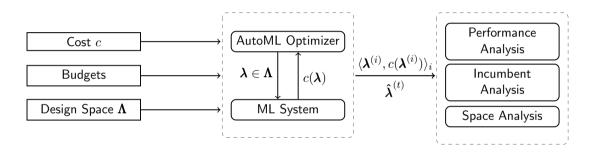
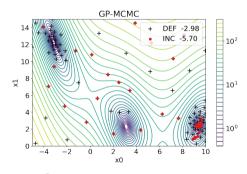
AutoML: Interpretability

Studying the AutoML Optimization Process

Bernd Bischl Frank Hutter Lars Kotthoff <u>Marius Lindauer</u> Joaquin Vanschoren

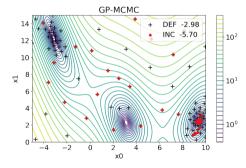


ightharpoonup focus on how the AutoML optimizer samples from the design space Λ



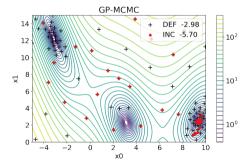
Source: [Lindauer et al. 2019]

Plot of a 1D or 2D function



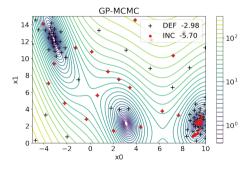
Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
- Background shows the ground truth (real function values)



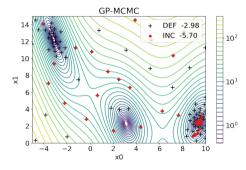
Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
- Background shows the ground truth (real function values)
- Dots are sampled points in the search space



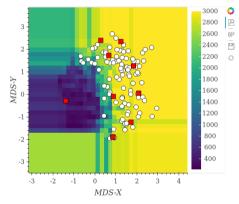
Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
- Background shows the ground truth (real function values)
- Dots are sampled points in the search space
- Typical approach in Bayesian Optimization community



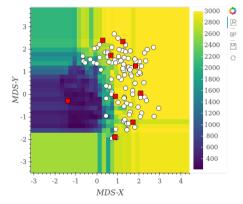
Source: [Lindauer et al. 2019]

- Plot of a 1D or 2D function
- Background shows the ground truth (real function values)
- Dots are sampled points in the search space
- Typical approach in Bayesian Optimization community
- → Impossible for higher dimensional problems?

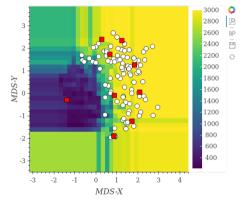


Source: [Lindauer et al. 2019]

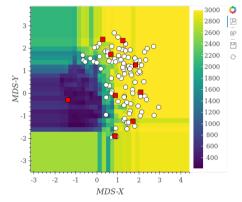
• Same idea as before but we have to project N-D into 2-D



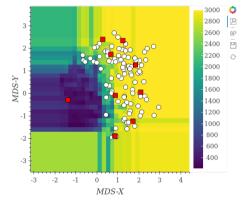
- Same idea as before but we have to project N-D into 2-D
 - ① Use an MDS to project down to 2-D



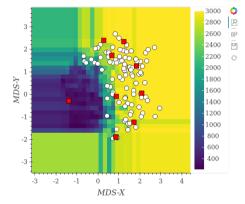
- Same idea as before but we have to project N-D into 2-D
 - $lue{1}$ Use an MDS to project down to 2-D
 - Each dot is single hyperparameter configuration



- Same idea as before but we have to project N-D into 2-D
 - **1** Use an MDS to project down to 2-D
 - Each dot is single hyperparameter configuration
 - Red squares are intermediate incumbents

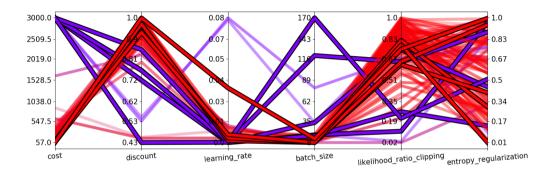


- Same idea as before but we have to project N-D into 2-D
 - **1** Use an MDS to project down to 2-D
 - Each dot is single hyperparameter configuration
 - Red squares are intermediate incumbents
 - The background is colored wrt a performance-estimate (e.g., reusing model fitted during BO)



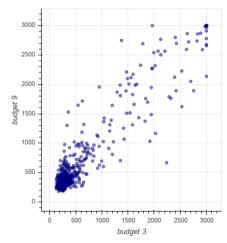
- Same idea as before but we have to project N-D into 2-D
 - ① Use an MDS to project down to 2-D
 - 2 Each dot is single hyperparameter configuration
 - Red squares are intermediate incumbents
 - The background is colored wrt a performance-estimate (e.g., reusing model fitted during BO)
 - Extension: Animation by showing how points get added over time

Parallel Coordinate Plot [Golovin et al. 2017]



- Each coordinate is one hyperparameter;
- Except the most left one: cost or loss

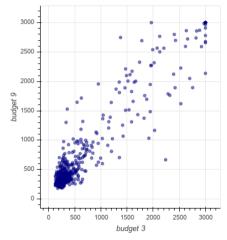
Multi-Fidelity Checks



Source: [Lindauer et al. 2019]

- Challenge of multi-fidelity approaches:
 - ► How to choose the fidelities (a.k.a. budgets)

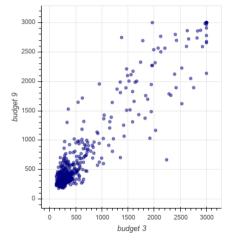
Multi-Fidelity Checks



Source: [Lindauer et al. 2019]

- Challenge of multi-fidelity approaches:
 - ► How to choose the fidelities (a.k.a. budgets)
- Important Property:
 - Decisions on small budgets should be reasonable for higher budgets

Multi-Fidelity Checks



Source: [Lindauer et al. 2019]

- Challenge of multi-fidelity approaches:
 - ► How to choose the fidelities (a.k.a. budgets)
- Important Property:
 - Decisions on small budgets should be reasonable for higher budgets
- Analysis:
 - Scatter plot of performance on Budget X vs. Budget Y
 - Each dot is sampled hyperparameter configuration
 - **3** Compute rank correlation (here: 0.69)