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def main():
    Print_Function()
    (x, y, z) = xyz = symbols('x,y,z',real=True)
    (o3d, ex, ey, ez) = Ga.build('e_x e_y e_z', g=[1, 1, 1], coords=xyz)
    grad = o3d.grad
    (u, v) = uv = symbols('u,v',real=True)
    (g2d, eu, ev) = Ga.build('e_u e_v', coords=uv)
    grad_uv = g2d.grad
    v_xyz = o3d.mv('v','vector')
    A_xyz = o3d.mv('A','vector',f=True)
    A_uv = g2d.mv('A','vector',f=True)
    print '#3d orthogonal ($A$ is vector function)'
    print 'A =', A_xyz
    print '%A^{2} =', A_xyz * A_xyz
    print 'grad|A =', grad | A_xyz
    print 'grad*A =', grad * A_xyz
    print 'v|(grad*A) =', v_xyz |(grad*A_xyz)
    print '#2d general ($A$ is vector function)'
    print 'A =', A_uv
    print '%A^{2} =', A_uv * A_uv
    print 'grad|A =', grad_uv | A_uv
    print 'grad*A =', grad_uv * A_uv
    A = o3d.lt('A')
    print '#3d orthogonal ($A,\\;B$ are linear transformations)'
    print 'A =', A
    print '\\f{\\det}{A} =', A.det()
    print '\\overline{A} =', A.adj()
    print '\\f{\\Tr}{A} =', A.tr()
    print '\\f{A}{e_x^e_y} =', A(ex^ey)
    print '\\f{A}{e_x}^\\f{A}{e_y} =', A(ex)^A(ey)
    B = o3d.lt('B')
    print 'A + B =', A + B
    print 'AB =', A * B
    print 'A - B =', A - B
    print '#2d general ($A,\\;B$ are linear transformations)'
    A2d = g2d.lt('A')
    print 'A =', A2d
    print '\\f{\\det}{A} =', A2d.det()
    print '\\overline{A} =', A2d.adj()
    print '\\f{\\Tr}{A} =', A2d.tr()
    print '\\f{A}{e_u^e_v} =', A2d(eu^ev)
    print '\\f{A}{e_u}^\\f{A}{e_v} =', A2d(eu)^A2d(ev)
    B2d = g2d.lt('B')
    print 'B =', B2d
    print 'A + B =', A2d + B2d
    print 'AB =', A2d * B2d
    print 'A - B =', A2d - B2d
    a = g2d.mv('a','vector')
    b = g2d.mv('b','vector')
    print r'a|\\f{\\overline{A}}{b}-b|\\f{\\underline{A}}{a} =',((a|A2d.adj()(b))-(b|A2d(a))).simplify()
    m4d = Ga('e_t e_x e_y e_z', g=[1, -1, -1, -1],coords=symbols('t,x,y,z',real=True))
    T = m4d.lt('T')
    print 'g =', m4d.g
    print r'\\underline{T} =',T
    print r'\\overline{T} =',T.adj()
    print r'\\f{\\det}{\\underline{T}} =',T.det()
    print r'\\f{\\mbox{tr}}{\\underline{T}} =',T.tr()
    a = m4d.mv('a','vector')
    b = m4d.mv('b','vector')

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print r'a|\f{\overline{T}}{b}-b|\f{\underline{T}}{a}=',((a|T.adj()(b))-(b|T(a))).simplify()
coords = (r, th, phi) = symbols('r,theta,phi', real=True)
(sp3d, er, eth, ephi) = Ga.build('e_r e_th e_ph', g=[1, r**2, r**2*sin(th)**2], coords=coords)
grad = sp3d.grad
sm_coords = (u, v) = symbols('u,v', real=True)
smap = [1, u, v] # Coordinate map for sphere of r = 1
sph2d = sp3d.sm(smap, sm_coords, norm=True)
(eu, ev) = sph2d.mv()
grad_uv = sph2d.grad
F = sph2d.mv('F', 'vector', f=True)
f = sph2d.mv('f', 'scalar', f=True)
print 'f =', f
print 'grad*f =', grad_uv * f
print 'F =', F
print 'grad*F =', grad_uv * F
tp = (th, phi) = symbols('theta,phi', real=True)
smap = [sin(th)*cos(phi), sin(th)*sin(phi), cos(th)]
sph2dr = o3d.sm(smap, tp, norm=True)
(eth, ephi) = sph2dr.mv()
grad_tp = sph2dr.grad
F = sph2dr.mv('F', 'vector', f=True)
f = sph2dr.mv('f', 'scalar', f=True)
print 'f =', f
print 'grad*f =', grad_tp * f
print 'F =', F
print 'grad*F =', grad_tp * F
return

```

Code Output: 3d orthogonal ( $A$  is vector function)

$$\begin{aligned}
 A &= A^x \mathbf{e}_x + A^y \mathbf{e}_y + A^z \mathbf{e}_z \\
 A^2 &= (A^x)^2 + (A^y)^2 + (A^z)^2 \\
 \nabla \cdot A &= \partial_x A^x + \partial_y A^y + \partial_z A^z \\
 \nabla A &= (\partial_x A^x + \partial_y A^y + \partial_z A^z) + (-\partial_y A^x + \partial_x A^y) \mathbf{e}_x \wedge \mathbf{e}_y + (-\partial_z A^x + \partial_x A^z) \mathbf{e}_x \wedge \mathbf{e}_z + (-\partial_z A^y + \partial_y A^z) \mathbf{e}_y \wedge \mathbf{e}_z \\
 v \cdot (\nabla A) &= (v^y \partial_y A^x - v^y \partial_x A^y + v^z \partial_z A^x - v^z \partial_x A^z) \mathbf{e}_x + (-v^x \partial_y A^x + v^x \partial_x A^y + v^z \partial_z A^y - v^z \partial_y A^z) \mathbf{e}_y + (-v^x \partial_z A^x + v^x \partial_x A^z - v^y \partial_z A^y + v^y \partial_y A^z) \mathbf{e}_z
 \end{aligned}$$

2d general ( $A$  is vector function)

$$\begin{aligned}
 A &= A^u \mathbf{e}_u + A^v \mathbf{e}_v \\
 A^2 &= (e_u \cdot e_u) (A^u)^2 + 2(e_u \cdot e_v) A^u A^v + (e_v \cdot e_v) (A^v)^2 \\
 \nabla \cdot A &= \partial_u A^u + \partial_v A^v \\
 \nabla A &= (\partial_u A^u + \partial_v A^v) + \frac{-(e_u \cdot e_u) \partial_v A^u + (e_u \cdot e_v) \partial_u A^u - (e_u \cdot e_v) \partial_v A^v + (e_v \cdot e_v) \partial_u A^v}{(e_u \cdot e_u)(e_v \cdot e_v) - (e_u \cdot e_v)^2} \mathbf{e}_u \wedge \mathbf{e}_v
 \end{aligned}$$

3d orthogonal ( $A, B$  are linear transformations)

$$\begin{aligned}
 A &= \begin{pmatrix} L(\mathbf{e}_x) = A_{xx} \mathbf{e}_x + A_{yx} \mathbf{e}_y + A_{zx} \mathbf{e}_z \\ L(\mathbf{e}_y) = A_{xy} \mathbf{e}_x + A_{yy} \mathbf{e}_y + A_{zy} \mathbf{e}_z \\ L(\mathbf{e}_z) = A_{xz} \mathbf{e}_x + A_{yz} \mathbf{e}_y + A_{zz} \mathbf{e}_z \end{pmatrix} \\
 \det(A) &= A_{xz}(A_{yx}A_{zy} - A_{yy}A_{zx}) - A_{yz}(A_{xx}A_{zy} - A_{xy}A_{zx}) + A_{zz}(A_{xx}A_{yy} - A_{xy}A_{yx}) \\
 \overline{A} &= \begin{pmatrix} L(\mathbf{e}_x) = A_{xx} \mathbf{e}_x + A_{xy} \mathbf{e}_y + A_{xz} \mathbf{e}_z \\ L(\mathbf{e}_y) = A_{yx} \mathbf{e}_x + A_{yy} \mathbf{e}_y + A_{yz} \mathbf{e}_z \\ L(\mathbf{e}_z) = A_{zx} \mathbf{e}_x + A_{zy} \mathbf{e}_y + A_{zz} \mathbf{e}_z \end{pmatrix} \\
 \text{Tr}(A) &= A_{xx} + A_{yy} + A_{zz} \\
 A(e_x \wedge e_y) &= (A_{xx}A_{yy} - A_{xy}A_{yx}) \mathbf{e}_x \wedge \mathbf{e}_y + (A_{xx}A_{zy} - A_{xy}A_{zx}) \mathbf{e}_x \wedge \mathbf{e}_z + (A_{yx}A_{zy} - A_{yy}A_{zx}) \mathbf{e}_y \wedge \mathbf{e}_z
 \end{aligned}$$

$$A(e_x) \wedge A(e_y) = (A_{xx}A_{yy} - A_{xy}A_{yx})\mathbf{e}_x \wedge \mathbf{e}_y + (A_{xx}A_{zy} - A_{xy}A_{zx})\mathbf{e}_x \wedge \mathbf{e}_z + (A_{yx}A_{zy} - A_{yy}A_{zx})\mathbf{e}_y \wedge \mathbf{e}_z$$

$$A+B=\left\{\begin{array}{l} L(\mathbf{e}_x)=\quad (A_{xx}+B_{xx})\mathbf{e}_x+(A_{yx}+B_{yx})\mathbf{e}_y+(A_{zx}+B_{zx})\mathbf{e}_z\\ L(\mathbf{e}_y)=\quad (A_{xy}+B_{xy})\mathbf{e}_x+(A_{yy}+B_{yy})\mathbf{e}_y+(A_{zy}+B_{zy})\mathbf{e}_z\\ L(\mathbf{e}_z)=\quad (A_{xz}+B_{xz})\mathbf{e}_x+(A_{yz}+B_{yz})\mathbf{e}_y+(A_{zz}+B_{zz})\mathbf{e}_z \end{array}\right\}$$

$$AB=\left\{\begin{array}{l} L(\mathbf{e}_x)=\quad (A_{xx}B_{xx}+A_{xy}B_{yx}+A_{xz}B_{zx})\mathbf{e}_x+(A_{yx}B_{xx}+A_{yy}B_{yx}+A_{yz}B_{zx})\mathbf{e}_y+(A_{zx}B_{xx}+A_{zy}B_{yx}+A_{zz}B_{zx})\mathbf{e}_z\\ L(\mathbf{e}_y)=\quad (A_{xx}B_{xy}+A_{xy}B_{yy}+A_{xz}B_{zy})\mathbf{e}_x+(A_{yx}B_{xy}+A_{yy}B_{yy}+A_{yz}B_{zy})\mathbf{e}_y+(A_{zx}B_{xy}+A_{zy}B_{yy}+A_{zz}B_{zy})\mathbf{e}_z\\ L(\mathbf{e}_z)=\quad (A_{xx}B_{xz}+A_{xy}B_{yz}+A_{xz}B_{zz})\mathbf{e}_x+(A_{yx}B_{xz}+A_{yy}B_{yz}+A_{yz}B_{zz})\mathbf{e}_y+(A_{zx}B_{xz}+A_{zy}B_{yz}+A_{zz}B_{zz})\mathbf{e}_z \end{array}\right\}$$

$$A-B=\left\{\begin{array}{l} L(\mathbf{e}_x)=\quad (A_{xx}-B_{xx})\mathbf{e}_x+(A_{yx}-B_{yx})\mathbf{e}_y+(A_{zx}-B_{zx})\mathbf{e}_z\\ L(\mathbf{e}_y)=\quad (A_{xy}-B_{xy})\mathbf{e}_x+(A_{yy}-B_{yy})\mathbf{e}_y+(A_{zy}-B_{zy})\mathbf{e}_z\\ L(\mathbf{e}_z)=\quad (A_{xz}-B_{xz})\mathbf{e}_x+(A_{yz}-B_{yz})\mathbf{e}_y+(A_{zz}-B_{zz})\mathbf{e}_z \end{array}\right\}$$

2d general ( $A, B$  are linear transformations)

$$A=\left\{\begin{array}{l} L(\mathbf{e}_u)=\quad A_{uu}\mathbf{e}_u+A_{vu}\mathbf{e}_v\\ L(\mathbf{e}_v)=\quad A_{uv}\mathbf{e}_u+A_{vv}\mathbf{e}_v \end{array}\right\}$$

$$\det(A)=A_{uu}A_{vv}-A_{uv}A_{vu}$$

$$\overline{A}=\left\{\begin{array}{l} L(\mathbf{e}_u)=\quad \frac{1}{(e_u\cdot e_u)(e_v\cdot e_v)-(e_u\cdot e_v)\wedge 2}\left(-(e_u\cdot e_u)(e_u\cdot e_v)A_{uv}+(e_u\cdot e_u)(e_v\cdot e_v)A_{uu}-(e_u\cdot e_v)\wedge 2A_{vv}+(e_u\cdot e_v)(e_v\cdot e_v)A_{vu}\right)\mathbf{e}_u+\frac{1}{(e_u\cdot e_u)(e_v\cdot e_v)-(e_u\cdot e_v)\wedge 2}\left((e_u\cdot e_u)\wedge 2A_{uv}-(e_u\cdot e_u)(e_u\cdot e_v)A_{uu}+(e_u\cdot e_u)(e_u\cdot e_v)A_{vv}-(e_u\cdot e_v)\wedge 2A_{vu}\right)\mathbf{e}_v\\ L(\mathbf{e}_v)=\quad \frac{1}{(e_u\cdot e_u)(e_v\cdot e_v)-(e_u\cdot e_v)^2}\left(-(e_u\cdot e_v)^2A_{uv}+(e_u\cdot e_v)(e_v\cdot e_v)A_{uu}-(e_u\cdot e_v)(e_v\cdot e_v)A_{vv}+(e_v\cdot e_v)^2A_{vu}\right)\mathbf{e}_u+\frac{1}{(e_u\cdot e_u)(e_v\cdot e_v)-(e_u\cdot e_v)^2}\left((e_u\cdot e_u)(e_u\cdot e_v)A_{uv}+(e_u\cdot e_u)(e_v\cdot e_v)A_{vv}-(e_u\cdot e_v)^2A_{uu}-(e_u\cdot e_v)(e_v\cdot e_v)A_{vu}\right)\mathbf{e}_v \end{array}\right.$$

$$\mathrm{Tr}\left(A\right)=-\frac{\left(e_u\cdot e_u\right)\left(e_v\cdot e_v\right)A_{uu}}{-\left(e_u\cdot e_u\right)\left(e_v\cdot e_v\right)+\left(e_u\cdot e_v\right)^2}-\frac{\left(e_u\cdot e_u\right)\left(e_v\cdot e_v\right)A_{vv}}{-\left(e_u\cdot e_u\right)\left(e_v\cdot e_v\right)+\left(e_u\cdot e_v\right)^2}+\frac{\left(e_u\cdot e_v\right)^2A_{uu}}{-\left(e_u\cdot e_u\right)\left(e_v\cdot e_v\right)+\left(e_u\cdot e_v\right)^2}+\frac{\left(e_u\cdot e_v\right)^2A_{vv}}{-\left(e_u\cdot e_u\right)\left(e_v\cdot e_v\right)+\left(e_u\cdot e_v\right)^2}$$

$$A(e_u\wedge e_v)=(A_{uu}A_{vv}-A_{uv}A_{vu})\mathbf{e}_u\wedge \mathbf{e}_v$$

$$A(e_u)\wedge A(e_v)=(A_{uu}A_{vv}-A_{uv}A_{vu})\mathbf{e}_u\wedge \mathbf{e}_v$$

$$B=\left\{\begin{array}{l} L(\mathbf{e}_u)=\quad B_{uu}\mathbf{e}_u+B_{vu}\mathbf{e}_v\\ L(\mathbf{e}_v)=\quad B_{uv}\mathbf{e}_u+B_{vv}\mathbf{e}_v \end{array}\right\}$$

$$A+B=\left\{\begin{array}{l} L(\mathbf{e}_u)=\quad (A_{uu}+B_{uu})\mathbf{e}_u+(A_{vu}+B_{vu})\mathbf{e}_v\\ L(\mathbf{e}_v)=\quad (A_{uv}+B_{uv})\mathbf{e}_u+(A_{vv}+B_{vv})\mathbf{e}_v \end{array}\right\}$$

$$AB=\left\{\begin{array}{l} L(\mathbf{e}_u)=\quad (A_{uu}B_{uu}+A_{uv}B_{vu})\mathbf{e}_u+(A_{vu}B_{uu}+A_{vv}B_{vu})\mathbf{e}_v\\ L(\mathbf{e}_v)=\quad (A_{uu}B_{uv}+A_{uv}B_{vv})\mathbf{e}_u+(A_{vu}B_{uv}+A_{vv}B_{vv})\mathbf{e}_v \end{array}\right\}$$

$$A-B=\left\{\begin{array}{l} L(\mathbf{e}_u)=\quad (A_{uu}-B_{uu})\mathbf{e}_u+(A_{vu}-B_{vu})\mathbf{e}_v\\ L(\mathbf{e}_v)=\quad (A_{uv}-B_{uv})\mathbf{e}_u+(A_{vv}-B_{vv})\mathbf{e}_v \end{array}\right\}$$

$$a\cdot \overline{A}(b)-b\cdot \underline{A}(a)=0$$

$$g=\begin{bmatrix}1&0&0&0\\0&-1&0&0\\0&0&-1&0\\0&0&0&-1\end{bmatrix}$$

$$\underline{T}=\left\{\begin{array}{l} L(\mathbf{e}_t)=\quad T_{tt}\mathbf{e}_t+T_{xt}\mathbf{e}_x+T_{yt}\mathbf{e}_y+T_{zt}\mathbf{e}_z\\ L(\mathbf{e}_x)=\quad T_{tx}\mathbf{e}_t+T_{xx}\mathbf{e}_x+T_{yx}\mathbf{e}_y+T_{zx}\mathbf{e}_z\\ L(\mathbf{e}_y)=\quad T_{ty}\mathbf{e}_t+T_{xy}\mathbf{e}_x+T_{yy}\mathbf{e}_y+T_{zy}\mathbf{e}_z\\ L(\mathbf{e}_z)=\quad T_{tz}\mathbf{e}_t+T_{xz}\mathbf{e}_x+T_{yz}\mathbf{e}_y+T_{zz}\mathbf{e}_z \end{array}\right\}$$

$$\overline{T}=\left\{\begin{array}{l} L(\mathbf{e}_t)=\quad T_{tt}\mathbf{e}_t-T_{tx}\mathbf{e}_x-T_{ty}\mathbf{e}_y-T_{tz}\mathbf{e}_z\\ L(\mathbf{e}_x)=\quad -T_{xt}\mathbf{e}_t+T_{xx}\mathbf{e}_x+T_{xy}\mathbf{e}_y+T_{xz}\mathbf{e}_z\\ L(\mathbf{e}_y)=\quad -T_{yt}\mathbf{e}_t+T_{yx}\mathbf{e}_x+T_{yy}\mathbf{e}_y+T_{yz}\mathbf{e}_z\\ L(\mathbf{e}_z)=\quad -T_{zt}\mathbf{e}_t+T_{zx}\mathbf{e}_x+T_{zy}\mathbf{e}_y+T_{zz}\mathbf{e}_z \end{array}\right\}$$

$$\det(\underline{T})=-T_{tz}\left(T_{xt}T_{yx}T_{zy}-T_{xt}T_{yy}T_{zx}-T_{xx}T_{yt}T_{zy}+T_{xx}T_{yy}T_{zt}+T_{xy}T_{yt}T_{zx}-T_{xy}T_{yx}T_{zt}\right)+T_{xz}\left(T_{tt}T_{yx}T_{zy}-T_{tt}T_{yy}T_{zx}-T_{tx}T_{yt}T_{zy}+T_{tx}T_{yy}T_{zt}+T_{ty}T_{yt}T_{zx}-T_{ty}T_{yx}T_{zt}\right)-T_{yz}\left(T_{tt}T_{xx}T_{zy}-T_{tt}T_{xy}T_{zx}-T_{tx}T_{xt}T_{zy}+T_{tx}T_{xy}T_{zx}-T_{tx}T_{xt}T_{zy}+T_{tx}T_{xy}T_{zx}-T_{tx}T_{xt}T_{zy}+T_{tx}T_{xy}T_{zx}\right)$$

$$\mathrm{tr}\left(\underline{T}\right)=T_{tt}+T_{xx}+T_{yy}+T_{zz}$$

$$a\cdot \overline{T}(b)-b\cdot \underline{T}(a)=0$$

$$f=f$$

$$\nabla f = \partial_u f \mathbf{e}_u + \frac{\partial_v f}{\sin(u)} \mathbf{e}_v$$

$$F = F^u \boldsymbol{e}_u + F^v \boldsymbol{e}_v$$

$$\boldsymbol{\nabla} F = \left( \frac{F^u}{\tan(u)} + \partial_u F^u + \frac{\partial_v F^v}{\sin(u)} \right) + \left( \frac{F^v}{\tan(u)} + \partial_u F^v - \frac{\partial_v F^u}{\sin(u)} \right) \boldsymbol{e}_u \wedge \boldsymbol{e}_v$$

$$f=f$$

$$\boldsymbol{\nabla} f = \partial_\theta f \boldsymbol{e}_\theta + \frac{\partial_\phi f}{\sin(\theta)} \boldsymbol{e}_\phi$$

$$F=F^\theta \boldsymbol{e}_\theta + F^\phi \boldsymbol{e}_\phi$$

$$\boldsymbol{\nabla} F = \left( \frac{F^\theta}{\tan(\theta)} + \partial_\theta F^\theta + \frac{\partial_\phi F^\phi}{\sin(\theta)} \right) + \left( \frac{F^\phi}{\tan(\theta)} + \partial_\theta F^\phi - \frac{\partial_\phi F^\theta}{\sin(\theta)} \right) \boldsymbol{e}_\theta \wedge \boldsymbol{e}_\phi$$