AutoML: Beyond AutoML

Structured Procastination

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Idea

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- incumbent driven methods (such as aggressive racing with adaptive capping) provide no theoretical guarantees about runtime
- task: for a fix set of configuration, identify the one with the best average runtime
- instead of top-down capping, use bottom up capping
- start with a minimal cap-time and increase it step by step
- unsuccessful runs (with too small cap-time) are procrastinated to later
- → worst-case runtime guarantees

Algorithm 1 Structured Procrastination

```
Input : finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\ldots,i^{(N)}

Output : best incumbent configuration \hat{\lambda}

for each \lambda \in \Lambda initialize a queue Q_{\lambda} with entries (i^{(k)},\kappa_0); // small queue in the beginning initialize a look-up table R(\lambda,i)=0; // optimistic runtime estimate
```

Algorithm 2 Structured Procrastination

while b remains do

```
Input : finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\ldots,i^{(N)}

Output : best incumbent configuration \hat{\pmb{\lambda}}

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Algorithm 3 Structured Procrastination

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Input : finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\ldots,i^{(N)}

Output : best incumbent configuration \hat{\pmb{\lambda}}

for each \pmb{\lambda} \in \pmb{\Lambda} initialize a queue Q_{\pmb{\lambda}} with entries (i^{(k)},\kappa_0); // small queue in the beginning initialize a look-up table R(\pmb{\lambda},i)=0; // optimistic runtime estimate
```

while b remains do

determine the best $\hat{\boldsymbol{\lambda}}$ according to $R(\boldsymbol{\lambda},\cdot)$;

Algorithm 4 Structured Procrastination

determine the best $\hat{\lambda}$ according to $R(\lambda, \cdot)$; get first element $(i^{(k)}, \kappa)$ from Q_{\S} ;

```
Input : finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\ldots,i^{(N)}

Output : best incumbent configuration \hat{\lambda}

for each \lambda \in \Lambda initialize a queue Q_{\lambda} with entries (i^{(k)},\kappa_0); // small queue in the beginning initialize a look-up table R(\lambda,i)=0; // optimistic runtime estimate while h remains do
```

Algorithm 5 Structured Procrastination

if terminates then $R(\hat{\lambda}, i^{(k)}) := t$;

```
Input : finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\dots,i^{(N)} Output : best incumbent configuration \hat{\pmb{\lambda}} for each \pmb{\lambda} \in \pmb{\Lambda} initialize a queue Q_{\pmb{\lambda}} with entries (i^{(k)},\kappa_0); // small queue in the beginning initialize a look-up table R(\pmb{\lambda},i)=0; // optimistic runtime estimate while b remains do determine the best \hat{\pmb{\lambda}} according to R(\pmb{\lambda},\cdot); get first element (i^{(k)},\kappa) from Q_{\hat{\pmb{\lambda}}}; Run \hat{\pmb{\lambda}} on i^{(k)} capped at \kappa;
```

Algorithm 6 Structured Procrastination

```
: finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\ldots,i^{(N)}
Input
Output: best incumbent configuration \hat{\lambda}
for each \lambda \in \Lambda initialize a queue Q_{\lambda} with entries (i^{(k)}, \kappa_0);
                                                                                                                // small queue in the beginning
initialize a look-up table R(\lambda, i) = 0;
                                                                                                                 // optimistic runtime estimate
while b remains do
      determine the best \hat{\lambda} according to R(\lambda, \cdot):
        get first element (i^{(k)}, \kappa) from Q_{\mathfrak{J}};
        Run \hat{\lambda} on i^{(k)} capped at \kappa;
        if terminates then
       R(\hat{\lambda}, i^{(k)}) := t;
      else
        \left| \begin{array}{c} R(\pmb{\hat{\lambda}},i^{(k)}) := \kappa; \\ \text{Insert } (i^{(k)},2\cdot\kappa) \text{ at the end of } Q_{\pmb{\hat{\lambda}}}; \end{array} \right.
```

Algorithm 7 Structured Procrastination

```
: finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\ldots,i^{(N)}
Input
Output: best incumbent configuration \hat{\lambda}
for each \lambda \in \Lambda initialize a queue Q_{\lambda} with entries (i^{(k)}, \kappa_0);
                                                                                                  // small queue in the beginning
initialize a look-up table R(\lambda, i) = 0;
                                                                                                    // optimistic runtime estimate
while b remains do
     determine the best \hat{\lambda} according to R(\lambda, \cdot):
       get first element (i^{(k)}, \kappa) from Q_{\mathfrak{J}};
       Run \hat{\lambda} on i^{(k)} capped at \kappa:
       if terminates then
      R(\hat{\lambda}, i^{(k)}) := t;
     else
          R(\hat{\lambda}, i^{(k)}) := \kappa;
         Insert (i^{(k)}, 2 \cdot \kappa) at the end of Q_{\mathfrak{s}};
     Replenish queue Q_{\hat{i}} if too small;
```

Algorithm 8 Structured Procrastination

```
: finite (small) set of configurations \Lambda, minimal cap-time \kappa_0, sequence of instances i^{(1)},\ldots,i^{(N)}
Input
Output: best incumbent configuration \hat{\lambda}
for each \lambda \in \Lambda initialize a queue Q_{\lambda} with entries (i^{(k)}, \kappa_0);
                                                                                                             // small queue in the beginning
initialize a look-up table R(\lambda, i) = 0;
                                                                                                              // optimistic runtime estimate
while b remains do
      determine the best \hat{\lambda} according to R(\lambda, \cdot):
        get first element (i^{(k)}, \kappa) from Q_{\mathfrak{J}};
        Run \hat{\lambda} on i^{(k)} capped at \kappa;
        if terminates then
       R(\hat{\lambda}, i^{(k)}) := t;
      else
            R(\hat{\lambda}, i^{(k)}) := \kappa;
        Insert (i^{(k)}, 2 \cdot \kappa) at the end of Q_{\mathbf{S}};
      Replenish queue Q_{\hat{i}} if too small;
return \hat{\boldsymbol{\lambda}} := \arg\min_{\boldsymbol{\lambda} \in \boldsymbol{\Lambda}} \sum_{k=1}^{N} R(\boldsymbol{\lambda}, i^{(k)})
```

Extensions

• We can derive theoretical optimality guarantees with structured procrastination (SP)

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- In practice, plain SP is rather slow and requires the setting of some hyperparameters

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- In practice, plain SP is rather slow and requires the setting of some hyperparameters
- Several extensions and similar ideas:
 - ► [Kleinberg et al. 2019]
 - ▶ [Weisz et al. 2018]
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