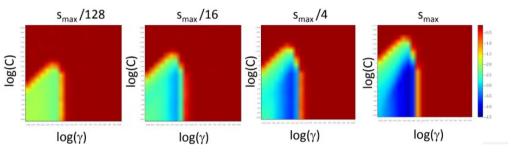
# Speedup Techniques for Hyperparameter Optimization

Multi-fidelity Bayesian optimization

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### Motivating example

• Performance of an SVM on MNIST and subsets of it:



- lacktriangle Computational cost grows quadratically in dataset size z
- lacktriangle Error shrinks smoothly with z
- ullet Evaluations on the smallest subset (about 400 data points) cost  $10\,000\times$  less than on the full data set

# Idea of Multi-fidelity Bayesian optimization [Kandasamy et al. 2017; Klein et al. 2016]

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- Denoting  $z_{\bullet}$  as the maximum fidelity (e.g.,  $z_{\bullet} = [N_{\bullet}, T_{\bullet}]$ ), our goal is to find:

$$\pmb{\lambda}^* = \operatorname*{arg\,min}_{\pmb{\lambda} \in \pmb{\Lambda}} f(\pmb{\lambda}) = \operatorname*{arg\,min}_{\pmb{\lambda} \in \pmb{\Lambda}} \hat{c}(\pmb{\lambda}, \pmb{z}_{\bullet})$$

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- Implications for Bayesian optimization
  - lacktriangle Model  $\hat{c}$  needs to be good at extrapolating from small to large z
  - lacktriangle Acquisition function now also needs to select z (i.e., take into account cost of evaluations)

#### Entropy Search: Reminder

• Define the  $p_{\min}$  distribution given data  $\mathcal{D}$ :

$$p_{\mathsf{min}}(\boldsymbol{\lambda}^* \mid \mathcal{D}) := p(\boldsymbol{\lambda}^* \in \operatorname*{arg\,min}_{\boldsymbol{\lambda} \in \boldsymbol{\Lambda}} f(\boldsymbol{\lambda}) \mid \mathcal{D})$$

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  - lacktriangleright It aims to be maximally certain about the location of  $oldsymbol{\lambda}^*$
- In a nutshell: select  $\lambda$  that maximizes the following acquisition function:

$$u_{ES}(\boldsymbol{\lambda}) := \mathcal{H}[p_{\mathsf{min}}(\cdot \mid \mathcal{D})] - \mathbb{E}_{p(\tilde{c}|\boldsymbol{\lambda},\mathcal{D})} \left[ \mathcal{H}[p_{\mathsf{min}}(\cdot \mid \mathcal{D} \cup \langle \boldsymbol{\lambda}, \tilde{c} \rangle)] \right]$$

 $\bullet$  We now care about the  $p_{\min}$  distribution for the maximal budget  $z_{\bullet}$ :

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- ullet We still want to minimize the entropy  $\mathcal{H}[p_{\mathsf{min}}]$
- Now we aim for the biggest reduction in entropy per time spent
  - Now we don't model only f, but also the cost  $c(\lambda, z)$
  - We choose the next  $(\lambda, z)$  by maximizing:

$$u_{ES}(\boldsymbol{\lambda},z\mid\mathcal{D}):=\mathbb{E}_{p(\tilde{c}\mid(\boldsymbol{\lambda},z),\mathcal{D})}\left[\frac{\mathcal{H}[p_{\mathsf{min}}(\cdot\mid\mathcal{D})]-\mathcal{H}[p_{\mathsf{min}}(\cdot\mid\mathcal{D}\cup\langle(\boldsymbol{\lambda},z),\tilde{c}\rangle}{c(\boldsymbol{\lambda},z)}\right]$$

- The entire algorithm iterates the following 2 steps until time is up:
  - **①** Select  $(\lambda, z)$  by maximizing:

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- **2** Observe performance  $f(\lambda, z)$  and cost  $c(\lambda, z)$  and update models for f and c
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#### Disadvantages

- Scalability of GPs is a big problem (limits size of initial design)
- ▶ Limited applicability of Gaussian processes

#### Questions to Answer for Yourself / Discuss with Friends

- Discussion. What kind of cost model would you use in Fabolas?
- Discussion. Could one use an acquisition function other than entropy search for Fabolas?