# Eric Lefort

Tenstorrrent Digital Design Engineering — Al and robotics research at TUM LSY Lab

Toronto, Canada

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## Education

2020–2025 University of Toronto, BASc, Engineering Science: Robotics Engineering, cGPA 3.82/4.0.

# Experience

May 2024— Learning Systems and Robotics Lab, Research Student.

Aug 2024 Technische Universität München. Supervisor: Dr. Angela Schoellig.

- Experimental reinforcement learning using reduced latent action space for more efficient exploration. Applications
  with high-dimensional and redundant action spaces.
- Implemented control pipeline for Franka Emika FR3 robot using libfranka and ROS.
- Creation of MuJoCo simulation environment for lego brick assembly and tuning collision physics

May 2023— **Tenstorrent Inc.**, Al Silicon Digital Design Co-op, System-On-Chip team.

Apr 2024 o Maintained Python script for parametric generation of chip interconnect network

- Added support for mesh interconnect topology

- Created SystemVerilog + C API for writing C-based Network-On-Chip tests in full-chip simulation.
- Design and optimized RISC-V CPU for data movement engine using Chipyard Rocket Chip generator. Benchmarking and optimizing memory system, bus widths, CDC, etc. for optimal PPA.
- May 2022— Computational Aerodynamics Group, Research Intern.
- Aug 2022 University of Toronto Institute for Aerospace Studies. Supervisor: Dr. David W. Zingg
  - Analyzed flow solver performance to identify avenues for improving CFD algorithms.
  - Researched unconventional methods to create meshes more quickly and easily.
  - Implemented finite-difference algorithms for solving partial differential equations.
- Sep 2021- University of Toronto Formula SAE Team, Senior Member, Aerodynamics, Manufacturing.
- Feb 2023 Used StarCCM to run simulations and optimize parameters for aerodynamic performance
- May 2021 Rocscience Inc, Software Developer.
- Aug 2021 Automated UI testing and creation of documentation using TestComplete and Python
  - Improved scalability and automation of UI testing process using Azure DevOps

#### Skills

- Coding Python, C, C++, MATLAB, Git, SystemVerilog, ROS
- Software Linux, Solidworks, Fusion360, StarCCM, LTSpice, LaTeX
- Machining Metalworking (mill, lathe, drills, etc.), Laser Cutter, 3D printer
- Languages English, French

# Projects

- Apr 2023 Design and training of variant chess engine using CNNs, Python, PyTorch, C.
  - Supervised training of a CNN model to perform chess board evaluation function
  - Implementation of heuristic search for atomic chess using trained evaluation function.
- Mar 2023 Built a mobile robot with path following and obstacle avoidance, C++.
  - Control using Arduino Uno. Scanning ultrasonic sensor to detect obstacles and perform path-finding
- Oct 2022 Programming TurtleBot Waffle Pi robots, ROS, Pvthon.
  - o Manually implemented bayesian methods using ROS to localize robot using landmarks.

### Achievements & Certifications

- Aug 2022 Kenneth Ward Smith Scholarship, FASE Scholarship, Academic Achievement.
- Apr 2022 NSERC USRA (turned down).
- Aug 2020 AP Scholar Award, College Board, Calculus BC, Physics C: Mechanics, Electricity & Magnetism.
  - Awarded for the achievement of three perfect 5/5 scores on AP examinations