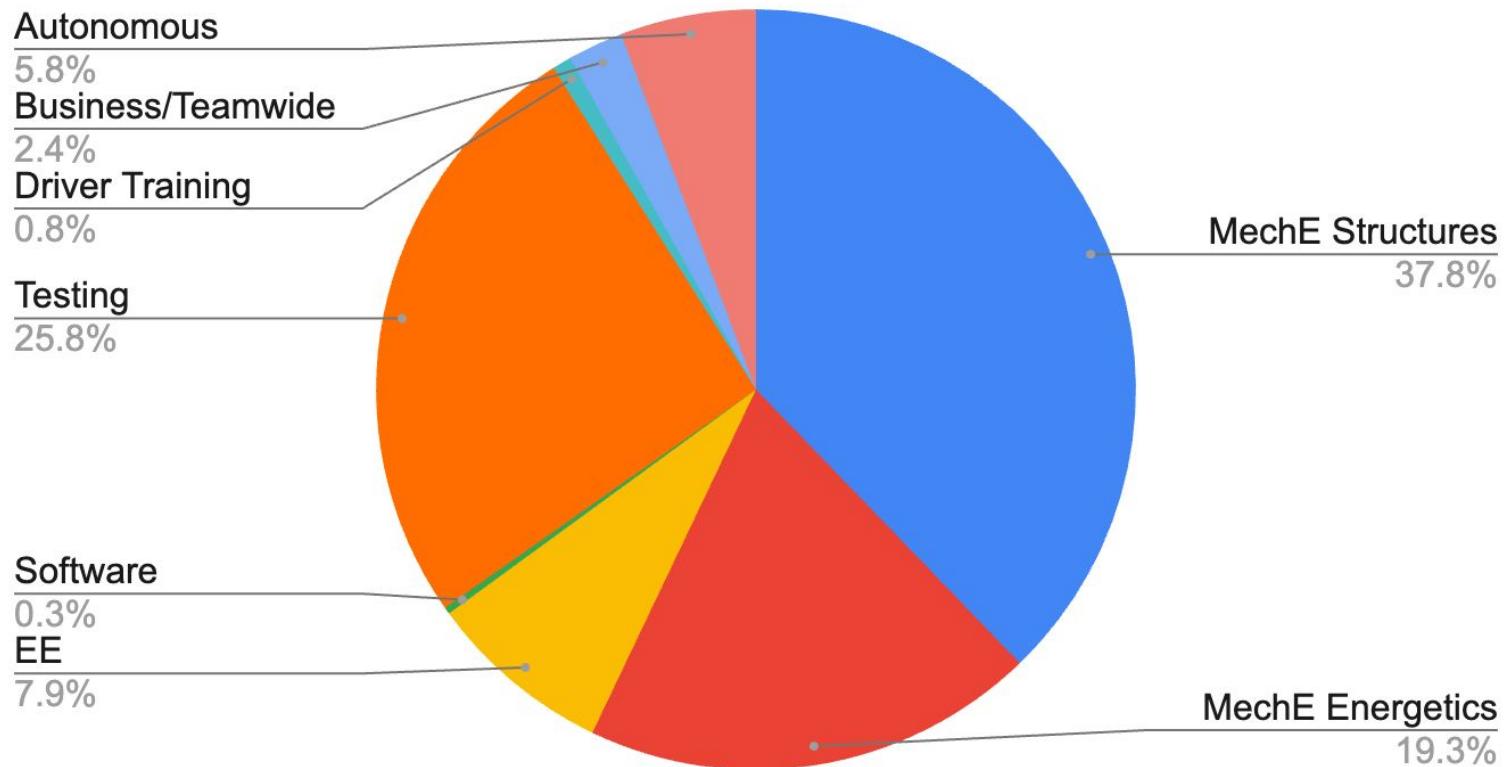
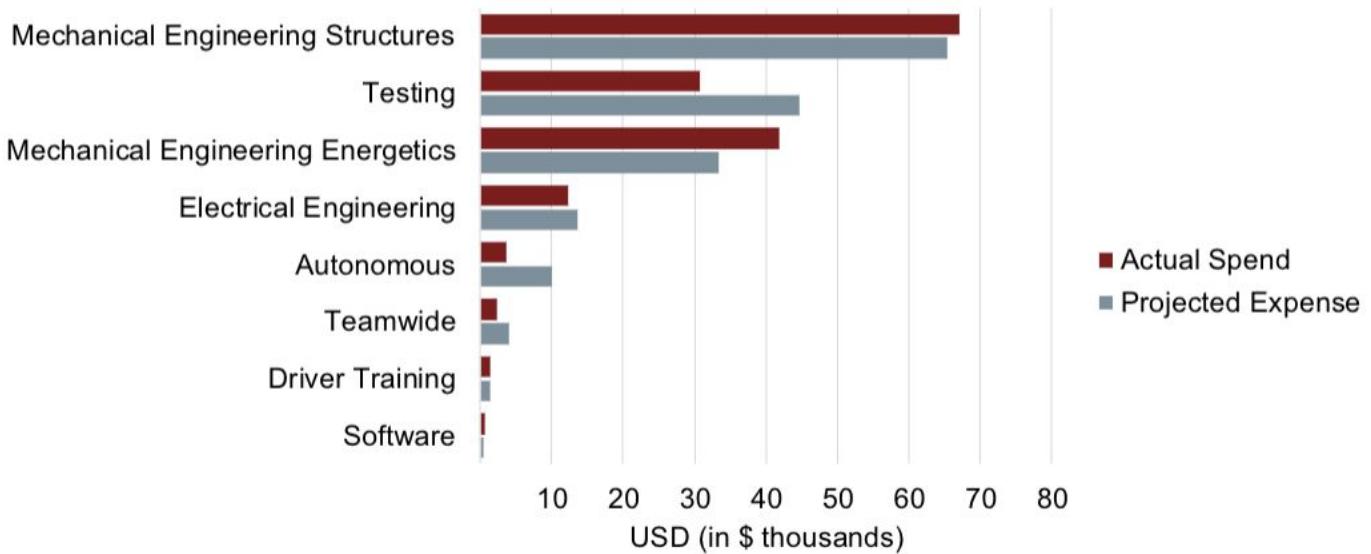
System	12	19	26	February 2025	2
System					
Waterjet cell holders Jan 7 - Jan 10					
Machine battery coldplates Jan 7 - Jan 12					
Box arrives Jan 7 - Jan 7					
Nickel strip bend jig Jan 9 - Jan 10					
Install compression limiters into cell holders Jan 11 - Jan 11					
Machine epoxying jig Jan 12 - Jan 14					
Tap coldplates Jan 13 - Jan 14					
Test coldplates Jan 15 - Jan 18					
Cut VHB strips Jan 15 - Jan 16					
Cut test busbar Jan 17 - Jan 17					
Bend test busbar Jan 18 - Jan 18					
Bend nickel strips Jan 18 - Jan 18					
Cut TIM standoffs Jan 19 - Jan 19					
Solder 2 carrier boards to nickel strips Jan 19 - Jan 20					
Electroplate test busbar Jan 19 - Jan 19					
Cut out all busbars and spacers Jan 20 - Jan 21					
Spot weld 2 carriers to cells Jan 21 - Jan 21					
Bend all busbars Jan 22 - Jan 23					
Test module w/ BMS head and segment Jan 22 - Jan 23					
HiPot test practice module Jan 24 - Jan 24					
Electroplate busbars Jan 24 - Jan 25					
Solder all nickel strips to carriers Jan 25 - Jan 26					
Print anti-wiggle for segments Jan 25 - Jan 25					
Print HVEE mounts Jan 26 - Jan 26					
Measure and cut bulb seal Jan 26 - Jan 26					
Spot weld all nickel strips to cells Jan 27 - Jan 29					
Battery					
Opened the last synced version due to poor connection	Force reload	X			

	Tr	Column 1	Date	Priority	SubTeam	System	Status	Tr	Notes
1	2	System Leads Assigned	June 19	██████	Team	Team	Done		
8	8	Architecture DR	July 21	██████	Team	Team	Done		
11	11	HV Electronics DR	July 27	██████	EE	HV Electro...	Done		
12	12	VCU/megaLV DR	July 27	██████	EE	VCU/Mega...	Done		
13	13	Preprep Sponsor	July 27	██████	Structures	Composites	Done		Amelia/Trevor talking with Specialty Materials. Currently progressing with figuring out sponsorship terms
21	21	Board Architecture DR	August 7	██████	EE	EE	Done		
24	24	sensor node rewrite DR	August 10	██████	SW	Software	Done		
28	28	VCU/megaLV Schematic	August 24	██████	EE	VCU/Mega...	Done		
33	33	HV Electronics Schematic	September 14	██████	EE	HV Electro...	Done		
39	39	Motor Inverter Spin	September 21	██████	EE	EE	Done		
40	40	MegaLV Software Done, begin testing on N	September 21	██████	SW	Software	Done		
43	43	Hybrid Registration	September 26	🏁	Team	Team	Done		Done
44	44	HV Electronics Layout	September 28	██████	EE	HV Electro...	Done		
53	53	VCU/megaLV Layout	October 7	██████	EE	VCU/Mega...	Done		VCU done, LVBatt
54	54	Inboard Sus Packaging	October 9	██████	Structures	Suspension	Done		Driven by frame DR1
57	57	Torque Vectoring DR	October 16	██████	SW	Controls	Done		
58	58	Motor inverter spin with Theo's code	October 16	██████	SW	Software	Done		
60	60	LV Harnessing Sent Out	October 18	██████	Energetics	Harnessing	Done		
65	65	Backplane Layout	October 20	██████	EE	EE	Done		
67	67	HV Electronics Sendout	October 21	██████	EE	HV Electro...	Done		
68	68	VCU/megaLV Sendout	October 21	██████	EE	VCU/Mega...	Done		
69	69	Backplane Sendout	October 21	██████	EE	EE	Done		
70	70	Hybrid ESF 1 Ready for Review	October 22	██████	EE	Team	Done		
76	76	Hybrid ESF 1 Submission	October 28	🏁	EE	Team	Done		20 Bonus points if approved 30 days before due date. 10 points if approved 15 days before due date
77	77	Power Limiting DR	October 28	██████	SW	Controls	Done		
83	83	Hybrid SES Submitted	November 1	🏁	Structures	Structures	Done		20 bonus points if approved before Nov 15: <a href="https://www.formula-hybrid.org/deadlines">https://www.formula-hybrid.org/deadlines</a>
99	99	Sus Links CoDR	November 9	██████	Structures	Suspension	Done		
102	102	Steering Wheel DR1	November 10	██████	Structures	Cockpit	Done		
104	104	CF Box go/no go	November 10	██████	Structures	Composites	Done		
122	122	Frame VR3 BOM, Jigging Order, Coping Ord	November 29	🏁	Structures	Frame	Done		
123	123	Frame Scrutineered	November 29	██████	Structures	Frame	Done		Needs to be done before sending out
127	127	Final HV Electronics Sendout	November 30	██████	EE	HV Electro...			

# Budget

**We budgeted and raised \$173,000 through 5 active funding channels**

**MY25 Earned Value Analysis**



# Budget Tracking

Overall Budget Summary				
Category	Description	Budgeted Amount	Actual Spent	Completion %
MechE Energetics		\$33,400.00	\$41,914.32	125.49%
	MechE Energetics: General Subteam	\$500.00	\$554.66	110.93%
	Energetics: Battery	\$16,800.00	\$19,268.64	114.69%
	Energetics: Cooling	\$3,500.00	\$5,723.78	163.54%
	Energetics: EE Boxes	\$1,100.00	\$2,800.61	254.60%
	Energetics: Harnessing	\$11,500.00	\$13,566.63	117.97%
EE		\$13,650.00	\$12,276.68	89.94%
	EE: General Subteam	\$1,450.00	\$9,014.01	621.66%
	EE: BMS/Battery	\$6,750.00	\$559.47	8.29%
	EE: CSB/Charger	\$1,000.00	\$579.20	57.92%
	EE: Dash	\$350.00	\$105.12	30.03%
	EE: HVLV	\$1,000.00	\$600.24	60.02%
	EE: International Fees from PCB's	\$50.00	\$76.27	152.54%
	EE: LVBatt	\$650.00	\$876.27	134.81%
	EE: RSP	\$200.00	\$0.00	0.00%
	EE: Sensor Node	\$1,500.00	\$274.23	18.28%
	EE: VCU	\$700.00	\$191.87	27.41%
Software		\$500.00	\$591.00	118.20%
	Software: General Subteam	\$500.00	\$591.00	118.20%
Autonomous		\$10,000.00	\$3,670.48	36.70%
	Autonomous: General Subteam	\$10,000.00	\$3,670.48	36.70%
Testing		\$44,600.00	\$30,800.08	69.06%
	Testing: General Subteam	\$200.00	\$7,412.73	3706.37%
	Testing: Comp Food/Gas	\$10,000.00	\$0.00	0.00%
	Testing: Comp Vehicle Rentals	\$500.00	\$0.00	0.00%
	Testing: Hybrid Housing	\$5,000.00	\$5,000.00	100.00%
	Testing: Michigan Housing	\$11,000.00	\$11,000.00	100.00%
	Testing: MY24 Maintenance	\$500.00	\$0.00	0.00%
	Testing: Trip Gas	\$2,000.00	\$135.15	6.76%
	Testing: Trip Food	\$3,600.00	\$0.00	0.00%
	Testing: Vehicle Rental	\$7,200.00	\$2,652.20	36.84%
	Testing: Registration Fees	\$4,600.00	\$4,600.00	100.00%
Driver Training		\$1,400.00	\$1,343.50	95.96%
	Driver: Sim PC	\$1,000.00	\$1,323.25	132.33%
	Driver: Sim VR	\$300.00	\$20.25	6.75%
	Driver: Software	\$100.00	\$0.00	0.00%
Business/Teamwide		\$4,090.00	\$2,244.00	54.87%
	Business: AWS Data	\$20.00	\$1.56	7.80%
	Business: Google Cloud Data	\$20.00	\$17.33	86.65%
	Business: Livery	\$1,000.00	\$0.00	0.00%
	Business: Media	\$200.00	\$23.90	11.95%
	Team: Shipping	\$500.00	\$1,369.39	273.88%

# Sponsors

 MIT MOTOSPORTS	Affiliate \$1,000+	Bronze \$2,500+	Silver \$5,000+	Gold \$10,000+	Titanium \$15,000+	Carbon \$20,000+
<b>Invitation to Team Events</b>	•	•	•	•	•	•
<b>Logo on Website + Sponsor Banners</b>	•	•	•	•	•	•
<b>Logo on Team Apparel</b>		•	•	•	•	•
<b>Logo on Car</b>		Small	Medium	Large	X-Large	Wing
<b>Social Media Features</b>			1x	2x	3x	4x
<b>Access to Team Resume Book</b>			•	•	•	•
<b>Networking Event with Team</b>				•	•	•
<b>Team Attendance at Sponsor's Event*</b>					•	•
<b>Title Benefits (Team Dinner, Car Access, etc.)</b>						•

\*In collaboration with MIT's Edgerton Center



# New Website



MENU

25  
Introducing  
Model Year



# Risk Management

## Rigorous Scrutineering and Technical Inspection process from alumni

The screenshot shows a MIT Wiki Service page titled "MY25 MechE Scrutineering". The left sidebar contains navigation links for Calendars, Analytics, PAGE TREE (with categories like Years, MY18-25), and Space tools. The main content area has two tables: "Design Reviews" and "Design Requirements".

**Design Reviews**

Design Review	Slides Link	Notes Link	Notes
DRDR		<a href="https://docs.google.com/document/d/1YbtM05lwUBTRHatzPAjkyq9Ka6qP7pseflobxQRiuQ/edit?usp=sharing">https://docs.google.com/document/d/1YbtM05lwUBTRHatzPAjkyq9Ka6qP7pseflobxQRiuQ/edit?usp=sharing</a>	
CoDR	<a href="https://docs.google.com/presentation/d/1tT4GjP71thi6Ot-SsOX_cbyehLpWfIyG9JvD9nKB/edit?usp=sharing">https://docs.google.com/presentation/d/1tT4GjP71thi6Ot-SsOX_cbyehLpWfIyG9JvD9nKB/edit?usp=sharing</a>		
DR1	<a href="https://docs.google.com/presentation/d/1uA4myq3uqHwTqlvJokINjMkcZKKkVCZZ9d3PL8PS-E/edit?usp=sharing">https://docs.google.com/presentation/d/1uA4myq3uqHwTqlvJokINjMkcZKKkVCZZ9d3PL8PS-E/edit?usp=sharing</a>	<a href="https://docs.google.com/document/d/18uXXml2SqlZtIVQJzQtSNLmzKZRb47fLRSoLq7tdo/edit?usp=sharing">https://docs.google.com/document/d/18uXXml2SqlZtIVQJzQtSNLmzKZRb47fLRSoLq7tdo/edit?usp=sharing</a>	
MaDR	<a href="https://docs.google.com/presentation/d/1QIUoSHBqA2qlwbyJEaCi2AIvX3FY4eyrOpVhluaWEJE/edit?usp=sharing">https://docs.google.com/presentation/d/1QIUoSHBqA2qlwbyJEaCi2AIvX3FY4eyrOpVhluaWEJE/edit?usp=sharing</a>		

**Design Requirements**

Design Requirement	Target	Expected	Scrutineer's Notes
Minimal deflection of brake pedal under 2kn load	Meet Value (Minimal) 0.00008921487897 meters	6061 Tys = 276 MPa	<ul style="list-style-type: none"><li>As was mentioned before, stress is not the same as strain. Stress has been listed instead of a maximum deflection in a unit of length. We calculated deflection to be as listed. However, what would be the difference for calculating stress and what parameters would we use? Please send help.</li><li>How are you determining what is the maximum deflection? I.E What data-driven method are you using to say whether or not a certain amount of deflection is allowable? Maximum deflection is being calculated using the formula for deflection of a cylinder. How else would we have to approach this measurement?</li></ul>
Pedal assembly have a minimum 25 mm clearance to the: 1. Rear face of the Anti Intrusion Plate	Meet Value	2-in from front bulkhead	<ul style="list-style-type: none"><li>Why 2 in when the rules only require 1 in?</li><li>More room extension of brake pedal and master cylinder wiring attachment to the frame.</li></ul>

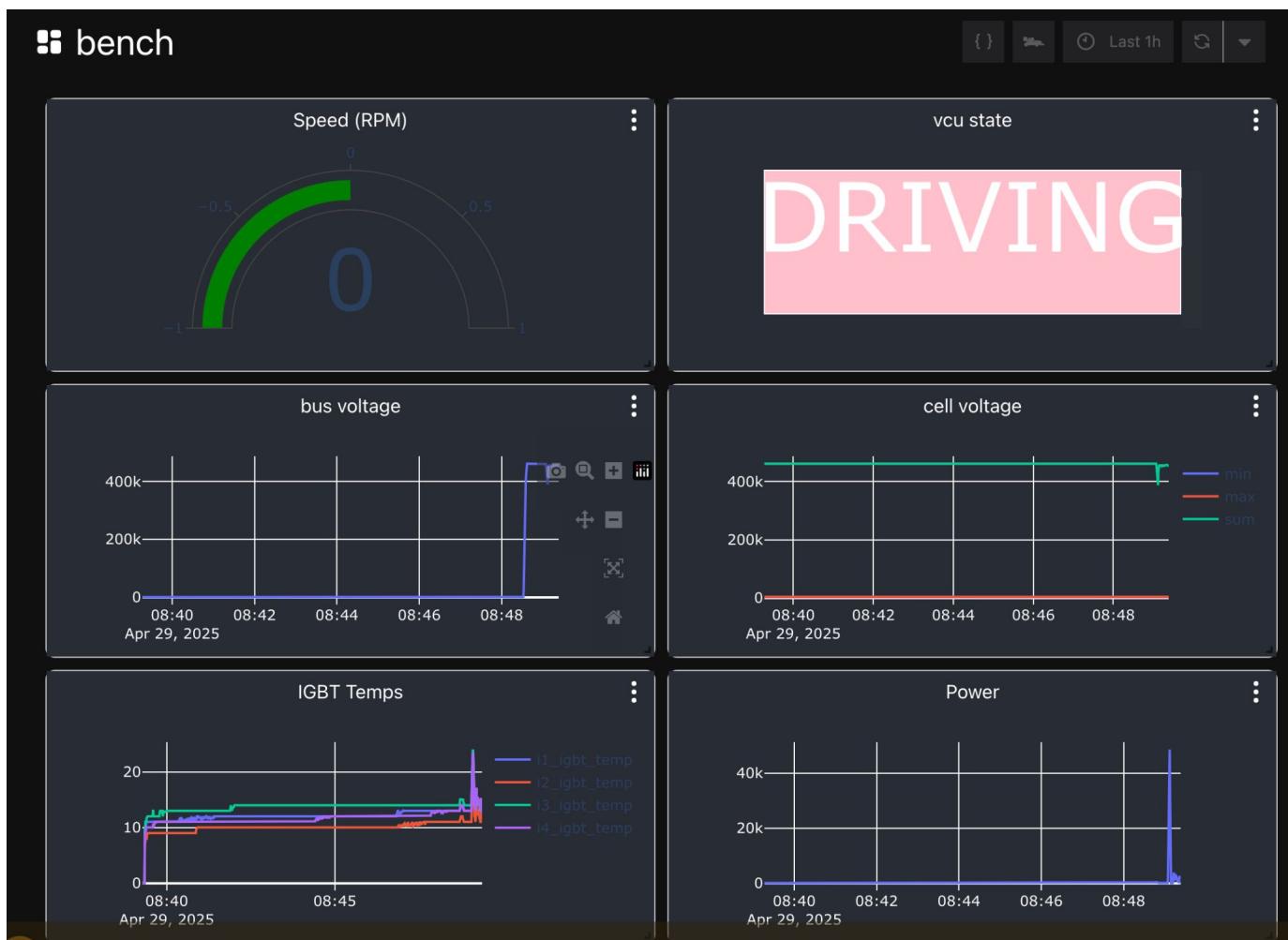
Go/no go dates, build gates

- Boron CF battery box

# Testing and Validation

Over 200km run:

- 5 Representative Endurances
  - Live telemetry to monitor temperatures, speeds, and bus voltage throughout the run
- > 10 Accel Runs
- > 10 Skid Pad Runs
  - Sweeping suspension set up, controls tuning
- > 10 hours of autocross driver training



This is the FE On Bench version of the telemetry website. It is restricted to only have some dashboard functionality for debugging. Please report any bugs or feature requests.

# Resources

- Include here anything that you referenced in the slides
  - Research papers, articles, books, someone else's data, ect.