COMPUTER VISION AND ROBOTICS · SLAM · DEEP LEARNING · PERCEPTION

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Education

University of California San Diego (UCSD) - Jacobs School of Engineering

La Jolla, CA. USA

M.S. IN ELECTRICAL AND COMPUTER ENGINEERING

Exp. Jun. 2020

Average GPA: 4.0/4.0

National Taiwan University (NTU)

Taipei, Taiwan

B.S. IN ELECTRICAL ENGINEERING

Sep. 2013 - Jan. 2018

• Average GPA: 4.14/4.3

Skills

Programming

Internships

C++, Python - scikit-learn/ Keras/ Tensorflow, Matlab, Robot Operating System (ROS), JavaScript (back-end), Arduino

Research Intern, AI Center at Inventec Corp.

Taipei, Taiwan

PROJECT: INDOOR NAVIGATION

Jul. 2018 - Sep. 2018

- · Developed robotic control system under ROS framework, successfully achieving cloud training and evaluation
- Trained and tested models using CNN deep reinforcement learning in Tensorflow, reaching success under virtual environment

Software Development Intern, Dell Technology

Taipei, Taiwan

PROJECT: TOOL DEVELOPMENT

- Jul. 2016 Aug. 2016
- Designed the architecture of software tools, to speed up debugging process for server development
 Created debugging tools from back-end algorithm to front-end interface in python, in use for over 1 year
- Research & Projects

Research Assistant, Visual Computing in UCSD (Prof. Manmohan Chandraker, Prof. Hao Su)

La Jolla, CA. USA

PROJECT: DEEP STRUCTURE FROM MOTION (SFM)

Oct. 2018 - Current

• Designed deep learning networks for feature detection or description in SFM pipeline, optimizing using self-supervised method

Researcher, Media IC & System Lab (Po-Chen Wu, Prof. Shao-Yi Chien)

Taipei, Taiwan

PROJECT: POSE TRACKING FROM A PLANAR TARGET

Nov. 2017 - Jan. 2018

- $\bullet \ \ \text{Designed "Particle Filter" to solve the problem of pose ambiguity, better tracking planar target in augment reality (AR)}$
- Experimented algorithm on Object Pose Tracking (OPT) Dataset, benchmarking with state-of-the-art "Kalman Filter" method

Project, Machine Learning (Prof. Hung-yi Lee)

Taipei, Taiwan

PROJECT: STACK EXCHANGE TAGS COMPETITION ON KAGGLE

Nov. 2016 - Jan. 2017

- · Devised automatic tag prediction from given titles and answers, learning connections between articles
- Constructed unsupervised learning model (TF-IDF) and Part-Of-Speech method in Python, achieving top 25% in 380 participants

Project, HackNTU Hardware Hackathon Competition

Taipei, Taiwan

PROJECT: CAR SAFETY SYSTEM

Mar. 2017

- · Invented system to reduce casualties in accidents within 24 hours, winning Enterprise Award from FET & Gatec
- Created prototype of safe car using wood, Arduino, and Linkit, exhibiting 3 features in demo

Researcher, Media IC & System Lab (Prof. Shao-Yi Chien)

Taipei, Taiwan

PROJECT: ODOMETRY FOR IMPRECISE AUGMENTED REALITY (AR)

Feb. 2016 - Jun. 2017

- $\bullet \ \ \, \text{Developed multimedia method based on "ORB-SLAM"}, aiming to reduce power consumption for AR devices$
- Experimented on SLAM with low-resolution image frames, achieving same RMSE loss on trajectory with 10% of original size
- · Remodeled gyro's data into ORB-SLAM as initial transformation matrix for localization, visualizing and interpreting the results

Leadership.

President of Aboriginal Service Club, NTU (Prof. Chien-Mo Li)

Taipei, Taiwan

LEADER OF PUBLIC RELATIONS/ VICE PRESIDENT/ PRESIDENT

Sep. 2014 - Jul. 2017

- · Arranged winter/summer camps in aboriginal villages in remote mountains of Taiwan, exposing primary school students to science
- Organized volunteer training with 60 teammates as club president for 6 months, operating 14 day services
- · Initiated effective communication and creative thinking between teammates, shaping positive environment in the club

Honors & Awards

2017	Certificate of Altruistic Award, NTU	Taipei, Taiwan
2016	Scholarship (USD\$5,000), Lin, Hsiung-Chen Foundation	Taipei, Taiwan
2014	Certification of Presidential Award, NTU (top 5% of all NTUEE students)	Taipei, Taiwan