

Homework #9

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Math 285: Homework #9

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Question 1. Consider S^1 as a subset of the unit circle. We see that it admits multiplication, given by:

$$e^{it} \cdot e^{iu} = e^{i(t+u)}$$

for $u, t \in \mathbb{R}$.

Viewed as complex numbers, we can also express complex multiplication by an element $\cos t + i \sin t \in S^1$ as:

$$(\cos t + i \sin t)(x + iy) = ((\cos t)x - (\sin t)y) + i((\sin t)x + (\cos t)y)$$

Then for $g = (\cos t, \sin t) \in S^1 \subset \mathbb{R}^2$, the left multiplication is given by:

$$l_g(x, y) = ((\cos t)x - (\sin t)y, (\sin t)x + (\cos t)y)$$

Let $\omega = -ydx + xdy$ be a 1-form on S^1 . Prove that $l_g^*\omega = \omega$ for all $g \in S^1$.

Solution. We recall that for any pullback, by 17.10 and 17.9:

$$l_g^*(-ydx + xdy) = -l_g^*(y)d(l_g^*(x)) + l_g^*(x)d(l_g^*(y))$$

Fixing a $g = (\cos t, \sin t)$, we see that l_g^* has the action of sending $x \mapsto (\cos t)x - (\sin t)y, y \mapsto (\sin t)x + (\cos t)y$.

Thus, we have that:

$$-l_g^*(y)d(l_g^*(x)) + l_g^*(x)d(l_g^*(y)) = -[(\sin t)x + (\cos t)y]d((\cos t)x - (\sin t)y) + [(\cos t)x - (\sin t)y]d((\sin t)x + (\cos t)y)$$

Doing some more algebra, we see that this is equal to:

$$-[(\sin t)x + (\cos t)y][\cos t dx - \sin t dy] + [(\cos t)x - (\sin t)y][(\sin t)dx + (\cos t)dy] =$$

$$-\sin t \cos t(xdx) + \sin^2 t(xdy) - \cos^2 t(ydx) + \sin t \cos t(ydy) + \cos t \sin t(xdx) + \cos^2 t(xdy) - \sin^2 t(ydx) - \sin t \cos t(ydy) =$$

$$(-\sin t \cos t + \cos t \sin t)xdx + \sin^2 t + \cos^2 t xdy + (\sin t \cos t - \sin t \cos t)ydy - (\sin^2 t + \cos^2 t)ydx =$$

$$-ydx + xdy = \omega$$

Since the choice of g were arbitrary, as we used no properties of t other than trigonometric identities, we have that $l_g^* \omega = \omega$ for all $g \in S^1$. □

Question 2. We say that a sum $\sum \omega_\alpha$ of differential k -forms on a manifold M is locally finite if the collection of supports $\{\text{supp } \omega_\alpha\}$ is locally finite. Suppose that we have two locally finite sums $\sum \omega_\alpha, \sum \tau_\beta$, and $f \in C^\infty(M)$.

- (a) Show that for every $p \in M$, there exists a neighborhood U such that $\sum \omega_\alpha$ is finite.
- (b) Show that $\sum (\omega_\alpha + \tau_\alpha)$ is a locally finite sum, and

$$\sum (\omega_\alpha + \tau_\alpha) = \sum \omega_\alpha + \sum \tau_\alpha$$

- (c) Show that $\sum f \omega_\alpha$ is a locally finite sum, and that:

$$\sum f \cdot \omega_\alpha = f \cdot \left(\sum \omega_\alpha \right)$$

Solution. (a)

Fix some $p \in M$. Since the supports of ω_α are locally finite, we know that there exists a neighborhood U of p such that only finitely many of $\text{supp}(\omega_\alpha) \cap U \neq \emptyset$. Choose such a neighborhood U , and index the supports with non-empty intersection $\text{supp}(\omega_{\alpha_i})$ for $i \in (1, \dots, n)$.

Then, consider the value of $\sum \omega_\alpha$. Of course, if the support has trivial intersection with U , then $\omega_\alpha = 0$ on U , as the support of a k -form is defined as the closure of the complement of the zero set, hence the complement of the support is contained within the zero set.

Then, we see that $\sum \omega_\alpha = \sum_{i=1}^n \omega_{\alpha_i}$. But, at each point $q \in U$, each ω_{α_i} is a alternating k -tensor, hence a k -linear real function. Then, at q , this is a finite sum of finite values, hence finite.

Since this is true for all $q \in U$, since the choice of q was arbitrary, this is finite for all of U , and we may say that $\sum \omega_\alpha = \sum_{i=1}^n \omega_{\alpha_i} < \infty$ on all of U .

- (b)

We start by proving a lemma:

Lemma. Let ω, τ be k -forms on a manifold M .

Then, we have that:

$$\text{supp}(\omega + \tau) \subseteq \text{supp}(\omega) \cup \text{supp}(\tau)$$

Proof. Clearly, we know that as sets:

$$\{p \in M : \omega_p + \tau_p \neq 0\} \subseteq \{p \in M : \omega_p \neq 0\} \cup \{p \in M : \tau_p \neq 0\}$$

as of course, if $\omega_p + \tau_p \neq 0$, then at least one of ω_p, τ_p is non-0.

Since we have that $\{p \in M : \omega_p \neq 0\} \subseteq \text{supp}(\omega)$, being the closure, and same with τ , we see that:

$$\{p \in M : \omega_p + \tau_p \neq 0\} \subseteq \text{supp}(\omega) \cup \text{supp}(\tau)$$

Now, since $\text{supp}(\omega)$ is closed, and same with $\text{supp}(\tau)$, we see that the right hand side is a closed set, being the finite union of closed sets.

Then, since the closure of the left-hand side, is the smallest closed set that contains the left-hand side, and that the right hand side is a closed set, we have that:

$$\text{supp}(\omega + \tau) = \text{cl}(\{p \in M : \omega_p + \tau_p \neq 0\}) \subseteq \text{supp}(\omega) \cup \text{supp}(\tau)$$

as desired. □

We start by proving the equality at a fixed point. Let p be an arbitrary point in M . Since $\sum \omega_\alpha$ is locally finite, we may find a neighborhood U such that the intersection with $\text{supp}(\omega_\alpha)$ is trivial for all but α_i , $i \in (1, \dots, n)$. Similarly, there exists V such that the intersection with $\text{supp}(\tau_\beta)$ is trivial for all but β_j , $j \in (1, \dots, m)$.

Then, on $U \cap V$, we have that:

$$\sum \omega_\alpha + \sum \tau_\beta = \sum_{i=1}^n \omega_{\alpha_i} + \sum_{j=1}^m \tau_{\beta_j} = \sum_{i=1}^{\max(m,n)} \omega_{\alpha_i} + \tau_{\beta_j}$$

where WLOG if $m < n$, we pad with $\beta_{m+1}, \dots, \beta_n = 0$.

Thus, on $p \in U \cap V$, we have that:

$$\sum \omega_\alpha + \sum \tau_\beta = \sum_{i=1}^n \omega_{\alpha_i} + \sum_{j=1}^m \tau_{\beta_j} = \sum_{i=1}^l \omega_{\alpha_i} + \tau_{\beta_i} = \sum \omega_\alpha + \tau_\beta$$

Moreover, we see that on $U \cap V$, only $\omega_{\alpha_i}, \tau_{\beta_j}$ potentially non-0 for $i \in (1, \dots, n), j \in (1, \dots, m)$. Hence, for whatever numbering $\sum_\alpha \omega_\alpha + \tau_\alpha$ takes on, only these can have supports with non-trivial intersection. Since by our lemma, the support of $\omega + \tau$ is contained within the union of the supports, only up to $m + n$ distinct $\omega_\alpha + \tau_\alpha$ may have supports with non-trivial intersection. Thus, $\sum_\alpha \omega_\alpha + \tau_\alpha$ is locally finite at p .

However, the choice of p was trivial. Thus, we can repeat this argument for every point $p \in M$, and thus the sum is locally finite on all of M , and the equality holds on all of M .

(c)

In the same vein as (b), we first look at the support. It should be clear that for a single k -form ω , that we have set-wise:

$$\{p \in M : \omega_p = 0\} \subseteq \{p \in M : f \cdot \omega_p = 0\}$$

as if $\omega_p = 0$, of course $f \cdot \omega_p = 0$.

Now, because complements reverse the inclusion, this implies that:

$$\{p \in M : f \cdot \omega_p \neq 0\}^c \subseteq \{p \in M : \omega_p \neq 0\}$$

Then, since the support of ω is the closure, we have that:

$$\{p \in M : f \cdot \omega_p \neq 0\}^c \subseteq \text{supp}(\omega)$$

And finally, since the right hand side is a closed set, the closure of the left hand set must be contained within the right hand side, and so we have that:

$$\text{supp}(f \cdot \omega) \subseteq \text{supp}(\omega)$$

Now, look at the sum $f \cdot \sum \omega_\alpha$. Fix some $p \in M$. Since $\sum \omega_\alpha$ is locally finite, we may find a neighborhood such that only finitely many ω_α have supports which intersect U non-trivially. Label these forms ω_{α_i} for $i \in (1, \dots, n)$.

Then, on U , we have that

$$f \cdot \sum \omega_\alpha = f \cdot \sum_{i=1}^n \omega_{\alpha_i}$$

as on U , since the intersection with the support is trivial, if $\alpha \notin \{\alpha_i\}_{i=1}^n$, then $\omega_\alpha = 0$ identically on U .

Thus, since this is now a finite sum, we may distribute into the sum, and we find that we have a neighborhood with p such that:

$$f \cdot \sum \omega_\alpha = f \cdot \sum_{i=1}^n \omega_{\alpha_i} = \sum_{i=1}^n f \cdot \omega_{\alpha_i} = \sum_{\alpha} f \cdot \omega_\alpha$$

where the last equality comes from the fact that $\omega_\alpha = 0 \implies f \cdot \omega_\alpha = 0$ for all $\alpha \notin \{\alpha_i\}_{i=1}^n$ because, by the statement proved about the containment of the supports, $f \cdot \omega_\alpha$ must be locally finite, as only the $\text{supp}(\omega_{\alpha_i})$ have non-trivial intersection with U , and thus only the $\text{supp}(f \cdot \omega_{\alpha_i})$ could have non-trivial intersection.

Finally, since this procedure may be done for every point p , this sum becomes an equality of functions across all $p \in M$ and is locally finite everywhere, and so we conclude that:

$$f \cdot \sum \omega_\alpha = \sum f \cdot \omega_\alpha$$

with $\sum f \omega_\alpha$ as locally finite. □

Question 3. Let U be the open set $(0, \infty) \times (0, \pi) \times (0, 2\pi) \subseteq \mathbb{R}^3$, with the spherical coordinates (ρ, ϕ, θ) . Define $F : U \rightarrow \mathbb{R}^3$ via:

$$F(\rho, \phi, \theta) = (\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi)$$

Let x, y, z be the standard coordinates on \mathbb{R}^3 . Show that:

$$F^*(dx \wedge dy \wedge dz) = \rho^2 \sin \phi \, d\rho \wedge d\phi \wedge d\theta$$

Solution. First, we recall that by proposition 18.10, the pullback commutes with the wedge product. Thus, we have that:

$$F^*(dx \wedge dy \wedge dz) = F^*(dx) \wedge F^*(dy) \wedge F^*(dz)$$

Now, by proposition 17.9, since F is clearly C^∞ , each coordinate being the product of C^∞ functions, we see that:

$$F^*(dx) \wedge F^*(dy) \wedge F^*(dz) = dF^*(x) \wedge dF^*(y) \wedge dF^*(z) = d(x \circ F) \wedge d(y \circ F) \wedge d(z \circ F) =$$

$$d(\rho \sin \phi \cos \theta) \wedge d(\rho \sin \phi \sin \theta) \wedge d(\rho \cos \phi)$$

Expanding, we compute:

$$d(\rho \sin \phi \cos \theta) \wedge d(\rho \sin \phi \sin \theta) \wedge (\rho \cos \phi) = (\sin \phi \cos \theta d\rho + \rho \cos \phi \cos \theta d\phi - \rho \sin \phi \sin \theta d\theta) \wedge$$

$$(\sin \phi \sin \theta d\rho + \rho \cos \phi \sin \theta d\phi + \rho \sin \phi \cos \theta d\theta) \wedge (\cos \phi d\rho - \rho \sin \phi d\phi)$$

We notice that since 3-forms are spanned exactly by $d\rho \wedge d\phi \wedge d\theta$, we can look at only the terms that have one of each of $d\rho, d\phi, d\theta$ in some order, as otherwise, because $df \wedge df = 0$, and we can alternate over the wedge product at the cost of a factor of (-1) the other terms that repeat any single form vanish:

$$= \sin \phi \cos \theta d\rho \wedge \rho \sin \phi \cos \theta d\theta \wedge (-\rho \sin \phi d\phi) + \rho \cos \phi \cos \theta d\phi \wedge \rho \sin \phi \cos \theta d\theta \wedge \cos \phi d\rho +$$

$$(-\rho \sin \phi \sin \theta d\theta) \wedge \sin \phi \sin \theta d\rho \wedge (-\rho \sin \phi d\phi) + (-\rho \sin \phi \sin \theta d\theta) \wedge \rho \cos \phi \sin \theta d\phi \wedge \cos \phi d\rho$$

Cleaning up with some algebra, this is equal to:

$$-\rho^2 \sin^3 \phi \cos^2 \theta (d\rho \wedge d\theta \wedge d\phi) + \rho^2 \sin \phi \cos^2 \phi \cos^2 \theta (d\phi \wedge d\theta \wedge d\rho) + \\ \rho^2 \sin^3 \phi \sin^2 \theta (d\theta \wedge d\rho \wedge d\phi) - \rho^2 \sin \phi \cos^2 \phi \sin^2 \theta (d\theta \wedge d\phi \wedge d\rho)$$

Factoring out a $\rho^2 \sin \phi$ from the entire sum, and using the alternating nature to swap 1 forms to rewrite everything in terms of $d\rho \wedge d\phi \wedge d\theta$:

$$\rho^2 \sin \phi (\sin^2 \phi \cos^2 \theta + \cos^2 \phi \cos^2 \theta + \sin^2 \phi \sin^2 \theta + \cos^2 \phi \sin^2 \theta) (d\rho \wedge d\phi \wedge d\theta)$$

Regrouping, we use the fact that $\sin^2 + \cos^2 = 1$ twice to find this to be equal to:

$$\rho^2 \sin \phi (\sin^2 \phi (\cos^2 \theta + \sin^2 \theta) + \cos^2 \phi (\cos^2 \theta + \sin^2 \theta)) (d\rho \wedge d\phi \wedge d\theta) =$$

$$\rho^2 \sin \phi (\sin^2 \phi + \cos^2 \phi) (d\rho \wedge d\phi \wedge d\theta) = \rho^2 \sin \phi d\rho \wedge d\phi \wedge d\theta$$

as desired. □

Question 4. Recall that the electrical and magnetic fields obey the following equations (Maxwell's equations):

$$\begin{cases} \nabla \times E = -\frac{\partial B}{\partial t} & \nabla \times B = \frac{\partial E}{\partial t} \\ \nabla \cdot E = 0 & \nabla \cdot B = 0 \end{cases}$$

Corresponding to the vector fields E, B , we have the following forms:

$$E = E_1 dx + E_2 dy + E_3 dz$$

$$B = B_1 dy \wedge dz + B_2 dz \wedge dx + B_3 dx \wedge dy$$

Let \mathbb{R}^4 be flat space-time with coordinates (x, y, z, t) . Define F to be the 2-form:

$$F = E \wedge dt + B$$

Decide which of Maxwell's equations are equivalent to the condition $dF = 0$, and prove this fact.

Solution. Before we claim anything, we compute F in terms of the wedge product of 1-forms:

$$F = E \wedge dt + B = (E_1 dx + E_2 dy + E_3 dz) \wedge dt + (B_1 dy \wedge dz + B_2 dz \wedge dx + B_3 dx \wedge dy) = \\ E_1 dx \wedge dt + E_2 dy \wedge dt + E_3 dz \wedge dt + B_1 dy \wedge dz + B_2 dz \wedge dx + B_3 dx \wedge dy$$

Now, computing dF , and notating $\frac{\partial E_i}{\partial x} = (E_i)_x$, and same for y, z , and similarly for B_i we see that:

$$dF = dE_1 dx \wedge dt + dE_2 dy \wedge dt + dE_3 dz \wedge dt + dB_1 dy \wedge dz + dB_2 dz \wedge dx + dB_3 dx \wedge dy =$$

$$(E_1)_y dy \wedge dx \wedge dt + (E_1)_z dz \wedge dx \wedge dt + (E_2)_x dx \wedge dy \wedge dt + (E_2)_z dz \wedge dy \wedge dt + (E_3)_x dx \wedge dz \wedge dt + (E_3)_y dy \wedge dz \wedge dt +$$

$$(B_1)_x dx \wedge dy \wedge dz + (B_1)_t dt \wedge dy \wedge dz + (B_2)_y dy \wedge dz \wedge dx + (B_2)_t dt \wedge dz \wedge dx + (B_3)_z dz \wedge dx \wedge dy + (B_3)_t dt \wedge dx \wedge dy$$

where we have omitted writing any cases where we would have two of the same 1-forms in the wedge product, because they vanish due to $df \wedge df = 0$.

Collecting like terms by the anticommutativity of the wedge product, we see this as equal to:

$$\begin{aligned} & [(B_1)_x + (B_2)_y + (B_3)_z](dx \wedge dy \wedge dz) + [-(E_1)_y + (E_2)_x dx + (B_3)_t](dx \wedge dy \wedge dt) + \\ & [-(E_2)_z + (E_3)_y + (B_1)_t](dy \wedge dz \wedge dt) + [(E_1)_z - (E_3)_x + (B_2)_t](dz \wedge dx \wedge dt) \end{aligned}$$

For this to vanish, we have the following equations then:

$$\begin{cases} (B_1)_x + (B_2)_y + (B_3)_z = 0 \\ (B_1)_t = (E_2)_z - (E_3)_y \\ (B_2)_t = -(E_1)_z + (E_3)_x \\ (B_3)_t = (E_1)_y - (E_2)_x \end{cases}$$

It should be clear, that the first equation corresponds to $\nabla \cdot B = 0$.

To see the final 3 equations, we compute $\nabla \times E$:

$$\begin{vmatrix} x & y & z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_1 & E_2 & E_3 \end{vmatrix} = [(E_3)_y - (E_2)_z]x + [(E_1)_z - (E_3)_x]y + [(E_2)_x - (E_1)_y]z$$

Thus, we see that the last three equations correspond exactly to:

$$\frac{\partial}{\partial t} B = -\nabla \times E$$

Thus, we have that $dF = 0$ is equivalent to the following of Maxwell's equations:

$$\begin{cases} \nabla \times E = -\frac{\partial B}{\partial t} \\ \nabla \cdot B = 0 \end{cases}$$

□

Question 5. Let $\omega = dx^1 \wedge \dots \wedge dx^n$ be the volume form and $X = \sum x^i \partial / \partial x^i$ be the radial vector field on \mathbb{R}^n . Compute the contraction $i_X \omega$.

Solution. First, we compute $i_X(dx^j)$:

$$i_X(dx^j) = dx^j(X) = dx^j \left(\sum_k x^k \frac{\partial}{\partial x^k} \right) = x^j$$

Now, using the fact that i_X is an antiderivation of degree -1 , we proceed inductively. Denote $dx^1 \wedge \dots \wedge dx^n = \bigwedge_i dx^i$, that is, in order.

We wish to show that for $n \geq 2$:

$$i_X(\omega) = \sum_{k=1}^n (-1)^{k-1} x^k \left(\bigwedge_{j \neq k} dx^j \right)$$

Technically, we see that for the special case $n = 1$, then this sum still makes sense, as the wedge product is over nothing, and we have that as we proved for $\omega = x^1$ as a 1-form, $i_X(\omega) = x^1$.

Suppose $n = 2$.

Then, of course, we have by the action on the 1-form:

$$i_X(\omega) = i_X(dx^1 \wedge dx^2) = i_X(dx^1) \wedge dx^2 + (-1)dx^1 \wedge i_X(dx^2) = x^1 dx^2 - x^2 dx^1$$

which is exactly what we want in the case $n = 2$.

Now, suppose that we have that:

$$i_X(\omega) = i_X(dx^1 \wedge \dots \wedge dx^l) = \sum_k^l (-1)^{k-1} x^k \left(\bigwedge_{j \neq k} dx^j \right)$$

for all $l < n$.

Then, consider $\omega = dx^1 \wedge \dots \wedge dx^n$. We have that:

$$i_X(\omega) = i_X(dx^1 \wedge \dots \wedge dx^n) = i_X(dx^1) \wedge \bigwedge_{j=2}^n dx^j + (-1)dx^1 \wedge i_X \left(\bigwedge_{j=2}^n dx^j \right)$$

By the inductive step, since $i_X \left(\bigwedge_{j=2}^n dx^j \right)$ is the action on a $n-1$ form, this is equal to:

$$x^1 \bigwedge_{j=2}^n dx^j - dx^1 \wedge \sum_{l=2}^n (-1)^{l-2} x^l \left(\bigwedge_{i \neq l, i=2}^n dx^i \right)$$

where we notice that we have $(-1)^{l-2}$ because the first term is at $l = 2$, so we need to do a mild bit of reindexing.

Bringing the (-1) into the sum and the dx^1 into the wedge product on the left, and rewriting the first term a bit, we see:

$$x^1(-1)^{1-1} \bigwedge_{j=1, j \neq 1}^n dx^j + \sum_{l=2}^n (-1)^{l-1} x^l \left(\bigwedge_{i \neq l, i=1}^n dx^i \right)$$

We identify the first term as the $l = 1$ term of the sum on the right, so we can combine this into a single sum:

$$\sum_{l=1}^n (-1)^{l-1} x^l \left(\bigwedge_{j=1, j \neq l}^n dx^j \right)$$

as desired.

Thus, we see that

$$i_X(\omega) = \sum_{l=1}^n (-1)^{l-1} x^l \left(\bigwedge_{j=1, j \neq l}^n dx^j \right)$$

□

Question 6. Let $U = (0, \infty) \times (0, 2\pi) \subseteq \mathbb{R}^2$. Define $F : U \rightarrow \mathbb{R}^2$ via $F(r, \theta) = (r \cos \theta, r \sin \theta)$. Decide whether F is orientation-preserving or reversing as a diffeomorphism onto its image.

Solution. As per the definition, we take the standard orientations (r, θ) for U and (x, y) for \mathbb{R}^2 . By definition then, we need to see what orientation equivalence class $F^*(dx^1 \wedge dx^2)$ lands in, where we see $dx^1 \wedge dx^2$ as a representative of the orientation class of counterclockwise orientation.

Well, by the commutativity with the wedge product and the commutativity with the differential, the pullback acts via the following:

$$\begin{aligned} F^*(dx^1 \wedge dx^2) &= F^*(dx) \wedge F^*(dy) = d(F^*(x)) \wedge d(F^*(y)) = d(r \cos \theta) \wedge d(r \sin \theta) = \\ &[\cos \theta dr - r \sin \theta d\theta] \wedge [\sin \theta dr + r \cos \theta d\theta] \end{aligned}$$

Again, using the fact that $dr \wedge dr = 0 = d\theta \wedge d\theta$, we look only at terms that contain $dr \wedge d\theta, d\theta \wedge dr$ as those will be the only surviving terms:

$$r \cos^2 \theta (dr \wedge d\theta) - r \sin^2 \theta d\theta \wedge dr = [r \cos^2 \theta + r \sin^2 \theta] dr \wedge d\theta = r dr \wedge d\theta$$

Since $r \in (0, \infty)$ we see that F^* takes $dx \wedge dy$ to the orientation class of $[dr \wedge d\theta]$ and hence is orientation preserving relative to the choice of orientations for the manifolds $(U, [dr \wedge d\theta]), (\mathbb{R}^2, [dx \wedge dy])$.

I realize at this point, I could've used Proposition 21.11 and just computed the Jacobian determinant. Take the ordering of the coordinates as $x^1 = r, x^2 = \theta$, and the ordering in the codomain as $y^1 = x = r \cos \theta, y^2 = y = r \sin \theta$.

$$\det \left[\frac{\partial F^i}{\partial x^j} \right] = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r$$

But again, since $r > 0$, we have that this is always positive, hence orientation preserving with respect to $[dr \wedge d\theta]$ and $[dx \wedge dy]$.

□