

## Problem 1: Newton Raphson

### Problem Statement

**a**

Using Newton-Raphson, solve the following system of equations in  $\mathbb{R}^2$ :

$$f_1(x) := 4x_2^2 + 4x_2 + 52x_1 - 19 = 0$$

$$f_2(x) := 169x_1^2 + 3x_2^2 + 111x_1 - 10x_2 - 10 = 0$$

starting from  $x^0 = (5, 0)$ .

Report  $x^1$  and  $x^2$ . Terminate your iteration when the 2-norm of  $f$  is less than  $10^{-10}$ . Report if it does not converge in 100 iterations. If it converges, report  $x^*$  and the iteration count.

Plot the error magnitudes  $\|x^k - x^*\|$  as a function of  $k$  on a semilog plot.

**b**

Repeat (a), but with forward-difference approximation, using  $h = 0.5$ .

**b**

Repeat (a), but with center-difference approximation, using  $h = 0.5$ .

**d**

Repeat (a), but using Jacobian surrogates defined by Broyden's method. Clearly state how you start the sequence of Jacobian surrogates and how you choose  $x^1$ .

**e**

Vary the starting point appropriately and discuss qualitatively how the iterative process in parts a-d behave. If you have to choose between methods b-d, which one would you choose? Will this change if evaluation of  $f$  is much more computationally expensive?

### Solution

**a-d**

See code at end of document for implementation, or my repo here:

<https://github.com/eric-silk/ECE530>

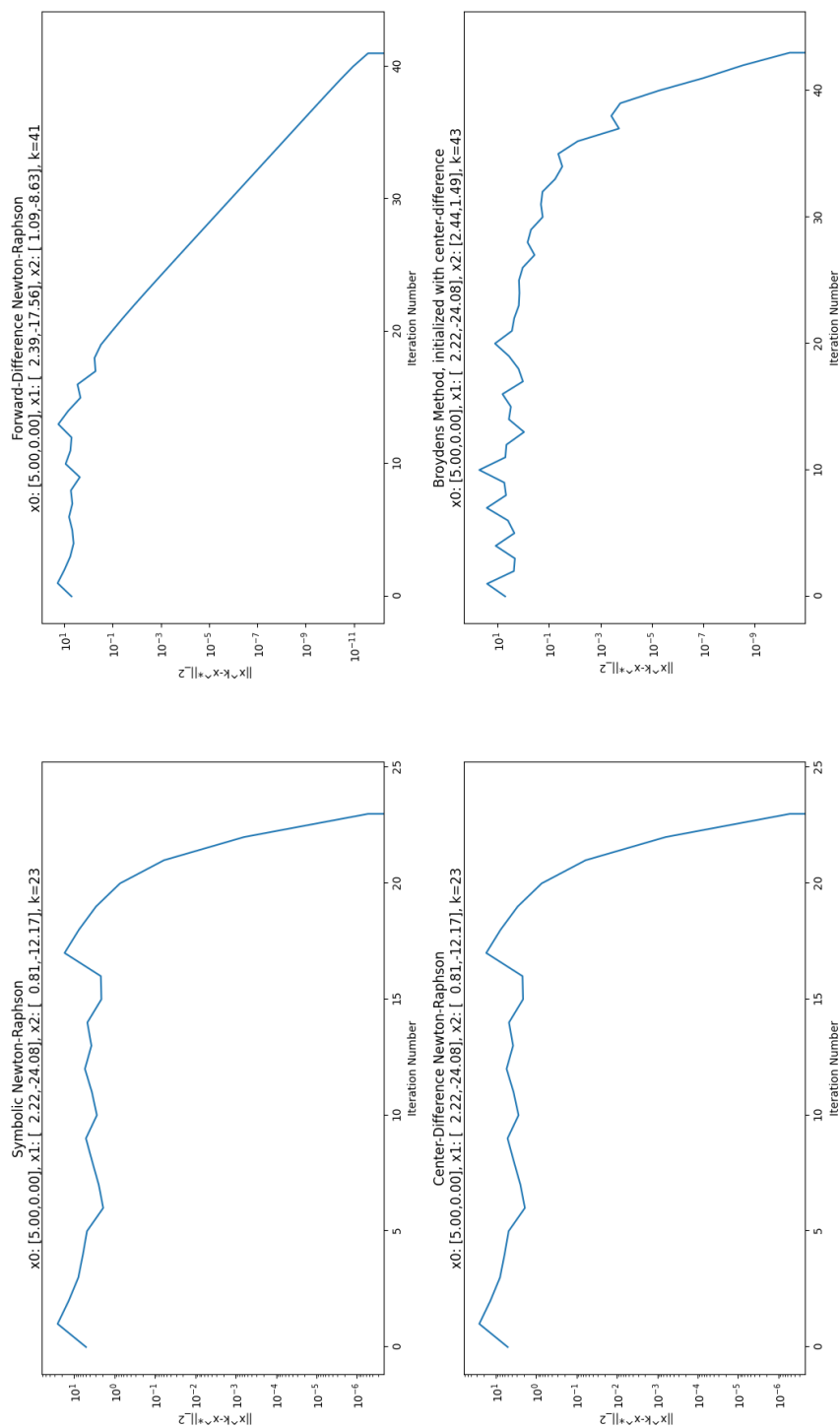
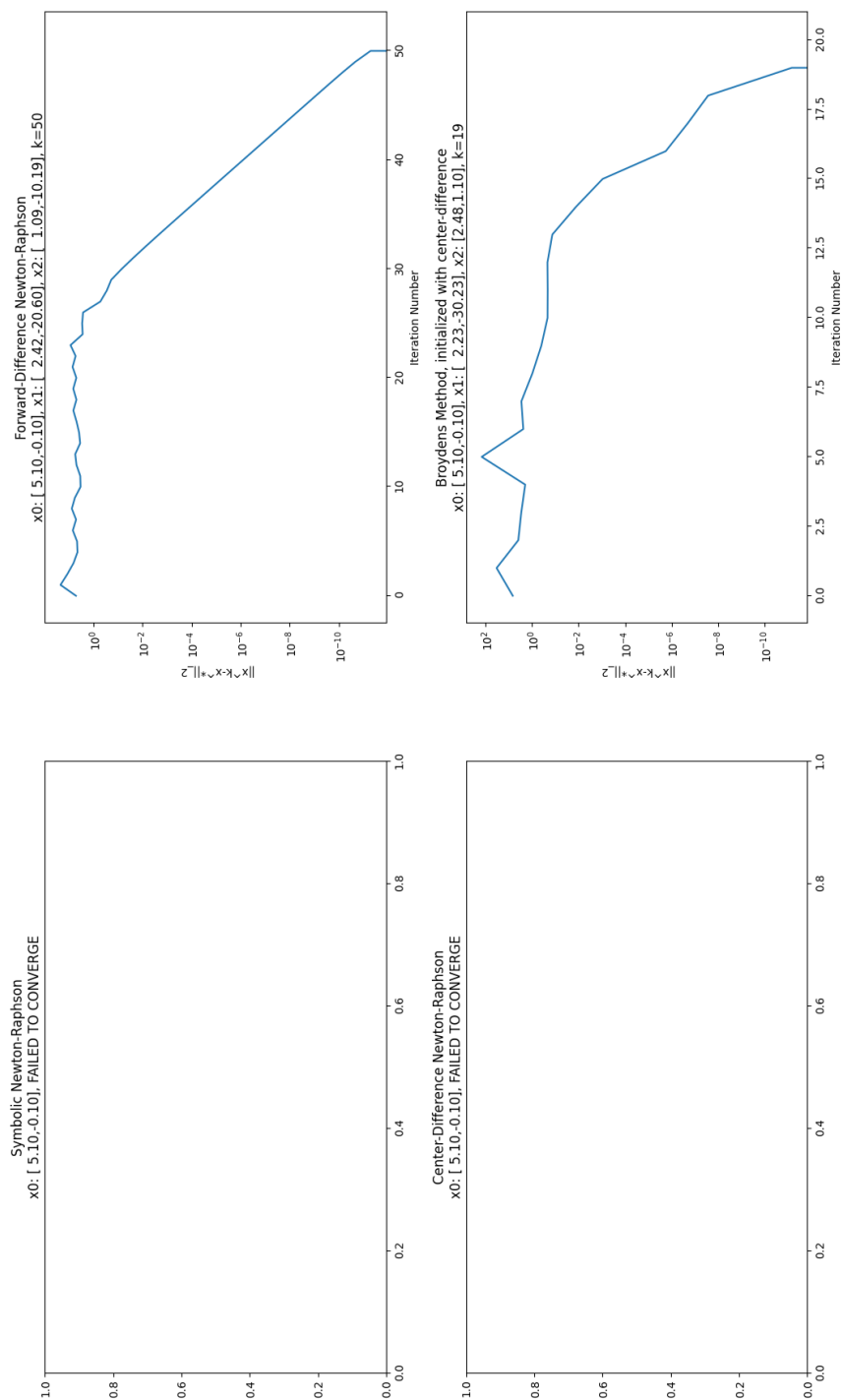


Figure 1: The four methods, started from (5, 0)

Figure 2: The four methods, started from  $(5.1, -0.1)$

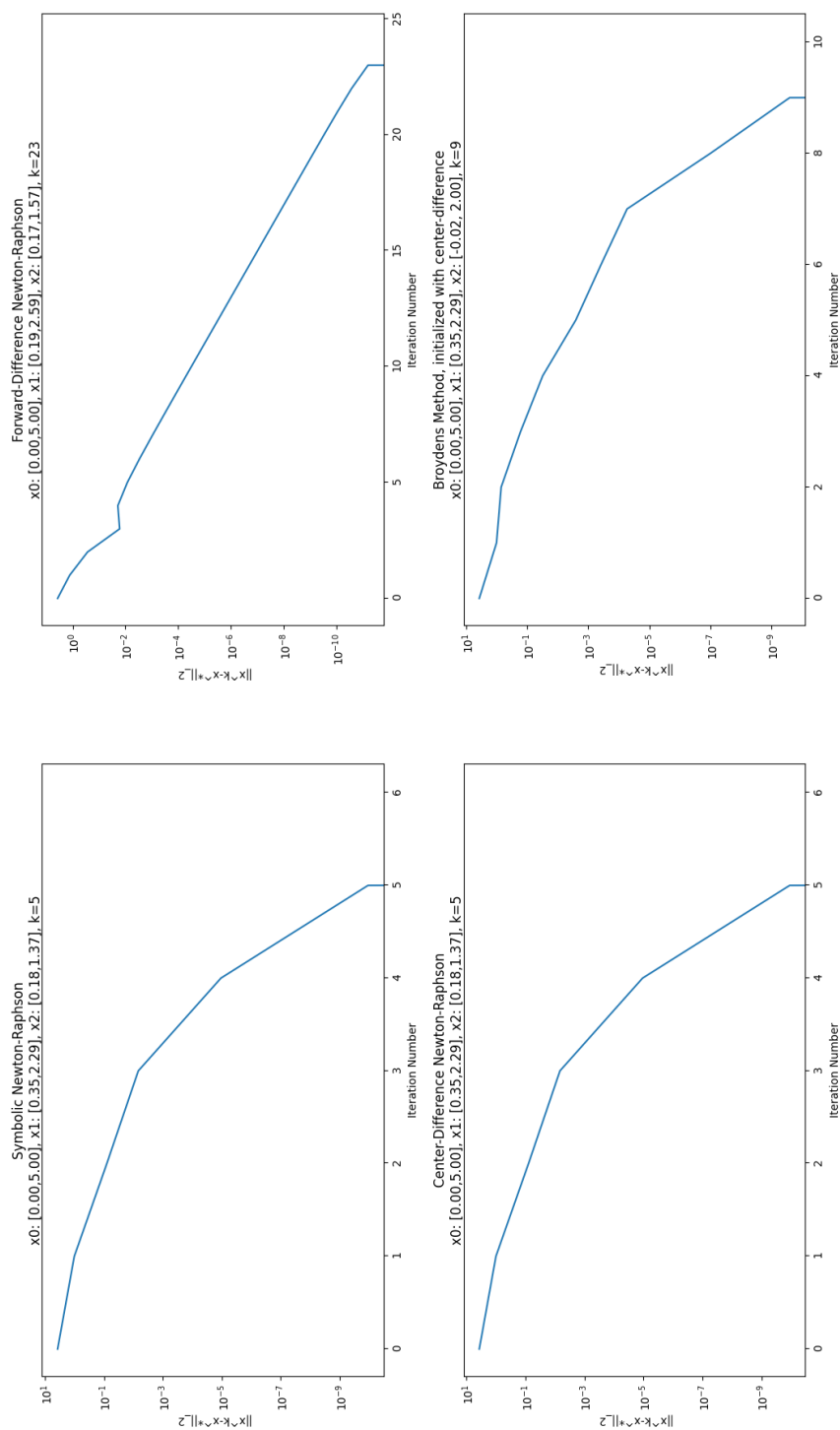
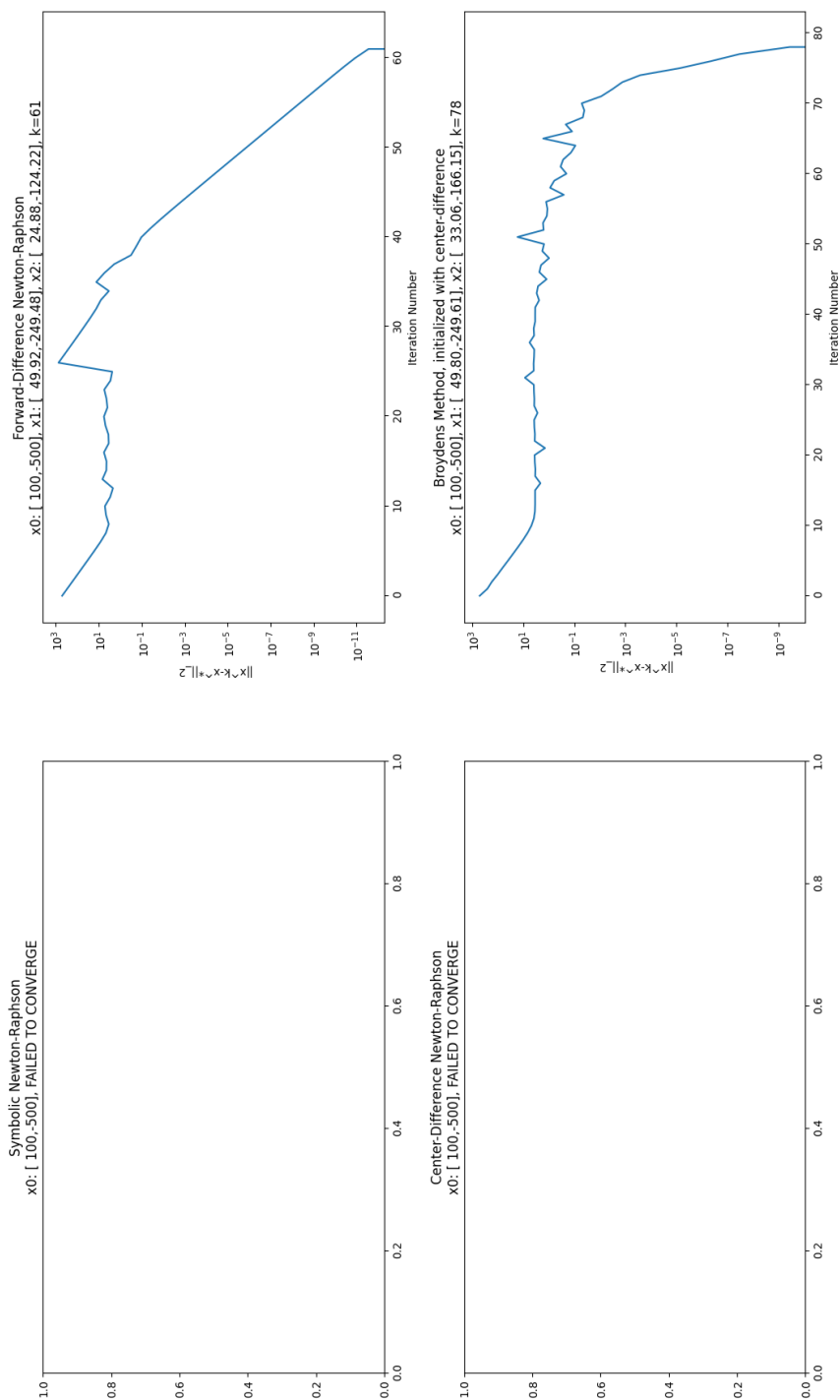


Figure 3: The four methods, started from (0, 5)

Figure 4: The four methods, started from  $(100, -500)$

## Problem 2: Understanding Numerical Differentiation

### Problem Statement

We have empirically seen in class that the approximation quality of center difference approximation is far superior to that of forward and backward difference ones, when performing numerical differentiation. In this problem, we gain analytical insight into this behavior.

Suppose  $f : \mathbb{R} \rightarrow \mathbb{R}$  is at least  $C^3$  over  $[a, b]$ . The following Taylor's series expansion of  $f$  might be useful:

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2}f''(x) + \frac{h^3}{6}f'''(\zeta)$$

$\forall x, x+h \in (a, b)$  where  $\zeta$  lies on the line segment joining  $x$  and  $x+h$ .

**a**

Show that

$$\left| \frac{f(x+h) - f(x)}{h} - f'(x) \right| \leq M|h| \forall x \in (a, b), M > 0$$

**b**

Show that

$$\left| \frac{f(x+h) - f(x-h)}{2h} - f'(x) \right| \leq N|h|^2 \forall x \in (a, b), N > 0$$

**c**

Qualitatively discuss what the results in (a) and (b) mean.

### Solution

**a**

Re-arrange the provided Taylor series expansion and take the absolute value of both sides:

$$\left| \frac{f(x+h) - f(x)}{h} - f'(x) \right| = \left| h \left( \frac{1}{2}f''(x) + \frac{1}{6}hf'''(\zeta) \right) \right| = |h| \left| \frac{1}{2}f''(x) + \frac{1}{6}hf'''(\zeta) \right|$$

Now we just need to bound the rightmost absolute value. From the class notes ("Solving nonlinear equations"), note that because  $\zeta$  lies on the line segment connecting  $a$  and  $b$ ,  $\zeta \in [a, b]$ . Because the function is  $C^3$  over  $[a, b]$ , there exists a scalar  $M_1$  and  $M_2$  that bounds  $f''$  and  $f'''$  (repspectively) from above. So:

$$\left| \frac{1}{2}f''(x) + \frac{1}{6}hf'''(\zeta) \right| \leq \left| \frac{1}{2}M_1 + \frac{1}{6}hM_2 \right|$$

Finally, because  $h$  is some fixed value, the whole quantity is bounded, and we can say:

$$\begin{aligned} \left| \frac{1}{2}M_1 + \frac{1}{6}hM_2 \right| &\leq M \\ \therefore \left| \frac{f(x+h) - f(x)}{h} - f'(x) \right| &\leq M|h| \end{aligned}$$

□

**b**

We can modify the expansion to consider a negative  $h$ , or equivalently the subtraction of a positive  $h$ :

$$f(x - h) = f(x) - hf'(x) + \frac{h^2}{2}f''(x) - \frac{h^3}{6}f'''(\zeta)$$

Then, subtract the two series to find:

$$\begin{aligned} f(x + h) - f(x - h) &= f(x) + hf'(x) + \frac{h^2}{2}f''(x) + \frac{h^3}{6}f'''(\zeta) - f(x) + hf'(x) - \frac{h^2}{2}f''(x) + \frac{h^3}{6}f'''(\zeta) \\ &= 2hf'(x) + \frac{2h^3}{6}f'''(\zeta) \end{aligned}$$

Rearranging:

$$\begin{aligned} \frac{f(x + h) - f(x - h)}{2h} - f'(x) &= \frac{h^2}{6}f'''(\zeta) \\ \left| \frac{f(x + h) - f(x - h)}{2h} - f'(x) \right| &= \left| \frac{h^2}{6}f'''(\zeta) \right| = |h^2| \left| \frac{1}{6}f'''(\zeta) \right| \end{aligned}$$

By the same logic as in (2.a), we know that  $f'''(\zeta)$  is upper bounded, so we can say:

$$\frac{1}{6}f'''(\zeta) \leq N$$

Thus:

$$\left| \frac{f(x + h) - f(x - h)}{2h} - f'(x) \right| \leq |h^2| N$$

□

**c**

As the proofs show, there's a cancellation effect that occurs for some of the more significant error terms, resulting in the far better approximation (at least for "small"  $h$ ). There's an "averaging" effect that reduces the error.

Expanding on the numerical example provided in class, it's worth looking at it as a form of a statistical filter<sup>1</sup>. Some "signal" (the error of the approximation) is oversampled at a  $2x$  rate and then is passed through an averaging filter. Assume that:

1. The samples are uncorrelated
2. The distribution of each sample is *normal*

which seems justified based on the numerical results presented in class. Then, letting  $X_i$  denote the distribution of the samples (where  $i = 1, 2$ ), and  $\bar{X}$  denote the average (i.e. the output of the filter), we can say:

$$\text{Var}(\bar{X}) = \text{Var}\left(\frac{1}{N} \sum_{i=1}^N X_i\right) = \text{Var}\left(\frac{1}{N} \sum_{i=1}^N X_i\right) = \frac{1}{N^2} \text{Var}\left(\sum_{i=1}^N X_i\right) = \frac{1}{N^2} \sum_{i=1}^N \text{Var}(X_i)$$

If the variances are the same ( $X_1 = X_2 = X$ ), then we get:

$$\text{Var}(\bar{X}) = \frac{1}{2} \text{Var}(X)$$

Now, this doesn't seem to imply quite aggressive reduction in variance as demonstrated by the numerical example given in class, but it's at least a way to start thinking about how this works.

<sup>1</sup>Note: I'm not exactly a wizard at stats, take this with a grain of salt...

## Code Listing

```

1 import time
2
3 import numpy as np
4 import matplotlib.pyplot as plt
5
6 h = 0.5
7
8
9 def f(x: np.ndarray) -> np.ndarray:
10     x1, x2 = x[0], x[1]
11     fx1 = 4 * x2**2 + 4 * x2 + 52 * x1 - 19
12     fx2 = 169 * x1**2 + 3 * x2**2 + 111 * x1 - 10 * x2 - 10
13
14     return np.array([fx1, fx2])
15
16
17 def Jf(x: np.ndarray) -> np.ndarray:
18     x1, x2 = x[0], x[1]
19     ret = np.array([[52.0, 8.0 * x2 + 4.0], [338.0 * x1 + 111.0, 6.0 * x2 - 10.0]])
20
21     return ret
22
23
24 def symbolic_newton(x):
25     return x - (np.linalg.pinv(Jf(x)) @ f(x))
26
27
28 def forward_difference_newton(x):
29     J = np.zeros((2, 2))
30     J[:, 0] = (f(x + np.array([h, 0])) - f(x)) / h
31     J[:, 1] = (f(x + np.array([0, h])) - f(x)) / h
32
33     return x - (np.linalg.pinv(J) @ f(x))
34
35
36 def center_difference_newton(x):
37     J = np.zeros((2, 2))
38     J[:, 0] = (f(x + np.array([h, 0])) - f(x - np.array([h, 0]))) / (2 * h)
39     J[:, 1] = (f(x + np.array([0, h])) - f(x - np.array([0, h]))) / (2 * h)
40
41     return x - (np.linalg.pinv(J) @ f(x))
42
43
44 class BroydensMethod:
45     def __init__(self, J0):
46         self.J = J0
47
48     def __call__(self, x):
49         fx = f(x)
50         dx = -np.linalg.solve(self.J, fx)
51         x_i = x + dx
52         dfx = f(x_i) - fx
53         self.J += np.outer((dfx - (self.J @ dx)), dx.T) / (
54             np.linalg.norm(dx, ord=2) ** 2
55         )
56
57         return x_i
58
59
60 def solve_and_plot(
61     desc: str,
62     iterator,
63     x0: np.ndarray,
64     fig: plt.Figure,
65     ax: plt.Axes,
66     epsilon: float = 1e-10,
67     iter: int = 100,
68 ) -> None:
69     _ = fig
70     x = x0
71     xs = []
72     xs.append(x0)
73     t0 = time.time()
74     tf = np.inf
75     converged = False
76     k = 0
77     for i in range(iter):
78         try:
79             x = iterator(x)
80             eps = np.linalg.norm(f(x), ord=2)
81             xs.append(x)
82             if eps < epsilon:
83                 tf = time.time() - t0
84                 print(f"Converged at iteration {i+1}")
85                 converged = True
86                 k = i
87                 break
88         except Exception as e:

```



```

89         print(f"Exception occurred at iterate {i}")
90         k = -1
91         raise e
92     else:
93         print(f"Failed to converge in {iter} iterations!")
94
95     xs = np.array(xs)
96     errors = xs - xs[-1]
97     errors = np.array([np.linalg.norm(i, ord=2) for i in errors])
98     convert = lambda x: np.array2string(
99         x, precision=2, separator=",", floatmode="fixed"
100     )
101     if converged:
102         ax.semilogy(errors)
103         ax.set_xlabel("Iteration Number")
104         ax.set_ylabel("||x^k - x^*||_2")
105         ax.set_title(
106             f"{desc}\nx0: {convert(x0)}, x1: {convert(xs[1])}, x2: {convert(xs[2])}, k={k}",
107             pad=-20,
108         )
109     else:
110         ax.set_title(f"{desc}\nx0: {convert(x0)}, FAILED TO CONVERGE")
111
112 if __name__ == "__main__":
113     x0s = [
114         np.array([5.0, 0.0]),
115         np.array([5.1, -0.1]),
116         np.array([0.0, 5.0]),
117         np.array([100, -500]),
118     ]
119
120     for x0 in x0s:
121         fig, axes = plt.subplots(2, 2)
122         fig.tight_layout()
123         solve_and_plot("Symbolic Newton-Raphson", symbolic_newton, x0, fig, axes[0, 0])
124
125         solve_and_plot(
126             "Forward-Difference Newton-Raphson",
127             forward_difference_newton,
128             x0,
129             fig,
130             axes[0, 1],
131         )
132
133         solve_and_plot(
134             "Center-Difference Newton-Raphson",
135             center_difference_newton,
136             x0,
137             fig,
138             axes[1, 0],
139         )
140
141         J0 = np.zeros((2, 2))
142         J0[:, 0] = (f(x0 + np.array([h, 0])) - f(x0 - np.array([h, 0]))) / (2 * h)
143         J0[:, 1] = (f(x0 + np.array([0, h])) - f(x0 - np.array([0, h]))) / (2 * h)
144         print(f"Broyden's Method J0:\n{J0}")
145         solve_and_plot(
146             "Broydens Method, initialized with center-difference",
147             BroydensMethod(J0),
148             x0,
149             fig,
150             axes[1, 1],
151         )
152
153 plt.show()
154

```