Problem 1: Where do you belong, Krylov?

Solution

 \mathbf{a}

$$Aq^{i} = \frac{q^{i+1}}{\|q^{i+1}\|} + \sum_{k=1}^{i} \langle Aq^{i}, q^{k} \rangle q^{k} \in \mathcal{K}_{i+1}$$

b

We firstly note that $q^1 = \frac{b}{\|b\|}$, and so we can note that it is a scaled version of b. Take this to be the first element of a Krylov subspace $\mathcal{K}^1 = q^1$. Furthermore, note that the definition of q^2 (or more generally, q^{i+1}) is equivalent to multiplying Aq^i and subtracting the projection of the prior q's. Critically, because the subspace is defined as the span of a set of vectors, the resulting set of orthonormal vectors define an equivalent Krylov subspace – they are, in fact, an orthonormal basis of this subspace.

So, we can say:

$$\mathcal{K}^{i} = \operatorname{span}\left(\left\{\frac{b}{\|b\|}, Aq_{1}, \dots, Aq_{i-1}\right\}\right)$$

$$\parallel$$

$$\left[Aq_{1} \mid \dots \mid Aq_{n}\right] = \left[Qh_{1} \mid \dots \mid Qh_{n}\right]$$

$$\Rightarrow Aq_{1} = Qh_{1}$$

$$Aq_{1} \in \mathcal{K}_{2} \Rightarrow Qh_{1} \in \mathcal{K}_{2}$$

$$\parallel$$

$$Aq_{1} = \begin{bmatrix} * \\ * \\ 0 \\ 0 \end{bmatrix}, Aq_{2} = \begin{bmatrix} * \\ * \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \dots Aq_{n} = \begin{bmatrix} * \\ * \\ * \\ \vdots \\ * \end{bmatrix}$$

 \mathbf{c}

See the code section at the end for the implementation. The result is:

Wow its upper Hessenberg, whoda thunk it
Wow its lower Hessenberg, whoda thunk it

Wow it's tridiagonal, its cuz the matrix A is Hermitian (or Symmetric cuz its real)

Problem 2: Ask Gram, Schmidt, or Givens for QR

Solution

 \mathbf{a}

Taken from "Linear Algebra Done Right" by Sheldon Axler.

Suppose v_1, \ldots, v_m is a lin. ind. list of vectors in V. Let $e_1 = \frac{v_1}{\|v_1\|}$. For $j = 2, \ldots, m$, define e_j inductively by:

$$e_j = \frac{v_j - \langle v_j, e_1 \rangle e_1 - \dots - \langle v_j, e_{j-1} \rangle e_{j-1}}{\|v_i - \langle v_i, e_1 \rangle e_1 - \dots - \langle v_i, e_{j-1} \rangle e_{j-1}\|}$$

(i.e. the Gram-Schmidt process definition). Then, e_1, \ldots, e_m is an orthonormal list of vectors in V s.t.:

$$\operatorname{span}(v_1, \dots, v_j) = \operatorname{span}(e_1, \dots, e_j) \forall j = 1, \dots, m$$

Note that for j = 1, span $(v_1) = \text{span}(e_1)$ because v_1 is a positive mulitple of e_1 . Suppose 1 < j < m and it has been verified that:

$$span(v_1, ..., v_{i-1}) = span(e_1, ..., e_{i-1})$$

Note that $v_j \notin \text{span}(v_1, \dots, v_{j-1})$ because $v_1 \dots, v_m$ are linearly independent. Thus, $v_j \notin \text{span}(e_1, \dots, e_{j-1})$. As such, we are not dividing by zero in the definition of e_j . We can also see that $||e_j|| = 1$ by its definition.

Let $k \in [1, j)$. Then:

$$\langle e_j, e_k \rangle = \left\langle \frac{v_j - \langle v_j, e_1 \rangle e_1 - \dots - \langle v_j, e_{j-1} \rangle e_{j-1}}{v_j - \langle v_j, e_1 \rangle e_1 - \dots - \langle v_j, e_{j-1} \rangle e_{j-1}}, e_k \right\rangle$$

$$= \frac{\langle v_j, e_k \rangle - \langle v_j, e_k \rangle}{v_j - \langle v_j, e_1 \rangle e_1 - \dots - \langle v_j, e_{j-1} \rangle e_{j-1}}$$

$$= 0$$

Thus e_1, \ldots, e_j is an orthonormal list.

From the definition of e_j , we see that $v_j \in \text{span}(e_1, \dots, e_j)$. Combined with the equivalency of the spans provided above, we know:

$$\operatorname{span}(v_1,\ldots,v_j)\subset\operatorname{span}(e_1,\ldots,e_j)$$

Both these lists are lin. ind., thus both subspaces have dimension j and are equal.

b

The inner loop requires:

$$(4m-1)(1-1)+(4m-1)+(2-1)+\ldots+(4m-1)(n-1)=(4m-1)(0+1+\ldots+n-1)=(4m-1)(\frac{1}{2}n(n+1)-1)$$

The outer portion requires (4m-1)*n operations. Summing:

$$= (4m+1)(\frac{1}{2}n(n+1)-1) + (4m+1)(n) = (4m+1)(\frac{1}{2}n(n)-1+n)$$

Simplifying and discarding lower order terms we find:

$$=2mn^2$$

Algorithm 1 Classical Gram-Schmidt, annotated with FLOP counts

```
for j=1,\ldots,n do v\leftarrow a^j for i=1,\ldots,j-1 do R_{ij}\leftarrow \langle v,q^i\rangle \{m \text{ multiplications, }(m-1) \text{ additions }\Longrightarrow 2m-1\} v\leftarrow v-R_{ij}q^i \{m \text{ multiplications, }m \text{ subtractions }\Longrightarrow 2m\} end for {Total cost is } q^j\leftarrow \frac{v}{\|v\|} \{m \text{ multiplications, }m-1 \text{ additions, }1 \text{ for sqrt }\Longrightarrow 2m\} R_{jj}\leftarrow \langle a^j,q^j\rangle \{m \text{ multiplications, }(m-1) \text{ additions }\Longrightarrow 2m-1\} end for Q=(q^1|\ldots|q^n)
```

 \mathbf{c}

An upper Hessenberg matrix of size $n \times n$ will require n-1 operations to zero out the non-zero elements below the diagonal, which will result in a QR decomposition. Givens matrices take the form:

$$G_n = \begin{bmatrix} 1 & \cdots & 0 & \cdots & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & & \vdots & & \vdots \\ 0 & \cdots & c & \cdots & -s & \cdots & 0 \\ \vdots & & \vdots & \ddots & \vdots & & \vdots \\ 0 & \cdots & s & \cdots & c & \cdots & \vdots \\ \vdots & & \vdots & & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & \cdots & 0 & \cdots & 1 \end{bmatrix}$$

The location of the c and s terms correspond to zeroing element i and j; that is, to zero element $A_{i,j}$, we set $s = G_{ji} = -Gij$ and $G_{k,k} = c$ for k = i, j (and 1 for $k \neq i, j$). The resulting algorithm is as follows:

Algorithm 2 QR Factorization of an Upper Hessenberg Matrix using Givens rotations

```
Input: A^1 \in \mathbb{R}^{n \times n}, A_{ij} = 0 \forall i > j+1 {This could be a parfor} for j = 1, \ldots, n-1 do i \leftarrow j+1 r^j \leftarrow \sqrt{\left[A^j_{jj}\right]^2 + \left[A^j_{ij}\right]^2} c \leftarrow A^j_{jj}/r s \leftarrow -A^j_{ij}/r G^j_{ji} \leftarrow s G^j_{ij} \leftarrow s G^j_{ij} \leftarrow c G^j_{ij} \leftarrow c A^{j+1} \leftarrow G^j A^j end for Q = \prod_{j=1}^{n-1} G^j R = A^{n-1}
```

Code

Problem 1

```
#!/usr/bin/env python3
import numpy as np
     float\_formatter = "{:.2 f}".format
     np.set_printoptions(formatter={"float_kind": float_formatter})
     \begin{array}{lll} \textbf{def} & \texttt{is\_upper\_hessenberg} \ (A: \ \texttt{np.ndarray}) \ \rightarrow \ \textbf{bool:} \\ & \texttt{return} & \texttt{np.isclose} \ (\texttt{np.tril} \ (A, \ k=-2), \ 0.0 \ , \ \ \texttt{atol=1e-3).all} \ () \end{array}
10
     def is-lower_hessenberg(A: np.ndarray) -> bool:
    return np.isclose(np.triu(A, k=2), 0.0, atol=1e-3).all()
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     # Adapted from: https://relate.cs.illinois.edu/course/cs450-s18/file-version/587 fb0505883e0622b9b144b532b5e9a4e7a3684/demos/upload/04-eigenvalues/Arnoldi%20iteration.html def arnoldi_iteration(A, b):
          arnoldi_iteration(A, b):

n = A.shape[0]

H = np.zeros((n, n))

Q = np.zeros((n, n))

# Normalize the input vector

Q[:, 0] = b / np.linalg.norm(b) # Use it as the first Krylov vector

for k in range(n):

u = A @ Q[:, k]

for j in range(k + 1):

qj = Q[:, j]

H[j, k] = qj @ u

u -= H[j, k] * qj

if k + 1 < n:

H[k + 1, k] = np.linalg.norm(u)

Q[:, k + 1] = u / H[k + 1, k]
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            return Q, H
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            42
43
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45
            print("Q:")
print(q)
print("H:")
print(h)
46
47
48
            uh = is_upper_hessenberg(h)
lh = is_lower_hessenberg(h)
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51
52
53
54
55
            print("Wow its upper Hessenberg, whoda thunk it")
if lh:
            56
57
58
                           "Wow it's tridiagonal, its cuz the matrix A is Hermitian (or Symmetric cuz its real)"
```