

# AutoML Lecture: Notation Cheat Sheet

Macro	Symbol	Meaning
<b>Machine Learning</b>		
<code>\dataset</code>	$\mathcal{D}$	Dataset
<code>\datasettrain</code>	$\mathcal{D}_{\text{train}}$	Training dataset
<code>\datasetval</code>	$\mathcal{D}_{\text{val}}$	Validation dataset
<code>\datasettest</code>	$\mathcal{D}_{\text{test}}$	Test dataset
<code>\datasets</code>	$\mathbf{D}$	Space of datasets
<code>\x</code>	$\mathbf{x}$	Feature vector
<code>\y</code>	$y$	Label
<code>\(\xI{i}, \yI{i}\)</code>	$(\mathbf{x}^{(i)}, y^{(i)})$	$i$ -th observation
<code>\loss(y, \fh(\x))</code>	$L(y, \hat{f}(\mathbf{x}))$	(empirical) loss
<code>\risks</code>	$\mathcal{R}$	risk
<code>\riske</code>	$\mathcal{R}_{\text{emp}}$	empirical risk
<code>\fx</code>	$f(\mathbf{x})$	continuous prediction function
<code>\Hspace</code>	$\mathcal{H}$	hypothesis space where $f$ is from
<code>\fh</code>	$\hat{f}$	estimated prediction function
<b>Hyperparameter Optimization</b>		
<code>\conf</code>	$\boldsymbol{\lambda}$	Hyperparameter configuration
<code>\conf_i</code>	$\lambda_i$	Value of $i$ -th hyperparameter
<code>\defconf</code>	$\lambda_{\text{def}}$	Default hyperparameter configuration
<code>\finconf</code>	$\hat{\boldsymbol{\lambda}}$	finally returned hyperparameter configuration
<code>\optconf</code>	$\boldsymbol{\lambda}^*$	Optimal hyperparameter configuration
<code>\pcs</code>	$\Lambda$	Space of possible hyperparameter configurations
<code>\algo</code>	$\mathcal{A}$	Algorithm (e.g. SVM, RF, DNN)
<code>\algos</code>	$\mathbf{A}$	Distribution or set of algorithms
<code>\cost(\conf)</code>	$c(\boldsymbol{\lambda})$	Target cost function (e.g., empirical risk, validation loss, runtime)
<code>\surro(\conf)</code>	$\hat{c}(\boldsymbol{\lambda})$	Surrogate (probabilistic) model of target function
<code>—</code>	$\mathcal{D}_{\text{Hist}} = \langle \boldsymbol{\lambda}^{(t)}, c(\boldsymbol{\lambda}^{(t)}) \rangle_{t=1}^T$	All observations collected for BO / HPO
<b>Gaussian Processes and Bayesian Optimization</b>		
<code>\gp</code>	$\mathcal{G}$	Gaussian process
<code>\bocount</code>	$t$	BO loop counter
<code>\bobudget</code>	$T$	BO loop counter max, the counter runs from 1 to this value
<code>\acq</code>	$u$	Acquisition Function, no args
<code>\pdf</code>	$\phi$	Standard Normal PDF
<code>\cdf</code>	$\Phi$	Standard Normal CDF
<code>\mean</code>	$\mu$	Mean
<code>\stddev</code>	$\sigma$	Standard Deviation
<code>\variance</code>	$\sigma^2$	Variance
<code>\noise</code>	$\nu$	Noise
<code>\realnum</code>	$\mathbb{R}$	Real numbers set
<code>\expectation</code>	$\mathbb{E}$	Expected value
<code>\kernel</code>	$\kappa$	kernel
<code>\constraintf</code>	$c$	Constraint function
<code>\normaldist</code>	$\mathcal{N}$	Normal distribution

Macro	Symbol	Meaning
<b>Algorithm Selection</b>		
<code>\feat</code>	$\mathbf{x}_{\text{meta}}$	Vector of (meta-) features
<code>\feats</code>	$\mathcal{X}_{\text{meta}}$	Space of (meta-)features
<code>\portfolio</code>	$\mathbf{P}$	Portfolio (i.e., discrete set) of algorithms or hyperparameter configurations
<code>\schedule</code>	$\mathcal{S}$	Schedule of algorithms or hyperparameter configurations
<b>Meta-Learning</b>		
<code>\weights</code>	$\theta$	Weights (a.k.a. parameters) of ML model (e.g., DNN)
<code>\metaweights</code>	$\phi$	Weights of meta-model
<code>\mdata</code>	$\mathcal{D}_{\text{meta}}$	Meta-dataset
<b>Reinforcement Learning</b>		
<code>\policy</code>	$\pi$	Reinforcement learning policy
<code>\policies</code>	$\Pi$	Space of policies
<code>\actionRL</code>	$a$	action in RL-setting
<code>\stateRL</code>	$s$	state in RL-setting
<code>\statesRL</code>	$\mathcal{S}$	Space of states
<code>\rewardRL</code>	$r$	Reward in RL-setting
<code>\rewardfuncRL</code>	$\mathcal{R}$	Random variable or function of reward
<b>Algorithm Configuration</b>		
<code>\cutoff</code>	$\kappa$	Cutoff (often runtime) of an algorithm run
<code>\inst</code>	$i$	a single instances (a.k.a. problem, dataset, task)
<code>\insts</code>	$\mathcal{I}$	Distribution over instances (a.k.a. problems, datasets, tasks)